SPIN TEST: Assessment of compliancy for centrifugal blood pumps

Albani G., Bonomi S., Criseo E., Pasini N., Rota A.



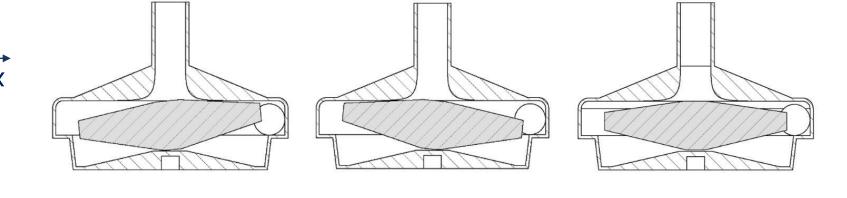
CASE STUDY



Centrifugal Blood Pumps: devices used during extracorporeal circulation; the blood flow enters from the inlet of the pump and is pushed by the rotor in such a way as to exit through the outlet, oriented at an angle of 90 ° to the inlet



Problem: movement of the impeller which tends to make a flickering movement along the z-x and z-y plane. This could cause haemolysis and thrombi



Solution: Spin Test to quantify the flickering of the impeller and classify the pumps

between compliant and non-compliant

Today's

approach



Company operator



Hearing the noise produced by the pump



Motion of

pump's impeller

Classify the pumps in compliant and not compliant

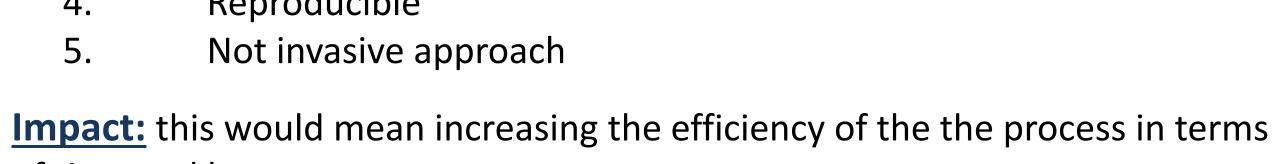
GOAL



Find a **STANDARDIZED**, **AUTOMATED** and **NON-DAMAGING** protocol to test the pump in order to assess its acceptability



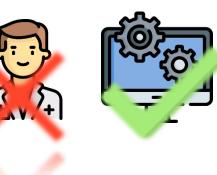
- Optimize the process
- Standardize the modality to eliminate the intra-subject variability
- Not distructive test
- Reproducible
- Not invasive approach



of time and human resources

New approach: the operator no longer has a determining role in the classification of the pumps. In fact, through a machine learning model, the classification becomes more objective





MATHERIALS AND METHODS

OPTICAL PROXIMITY SENSORS

Explanation: when a voltage is applied, the diode emits IR light that propagates until hits an object and it is reflected towards the sensor

Efficacy: measure how much the impeller approaches or moves away from the sensors

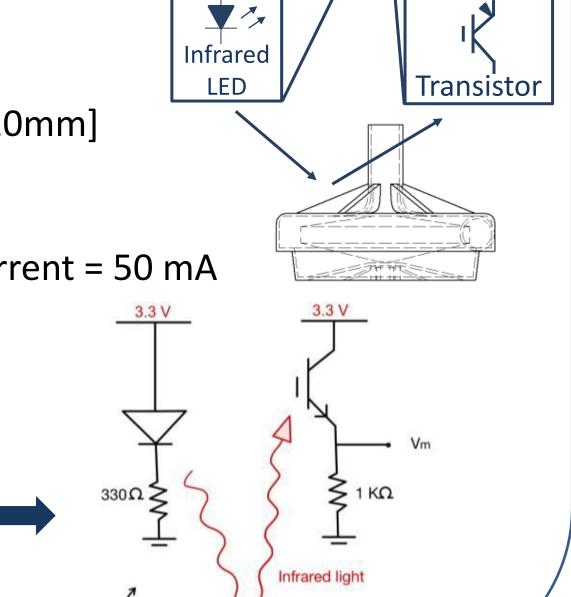
OPB730F sensors

- ✓ Linearity range [2.5-10mm]
- ✓ Filter ✓ Internal barrier
- ✓ Max Input diode's current = 50 mA





Every sensor used is associated to a circuit



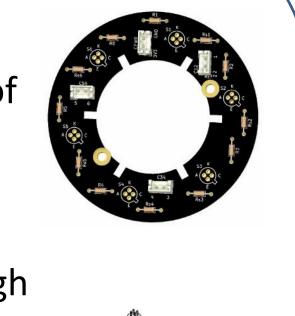
PCB AND DEVELOPMENT BOARD

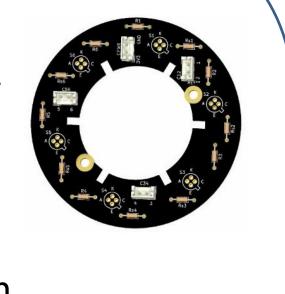
PCB (Printed Circuit Board): 6 sensors were used to achieve a precise measure of the impeller fluttering.

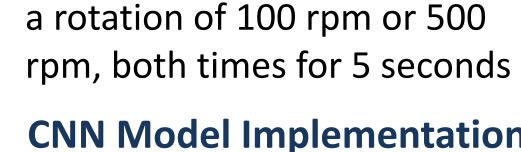
The PCB reduces the extension of the circuits and makes the set-up compact. The PCB is then fixed to the pump through

a support which allows maintaining the sensors in the right position

Development Board: the development board is what brings the output signals of the sensors as input for the graphical interface. In this way the signals are displayed to the operator in a clear way







using two kinds of test: imposing 1250

CNN Model Implementation

compliant and non compliant.

Data acquisition was performed

1. The raw data obtained from the sensors is elaborated using data augmentation, in this way it is obtained the training set

MACHINE LEARNING

Data Acquisition: the set-up with is used to register the

signal from 51 pumps. These were divided a priori between

- 2. Preparation of test-set
- 3. Definition of model architecture

Model Tuning: defining optimal parameters to get the best result with the model architecture chosen. The parameters to be optimized are: dimension of the windows used to elaborate the data, filters' dimension and their number

RESULTS AND DISCUSSION

MODEL IDEA

The classifier works applying a simply threshold:

1, $S \ge 0.5 \Rightarrow Compliant$

 $0, S < 0.5 \Rightarrow Non Compliant$

The confidence of the classificator is given by:

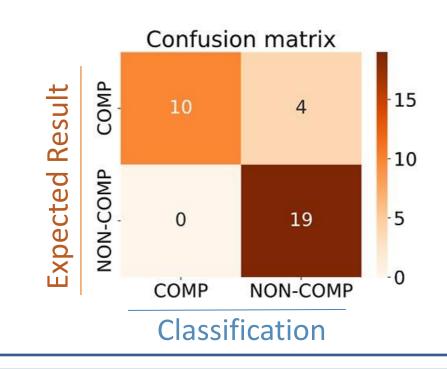
 $K=2\cdot |S-0.5|\cdot 100$

THE DATASET

Initial dataset is composed by 33 pumps:

- 11 pumps are used to calculate the the accuracy of the model
- 22 pumps are used for the training phase

Initial Results	
29 pumps	Properly classified
4 pumps	False negative
Accuracy	0.88



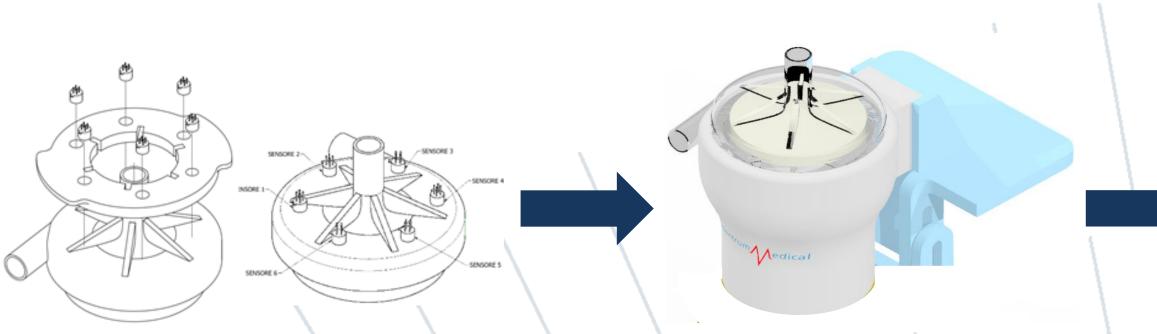
VALIDATION TEST

Test on-site at Qura s.r.l. to validate our model: 13 pumps tested not included in the training dataset

Results	
11 pumps	Properly classified
2 pumps	False negative
Accuracy	0.84

The results confirm the validity of the model

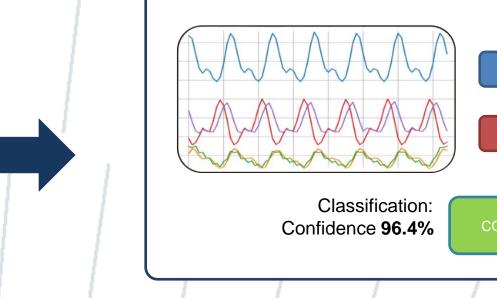
FINAL PROTOCOL



Placing the PCB and the sensors' support on the pump

Mount the pump on the driver and set test velocity

The classifier, based on the training dataset, classifies the pump in compliant or not compliant



The graphic interface shows the result of the classification with the confidence and the signals acquired

STOP



