Report N° MSc Thesis: Active Constraints

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Title: *To Be Defined*

General guidelines

Development of surgical training tasks implementing Active Constraints of different nature and with different levels of intervention, in order to evaluate their efficacy and role in Robot-Assisted Minimally Invasive Sugery.

- *Phase 1:* Software Development in a virtual environment (Unity)
- *Phase 2:* Implementing on the dVRK, followed by experimental tests with data gathering, analysis and validation

Progress

Next Steps

Screenshots