

Alberto Rota

Biomedical Engineer

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ABOUT ME

I'm a passionate and dedicated biomedical engineer currently working on Computer Vision Deep Learning algorithms for surgical robotics. Driven by a learning-prone attitude, I successfully led and contributed to and a number of team projects on robotics, artificial intelligence.

Determined to make a difference in the healthcare industry. I'm cooking and enogastronomy enthusiast, blues guitar player and passionate about travelling.

EDUCATION

PhD in Bioengineering

> February 2023 - Ongoing

Asensus Surgical & NEARLabMRS - Politecnico di Milano, IT Working on Deep-Learning and Computer Vision algorithms for 3D reconstruction [NDA protected]

MSc in Biomedical Engineering

> September 2020 - December 2022

Politecnico di Milano, IT

Thesis: Implementation and Assessment of an Augmented Surgical Training Curriculum with a daVinci robot: an experimental study at NEARLab Medical Robotics 🚺

Erasmus Exchange Program

> February 2022 - June 2022

University of Liege, BE

SKILLS

Language

Italian: Native speaker English: TOEIC Level C1, 2020

French: Level A2+

Programming/IT: Python, C++, C, MATLAB, C#, Git, Docker

AI: PyTorch, TensorFlow, Keras, SciKit CAD: Autodesk Inventor, Blender

Engineering: ROS, OpenFOAM, ImageJ, Unity Hardware: Microcontollers, 3Dprinting, KiCAD

Office: LaTeX, Microsoft Office Suite

Graphics: InkScape

WebDev: Designer and maintainer of NEARLab's Website

This CV was last updated on August 25th 2023. I authorize the processing of personal data according to EU Regulation 679/2016 or according to the reader's local regulations if not in the EU

Clicking **(**) will open a GitHub page Clicking 🗐 will open a research paper Clicking mill open a webpage

RELEVANT WORK

μVES ()

> February 2020 - July 2022

A fully automated algorithm for the topo-morphological analysis of 3D microvascular networks images from confocal microscopy, with DL image segmentation Mastered problem-solving and teamworking skills

ECC Pump conformity test ()



> September 2021 - March 2022

An IR-based embedded device for testing the conformity of centrifugal pumps for ECC - In collaboration with Qura s.r.l. Mastered time management and leadership skills

Deep Learning for SuperResolution of CT scans



> November 2021 - December 2022

A CNN for data-driven upscale and noise reduction of CT scans of the abdomen and pelvis

STEVE (7)

> February 2022 - December 2022

A haptic-enhanced surgical robotics VR simulator for surgical training

Mastered communication skills

RESEARCH PAPERS

A three-dimensional method for morphological analysis and flow velocity estimation in microvasculature on-a-chip Rota A., Possenti L., Offeddu G.S., Senesi M., Stucchi A., Venturelli I., Rancati T., Zunino P., Costantino M.L., Kamm R.D. -Bioengineering & Translational Medicine 2023

Recent Advancements in Augmented Reality for Robotic Applications: A Survey 🗐

Fu J., Rota A., Li S., Zhao J., Liu Q., Iovene E., Ferrigno G., De Momi E. - MDPI Actuators 2023

A Unity-based Da Vinci Robot Simulator for Surgical Training Fan K., Marzullo A., Pasini N., Rota A., Pecorella M., Ferrigno G., De Momi E. - IEEE BioRob2022

Improving Surgical Robotics Training with Haptic Virtual Fixtures: An Experimental Study

Rota A., Fan K., De Momi E. - I-RIM3D 2022

AWARDS

> **Best Innovation** award at the 2023 Hamlyn Surgical Robotics challenge

War Ex

> Best Development award at the 2022 Capstone Project event at Politecnico di Milano