# Reinforcement Learning Lab

Lesson 5: Dyna-Q

#### Davide Corsi and Alberto Castellini

University of Verona email: davide.corsi@univr.it

Academic Year 2022-23



1/5

Corsi and Castellini Reinforcement Learning Lab

## **Environment Setup**

The first step for the setup of the laboratory environment is to update the repository and load the miniconda environment.

• Update the repository of the lab:

```
cd RL—Lab
git stash
git pull
git stash pop
```

• Activate the *miniconda* environment:

```
conda activate rl-lab
```

#### Safe Procedure

Always back up the previous lessons' solutions before executing the repository update.

2/5

Corsi and Castellini Reinforcement Learning Lab Academic Year 2022-23

## Today Assignment

In today's lesson, we implement the Dyna-Q algorithm in Python. In particular, the file to complete is:

```
RL—Lab/lessons/lesson_5_code.py
```

Inside the file, a function is partially implemented. The objective of this lesson is to complete it.

def dynaQ()

Expected results can be found in:

 $RL-Lab/results/lesson\_5\_results.txt$ 

# Algorithm: Dyna-Q

#### Tabular Dyna-Q

Initialize Q(s, a) and Model(s, a) for all  $s \in S$  and  $a \in A(s)$  Loop forever:

- (a)  $S \leftarrow \text{current (nonterminal) state}$
- (b)  $A \leftarrow \varepsilon$ -greedy(S, Q)
- (c) Take action A; observe resultant reward, R, and state, S'
- (d)  $Q(S, A) \leftarrow Q(S, A) + \alpha \left[ R + \gamma \max_{a} Q(S', a) Q(S, A) \right]$
- (e)  $Model(S, A) \leftarrow R, S'$  (assuming deterministic environment)
- (f) Loop repeat n times:

 $S \leftarrow \text{random previously observed state}$ 

 $A \leftarrow$  random action previously taken in S

 $R, S' \leftarrow Model(S, A)$ 

$$Q(S, A) \leftarrow Q(S, A) + \alpha [R + \gamma \max_{a} Q(S', a) - Q(S, A)]$$

Figure: Pseudocode for Dyna-Q, from the Sutton and Barto book *Reinforcement Learning: An Introduction* 

4/5

# Assignment Notes

Today's assignment is based on the *DangerousGridWorld* environment and makes use of the epsilon\_greedy() function (provided).

### Hint (Code)

The solutions of the previous lessons can be used to complete today's assignment. In particular, the update rule for the Q-table can be adapted from Less. 4 while the general structure follows the solution of Less. 3.

#### Results Disclaimer

Given the (high) stochasticity of the method, the obtained results may differ.

### Hint (NumPy)

Numpy provides useful functions to simplify the assignment. In particular, numpy.random.choice() and numpy.where() are used in the suggested solution. More details can be found on the official website (here).

5/5