```
 \begin{aligned} \mathbf{Data}: & \text{ high dimensional data } \mathbf{X} = \{\mathbf{x}_1, \dots, \mathbf{x}_N\} \subseteq \mathbb{R}^D, \text{ Target Perplexity } P, \text{ Number of iterations } T \\ & \mathbf{Result}: \text{ low dimensional data } \mathbf{Y} = \{\mathbf{y}_1, \dots, \mathbf{y}_N\} \subseteq \mathbb{R}^d \text{ such that } d \ll D \text{ (usually d} = 2 \text{ or 3)} \\ & \text{ subtract mean } \forall i = 0..N \quad \mathbf{x}_i = \mathbf{x}_i - \bar{\mathbf{x}}; \\ & \text{ recale data } \forall i = 0..N \quad k = 0..D \quad (\mathbf{x}_i)_k = (\mathbf{x}_i)_k / \max_{i',k'} (\mathbf{x}_{i'})_{k'}; \\ & \text{ compute squared eucledian distances } d_{ij} = \|\mathbf{x}_i - \mathbf{x}_j\|^2 \text{ ;} \\ & \text{ for } i = 0..N \text{ do} \\ & \text{ initialize } \sigma_i; \\ & \text{ repeat} \\ & & \forall j = 0..N \quad p_j|_i = \frac{\exp(-d_{ij}/2\sigma_i^2)}{\sum_{k \neq i} \exp(-d_{ik}/2\sigma_i^2)}; \\ & \text{ per}_i = 2^{\sum_j p_j|_i \log_2 p_j|_i}; \\ & \text{ until } per_i = P; \\ & \text{ end} \\ & \text{ symmetrize } p_{ij} = \frac{p_{j|_i + p_{i|_j}}}{2N}; \\ & \text{ sample inital } \mathbf{Y}^{(0)} = \{\mathbf{y}_1^{(0)}, \dots, \mathbf{y}_N^{(0)}\} \text{ from gaussian distribution;} \\ & \text{ for } t = 1..T \text{ do} \\ & \text{ compute } \forall i, j = 0..N \quad q_{ij} = \frac{(1 + \|\mathbf{y}_i^{(t-1)} - \mathbf{y}_j^{(t-1)}\|^2)^{-1}}{\sum_{k \neq i} (1 + \|\mathbf{y}_k^{(t-1)} - \mathbf{y}_i^{(t-1)}\|^2)^{-1}}; \\ & \text{ compute } \forall i = 0..N \quad \frac{\partial C}{\partial \mathbf{y}^{(t-1)}} = 4 \sum_{j} (p_{ij} - q_{ij})(\mathbf{y}_i^{(t-1)} - \mathbf{y}_j^{(t-1)})(1 + \|\mathbf{y}_i^{(t-1)} - \mathbf{y}_j^{(t-1)}\|^2)^{-1}; \\ & \text{ update } \forall i = 0..N \quad \mathbf{y}_i^{(t)} = \mathbf{y}_i^{(t-1)} + \eta \frac{\partial C}{\partial \mathbf{y}_i^{(t-1)}} + \alpha(t)(\mathbf{y}_i^{(t-1)} - \mathbf{y}_i^{(t-2)}); \\ & \text{ subtract mean } \forall i = 0..N \quad \mathbf{y}_i^{(t-1)} = \mathbf{y}_i^{(t-1)} - \bar{\mathbf{y}}_i^{(t-1)}; \end{aligned}
```

**Algorithm 1:** t-SNE Algorithm