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➤ Optimizing Complex Structures

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➤ Outline

- Genetic Programming
- Linear Genetic Programming
- Grammatical Evolution
- Examples



➤ Genetic Programming

- Genetic Programming
 - John Koza, 1992
 - Extend EAs to anything
 - Focus on computer programs
- Internal representation
 - Binary trees
 - Specialized mutations and crossovers
 - Search space difficult to characterize (or even visualize!)

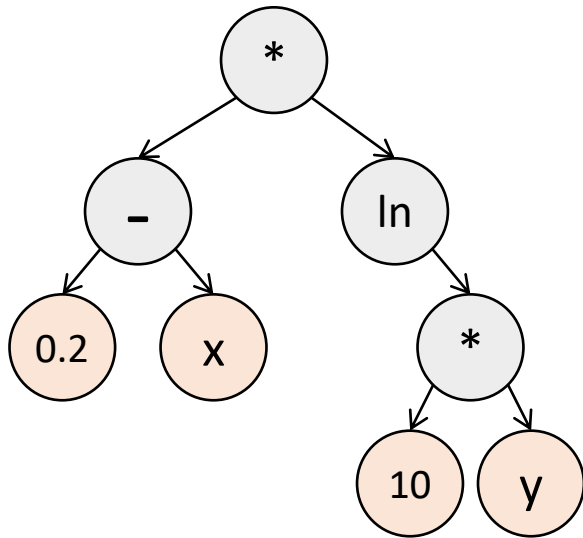


➤ Genetic Programming

- General idea: OPTIMIZE ALL THE THINGS with EAs
 - If you can *describe* a candidate solution to a problem...
 - ...and *variators* (e.g. mutations, crossovers)...
 - ...and you can *define a fitness/objective function*...
 - ...EAs can explore the *space of all possible solutions*!
- It worked for *life on Earth*!
 - DNA is pretty complicated
 - Genome doesn't need to be *just numbers*



➤ Genetic Programming

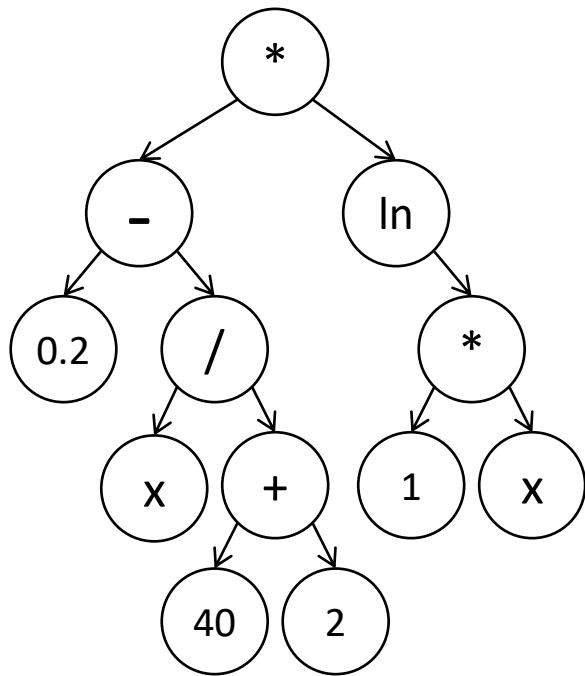


Operators: +, -, *, /, ln...

Terminals: reals, ints, vars, ...

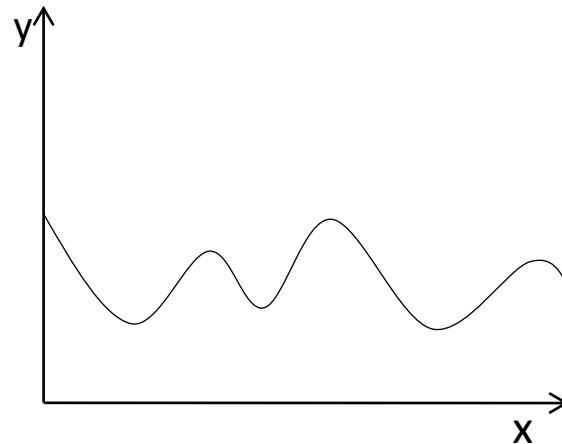
$$f(x, y) = (0.2 - x) * \ln(10 * y)$$

➤ Symbolic Regression



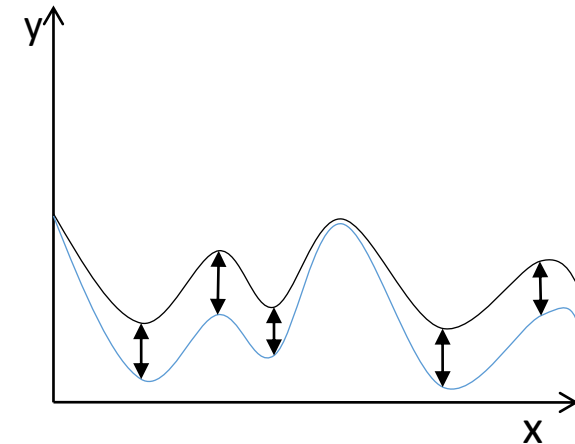
Genotype/Internal representation

$$f(x) = [0.2 - (x/42)] * \ln(x)$$



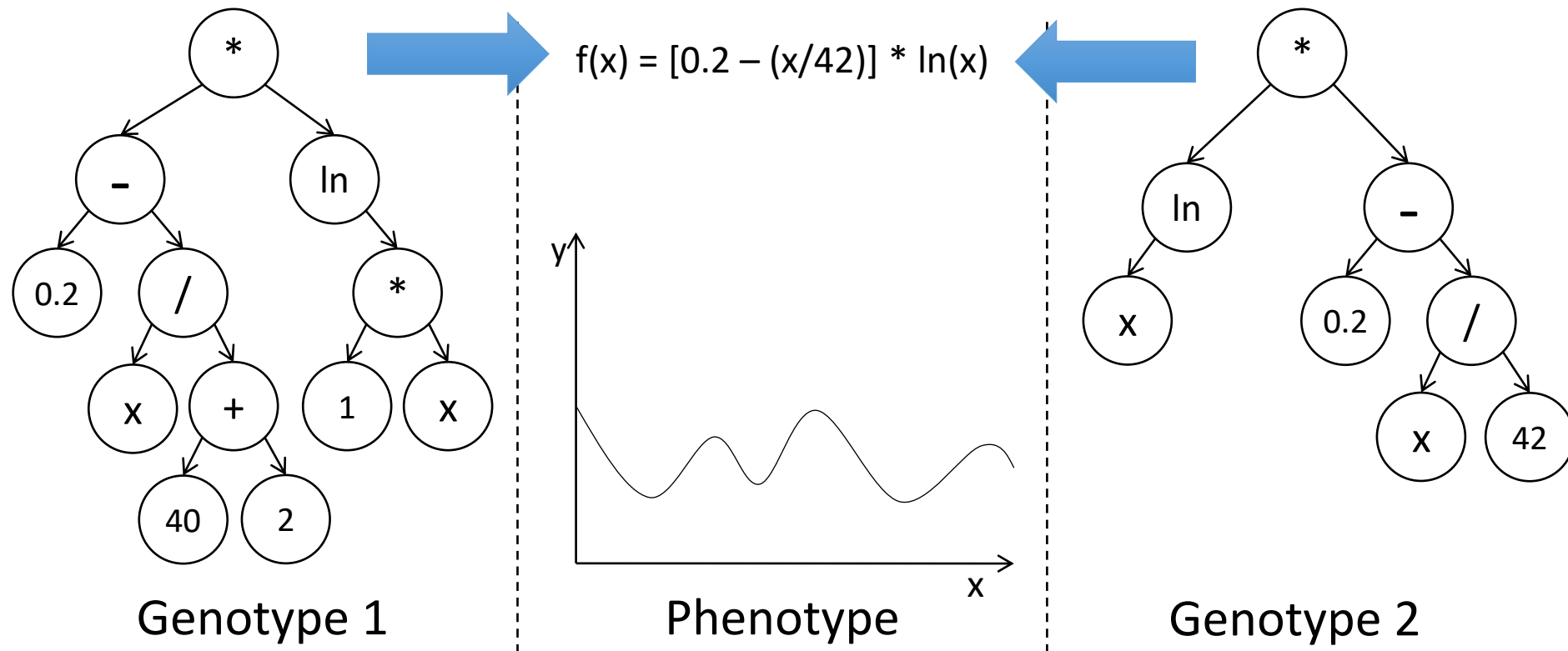
Phenotype

$$\text{Fitness} = \sum_{i=0}^N \text{abs}(f(x_i) - g(x_i))$$

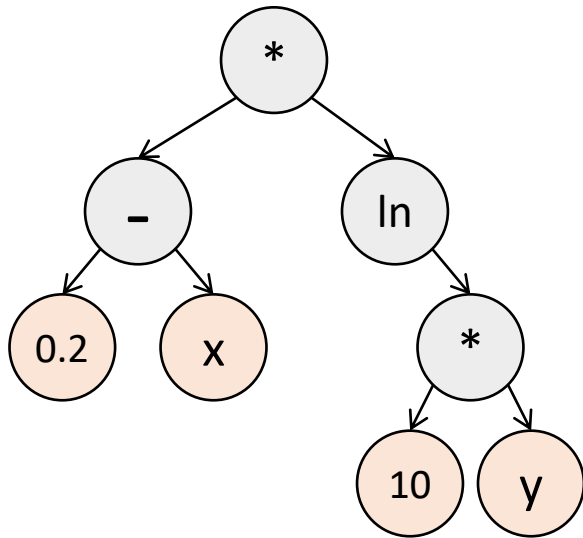


Fitness/Objective function

➤ Symbolic Regression



➤ Genetic Programming

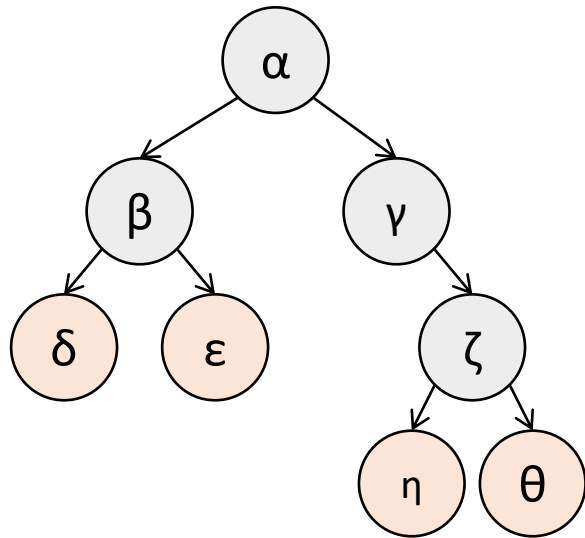


Operators: +, -, *, /, ln...

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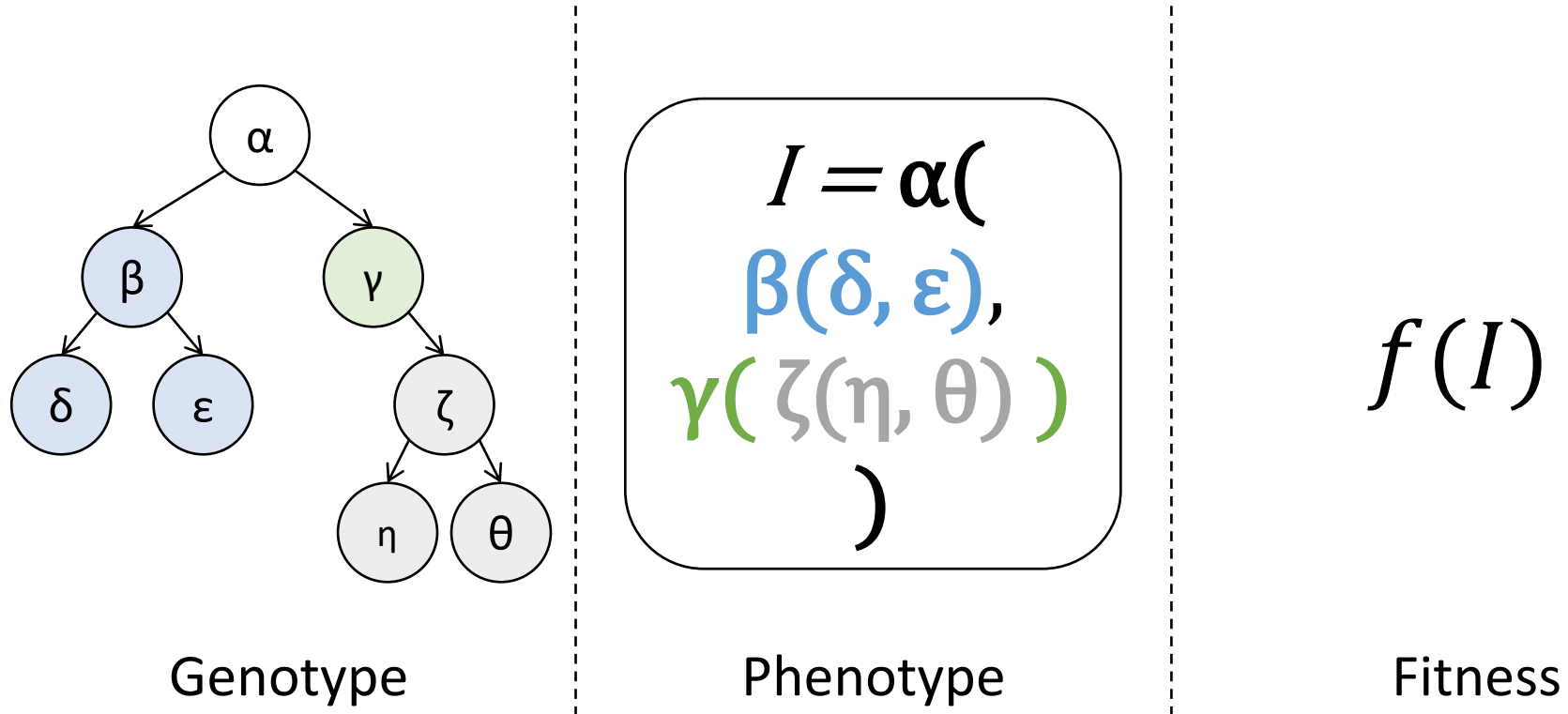
➤ Genetic Programming



Operators: $\alpha, \beta, \gamma, \zeta, \lambda, \pi, \varsigma, \dots$

Terminals: $\delta, \epsilon, \eta, \theta, \rho, \sigma, \tau, \dots$

➤ Genetic Programming



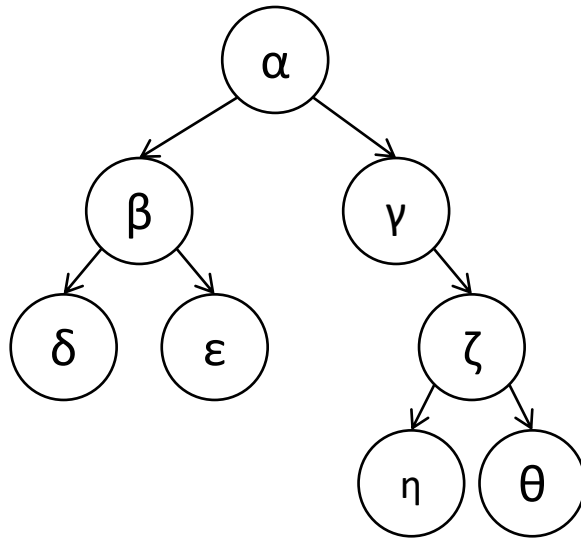
➤ Genetic Programming

- How to explore this complex search space?



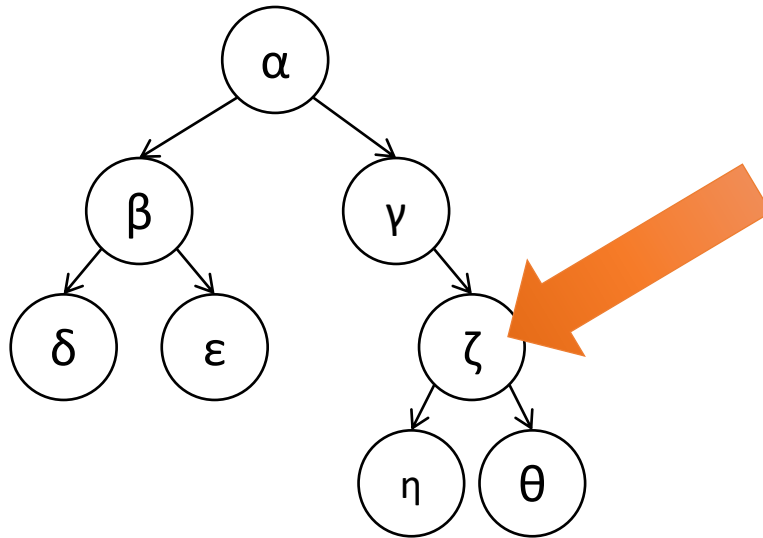
➤ Genetic Programming

- Mutation(s)



➤ Genetic Programming

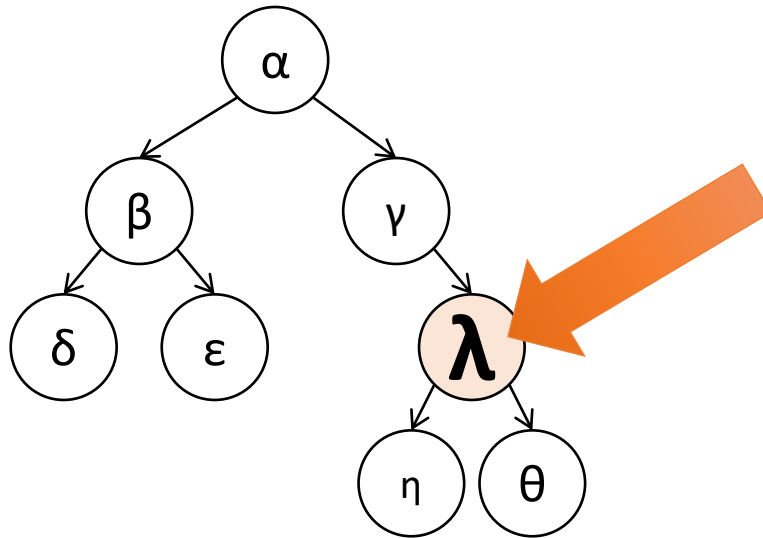
- Mutation(s)



POINT MUTATION

➤ Genetic Programming

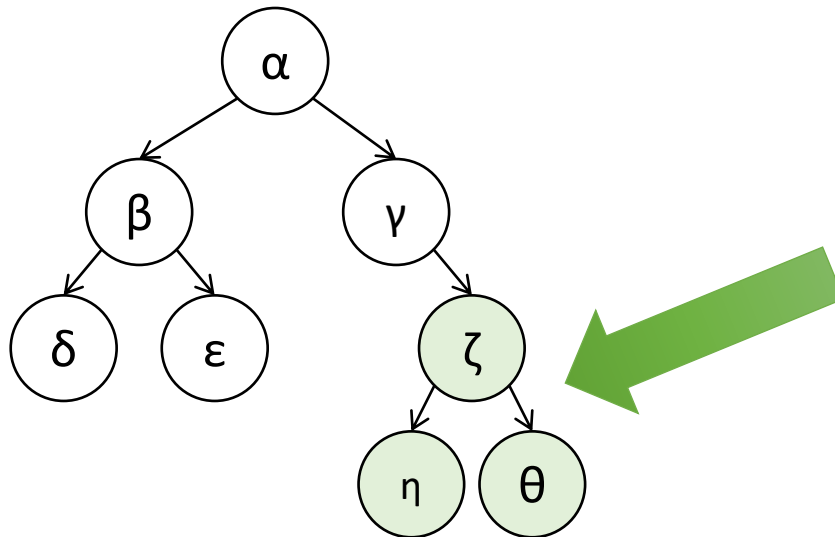
- Mutation(s)



POINT MUTATION

➤ Genetic Programming

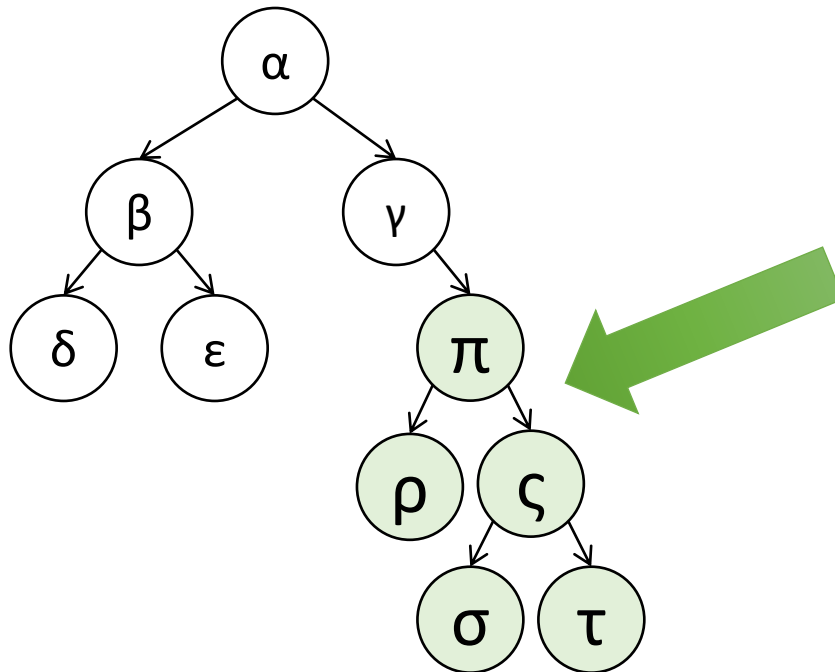
- Mutation(s)



SUBTREE MUTATION

➤ Genetic Programming

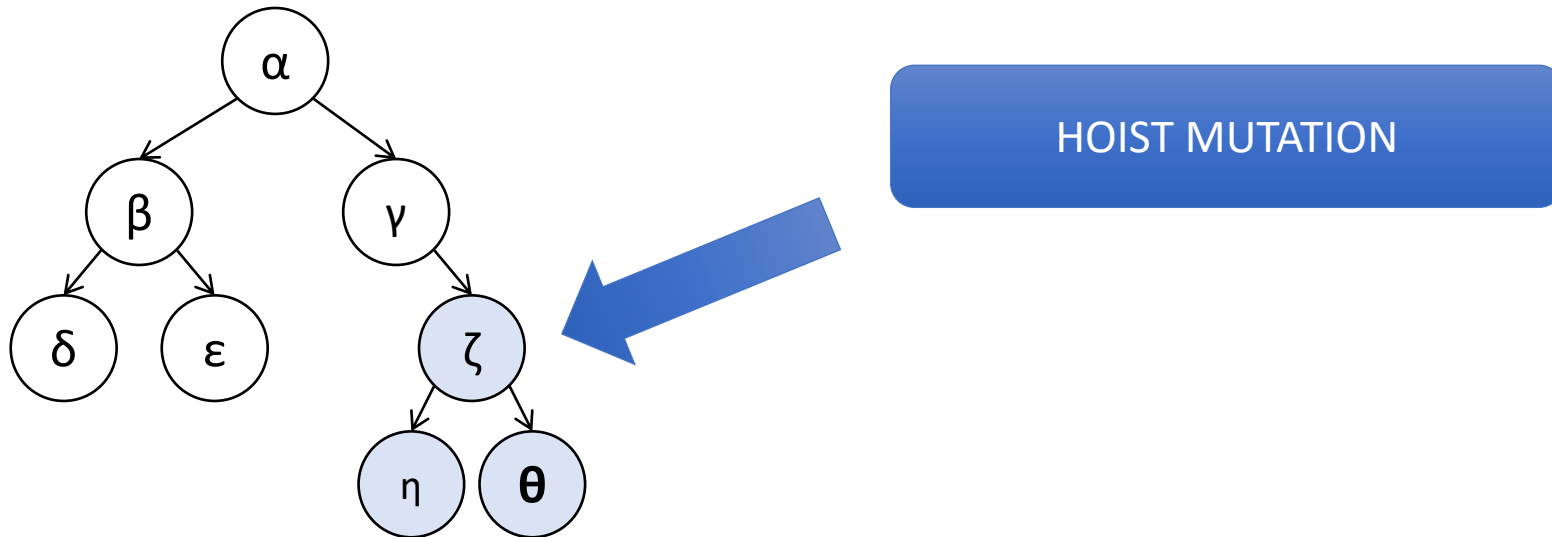
- Mutation(s)



SUBTREE MUTATION

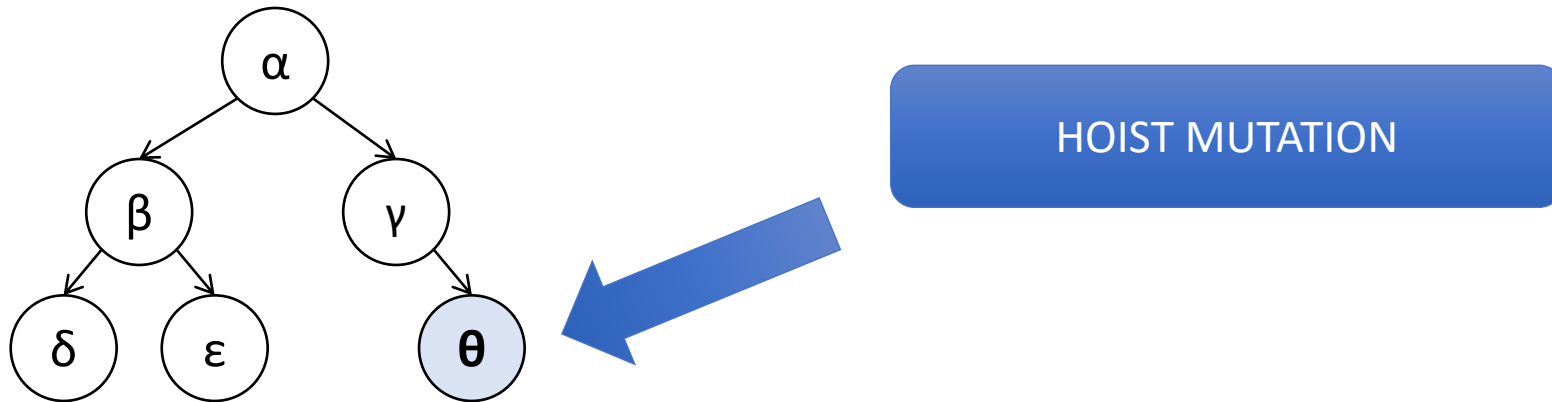
➤ Genetic Programming

- Mutation(s)



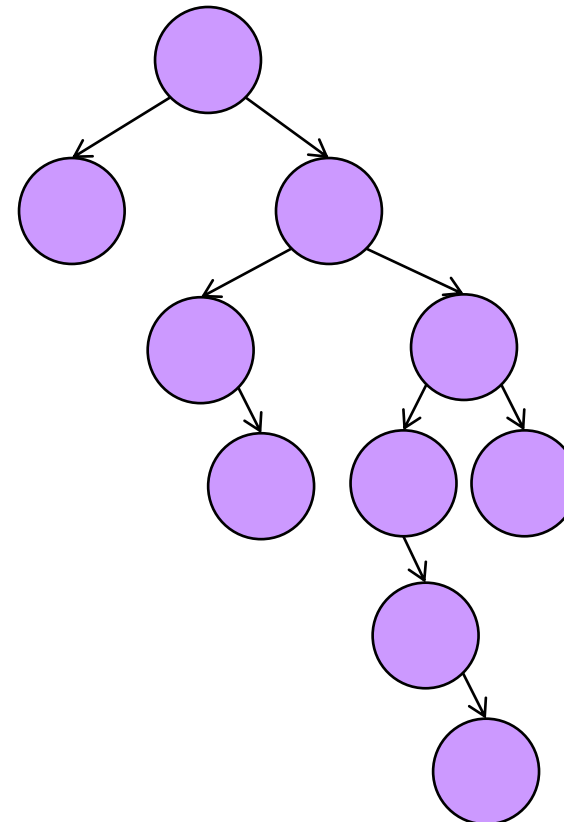
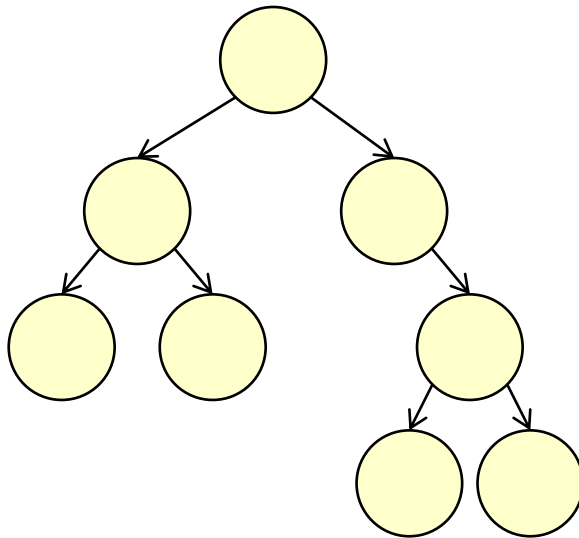
➤ Genetic Programming

- Mutation(s)



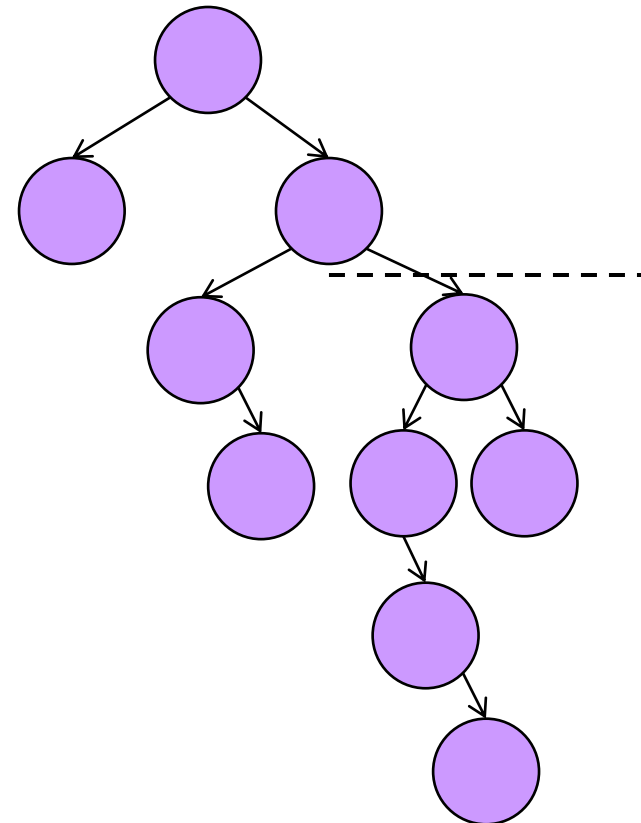
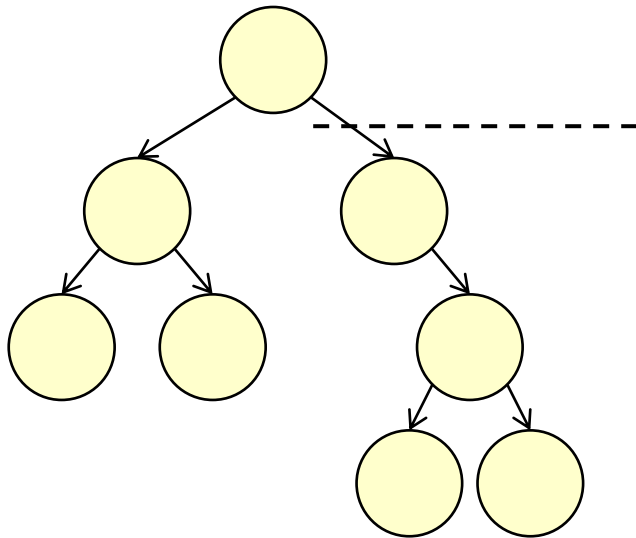
➤ Genetic Programming

- Crossover(s)



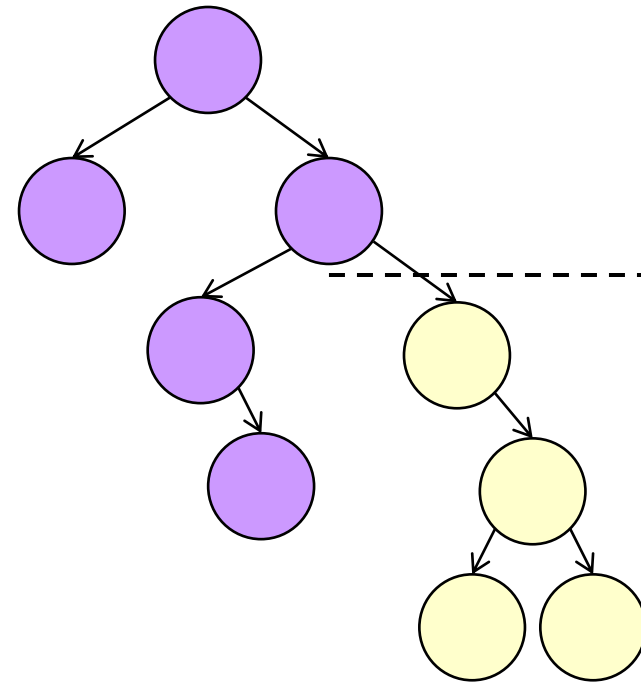
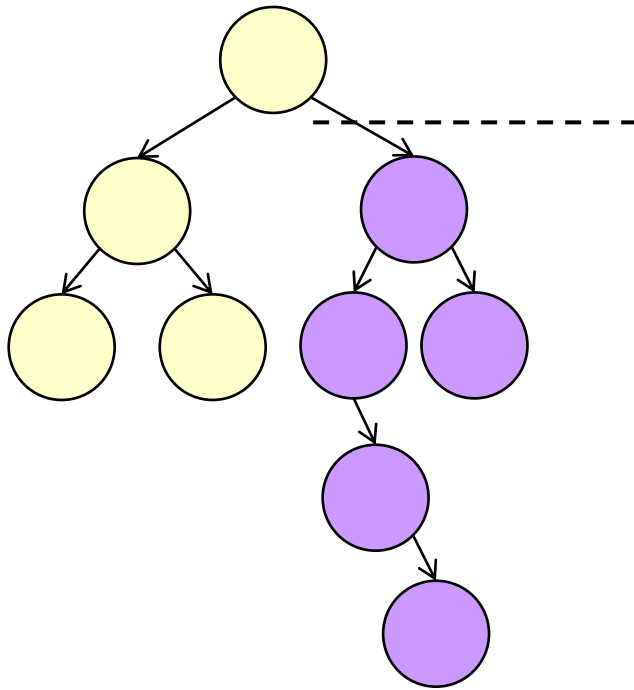
➤ Genetic Programming

- Crossover(s)



➤ Genetic Programming

- Crossover(s)



➤ Genetic programming: issues

- “Bloating”
 - As the optimization proceeds, trees tend to become bigger
 - With no positive impact on objective function value
 - **Solution:** add term to objective function to penalize size
 - **Solution:** use a multi-objective approach (minimize size)
- Analyzing this in terms of ML, it could be *overfitting*
 - Bigger model, more parameters, easier to fit a function
 - For bigger models also easier to “memorize” training set



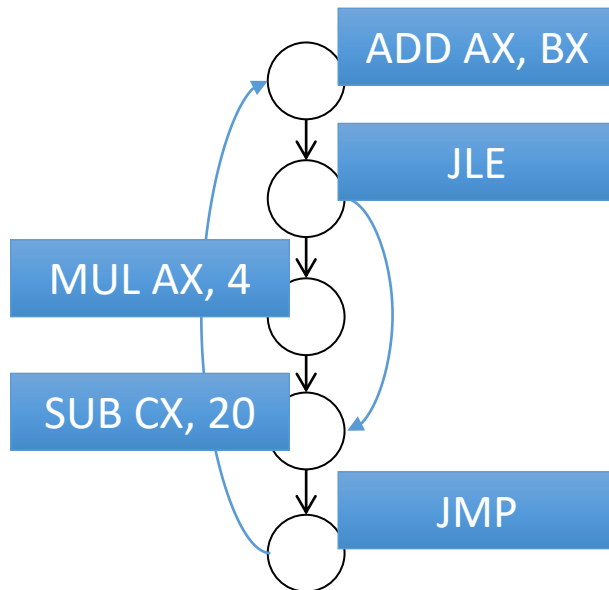
➤ Genetic Programming

- What are we doing?
- Blending optimization and machine learning?
 - If your candidate solution is a *model*...
 - ...then you are (arguably) doing *machine learning*!
- Terminology is still *in development*
- Researchers in GP getting closer to the ML community



➤ Linear Genetic Programming

- Evolving linear graphs
- Used for evolving computer programs
- Backward/forward arcs interpreted as jumps

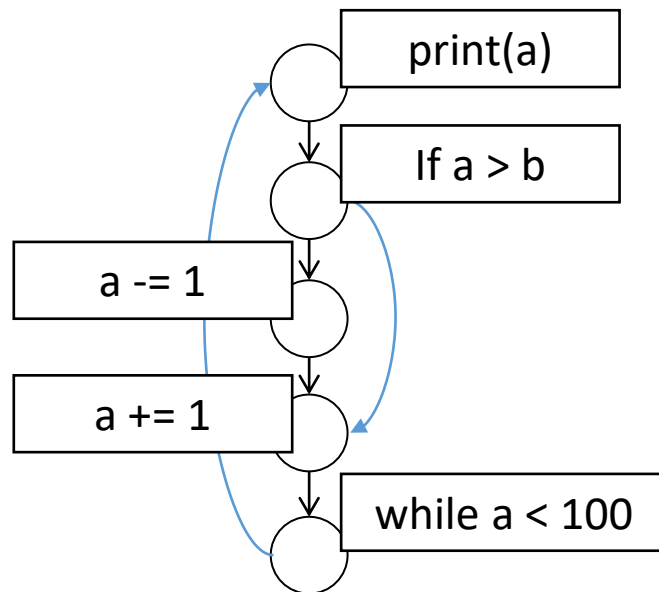


```
label1: ADD AX, BX  
  
JLE label2  
  
MUL AX, 4  
  
label2: SUB CX, 20  
  
JMP label1
```



➤ Linear Genetic Programming

- Evolving linear graphs
- Used for evolving computer programs
- Backward/forward arcs interpreted as jumps



```
while a < 100 :  
    print(a)  
    if a > b :  
        a += 1  
    else :  
        a -= 1
```

➤ Grammatical Evolution

- “Grammar” in computer science
 - Defines a way to generate/validate a sequence of symbols
 - Used to check syntax coherence of programming languages
 - Evolutionary algorithm generate candidate solutions w/ grammar

$\{start\} \rightarrow a|b$

$a \rightarrow a|b$

$b \rightarrow b|\{end\}$

ab ✓

aaaaaabbabbbbbb ✓

aba ✗

➤ Example: Evolving AIs

- Real-time strategy (RTS)
 - Planet Wars (Google)
 - StarCraft
 - Student StarCraft AI Tournament
- Trade-off
 - ANNs are better
 - You can read GP trees



➤ Example: Genetic Improvement

- Automatic correction of software bugs
- Individual: series of code modifications
- Fitness/Objective function
 - A series of test cases
 - They still have to work

Comment line 52
Swap lines 3 and 22
Change variables lines 42 and 11
...



➤ Example: Genetic Improvement

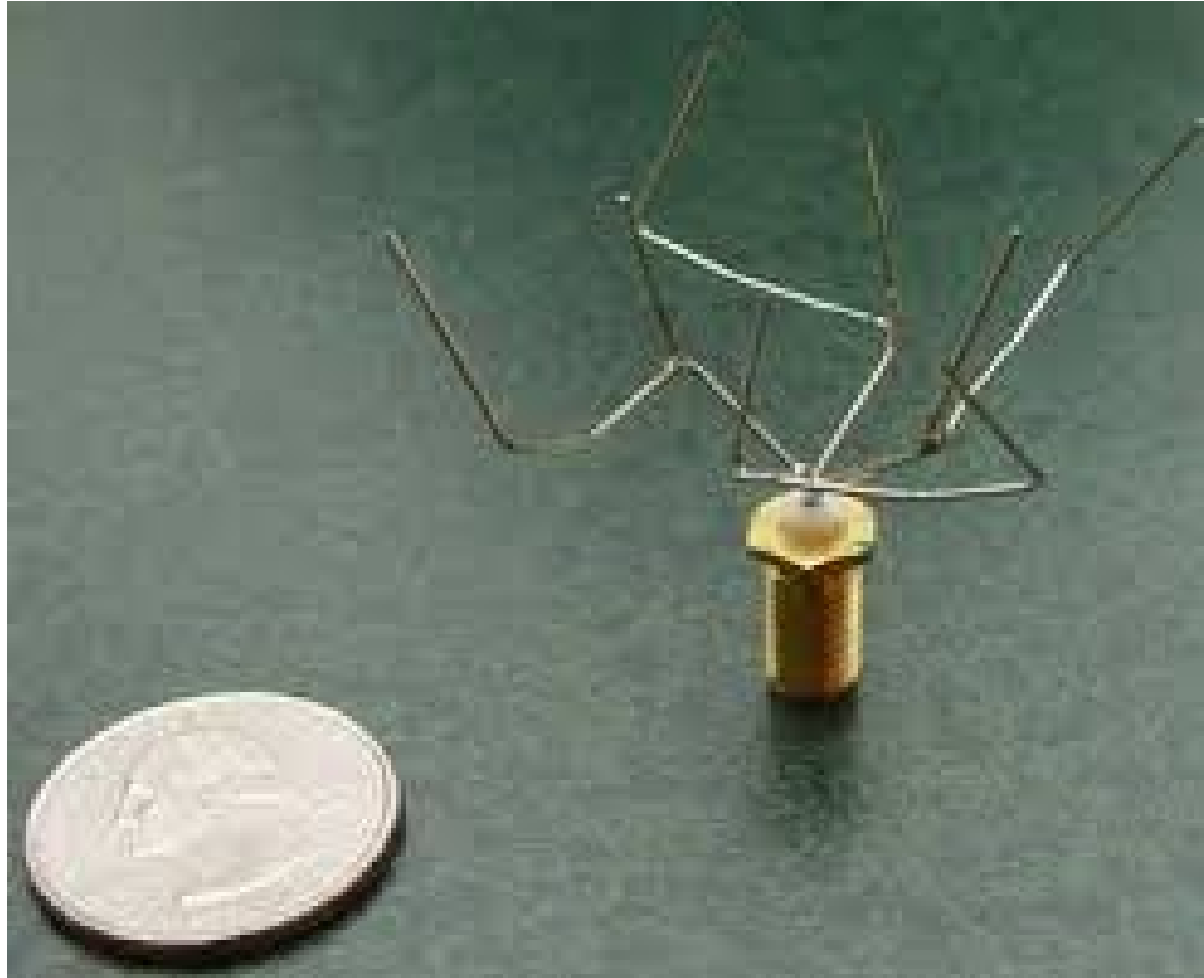
- But does it *really* work?
 - Aren't EAs introducing other bugs?
 - Aren't HUMANS introducing other bugs?
 - In the end, you just need to be *as good as* the average programmer, and you save time
 - Still experimental

Langdon, William B. **Genetically Improved Software**, 2015

Justyna Petke and Saemundur O. Haraldsson and Mark Harman and William B. Langdon and David R. White and John R. Woodward. **Genetic Improvement of Software: a Comprehensive Survey**, 2017

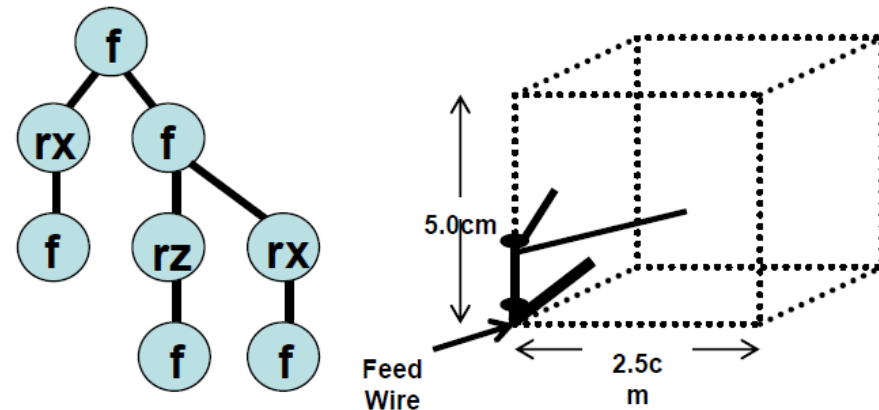


➤ Example: ?

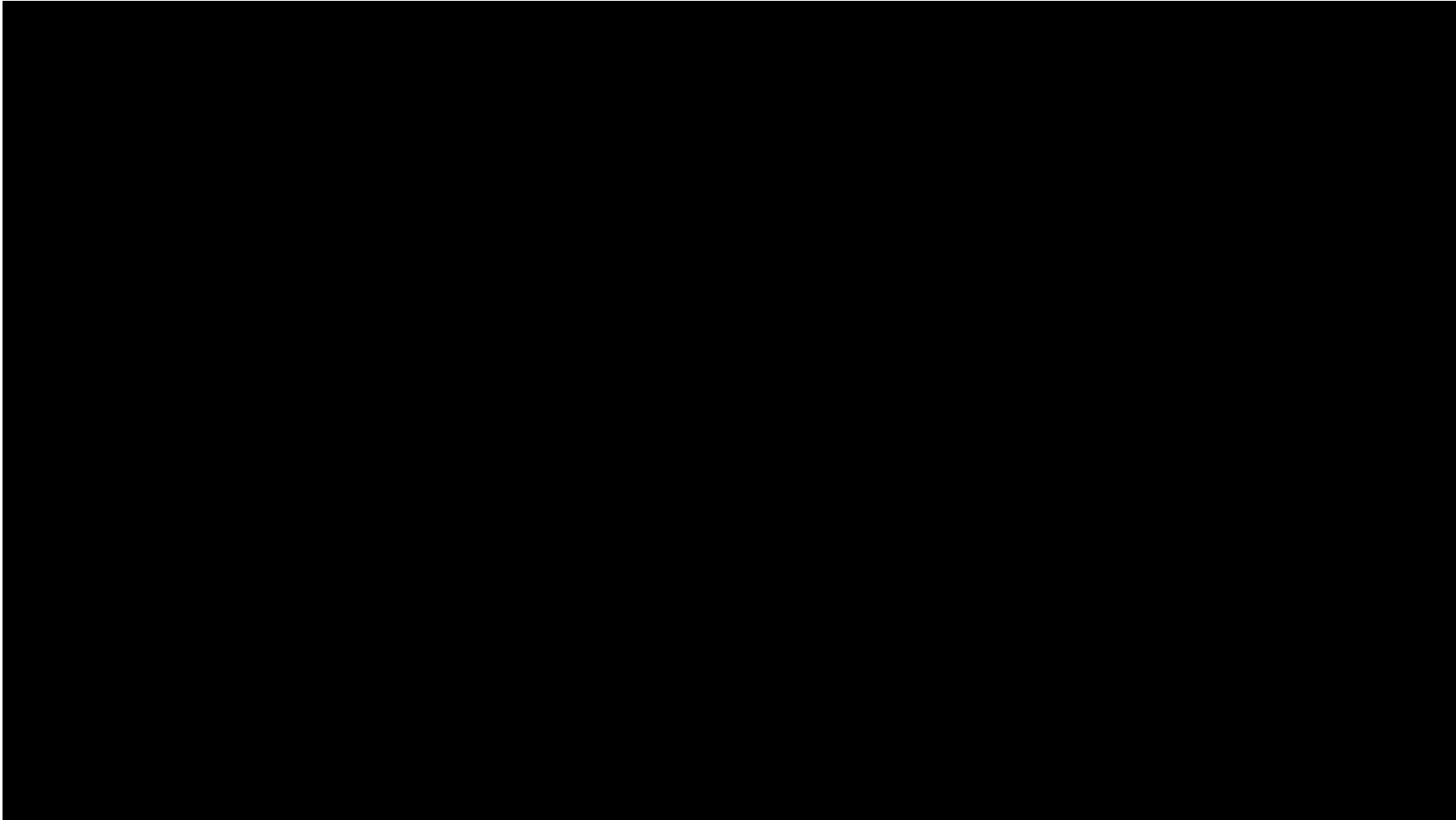


➤ Example: Antennas

- Design of antennas for satellite ST5 (2006)
- Lots of constraints: weight, size, efficiency...
- Genome/representation is a tree
 - Forward (length, radius)
 - Rotate_x (angle)
 - Rotate_y (angle)
 - Rotate_z (angle)
- It worked!

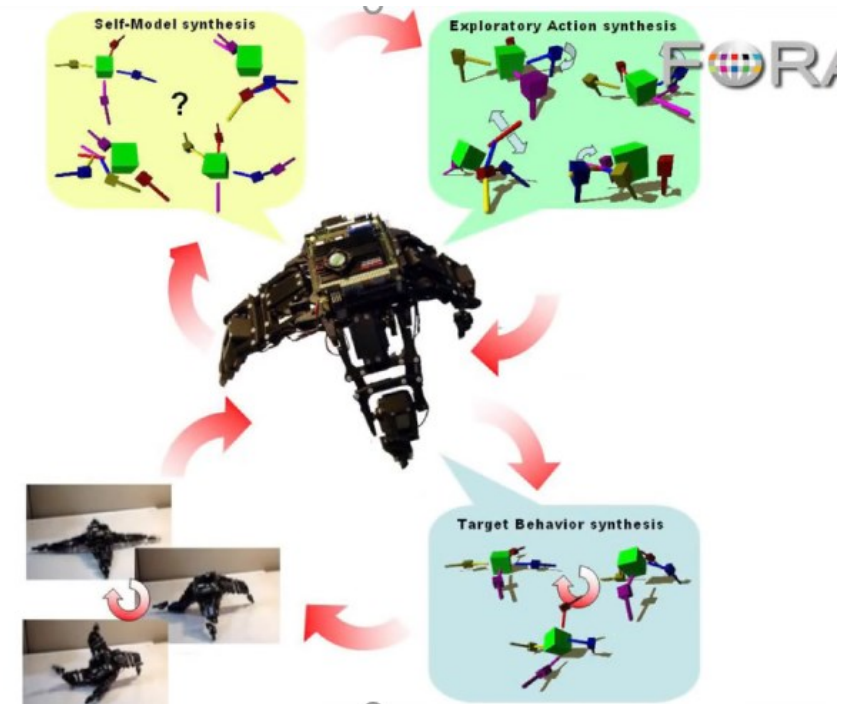


➤ Example: Robot Movement



➤ Hod Lipson mentioned something...

- While speaking about the candidate models for the robot
- He said “next, we are going to compare the models on the **most discriminating movement**”
- Candidate models fit the data they have already seen
- It make sense to test them on new data where they have **different predictions**
- **But how do we know what is the movement for which the models have the most different predictions?**



➤ He did not say! But we know...

- It's **optimization!**
 - You have a vast search space of possible movements
 - And an archive of candidate models
 - Search for the candidate movement that **maximizes** the difference in prediction between candidate models
- Competitive Co-evolutionary Algorithms
 - Lipson and Schmidt, “Coevolving Fitness Models for Accelerating Evolution and Reducing Evaluations”, 2007
 - Lipson and Schmidt, “Coevolution of Fitness Predictors”, 2008



➤ Example: Soft Robot Movement

Evolved Electrophysiological Soft Robots



Nick Cheney¹
Jeff Clune²
Hod Lipson¹



¹ Creative Machines Lab, Cornell University

² Evolving AI Lab, University of Wyoming

INR

Optimizing complex structures

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➤ Genetic Programming vs Generative NNs?

- Generative neural networks
 - Learn from existing training samples (e.g. images or text)
 - Able to create high-quality results, fast inference (slow training)
 - Generalize poorly “out of distribution”
- Genetic programming
 - Can create unique structures, never seen before
 - Needs an ad-hoc objective function to sample
 - Extremely slow (one whole run for one creation)
 - Human-interpretable (up to a certain limit)



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➤ Questions?

Bibliography

- Koza, *Genetic Programming*, 1992
- Garcia-Sanchez et al., *Towards Automatic StarCraft Strategy Generation Using Genetic Programming*, 2015
- Lipson & Pollack, *Automatic design and manufacture of robotic lifeforms*, 2000

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