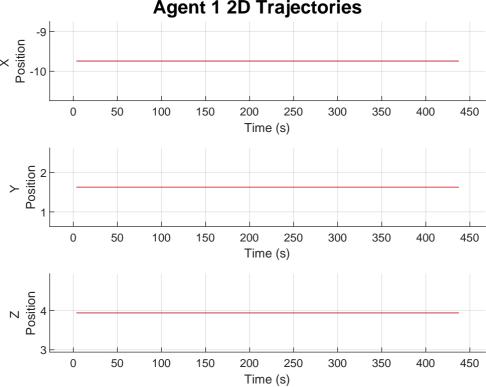
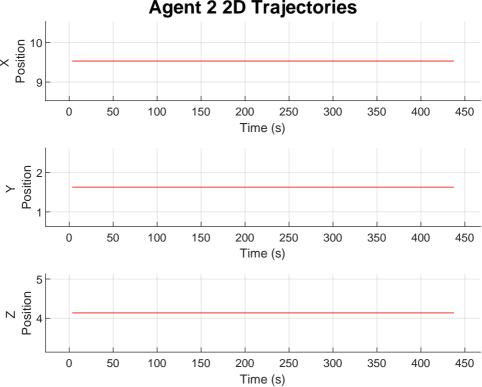
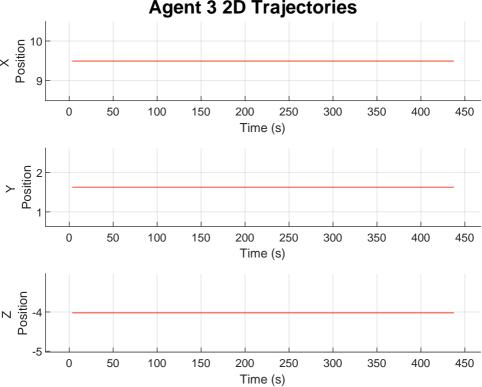
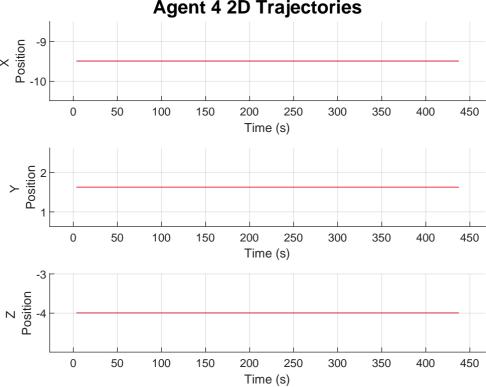


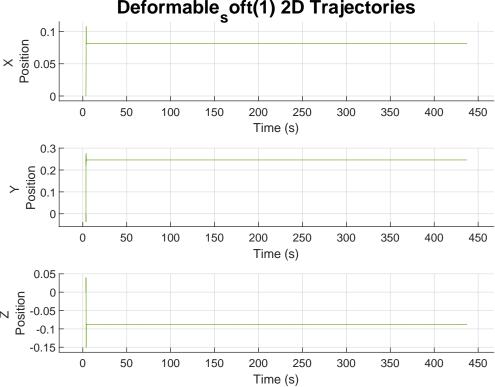
## All 3D Trajectories Agent 1 Agent 1 start Agent 1 end Agent 1 dest Agent 2 Agent 2 start Agent 2 end 1.5 Agent 2 dest Agent 3 Y Axis Agent 3 start Agent 3 end 0.5 Agent 3 dest Agent 4 0 Agent 4 start Agent 4 end -10 Agent 4 dest Deformable\_oft(1) -5 Deformable oft(1) start 0 Deformable oft(1) end 5 X Axis Z Axis 10

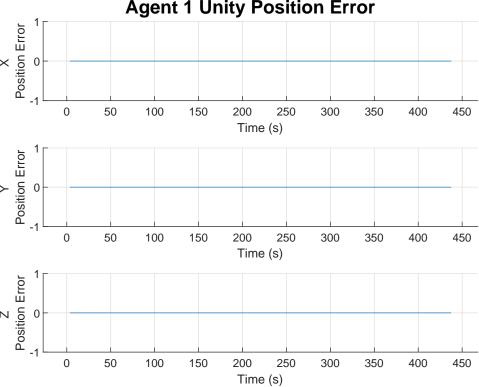


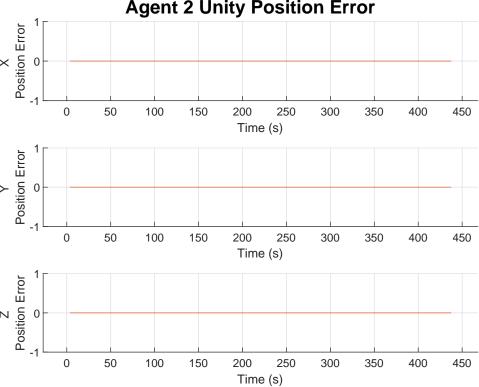


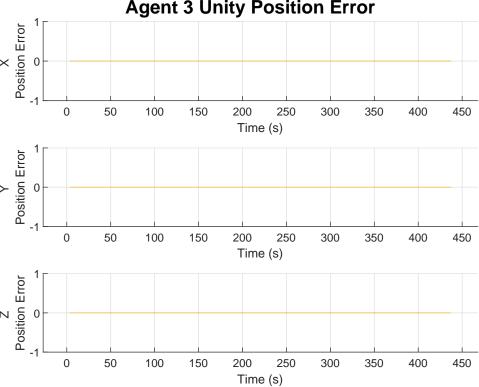


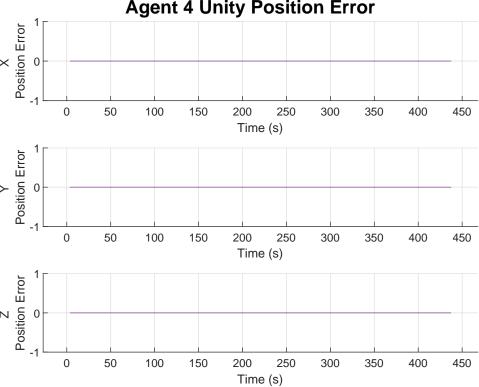


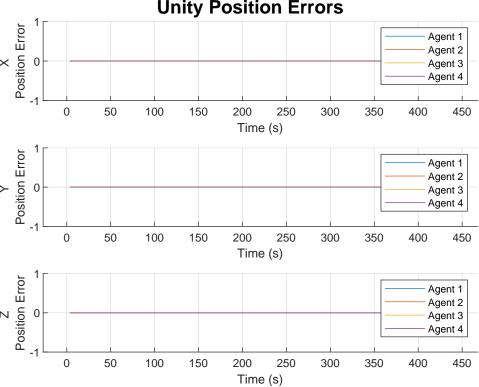


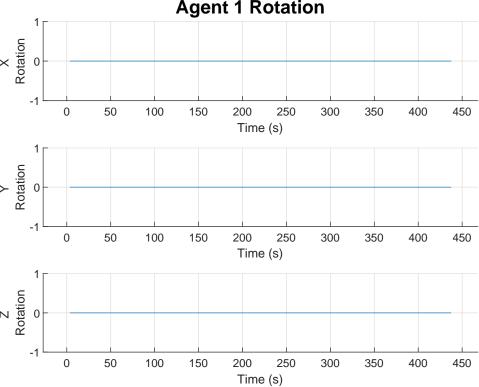


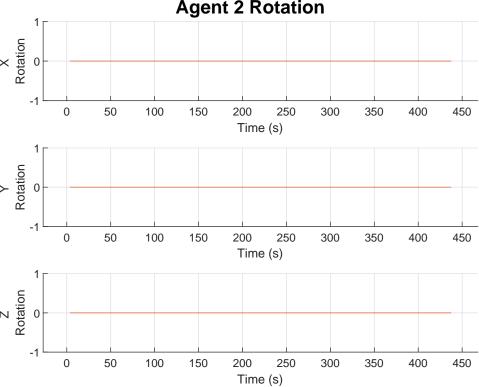


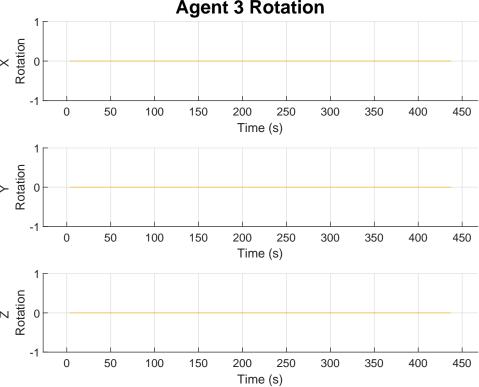


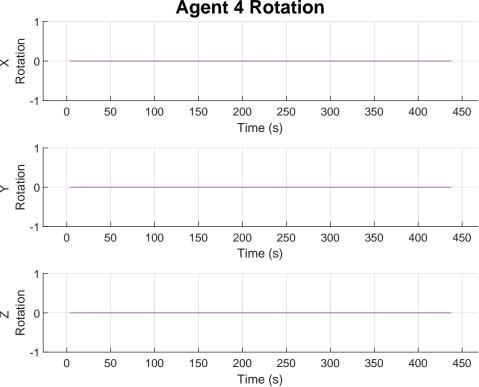


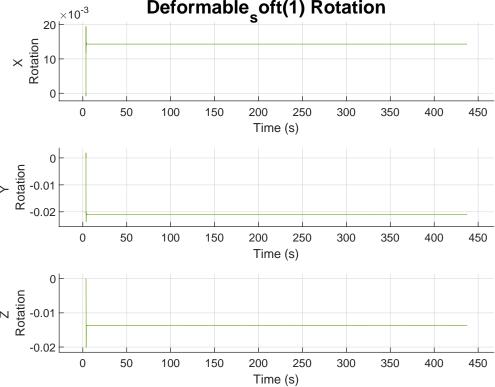


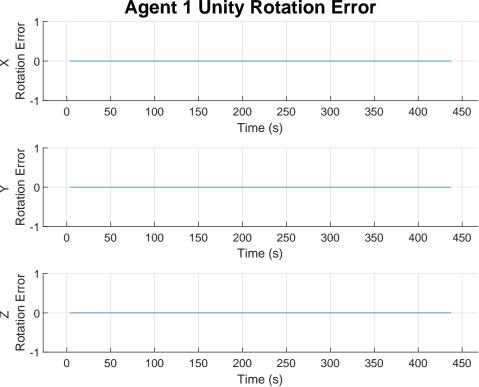


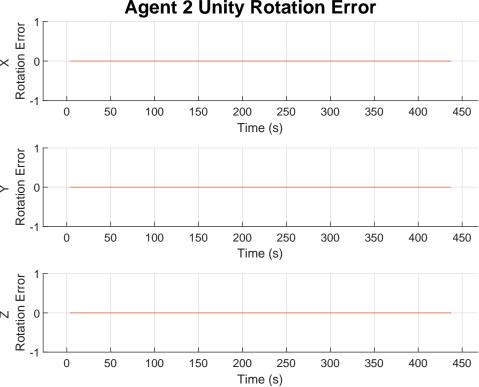


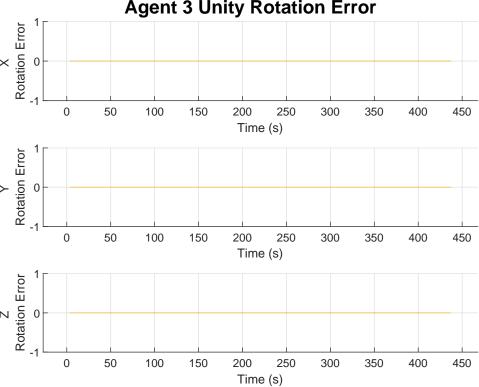


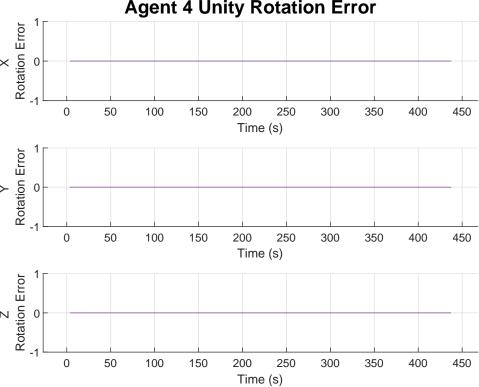


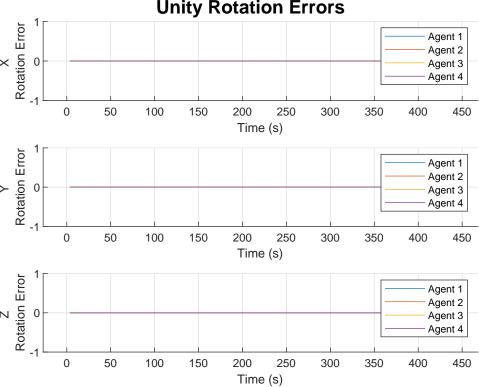


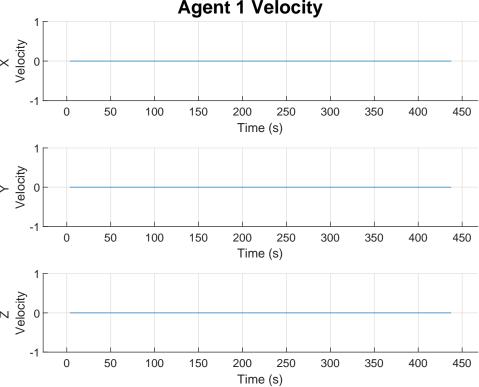


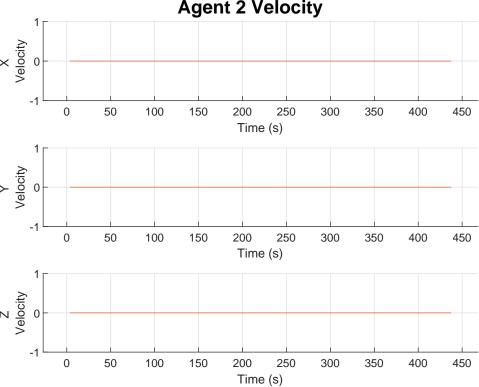


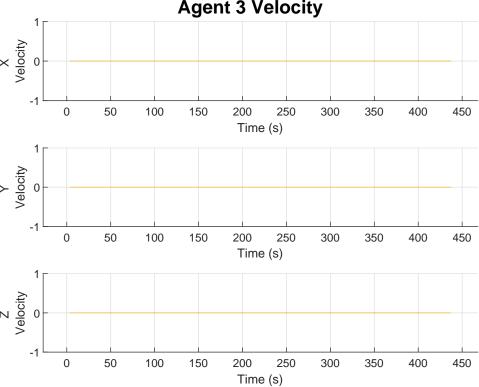


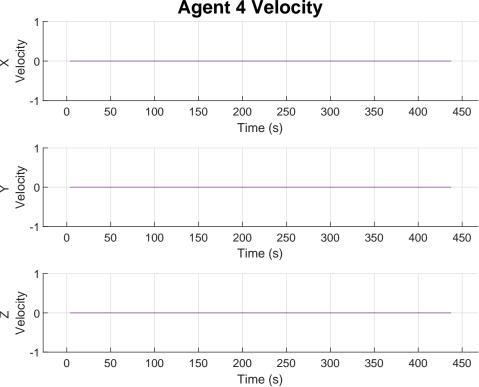


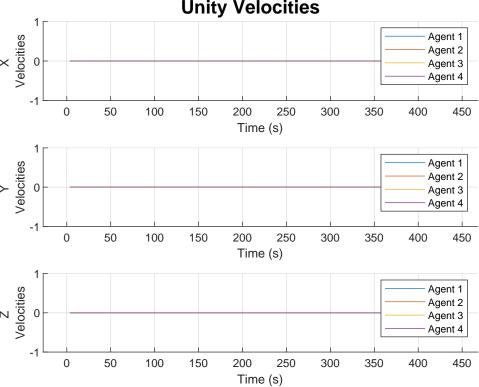


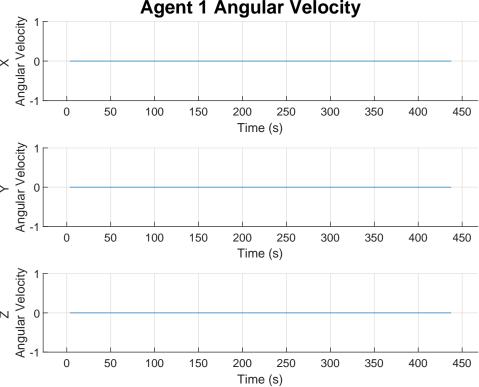


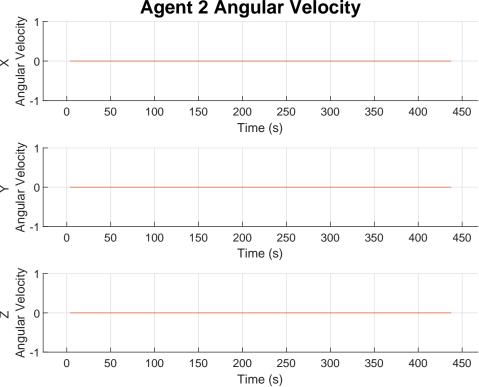


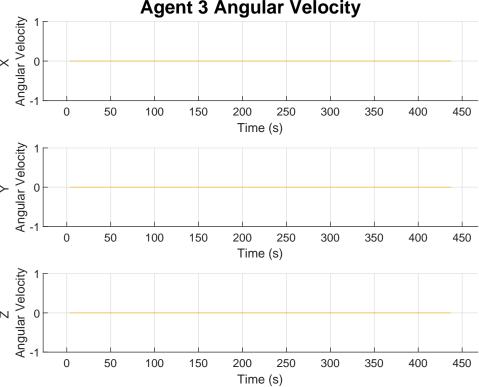


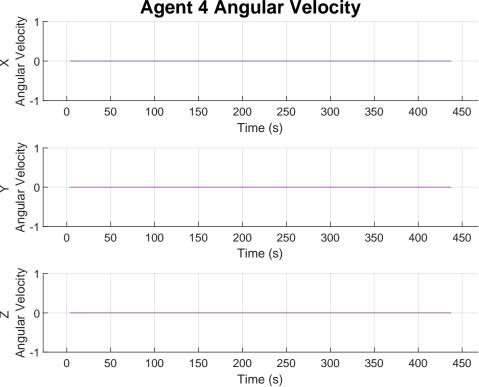


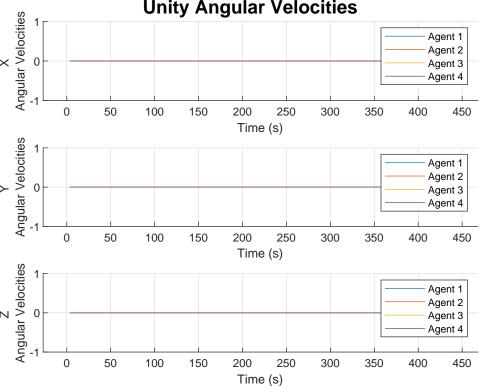


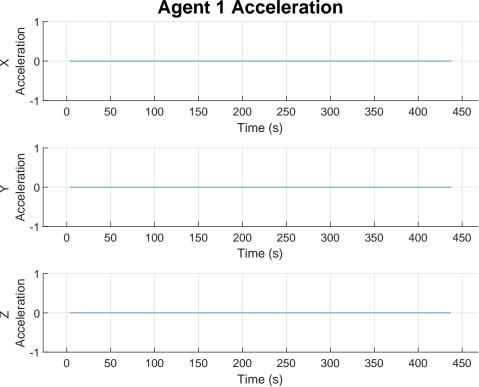


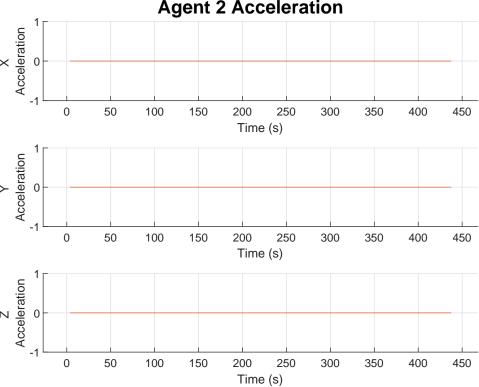


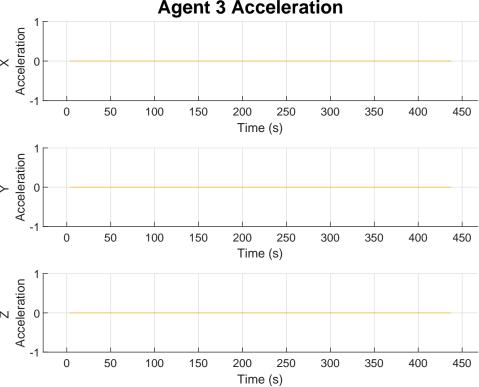


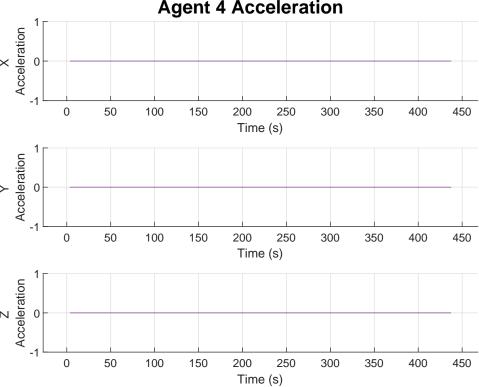


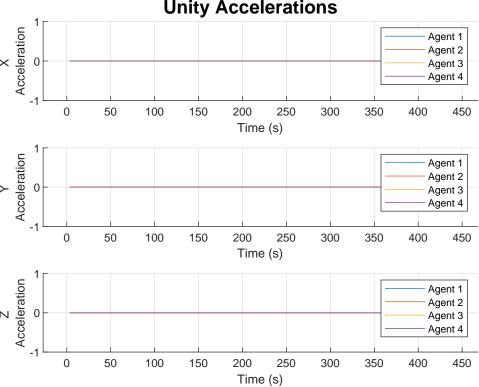


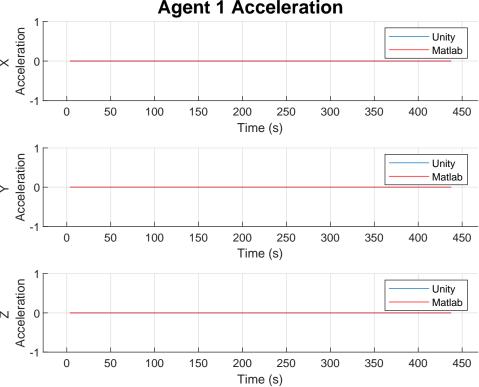


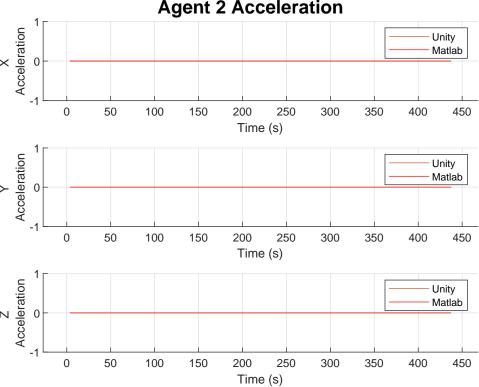


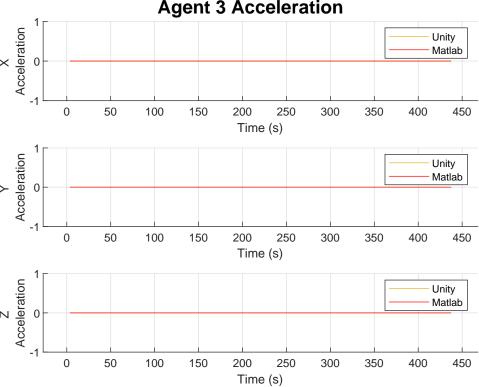


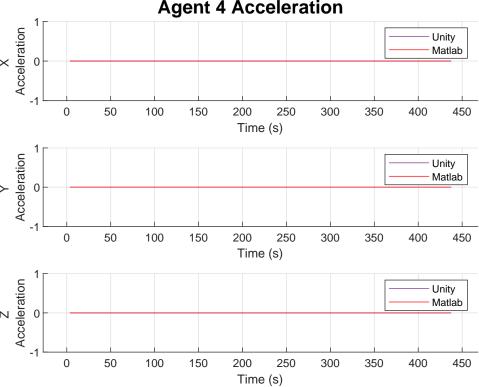


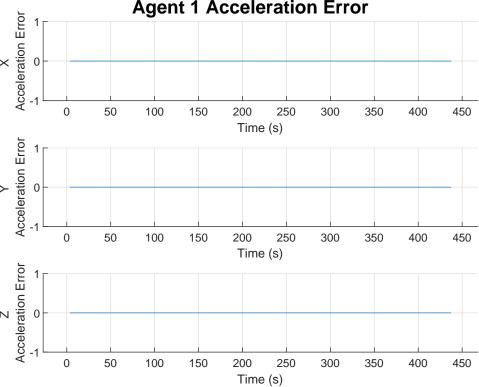


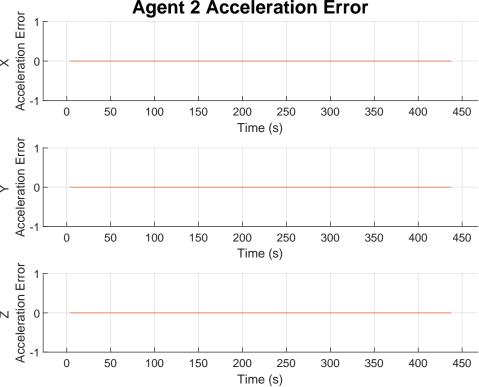


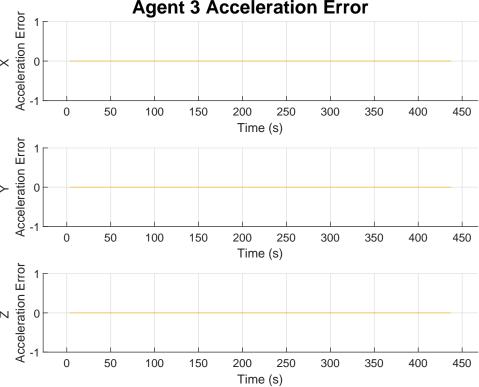


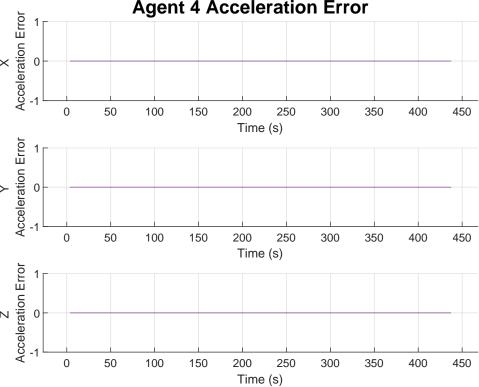


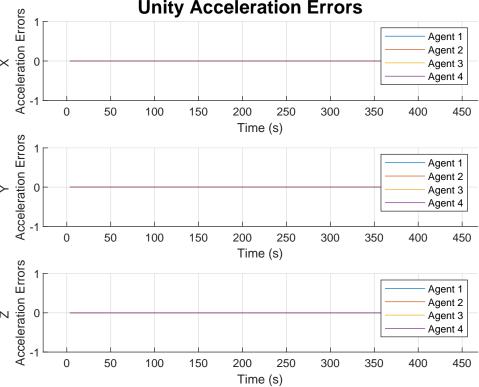


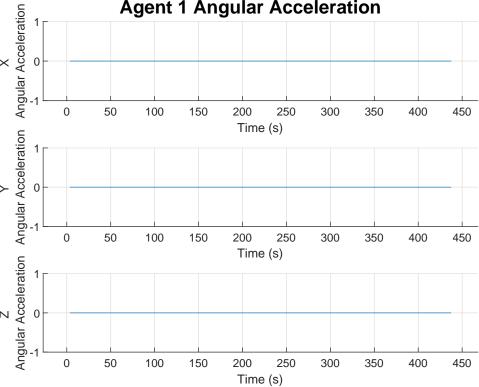


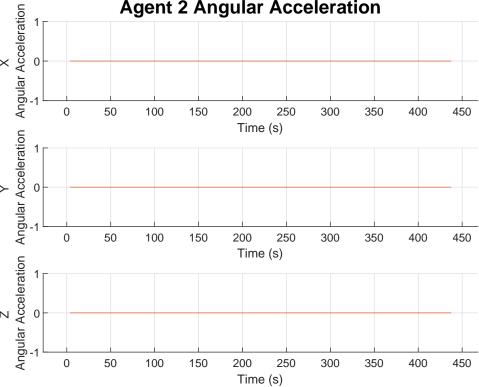


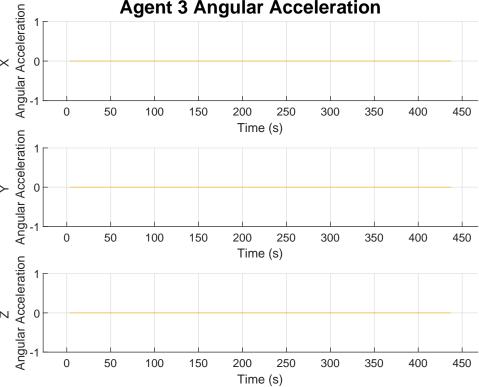


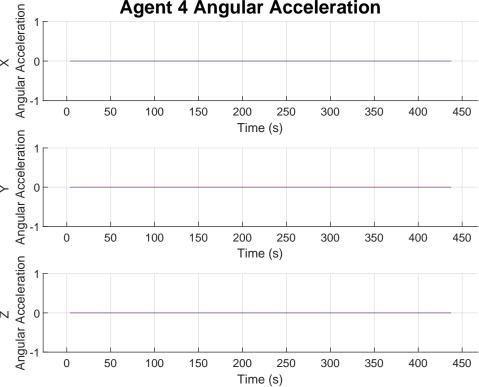


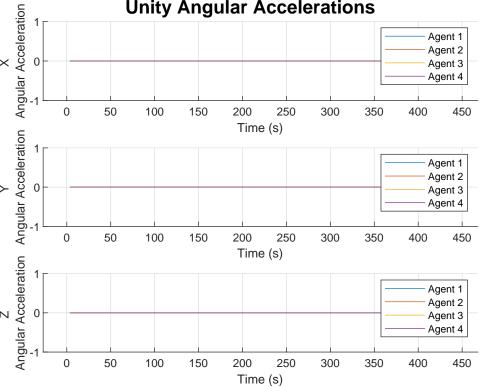


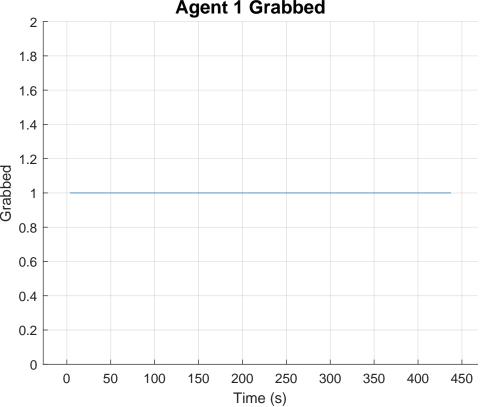


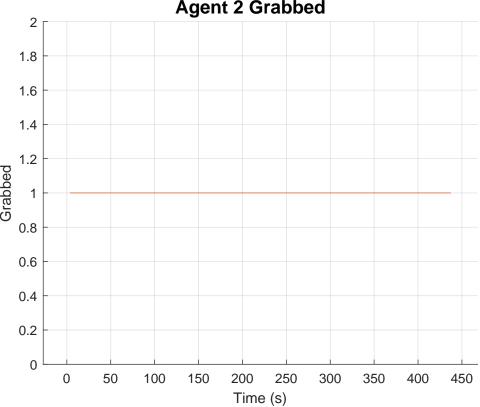


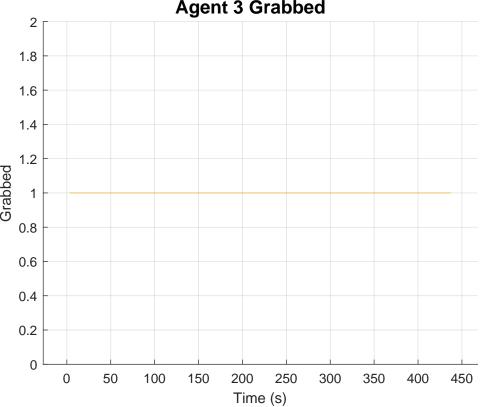


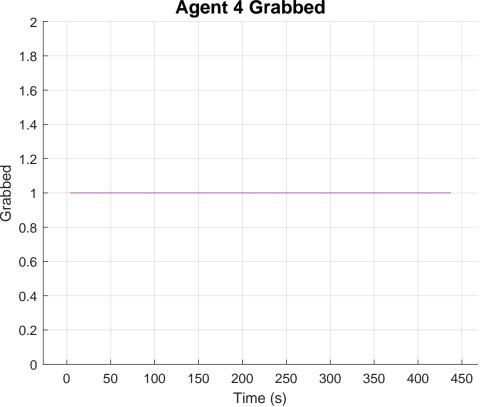


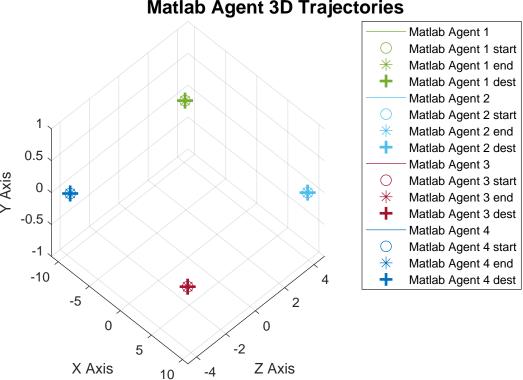


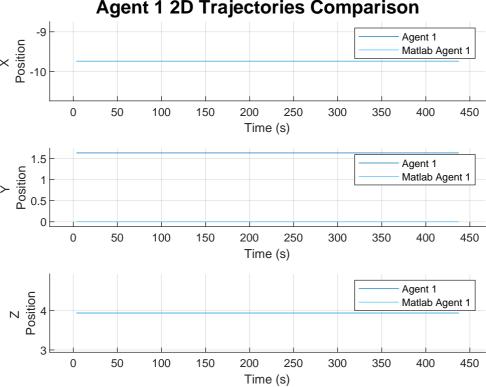


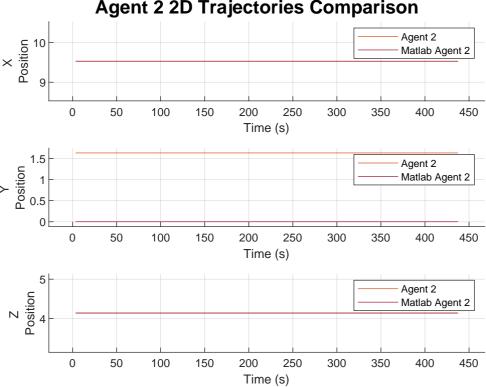


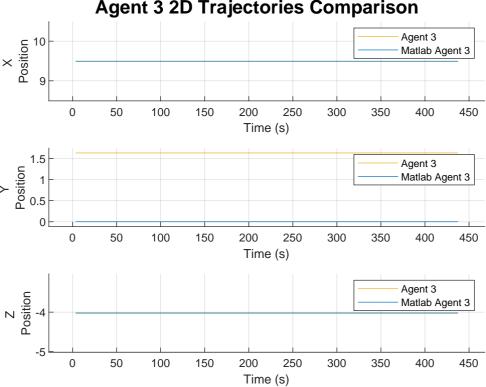


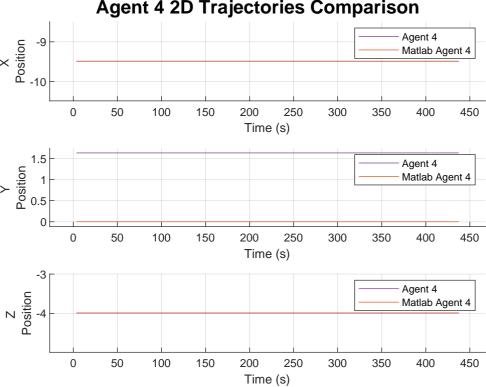


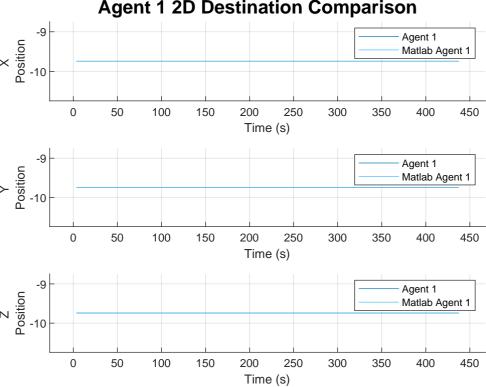


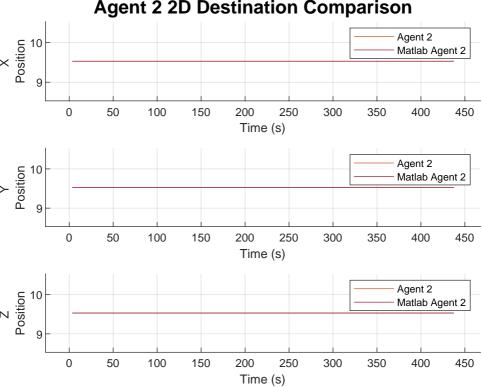


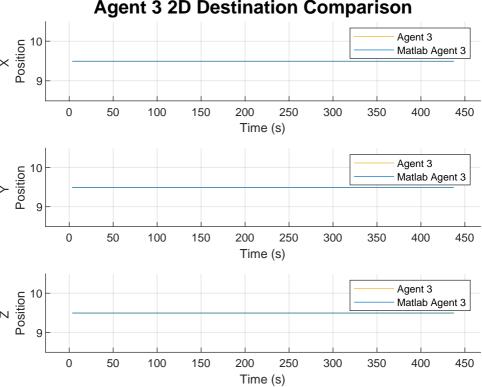


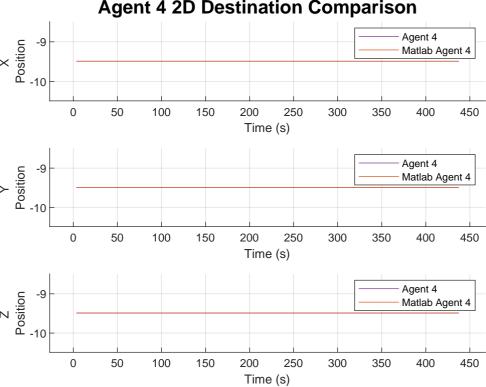


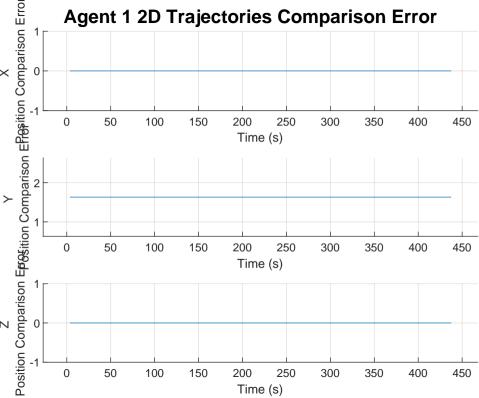


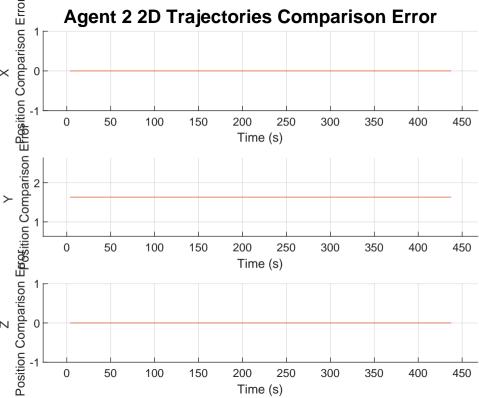


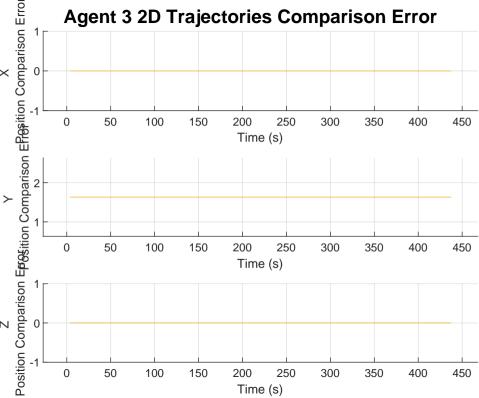


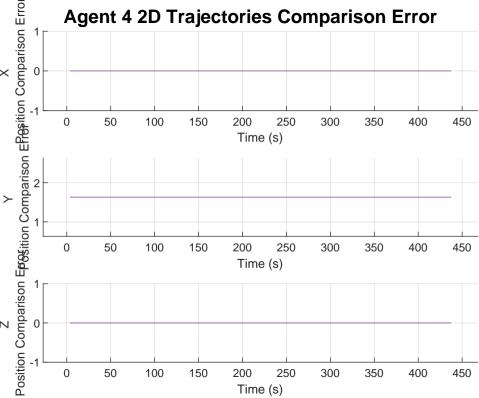


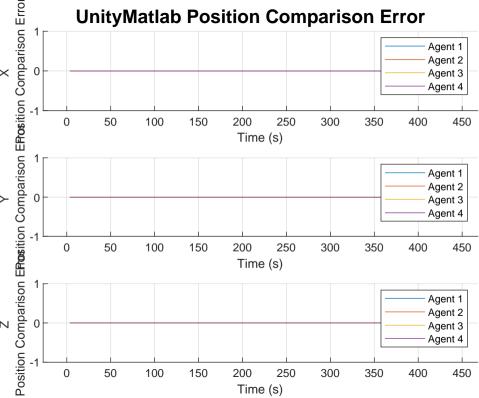


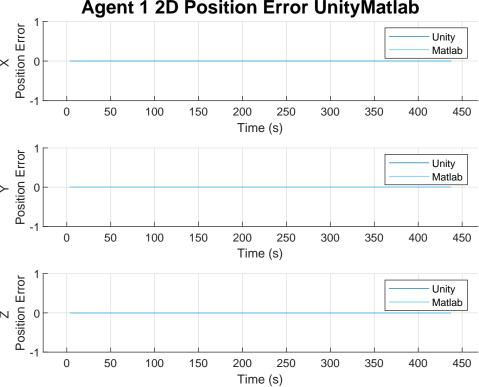


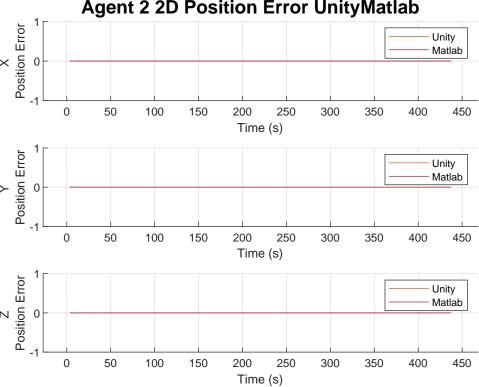


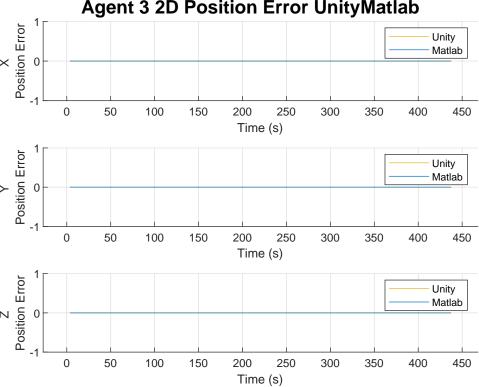


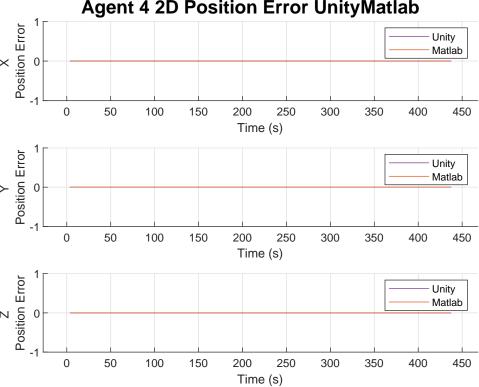


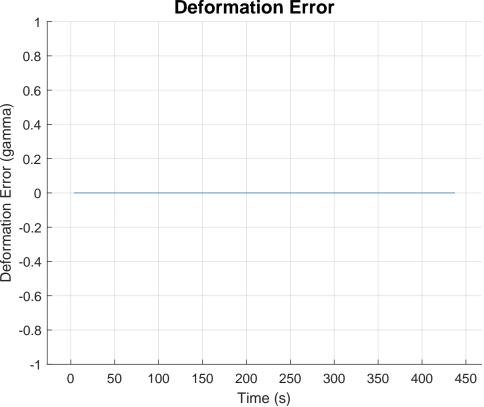


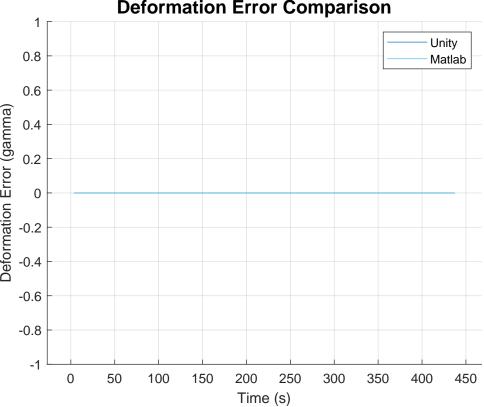


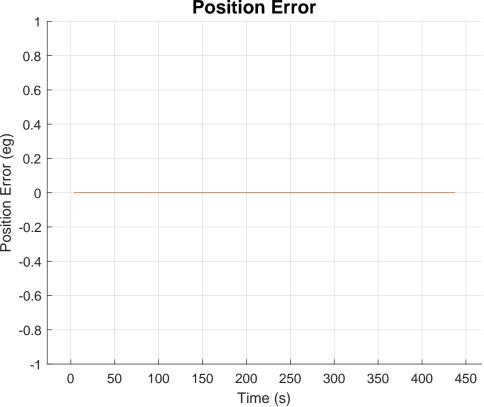


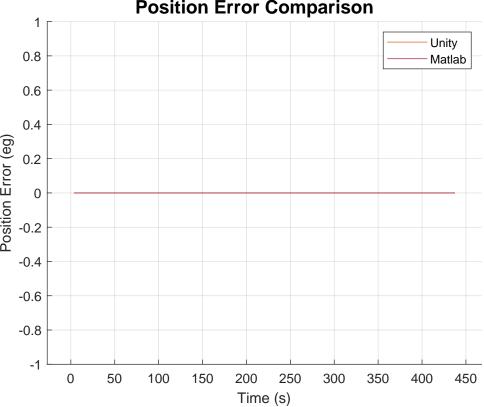


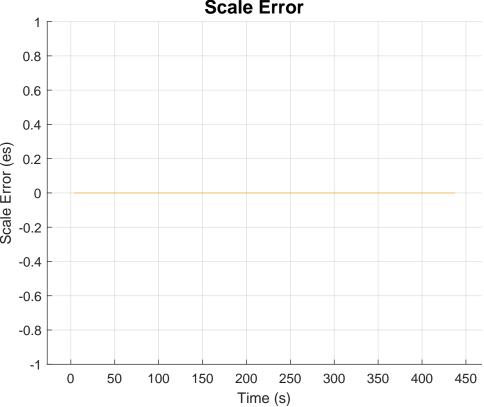


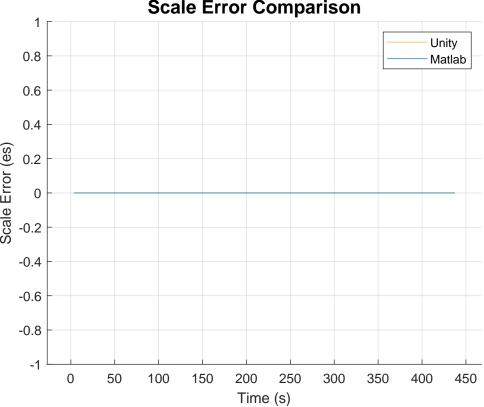


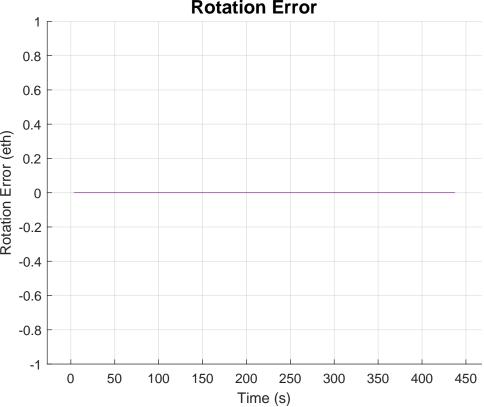


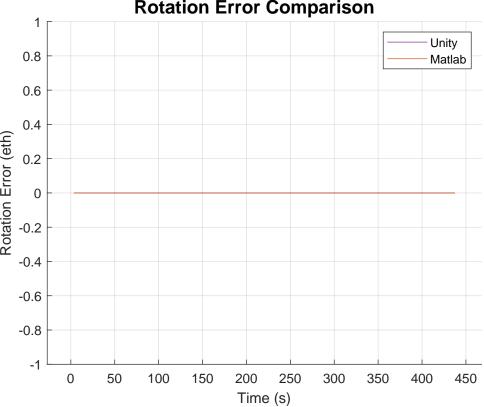


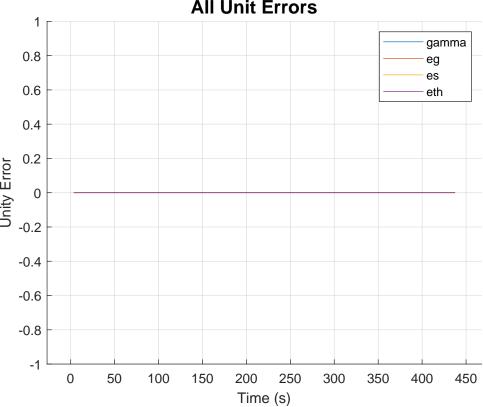


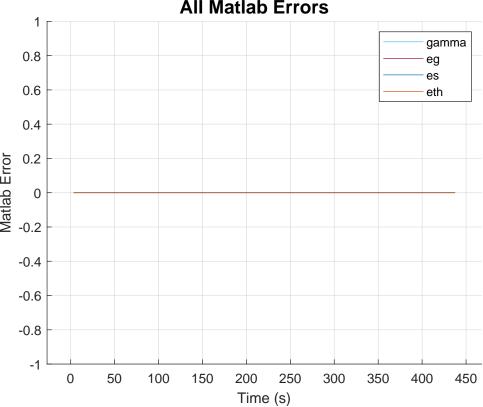


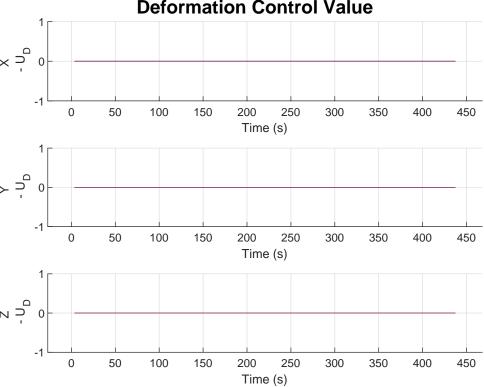


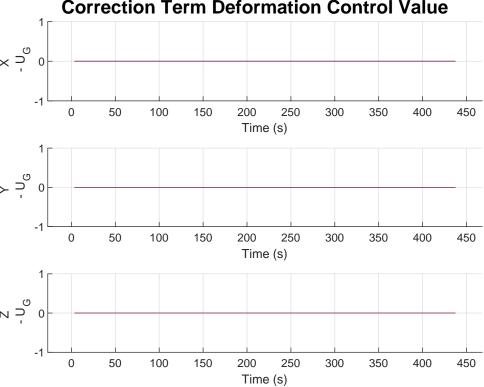


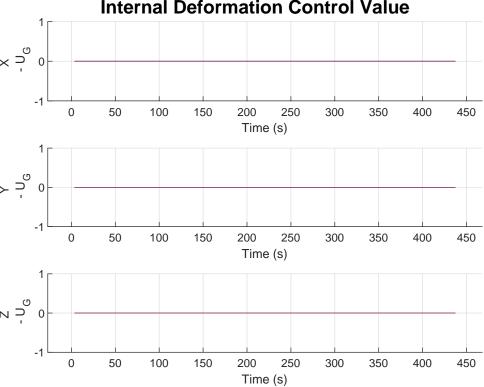


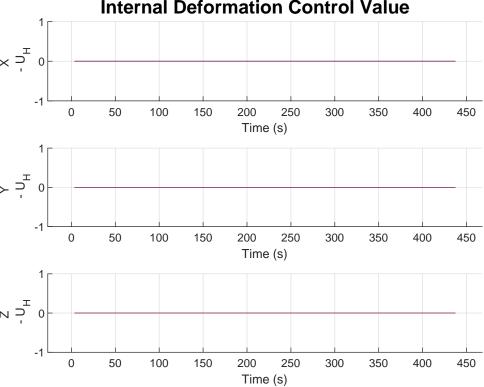


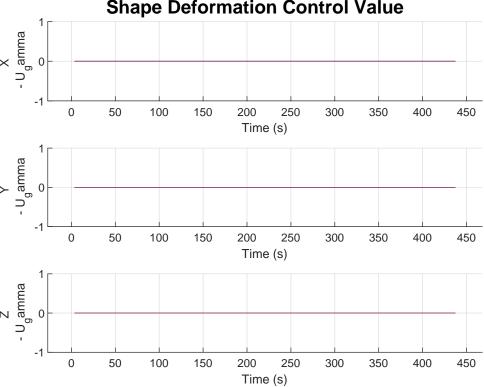












## Scale Control Value Time (s) Time (s) Time (s)

