

$$T\vec{v}_k = a_{1,k}\vec{w}_1 + a_{2,k}\vec{w}_2 + \dots + a_{n,k}\vec{w}_n, \text{ for } k \text{ from } 1 \text{ to } m.$$

$$\begin{matrix} \vec{w}_1 \\ \vec{w}_2 \\ \vdots \\ \vec{w}_n \end{matrix} \rightarrow \begin{bmatrix} a_{1,1} & a_{1,2} & \dots & a_{1,m} \\ a_{2,1} & \dots & \dots & \vdots \\ \vdots & \ddots & \ddots & \vdots \\ a_{n,1} & \dots & \dots & a_{n,m} \end{bmatrix} \begin{matrix} \text{domain} \\ \text{codomain} \end{matrix}$$

example: $D: P_{\leq 3}(\mathbb{R}) \rightarrow P_{\leq 2}(\mathbb{R})$

derivative

$$\rightarrow P_{\mathbb{R}}(\mathbb{R})$$

\rightarrow codomain is dictated by
specifies of the problem,
but you can choose.

Basis of $P_{\leq 3}(\mathbb{R}) = \{1, x, x^2, x^3\}$

of $P_{\leq 2}(\mathbb{R}) = \{1, x, x^2\}$.

$$M(D) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{bmatrix}$$

$$\begin{aligned} 1 &\mapsto 0 \\ x &\mapsto 1 \\ x^2 &\mapsto 2x \\ x^3 &\mapsto 3x^2 \end{aligned}$$

$$\begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

- e.g. if we keep same basis of V and use it as basis for W ,
we will add a row of 0's.

- take the original setup: $D: P_{\leq 3}(\mathbb{R}) \rightarrow P_{\leq 2}(\mathbb{R})$, and the following

bases: $1, x-1, (x-1)(x-2), x(x-1)(x-2)$

$1, x-1, (x-1)(x-2).$

$$x(x-1) = (x-2)(x-1) + 2(x-1)$$

$$\begin{aligned} (x-1)(x-2) + (x-2) \\ \Rightarrow (x-1)(x-2) + (x-1) - 1 \end{aligned}$$

$$3(x-1)(x-2) + 3(x-1) - 1$$

$$\begin{aligned} 1 &\mapsto 0 \\ x-1 &\mapsto 1 \\ (x-1)(x-2) &\mapsto (x-1) + (x-2) = 2(x-1) - 1 \\ x(x-1)(x-2) &\mapsto x(x-1) + x(x-2) + (x-1)(x-2) = (x-1)(x-2) + (x-1)(x-2) + 2(x-1) \\ &\quad - (x-1)(x-2) + (x-1) - 1 \end{aligned}$$

So, in sum,

$$1 \mapsto 0$$

$$x-1 \mapsto 1$$

$$(x-1)(x-2) \mapsto 2(x-1)-1$$

$$x(x-1)(x-2) \mapsto 3(x-1)(x-2)+3(x-1)-1.$$

WRT these 4 bases,

$$M \approx \begin{bmatrix} 0 & 1 & -1 & -1 \\ 0 & 0 & 2 & 3 \\ 0 & 0 & 0 & 3 \end{bmatrix}$$

• M injective: null space is trivial.

$$\text{Null}(M) = \{T \in \mathcal{L}(V, W) : M(T) = 0\}$$

↳ That means for any $T \in \text{Null}(M)$, $T \vec{v}_k = \vec{0} \forall k$.

↳ So, T sends all bases to 0, which means sum of all bases to 0 \rightarrow all V sent to 0.

↳ Therefore, $T = \text{zero map} \rightarrow M(T) = [0]$.

\Rightarrow null space is trivial.

$M(T+S) = M(T) + M(S) \rightarrow$ add coeffs
 $M(\alpha T) = \alpha M(T) \rightarrow$ multi coeffs
 $M : \mathcal{L}(V, W) \rightarrow \mathbb{F}^{\dim W \times \dim V}$
 is also a linear map!

And also an isomorphism (or bijective linear map)

• M surjective: Take an arbitrary element in $\mathbb{F}^{\dim W \times \dim V}$
 $A = [a_{ij}]_{i=1, j=1}^{\dim W, \dim V}$

define T by $T \vec{v}_j := \sum_{i=1}^{\dim W} a_{ij} \vec{w}_i$.

This determines a linear map $T: V \rightarrow W$,

and its matrix $M(T) = A$.

So, M is an isomorphism b/w $\mathcal{L}(V, W)$ and $\mathbb{F}^{\dim W \times \dim V}$.

Claim: $\dim \mathbb{F}^{n,m} = nm$.

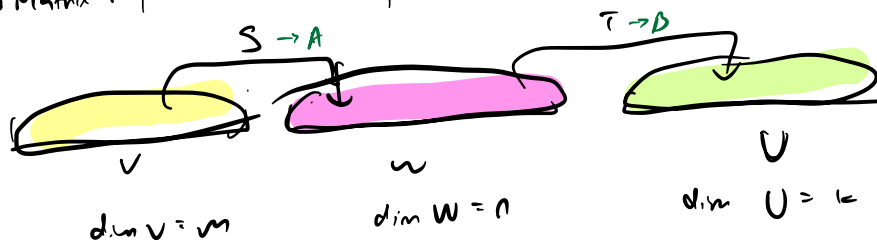
• canonical basis of $(E_{i,j}, i=1 \dots n, j=1 \dots m)$.

$$\text{for } \mathbb{F}^{2,3} \quad \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} = E_{1,3}$$

Corollary: $\dim(\mathcal{L}(V, W)) = \dim V \cdot \dim W$.
 isomorphisms preserve dimensions.

Because M is an isomorphism, and

• Matrix respects the composition of linear maps



$$M(S \circ T) = ?$$

$$(S \circ T) \vec{v}_j = S(T \vec{v}_j) = S \left(\sum_{i=1}^n a_{ij} \vec{w}_i \right)$$

$$= \sum_{i=1}^n a_{ij} S \vec{w}_i = \sum_{i=1}^n a_{ij} \sum_{k=1}^k b_{ki} \vec{u}_k = \left(\sum_{k=1}^k \sum_{i=1}^n a_{ij} b_{ki} \right) \vec{u}_k$$

usual matrix products

So comp. of lin. maps is represented as a matrix product.

$$(BA)_{kj}$$