

Lecture 6

span reprisal

find the basis?

$$\vec{v}_1 = (0, 0, 0) \quad \vec{v}_2 = (2, 1, 0) \quad \vec{v}_3 = (e, \pi, -1) \quad \vec{v}_4 = (1, 1, 1)$$

note: $1 \cdot \vec{v}_1 + 0 \cdot \vec{v}_2 + 0 \cdot \vec{v}_3 + 0 \cdot \vec{v}_4 = \vec{0}$. so we remove \vec{v}_1 .

\vec{v}_2 isn't already in a span. It's not the $\vec{0}$ vector.

\vec{v}_3 is not in span of \vec{v}_2 because of the nonzero 3rd element in \vec{v}_3 .

$\vec{v}_4 \rightarrow a_2 \vec{v}_2 = (e+1, \pi+1, 0)$. there is no a_2 solving this

example 2:

$$(1, 0, 1), (0, 0, 0), (-1, 0, 1), (1, 2, 3), (4, 5, 6)$$

$$\rightarrow (1, 0, 1), (1, 2, 3), (4, 5, 6)$$

$$\text{basis} = \{(1, 0, 1), (1, 2, 3), (4, 5, 6)\}$$

$\times \frac{1}{2} \rightarrow$ doesn't matter.

Basis

Claim: length of any linearly indep. list \leq length of any spanning list.

Proof. Suppose $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_m$ linearly independent and $\vec{w}_1, \vec{w}_2, \dots, \vec{w}_n$

is the span of V . Assume $m > n$.

Step 1: Consider the list

$$\vec{v}_1, \vec{w}_1, \vec{w}_2, \dots, \vec{w}_n$$

But \vec{v}_1 not in span of previous.

so there exists $j \in \{1, \dots, n\}$ s.t. \vec{v}_1 in span of

$\{\vec{v}_1, \vec{v}_1, \vec{w}_1, \dots, \vec{w}_{j-1}\}$. So we remove \vec{w}_j and continue in the same way.

\Rightarrow add $\vec{v}_2 \Rightarrow \vec{v}_1, \vec{v}_2, \vec{v}_1, \vec{w}_1, \dots, \vec{w}_n$. so we can find and remove another \vec{w}_k .

$\vec{w}_1, \vec{w}_2, \dots, \vec{w}_n$ is the span

so \vec{v}_1 must be in this span and it's linearly dependent.

So some $k \in \{1, \dots, j-1, j+1, \dots\}$ s.t. \vec{w}_k can be removed without changing the span.

As a result, we can perform the swap m times, since none of the \vec{v}_i are in the span of the preceding ones.

→ so we end up w/ $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_m, \underbrace{\vec{w}_1, \dots}_{\text{possibly some } w}}\}$
we always need to remove w_j .

→ however, if $m > n$, we will run out of \vec{w} 's to remove. → the spanning set will be at most size n .
otherwise, we will have to remove something in the set to add w_{j+1} , but we don't have any w_j left. So we have to remove some v_i , contradiction.

→ we say that a list of vectors is a basis for U if it's simultaneously linearly independent & spanning set (for U).

Thus: every vector space that's finite dimensional has a finite basis.

→ finite-dimensional = finite list of vectors spans the space.

→ needn't start reading Axler before class.

→ remove some vecs. from span to create basis

→ finitely sized basis. ■

→ basis needs to be linearly-independent & spanning. so

$|\text{one basis}| \leq |\text{another basis}|$. But swapping "one basis"

w/ "another basis" $\Rightarrow |\text{one basis}| \geq |\text{another basis}|$

$\Rightarrow |\text{one basis}| = |\text{another basis}|$

\Rightarrow all bases of U are same sized.

$\dim \mathbb{R}^n = n$, classical basis $(1, 0, \dots, 0), (0, 1, 0, \dots, 0) \dots (0, 0, \dots, 1)$

How can you restate the lin. ind. of v_1, \dots, v_n using the notion of span & direct sum?

$(\vec{v}_1, \dots, \vec{v}_n)$ is lin. indep. $\Leftrightarrow \text{span}(\vec{v}_1) \oplus \text{span}(\vec{v}_2) \oplus \dots \oplus \text{span}(\vec{v}_n)$
is direct.

$W \subseteq V$, V is finite-dimensional. is there a basis for W ?

$\hookrightarrow V = \mathbb{R}^3, W := \{(x, x, 0) : x \in \mathbb{R}\}$

$\hookrightarrow (1, 0, 0), (0, 1, 0), (0, 0, 1)$

If W is nontrivial, then $\exists w_1 \in W$, and w_1 is not the 0 vector. If $\text{span}(w_1) = W$, then done.

If not then take another vector $w_2 \notin \text{span}(w_1)$. Now if $\text{span}(w_1, w_2)$, then we're done. Otherwise $\exists w_3 \dots$

I see where this is going. But it can't go more than $\dim V$ steps, because the # vectors we're gathering now can't exceed the size of the spanning set of V , & is a subset of that spans W .

\rightarrow moreover, $W \subseteq V$ & V finite dimensional, W has direct complement U s.t. $W \oplus U = V$.

We already know \exists a basis $w_1 \dots w_k$ for W . Likewise we have $v_1 \dots v_n$ for V .

List the w 's first, then v 's:

$w_1, w_2, \dots, w_k, v_1, \dots, v_n$

$\underbrace{\hspace{10em}}$

lin. independent

$\underbrace{\hspace{10em}}$

could \exists dependencies, that we throw out.

anything else we add is the direct complement!