HERMITIAN MODULAR FORMS FOR FIELDS OF LOW DISCRIMINANT

DIPLOMA THESIS in Mathematics

by Albert Zeyer

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Supervisor: Prof. Dr. Aloys Krieg Second examiner: Dr. Martin Raum

written at the Lehrstuhl A für Mathematik Prof. Dr. A. Krieg

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Chapter 1

Introduction

We develop an algorithm to compute Fourier expansions of Hermitian modular forms of degree 2 over $\operatorname{Sp}_2(\mathcal{O})$ for $\mathcal{O}\subseteq\mathbb{Q}(\sqrt{-\Delta})$, $\Delta\in\{3,4,8\}$.

In [PY07], spaces of Siegel modular cusp forms are calculated.

A similar algorithm is also [Rau12, Algorithm 4.3] for Jacobi forms.

We are doing the same for Hermitian modular forms.

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Chapter 2

Preliminaries

 \mathbb{N} denotes the set $\{1,2,3,\ldots\}$, $\mathbb{N}_0=\mathbb{N}\cup\{0\}$ and \mathbb{Z} are all **integers**. \mathbb{Q} are all the **rational numbers**, \mathbb{R} are the **real numbers** and \mathbb{C} are the **complex numbers**. $\mathbb{R}^+:=\{x\in\mathbb{R}\mid x>0\}$, \mathbb{R}^\times and \mathbb{C}^\times denotes all non-zero numbers.

Let $\operatorname{Mat}_n(R)$ be the set of all $n \times n$ matrices over some commutative ring R. Likewise, $\operatorname{Mat}_n^T(R)$ are the symmetric $n \times n$ matrices. X^T is the transposed matrix of $X \in \operatorname{Mat}_n(R)$. \overline{Z} is the conjugated matrix of $Z \in \operatorname{Mat}_n(\mathbb{C})$. For $R \subseteq \mathbb{C}$, $\overline{R} \subseteq R$, the set of Hermitian matrices in R is defined as

$$\operatorname{Her}_n(R) = \left\{ Z \in \operatorname{Mat}_n(R) \mid \overline{Z}^T = Z \right\}.$$

A matrix $Y \in \operatorname{Mat}_n(\mathbb{C})$ is greater 0 if and only if $\forall x \in \mathbb{C}^n - \{0\} : Y[x] := \overline{x}^T Y x \in \mathbb{R}^+$. Such matrices are called the **positive definitive matrices**, defined by

$$\mathcal{P}_n(R) = \{ X \in \operatorname{Mat}_n(R) \mid X > 0 \}$$

for $R \subseteq \mathbb{C}$. Note that $\mathcal{P}_n(R) \subseteq \operatorname{Her}_n(R)$, i.e. all positive definite matrices are Hermitian. For a matrix over \mathbb{R} , it means that it is also symmetric.

For $A,X\in \operatorname{Mat}_n(\mathbb{C})$, we define $A[X]:=\overline{X}^TAX$. The **denominator** of a matrix $Z\in \operatorname{Mat}_n(\mathbb{Q})$ is the smallest number $x\in \mathbb{N}$ such that $xZ\in \operatorname{Mat}_n(\mathbb{Z})$. We also write $\operatorname{denom}(Z)=x$. $1_n\in \operatorname{Mat}_n(\mathbb{Z})$ denotes the **identity matrix**. We use the **Gauß notation** $[a,b,c]:=\left(\frac{a}{b}\frac{b}{c}\right)\in \operatorname{Her}_n(\mathbb{C})$.

The general linear group is defined by

$$\operatorname{GL}_n(R) = \{ X \in \operatorname{Mat}_n(R) \mid \det(X) \text{ is a unit in } R \}$$

and the special linear group by

$$\operatorname{SL}_n(R) = \{ X \in \operatorname{Mat}_n(R) \mid \det(X) = 1 \}.$$

The orthogonal group is defined by

$$O_n(R) = \{X \in GL_n(R) \mid X^T 1_n X = 1_n\} \subseteq GL_n(R).$$

The **symplectic group** is defined by

$$\operatorname{Sp}_n(R) = \left\{ X \in \operatorname{GL}_{2n}(R) \mid \overline{X}^T J_n X = J_n \right\} \subseteq \operatorname{GL}_{2n}(R) \subseteq \operatorname{Mat}_{2n}(R)$$

where $J_n := \begin{pmatrix} 0 & -1_n \\ 1_n & 0 \end{pmatrix} \in \operatorname{SL}_{2n}(R)$ (as in [Der01]). (Note that some authors (e.g. [PY07]) define J_n negatively.) $\operatorname{Sp}_n(R)$ is also called the **unitary group**. Note that [Der01] uses $\operatorname{U}_n(R) = \operatorname{Sp}_n(R)$. Also note that $M = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \operatorname{Sp}_1(\mathbb{Z}) \Leftrightarrow ad - bc = 1 \Leftrightarrow M \in \operatorname{SL}_2(\mathbb{Z})$. Thus, $\operatorname{Sp}_1(\mathbb{Z}) = \operatorname{SL}_2(\mathbb{Z})$.

In addition, for a ring $R \subseteq \mathbb{C}$, define

$$\operatorname{Rot}(U) := \begin{pmatrix} \overline{U}^T \\ U^{-1} \end{pmatrix} \in \operatorname{Sp}_2(R), \qquad U \in \operatorname{GL}_2(R)$$
$$\operatorname{Trans}(H) := \begin{pmatrix} 1_2 & H \\ & 1_2 \end{pmatrix} \in \operatorname{Sp}_2(R), \qquad H \in \operatorname{Her}_2(R)$$

and note that we have $J_2 = \binom{1}{2}^{-12} \in \operatorname{Sp}_2(R)$. Those tree types of matrices form a generator set for the group $\operatorname{Sp}_2(R)$.

For $Z \in \operatorname{Mat}_n(\mathbb{C})$, we call

$$\Re(Z) := \frac{1}{2} \left(Z + \overline{Z}^T \right) \in \operatorname{Mat}_n(\mathbb{C})$$

the real part and

$$\Im(Z) := \frac{1}{2i} \left(Z - \overline{Z}^T \right) \in \operatorname{Mat}_n(\mathbb{C})$$

the **imaginary** part of Z and we have $Z = \Re(Z) + i\Im(Z)$. Note that we usually have $\Re(Z), \Im(Z) \notin \operatorname{Mat}_n(\mathbb{R})$ but we have $\Re(Z), \Im(Z) \in \operatorname{Her}_n(\mathbb{C})$.

We say that some function $f: A \to \mathcal{B}$ with $A \subseteq \operatorname{Mat}_n(R)$, $\mathcal{B} \subseteq R$ is k-invariant under some $\mathcal{X} \subseteq \operatorname{Mat}_n(R)$ where $\mathcal{A}[\mathcal{X}] \subseteq A$ if and only if $\det(U)^k f(T[U]) = f(T)$ for all $T \in \mathcal{A}$, $U \in \mathcal{X}$.

2.1 Elliptic modular forms

Elliptic modular forms are holomorphic functions over the set

$$\mathcal{H}_1 := \{ z \in \mathbb{C} \mid \Im(z) > 0 \} \subseteq \mathbb{C}$$

which is called the **Poincaré upper half plane**.

Let f be a holomorphic function $\mathcal{H}_1 \to \mathbb{C}$. Let Γ be a subgroup of $\mathrm{Sp}_1(\mathbb{Z}) = \mathrm{SL}_2(\mathbb{Z})$. **Modular forms** are functions which are invariant with regard to a specific **translation**. In this case, the translation is given by some $M \in \Gamma$ and a **weight** $k \in \mathbb{Z}$. We also call Γ the **translation group**.

Let
$$M = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \Gamma$$
 and $\tau \in \mathcal{H}_1$. We write

$$M\tau := \frac{a\tau + b}{c\tau + d}.$$

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We define the **translated function** $f|M\colon \mathcal{H}_1 \to \mathbb{C}$ as

$$(f|M)(\tau) := (c\tau + d)^{-k} \cdot f(M\tau).$$

An **Elliptic modular form** with weight $k \in \mathbb{Z}$ over Γ is a holomorphic function

$$f:\mathcal{H}_1\to\mathbb{C}$$

with

- (1) $f|M = f \quad \forall M \in \Gamma$,
- (2) $f(\tau) = O(1)$ for $\tau \to i\infty$.

Thus, (1) yields the equation

$$f\left(\frac{a\tau+b}{b\tau+c}\right) = (c\tau+d)^k \cdot f(\tau) \quad \forall \ \left(\begin{smallmatrix} a & b \\ c & d \end{smallmatrix}\right) \in \Gamma, \tau \in \mathcal{H}_1.$$

 $\mathcal{M}_k(\Gamma)$ denotes the vector space of such Elliptic modular forms.

In this work, we use a specific subgroup of $\mathrm{Sp}_1(\mathbb{Z}).$ We define

$$\Gamma_0(l) := \left\{ \left(\begin{array}{cc} a & b \\ c & d \end{array} \right) \in \operatorname{Sp}_1(\mathbb{Z}) \,\middle|\, c \equiv 0 \pmod{l} \right\} \subseteq \operatorname{Sp}_1(\mathbb{Z}) \subseteq \operatorname{Mat}_2(\mathbb{Z})$$

as a subgroup of $\mathrm{Sp}_1(\mathbb{Z})$.

An **Elliptic modular cusp form** is an Elliptic modular form $f \colon \mathcal{H}_1 \to \mathbb{C}$ with

$$\lim_{t \to \infty} f(it) = 0.$$

We can represent the cusps with $\Gamma \setminus \mathbb{Q}$.

More general cusps: $\Gamma \backslash \operatorname{SL}_2(\mathbb{Q}) \div \Gamma_{\infty,\mathbb{Q}}$, where $\Gamma_{\infty,\mathbb{Q}}$ are the upper triangular matrices in $\operatorname{GL}_2(\mathbb{Z})$.

2.2 Siegel modular forms

Siegel modular forms are a generalization of Elliptic modular forms for higher dimensions. Let

$$\mathcal{H}_n := \left\{ Z \in \operatorname{Mat}_n^T(\mathbb{C}) \mid \Im(Z) > 0 \right\}$$

be the **Siegel upper half space**. We call $\operatorname{Sp}_n(\mathbb{Z})$ the **Siegel modular group**. Siegel modular forms are holomorphic functions $\mathcal{H}_n \to \mathbb{C}$ for a given **degree** $n \in \mathbb{N}$.

The translation group Γ is a subgroup of $\operatorname{Sp}_n(\mathbb{Z})$. For $M=\left(\begin{smallmatrix}A&B\\C&D\end{smallmatrix}\right)\in\Gamma$ and $Z\in\mathcal{H}_n$, we write

$$M \cdot Z := (AZ + B) \cdot (CZ + D)^{-1}.$$

Generalizing the Elliptic translation, the Siegel translated function $f|M\colon \mathcal{H}_n \to \mathbb{C}$ is defined as

$$(f|M)(Z) := \det(CZ + D)^{-k} \cdot f(M \cdot Z)$$

A **Siegel modular form** of degree $n \in \mathbb{N}$ with weight $k \in \mathbb{Z}$ over Γ is a holomorphic function

$$f\colon \mathcal{H}_n \to \mathbb{C}$$

with

- (1) $f|M = f \quad \forall M \in \Gamma$,
- (2) for n = 1: f(Z) = O(1) for $Z \to i\infty$

 $\mathcal{M}_k^{\mathcal{H}_n}(\Gamma)$ denotes the vector space of such Siegel modular forms.

Note that Elliptic modular forms are Siegel modular forms of degree n=1. Thus we have $\mathcal{M}_k(\Gamma)=\mathcal{M}_k^{\mathcal{H}_1}(\Gamma)$.

Siegel modular forms aren't directly used in this work. However, the idea of this work is inspired by [PY07] and they are using them.

2.3 Hermitian modular forms

Let

$$\mathbb{H}_n := \{ Z \in \operatorname{Mat}_n(\mathbb{C}) \mid \Im(Z) > 0 \}$$

be the **Hermitian upper half space**. Note that these matrices are not symmetric as the Siegel upper half space \mathcal{H}_n but we have $\mathcal{H}_n \subseteq \mathbb{H}_n$ and $\mathcal{H}_1 = \mathbb{H}_1 \subseteq \mathbb{C}$.

Hermitian modular forms are holomorphic functions $\mathbb{H}_n \to \mathbb{C}$. They are a generalization of Siegel modular forms where the **translation group** Γ is not a subgroup of $\mathrm{Sp}_n(\mathbb{Z})$ but a subgroup of $\mathrm{Sp}_n(\mathcal{O})$ for some $\mathcal{O} \subseteq \mathbb{C}$.

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More specificially, let $\Delta \in \mathbb{N}$ so that we have the imaginary quadratic number field $\mathbb{K} := \mathbb{Q}(\sqrt{-\Delta})$ where $-\Delta$ is the fundamental discriminant. Then, let $\mathcal{O} \subseteq \mathbb{Q}(\sqrt{-\Delta})$ be the maximum order. We call $\operatorname{Sp}_n(\mathcal{O})$ the **Hermitian modular group**. Let Γ be a subgroup of $\operatorname{Sp}_n(\mathcal{O})$.

Again, with $M=(\begin{smallmatrix}A&B\\C&D\end{smallmatrix})\in\Gamma$, $Z\in\mathbb{H}_n$, $M\cdot Z:=(AZ+B)\cdot(CZ+D)^{-1}$ as for Siegel modular forms and the **weight** $k\in\mathbb{Z}$, we define the **translated function** $f|M:\mathbb{H}_n\to\mathbb{C}$ as

$$(f|M)(Z) := \det(CZ + D)^{-k} \cdot f(M \cdot Z).$$

A Hermitian modular form of degree $n \in \mathbb{N}$ with weight $k \in \mathbb{Z}$ over Γ is a holomorphic function

$$f: \mathbb{H}_n \to \mathbb{C}$$

with

- (1) $f|M = f \quad \forall M \in \Gamma, Z \in \mathbb{H}_n$
- (2) for n = 1: f is holomorphic in all cusps.

 $\mathcal{M}_k^{\mathbb{H}_n}(\Gamma)$ denotes the vector space of such Hermitian modular forms.

As it can be done for Siegel modular forms, we generalize this further by introducing a **Multiplicative character** $\nu \colon \Gamma \to \mathbb{C}^{\times}$. Thus, for $M_1, M_2 \in \Gamma$, we have $\nu(M_1) \cdot \nu(M_2) = \nu(M_1 \cdot M_2)$.

A **Hermitian modular form** over Γ and ν is a holomorphic function

$$f \colon \mathbb{H}_n \to \mathbb{C}$$

with

- (1) $f|M = \nu(M) \cdot f \quad \forall M \in \Gamma, Z \in \mathbb{H}_n$,
- (2) for n = 1: f is holomorphic in all cusps.

 $\mathcal{M}_k^{\mathbb{H}_n}(\Gamma,\nu)$ denotes the vector space of such Hermitian modular forms.

For $f \in \mathcal{M}_k^{\mathbb{H}_n}(\Gamma, \nu)$, define the **Siegel** Φ **-operator** as

$$(f|\Phi)(Z'):=\lim_{t\to\infty}f\left(\begin{array}{cc}Z'&0\\0⁢\end{array}\right),\quad Z'\in\mathbb{H}_{n-1}.$$

Then (see [Der01]), $f|\Phi\colon \mathbb{H}_{n-1}\to \mathbb{C}$ is a well-defined Hermitian modular form of degree n-1.

A Hermitian modular form $f \in \mathcal{M}_k^{\mathbb{H}_n}(\Gamma, \nu)$ is a **Hermitian modular cusp form**, if and only if for all $R \in \mathrm{Sp}_n(\mathbb{K})$, it holds

$$(f|R)|\Phi \equiv 0.$$

In this work, we will always use Hermitian modular forms of degree n=2.

2.3.1 Properties

Because $-\Delta$ is fundamental, we have two possible cases:

- 1. $\Delta \equiv 3 \pmod{4}$ and Δ is square-free, or
- 2. $\Delta \equiv 0 \pmod{4}$, $\Delta/4 \equiv 1, 2 \pmod{4}$ and $\Delta/4$ is square-free.

And for the **maximum order** \mathcal{O} , we have (compare [Der01])

$$\begin{split} \mathcal{O} &= \mathbb{Z} + \mathbb{Z} \frac{-\Delta + i\sqrt{\Delta}}{2}, \\ \mathcal{O}^{\#} &= \mathbb{Z} \frac{i}{\sqrt{\Delta}} + \mathbb{Z} \frac{1 + i\sqrt{\Delta}}{2}. \end{split}$$

From now on, we will always work with Hermitian modular forms of degree n=2. We also use $\Gamma=\mathrm{Sp}_2(\mathcal{O})$ for simplicity.

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Chapter 3

Theory

Lemma 3.1. Let $f: \mathbb{H}_2 \to \mathbb{C}$ be a Hermitian modular form of weight k with $\nu \equiv 1$. Let $S \in \mathcal{P}_2(\mathcal{O})$. Then, $\tau \mapsto f(S\tau): \mathbb{H}_1 \subseteq \mathbb{C} \to \mathbb{C}$ is an Elliptic modular form of weight 2k to $\Gamma_0(l)$, where l is the denominator of S^{-1} .

Proof. Define $\Gamma^H := \operatorname{Sp}_2(\mathcal{O})$ as the translation group for f. Let $\tau \in \mathbb{H}_1$. With $S = [s, t, u] \in \mathcal{P}_2(\mathbb{C})$ we have

$$\Im(S\tau) = \frac{1}{2i} \left(S\tau - \overline{S}^T \overline{\tau} \right)$$

$$= \frac{1}{2i} S(\tau - \overline{\tau})$$

$$= \frac{1}{2i} S \cdot 2i \Im(\tau)$$

$$= S\Im(\tau) > 0,$$

thus $S\tau \in \mathbb{H}_2$. Thus, $\tau \mapsto f(S\tau)$ is a function $\mathbb{H}_1 \to \mathbb{C}$.

Let $l := \det(S)$. That is the denominator of S^{-1} . Let $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \Gamma_0(l) \subseteq \mathrm{SL}_2(\mathbb{Z})$. We have

$$S\frac{a\tau + b}{c\tau + d}$$

$$= (a(S\tau) + bS) \cdot ((cS^{-1})(S\tau) + d)^{-1}$$

$$= \begin{pmatrix} a1_2 & bS \\ cS^{-1} & d1_2 \end{pmatrix} \cdot S\tau.$$

Define

$$M := \begin{pmatrix} a1_2 & bS \\ cS^{-1} & d1_2 \end{pmatrix} \in \operatorname{Mat}_4(\mathbb{C}).$$

With l|c, we also have $cS^{-1}=\frac{c}{l}[u,-t,s]\in \mathrm{Mat}_2(\mathcal{O})$, thus we have $M\in \mathrm{Mat}_4(\mathcal{O})$. Recall

that we have $S=\overline{S}^T$ and ad-bc=1. Verify that we have $M\in \mathrm{Sp}_2(\mathcal{O})=\Gamma^H$:

$$\overline{M}^{T} J_{2} M
= \left(\begin{array}{ccc} a1_{2} & bS \\ cS^{-1} & d1_{2} \end{array} \right)^{T} J_{2} \left(\begin{array}{ccc} a1_{2} & bS \\ cS^{-1} & d1_{2} \end{array} \right)
= \left(\begin{array}{ccc} (-acS^{-1} + ac\overline{S^{-1}}^{T}) & (-ad1_{2} + cb\overline{S^{-1}}^{T}S) \\ (-bc\overline{S}^{T}S^{-1} + ad1_{2}) & (-bd\overline{S}^{T} + bdS) \end{array} \right)
= J_{2}.$$

Thus, because f is a Hermitian modular form, we have

$$f\left(S\frac{a\tau+b}{c\tau+d}\right)$$

$$= f\left(M \cdot S\tau\right)$$

$$= \nu(M) \cdot \det(cS^{-1}S\tau + d1_2)^k \cdot f(S\tau)$$

$$= (c\tau+d)^{2k} \cdot f(S\tau).$$

Thus, f is an Elliptic modular form of weight 2k to $\Gamma_0(l)$.

Remark 3.2. Let us analyze the case $\nu \not\equiv 1$. According to [Der01], only for $\Delta \equiv 0 \pmod{4}$, there is a single non-trivial Abel character ν . This ν has the following properties (see [Der01]):

$$\nu(J_2) = 1,$$

$$\nu(\operatorname{Trans}(H)) = (-1)^{h_1 + h_4 + |h_2|^2}, \qquad H = [h_1, h_2, h_4] \in \operatorname{Her}_2(\mathcal{O})$$

$$\nu(\operatorname{Rot}(U)) = (-1)^{|1 + u_1 + u_4|^2 |1 + u_2 + u_3|^2 + |u_1 u_4|^2} \qquad U = \begin{pmatrix} u_1 & u_2 \\ u_3 & u_4 \end{pmatrix} \in \operatorname{GL}_2(\mathcal{O})$$

Consider the proof of the previous lemma. To calculate $\nu(M)$ with the given equations, we need to represent M in the generating system J_2 , Trans(H) and Rot(U).

We must consider two different cases. Recall that we have $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \mathrm{SL}_2(\mathbb{Z})$, i.e. ad - bc = 1, $S = [s, t, u] \in \mathcal{P}_2(\mathcal{O})$ and

$$M = \begin{pmatrix} a1_2 & bS \\ cS^{-1} & d1_2 \end{pmatrix} \in \operatorname{Sp}_2(\mathcal{O}).$$

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Case 1: c = 0. Then we have ad = 1. Define $T := \frac{b}{d}S$. Then we have

$$\operatorname{Trans}\left(\frac{b}{d}S\right)\operatorname{Rot}\left(\frac{1}{d}1_{2}\right)$$

$$= \begin{pmatrix} 1_{2} & \frac{b}{d}S \\ & 1_{2} \end{pmatrix} \begin{pmatrix} \frac{1}{d}1_{2} \\ & d1_{2} \end{pmatrix}$$

$$= \begin{pmatrix} \frac{1}{d}1_{2} & bS \\ & d1_{2} \end{pmatrix}$$

$$= M.$$

And we have

$$\begin{split} \nu\left(\operatorname{Trans}\left(\frac{b}{d}S\right)\right) &= (-1)^{\frac{b}{d}s + \frac{b}{d}u + \left|\frac{b}{d}t\right|^2}, \\ \nu\left(\operatorname{Rot}\left(\frac{1}{d}\mathbf{1}_2\right)\right) &= (-1)^{\left|1 + \frac{2}{d}\right|^2 + \left|\frac{1}{d^2}\right|^2} = 1. \end{split}$$

Case 2: $c \neq 0$. Then we have

$$\operatorname{Trans}\left(\frac{a}{c}S\right)\operatorname{Rot}\left(-\frac{1}{c}S\right)\left(-J_{2}\right)\operatorname{Trans}\left(-\frac{d}{c}S\right)^{-1}$$

$$=\begin{pmatrix} 1_{2} & \frac{a}{c}S \\ 1_{2} \end{pmatrix}\begin{pmatrix} -\frac{1}{c}\overline{S}^{T} \\ -cS^{-1} \end{pmatrix}\left(-J_{2}\right)\begin{pmatrix} 1_{2} & -\frac{d}{c}S \\ 1_{2} \end{pmatrix}^{-1}$$

$$=\begin{pmatrix} -\frac{1}{c}\overline{S}^{T} & -a1_{2} \\ -cS^{-1} \end{pmatrix}\begin{pmatrix} 1_{2} \\ -1_{2} \end{pmatrix}\begin{pmatrix} 1_{2} & \frac{d}{c}S \\ 1_{2} \end{pmatrix}$$

$$=\begin{pmatrix} -\frac{1}{c}\overline{S}^{T} & a1_{2} \\ -cS^{-1} \end{pmatrix}\begin{pmatrix} 1_{2} \\ -1_{2} & -\frac{d}{c}S \end{pmatrix}$$

$$=\begin{pmatrix} a1_{2} & -\frac{1}{c}\overline{S}^{T} + \frac{ad}{c}S \\ cS^{-1} & d1_{2} \end{pmatrix}$$

$$=M.$$

And we have

$$\nu\left(\operatorname{Trans}\left(\frac{a}{c}S\right)\right) = (-1)^{\frac{a}{c}s + \frac{a}{c}u + \left|\frac{a}{c}t\right|^{2}},$$

$$\nu\left(\operatorname{Rot}\left(-\frac{1}{c}S\right)\right) = (-1)^{\left|1 - \frac{1}{c}s - \frac{1}{c}u\right|^{2}\left|1 - \frac{2}{c}\Re(t)\right|^{2} + \left|\frac{su}{c^{2}}\right|^{2}},$$

$$\nu\left(-J_{2}\right) = -1,$$

$$\nu\left(\operatorname{Trans}\left(-\frac{d}{c}S\right)\right)^{-1} = (-1)^{-\frac{d}{c}s - \frac{d}{c}u + \left|\frac{d}{c}t\right|^{2}}.$$

As a conclusion for now, it looks complicated to restrict $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$, i.e. the translation group Γ^E for the Elliptic modular forms, to satisfy $\nu(M)=1$. For example, for the case c=0, one fulfilling condition would be 2|b.

To avoid such complications, we will use $\nu \equiv 1$ for the rest of our work.

Lemma 3.3. Prop 7.3. von Poor für herm Modulformen. $\Gamma(\mathcal{L}) \supseteq \Gamma_0(l)$ for $l \in \mathbb{Z}^+, ls^{-1} \in \mathcal{P}_n(\mathcal{O})$.

We want to calculate a generating set for the Fourier expansions of Hermitian modular forms. Now we will formulate the main algorithm of our work.

Algorithm 3.4. We have the Hermitian modular form degree n=2 fixed, as well as some Δ (for now, $\Delta \in \{3,4,8\}$). Then we select some form weight $k \in \mathbb{Z}$ ($k \in \{1,\ldots,20\}$ or so), let $\mathcal{O} \subseteq \mathbb{Q}(\sqrt{-\Delta})$ be the maximum order (see chapter 2.3.1) and some subgroup Γ of $\mathrm{Sp}_2(\mathcal{O})$. Then we select an abel character $\nu \colon \Gamma \to \mathbb{C}^\times$ of $\mathrm{Sp}_2(\mathcal{O})$ (we just use $\nu \equiv 1$, see remark 3.2).

We define the index set

$$\Lambda := \left\{ 0 \le \begin{pmatrix} a & b \\ \overline{b} & c \end{pmatrix} \in \operatorname{Mat}_2(\mathcal{O}^{\#}) \, \middle| \, a, c \in \mathbb{Z} \right\}.$$

Fix $B \in \mathbb{N}$ as a limit. Select a precision

$$\mathcal{F} := \left\{ \left(\begin{array}{cc} a & b \\ \overline{b} & c \end{array} \right) \in \Lambda \,\middle|\, 0 \le a, c < B \right\} \subseteq \Lambda.$$

1. We start with l = 1 and increase it but only use the square-free numbers.

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- 2. Set $S = \{\},$
- 3. Enumerate matrices $S \in \operatorname{Mat}_2^T(\mathbb{Z})$, and set $\mathcal{S} \leftarrow \mathcal{S} \cup \{S\}$ and for each time you add a new matrix perform the following steps.
- 4. We set

$$\mathcal{M}^H_{k,\mathcal{S},\mathcal{F}} := \left\{ (a[S])_{S \in \mathcal{S}} \ \middle| \ a \in \mathbb{Q}^{\mathcal{F}} \text{ is } \mathrm{GL}_2(\mathcal{O}) \text{ invariant} \right\} \subseteq \bigoplus_{S \in \mathcal{S}} \mathbb{Q}^{\mathcal{F}(S)},$$

where

$$a[S] := \mathbb{N}_0 \to \mathbb{Q}, n \mapsto \sum_{T \in \Lambda, \operatorname{tr}(ST) = n} a(T),$$

The elements $a \in \mathbb{Q}^{\mathcal{F}}$ are Fourier expansions of Elliptic modular forms ($\mathbb{H}_1 \to \mathbb{C}$) and $a(T) \in \mathbb{Q}$ for $T \in \mathcal{F} \subseteq \operatorname{Mat}_2(\mathcal{O}^{\#})$ are the Fourier coefficients. Recall that a being invariant under $\operatorname{GL}_2(\mathcal{O})$ means that we have

$$\det(U)^k a(T[U]) = a(T) \ \forall \ U \in \mathrm{GL}_2(\mathcal{O}).$$

With $[a,b,c] \in \mathcal{F}$, we have $0 \le a,c < B$, thus there are only a finite number of possibilities. Because $0 \le [a,b,c]$, we get $ac-|b|^2 \ge 0$ and thus b is also always limited. Thus, \mathcal{F} is finite but it might be huge for even small B. Restricting the elements in \mathcal{F} by the $\mathrm{GL}_2(\mathcal{O})$ -invariation makes the set $\{x \in \mathcal{F} \mid x \text{ is } \mathrm{GL}_2(\mathcal{O}) \text{ invariant}\} \subseteq \mathcal{F}$ much smaller and better to handle in computer calculations. We use this set to identify a base of the finite dimension vector space $\{x \in \mathbb{Q}^{\mathcal{F}} \mid x \text{ is } \mathrm{GL}_2(\mathcal{O}) \text{ invariant}\}$.

We identify

$$\bigoplus_{S \in \mathcal{S}} \mathbb{Q}^{\mathcal{F}(S)} = \mathbb{Q}^N, \ N = \sum_{S \in \mathcal{S}} \mathcal{F}(S).$$

For a given $S \in \mathcal{S}$ and limit $B \in \mathbb{N}$ which restricts $\mathcal{F} \subset \Lambda$, $\mathcal{F}(S) \in \mathbb{N}_0$ is the limit such that for any $T \in \Lambda - \mathcal{F}$, $\operatorname{tr}(ST) \geq \mathcal{F}(S)$. Thus, for calculating the Fourier coefficients $T \in \Lambda$ with $\operatorname{tr}(ST) \in \{0, \dots, \mathcal{F}(S) - 1\}$, it is sufficient to enumerate the $T \in \mathcal{F}$.

Let S = [s, t, u] and T = [a, b, c]. Recall that $S \in \operatorname{Mat}_2^T(\mathbb{Z})$. Then we have

$$tr(ST) = as + \overline{t}b + t\overline{b} + cu = as + cu + 2t\Re(b).$$

Because $T \ge 0$, we have $ac \ge |b|^2$ and thus $\Re(b) \le \sqrt{ac} \le \max(a,c)$. Thus, $2t\Re(b) \ge -2|t|\max(a,c)$. We also have $as + cu \ge \max(a,c)(s+u)$. Assuming $T \in \Lambda - \mathcal{F}$, we

have $\max(a, c) \geq B$. For such T, we get

$$tr(ST) \ge B \cdot (s + u - 2|t|).$$

Given S > 0, we have $su > t^2$. Then we have

$$\begin{aligned} s + u - 2 |t| &> 0 \\ \Leftrightarrow & su + u^2 - 2 |t| \, u > 0 \\ \Leftrightarrow & \left(t^2 + u^2 - 2 |t| \, u \right) + \left(su - t^2 \right) > 0 \\ \Leftrightarrow & \left(|t| - u \right)^2 + \left(su - t^2 \right) > 0. \end{aligned}$$

All inequalities were sharp estimations¹, thus we get

$$\mathcal{F}(S) = B \cdot (s + u - 2|t|).$$

We want to calculate the matrix of the linear function

$$\left\{x \in \mathbb{Q}^{\mathcal{F}} \mid x \text{ is } \mathrm{GL}_2(\mathcal{O}) \text{ invariant}\right\} \to \bigoplus_{S \in \mathcal{S}} \mathbb{Q}^{\mathcal{F}(S)}, \ a \mapsto (a[S])_{S \in \mathcal{S}}.$$

The base of the destination room is canonical. The dimension is N. The base of the source room can be identified by $\{x \in \mathcal{F} \mid x \text{ is } \mathrm{GL}_2(\mathcal{O}) \text{ invariant}\}.$

And we set

$$\mathcal{M}_{k,\mathcal{S},\mathcal{F}} := \bigoplus_{S \in \mathcal{S}} \mathcal{F} \mathcal{E}_{\mathcal{F}(S)}(\mathcal{M}_k(\Gamma_0(l_S)))$$

where $\mathcal{M}_k(\Gamma_0(l_S))$ is the vectorspace of Elliptic modular forms over $\Gamma_0(l_S)$.

5. If

$$\dim \mathcal{M}_{k,\mathcal{S},\mathcal{F}}^H \cap \mathcal{M}_{k,\mathcal{S},\mathcal{F}} = \dim \mathcal{M}_k^{\mathbb{H}_2}(\Gamma,\nu),$$

then we are ready and we can reconstruct the Fourier expansion in the following way:

If not, then return to step 3, and enlarge S.

¹For example, let S=[2,-1,1]. Then you have s+u-2|t|=1. With c=B and a=b=1, you hit the limit $\mathrm{tr}(ST)=2+B-2=B=\mathcal{F}(S)$.

Chapter 4

Implementation

In this chapter, we are describing the implementation.

Chapter 5

Conclusion

Blub

18 6 REFERENCES

Chapter 6

References

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