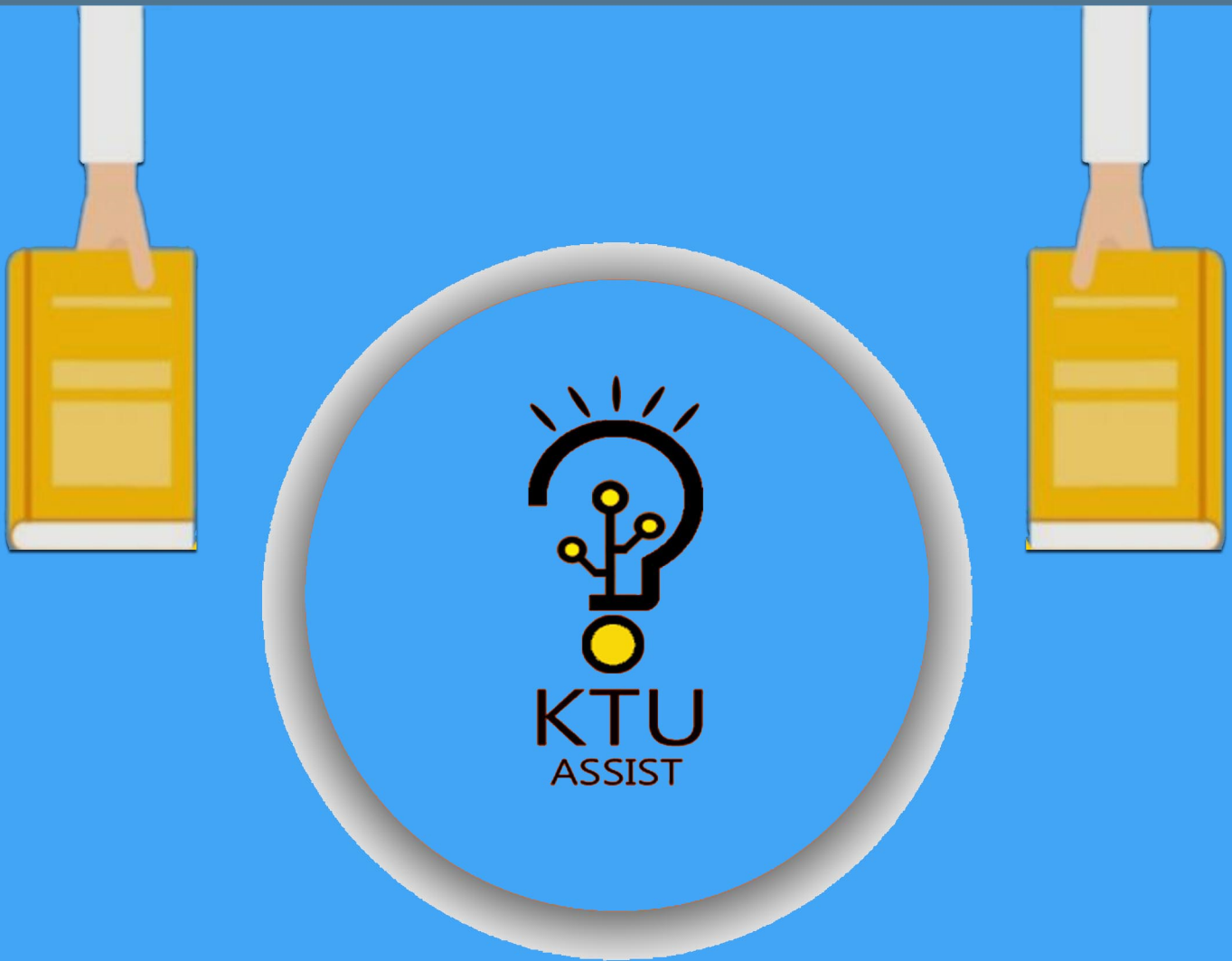


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STUDY MATERIALS



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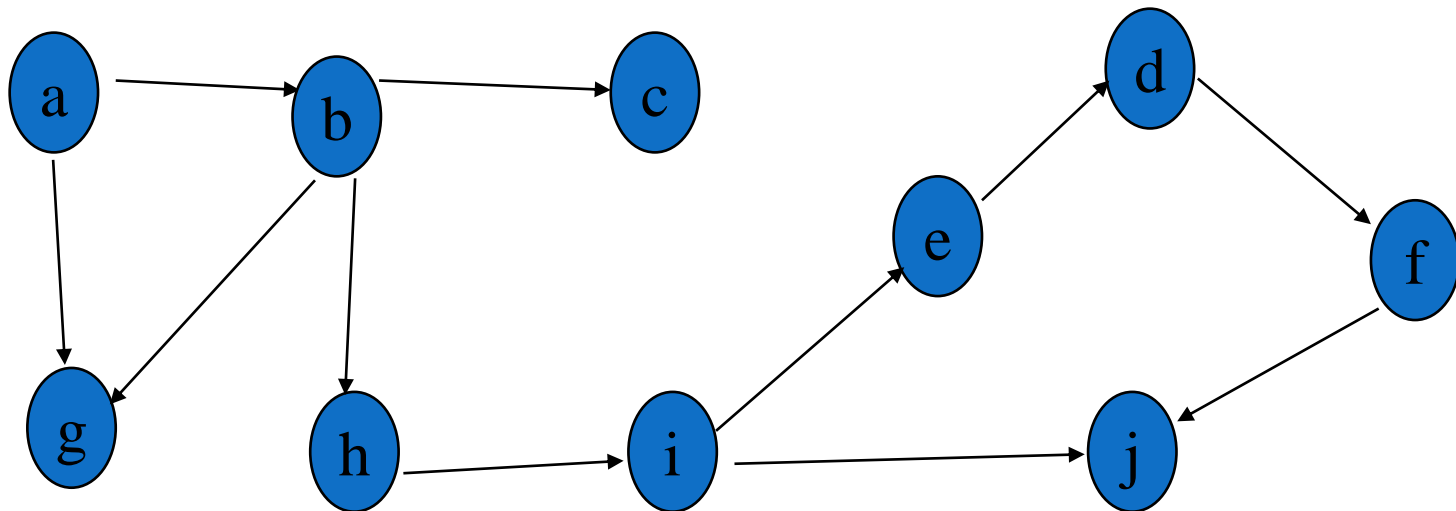
Depth First Search & Breadth First Search

Graph Search (traversal)

- Graph traversal : **searching a vertex in a graph**
- There are two graph traversal techniques and they are as follows
 - **DFS (Depth First Search)**
 - **BFS (Breadth First Search)**
- DFS - go as far as possible along a single path until reach a dead end (a vertex with no edge out or no neighbor unexplored) then backtrack
- BFS - one explore a graph level by level away (explore all neighbors first and then move on)

Depth-First Search (DFS)

- The basic idea behind this algorithm is that it traverses the graph using recursion
 - Go as far as possible until you reach a deadend
 - Backtrack to the previous path and try the next branch
- The graph below, started at node a, would be visited in the following order: a, b, c, g, h, i, e, d, f, j



DFS: Color Scheme

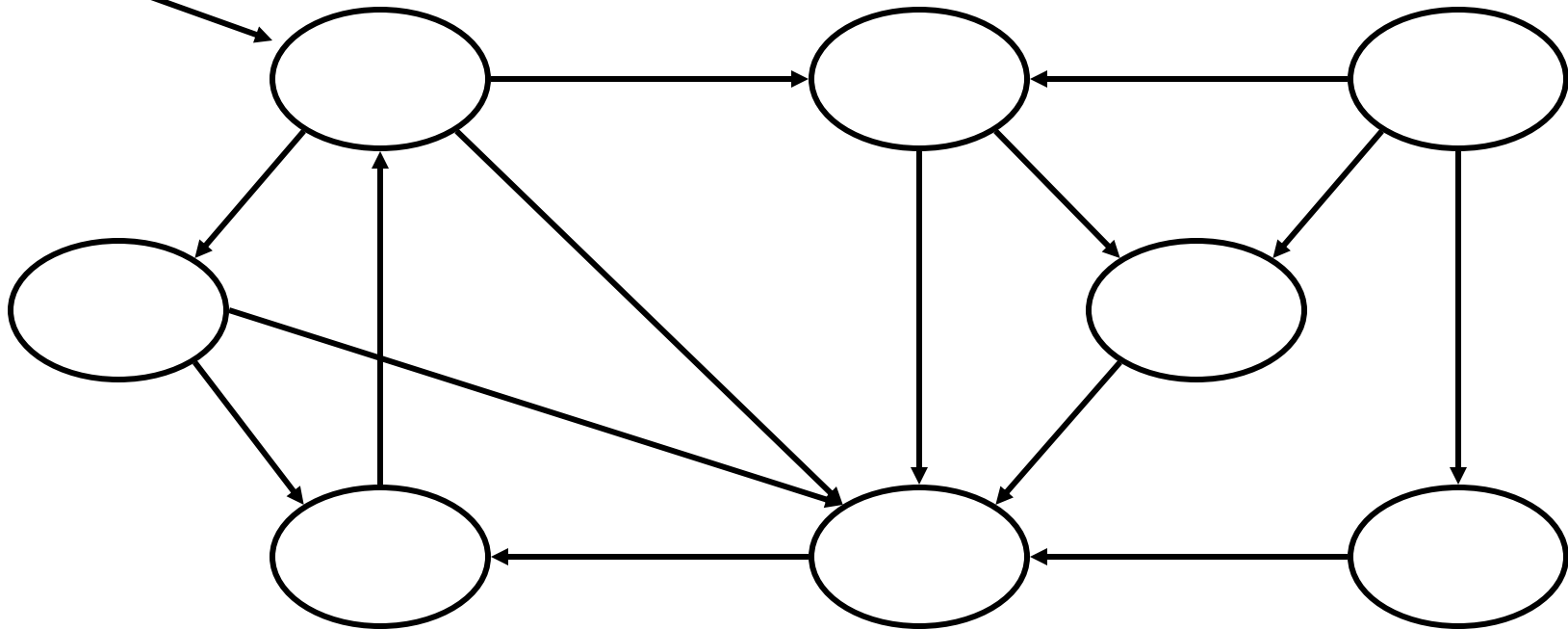
- Vertices initially colored white
- Then colored gray when discovered
- Then black when finished

DFS: Time Stamps

- Discover time $d[u]$: when u is first discovered
- Finish time $f[u]$: when backtrack from u
- $d[u] < f[u]$

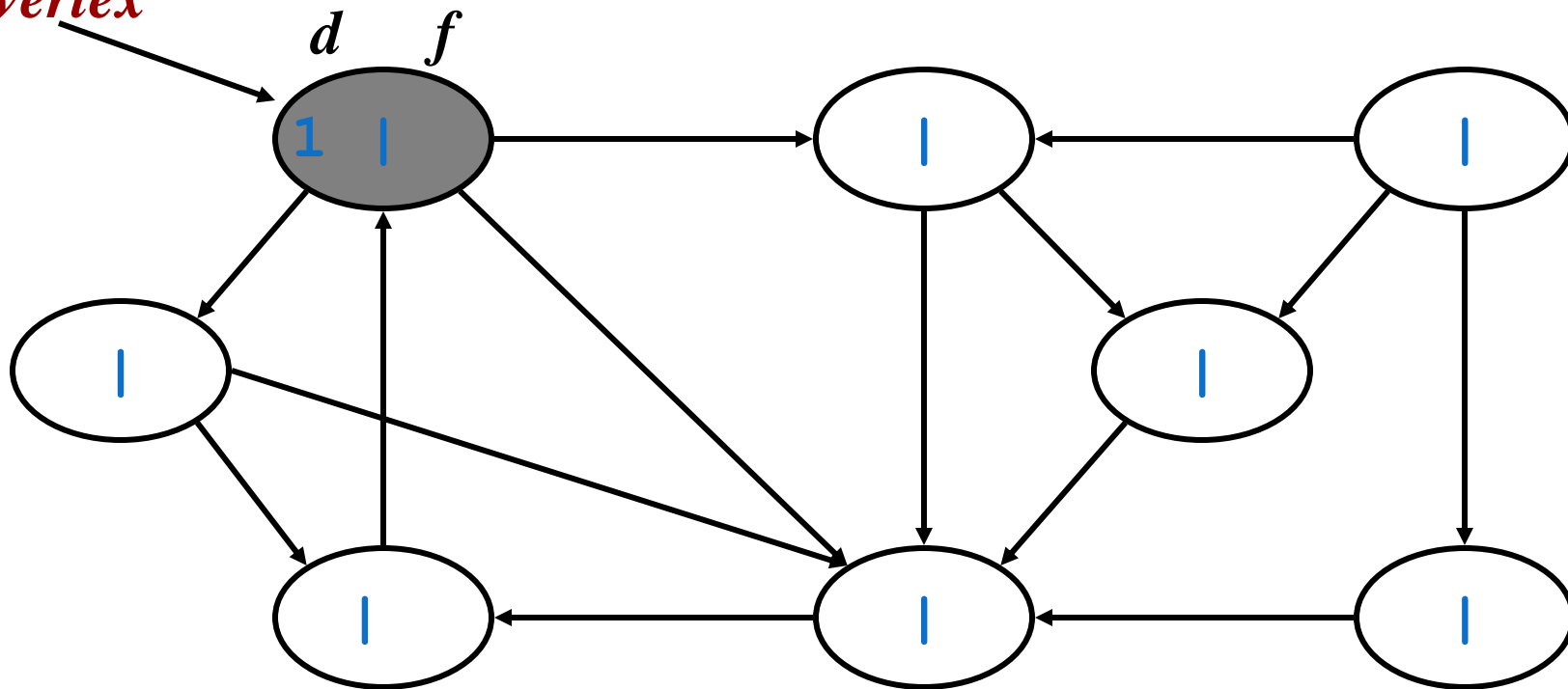
DFS Example

*source
vertex*



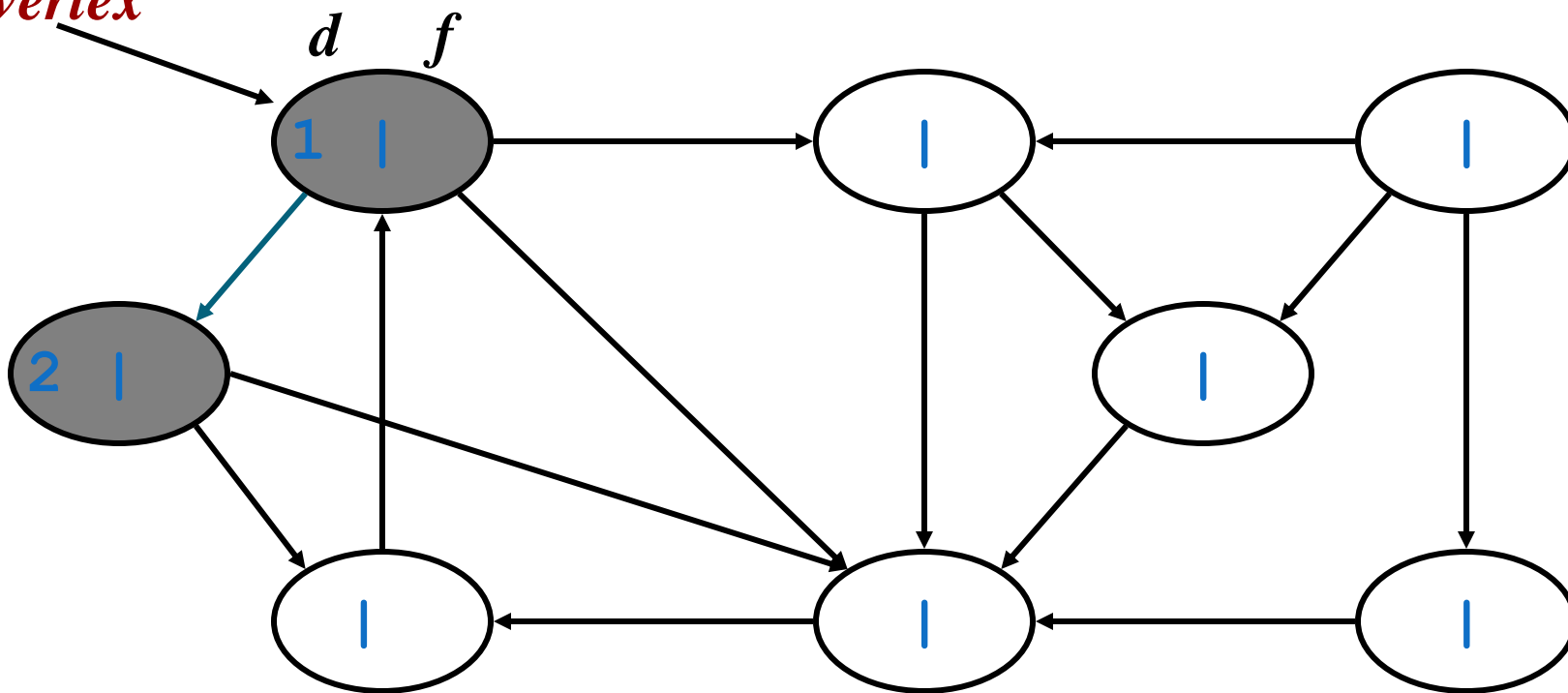
DFS Example

*source
vertex*



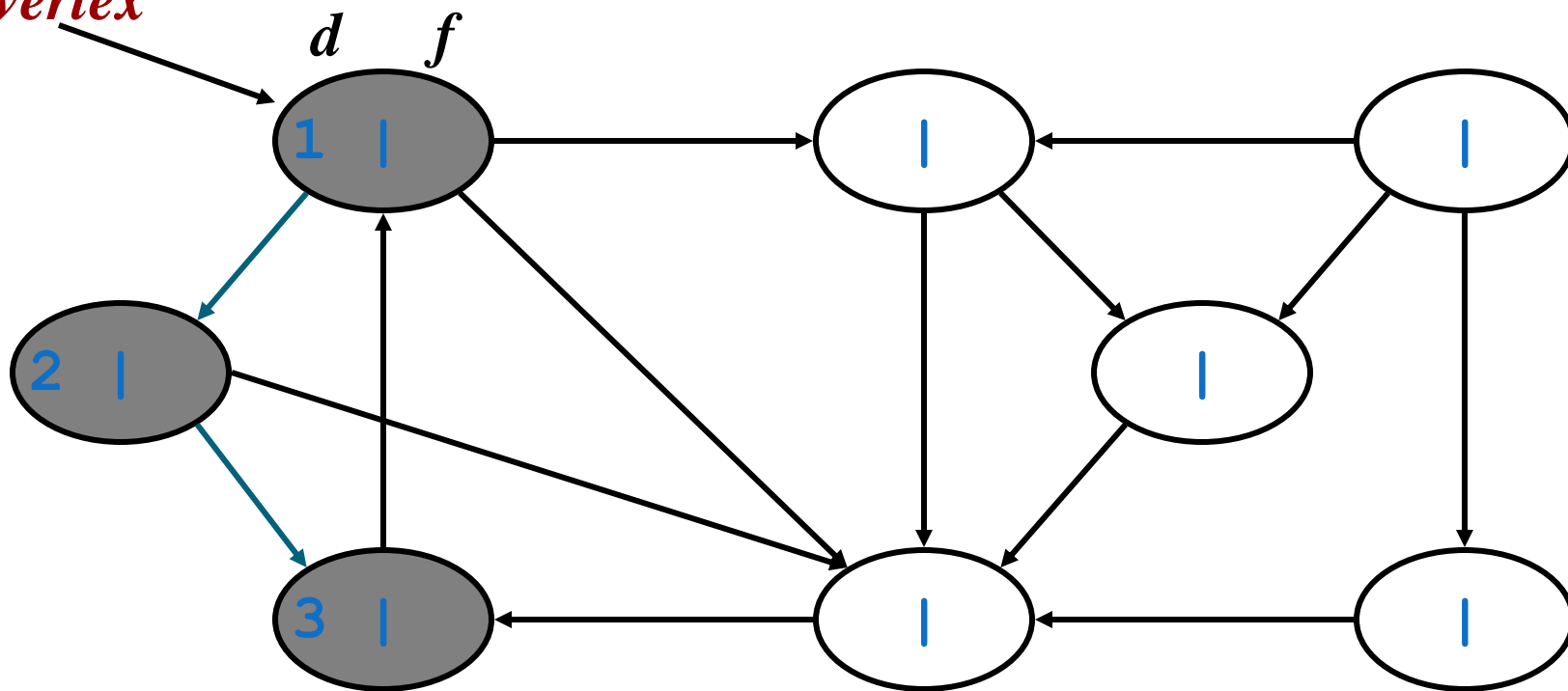
DFS Example

source
vertex



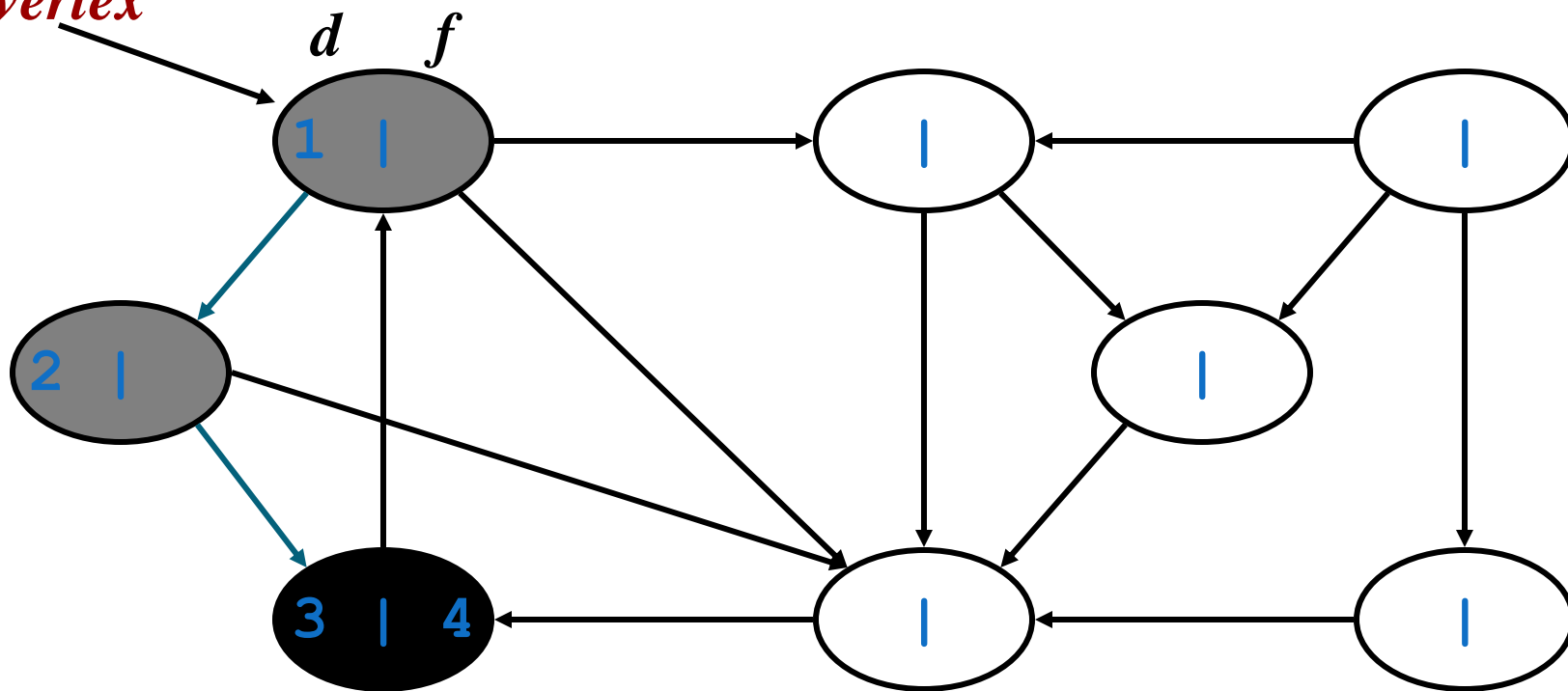
DFS Example

*source
vertex*



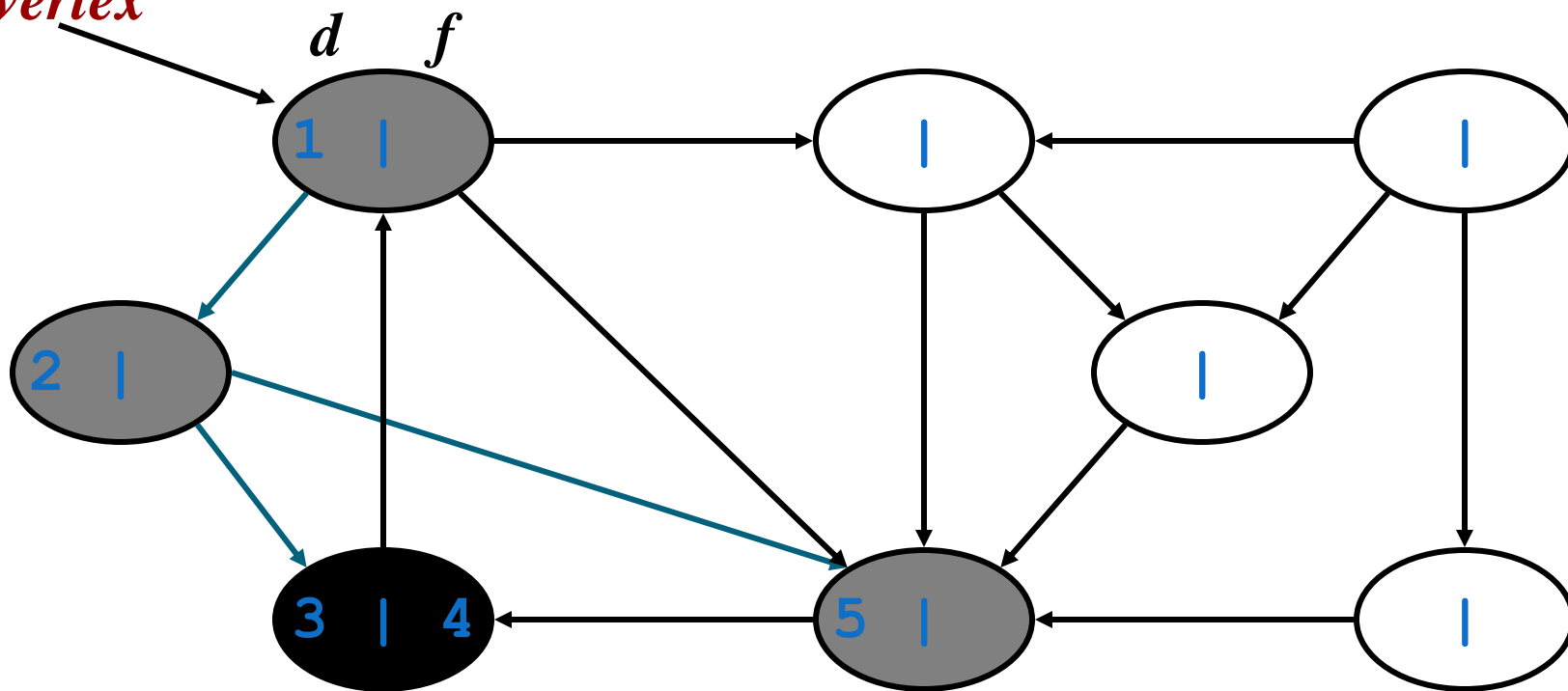
DFS Example

*source
vertex*



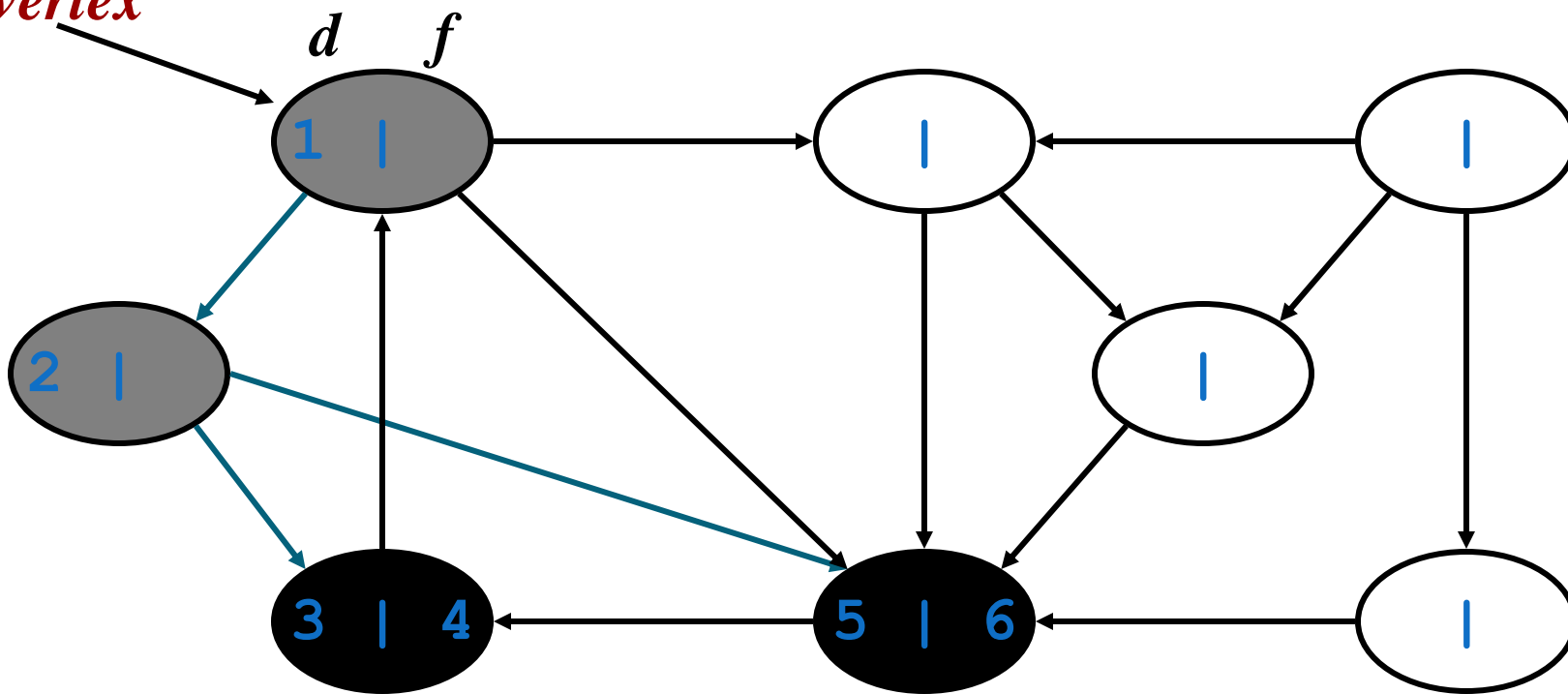
DFS Example

*source
vertex*



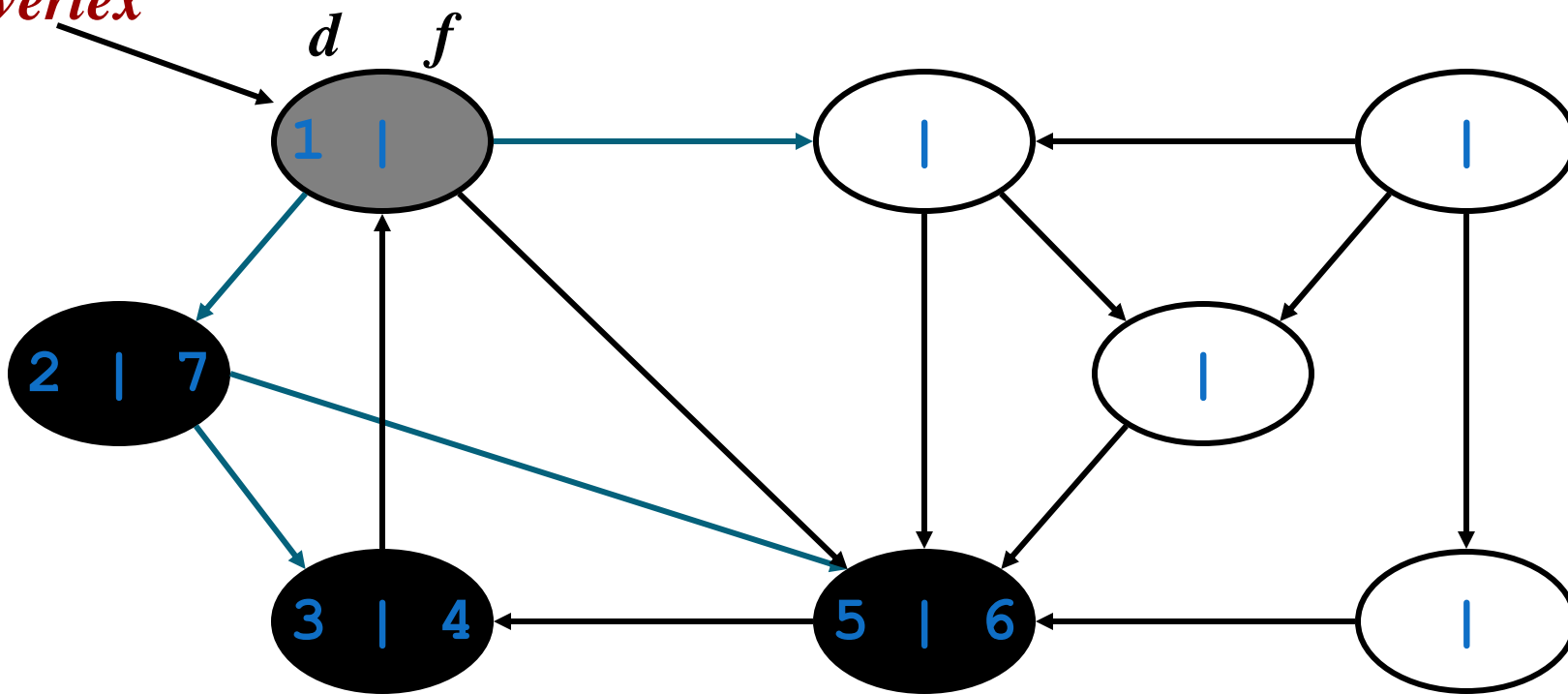
DFS Example

source
vertex



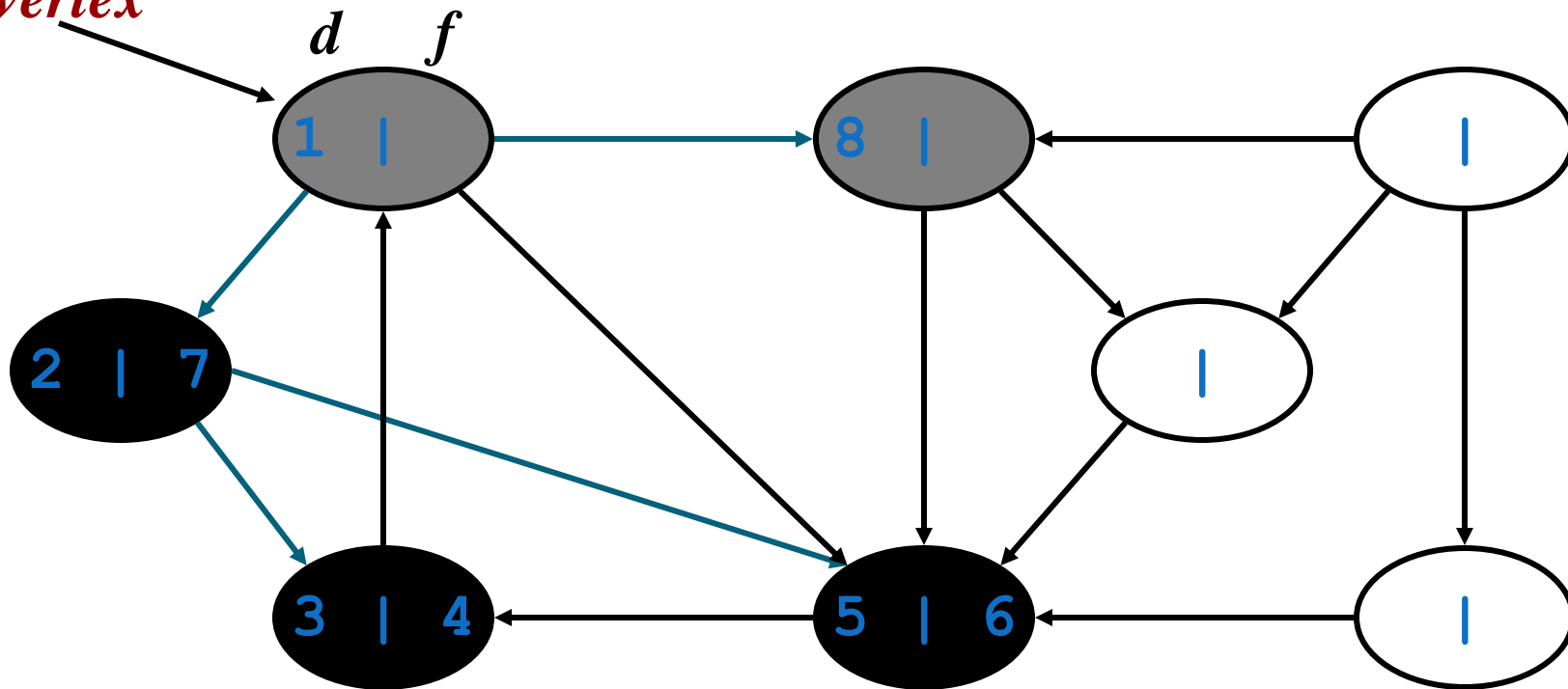
DFS Example

source
vertex



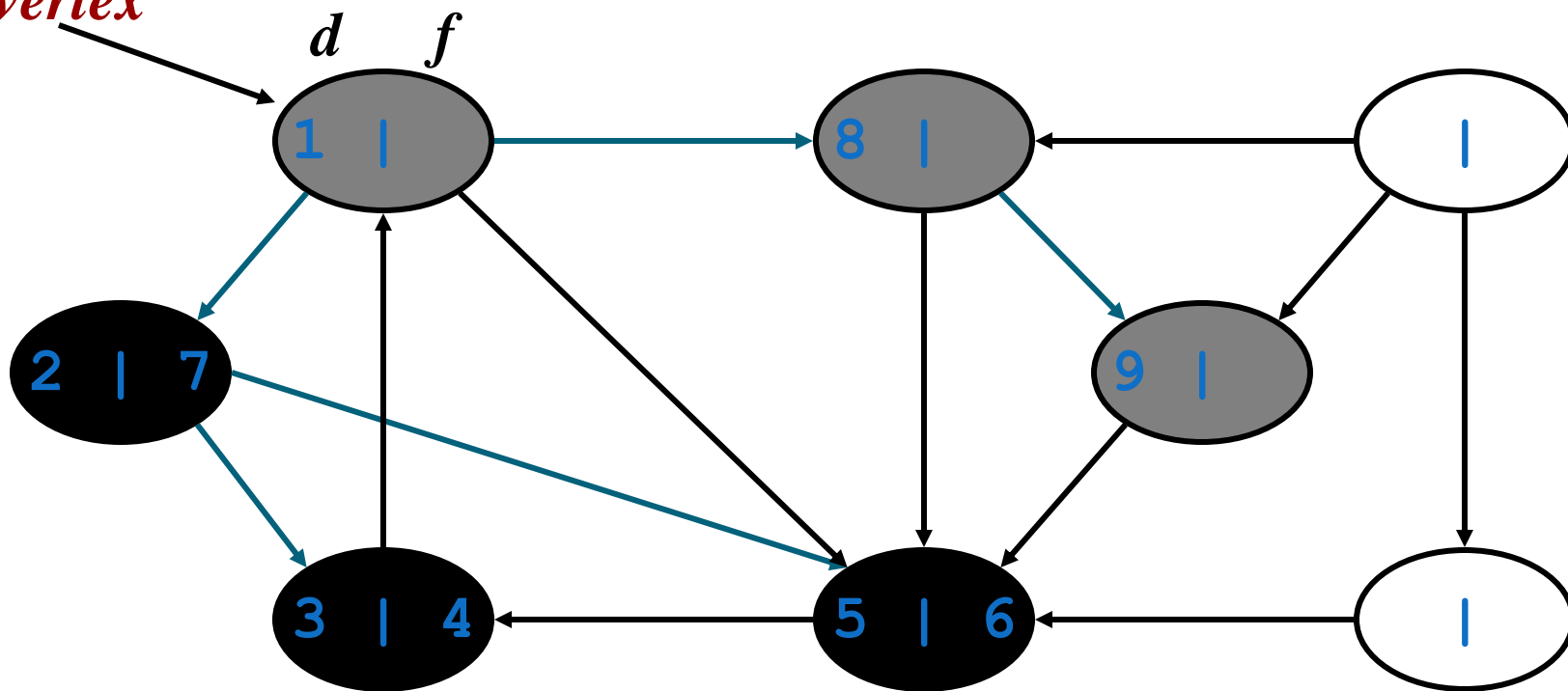
DFS Example

*source
vertex*



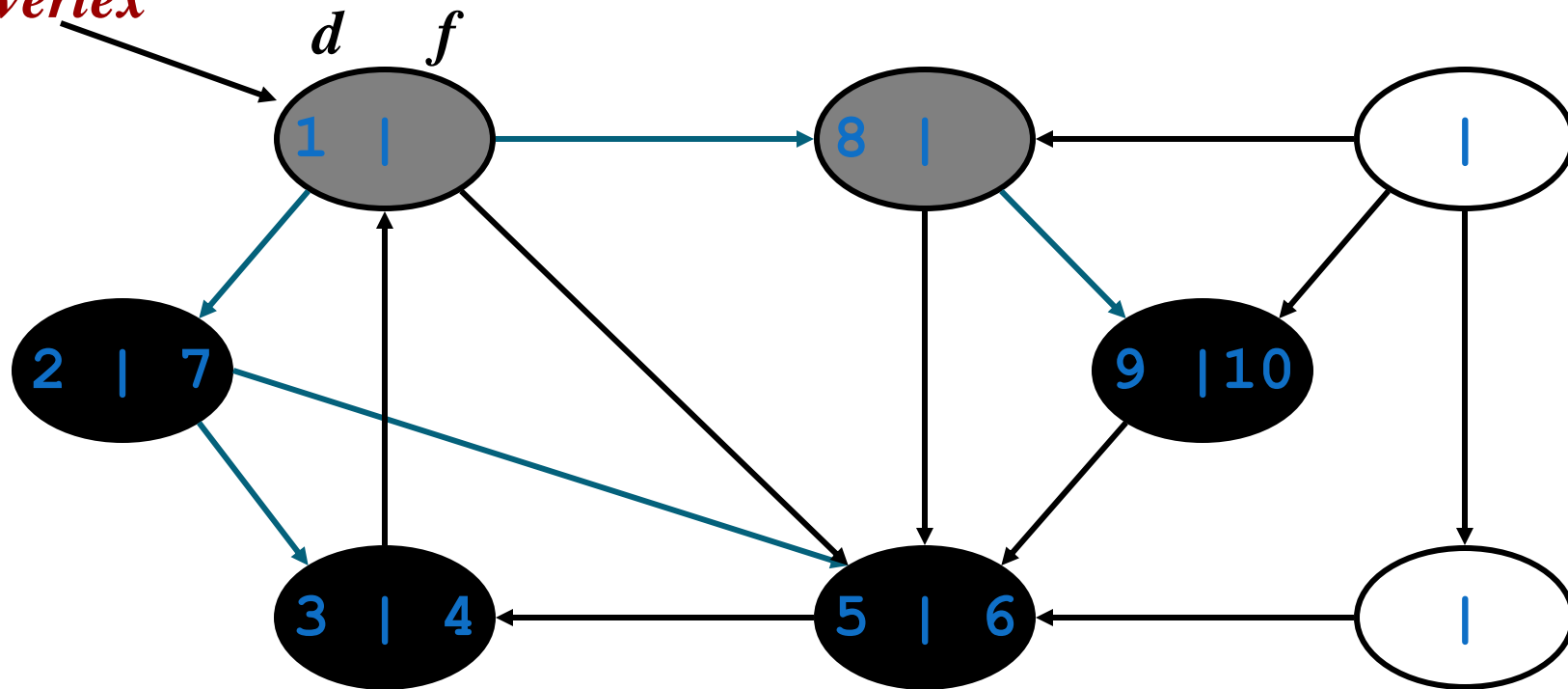
DFS Example

*source
vertex*



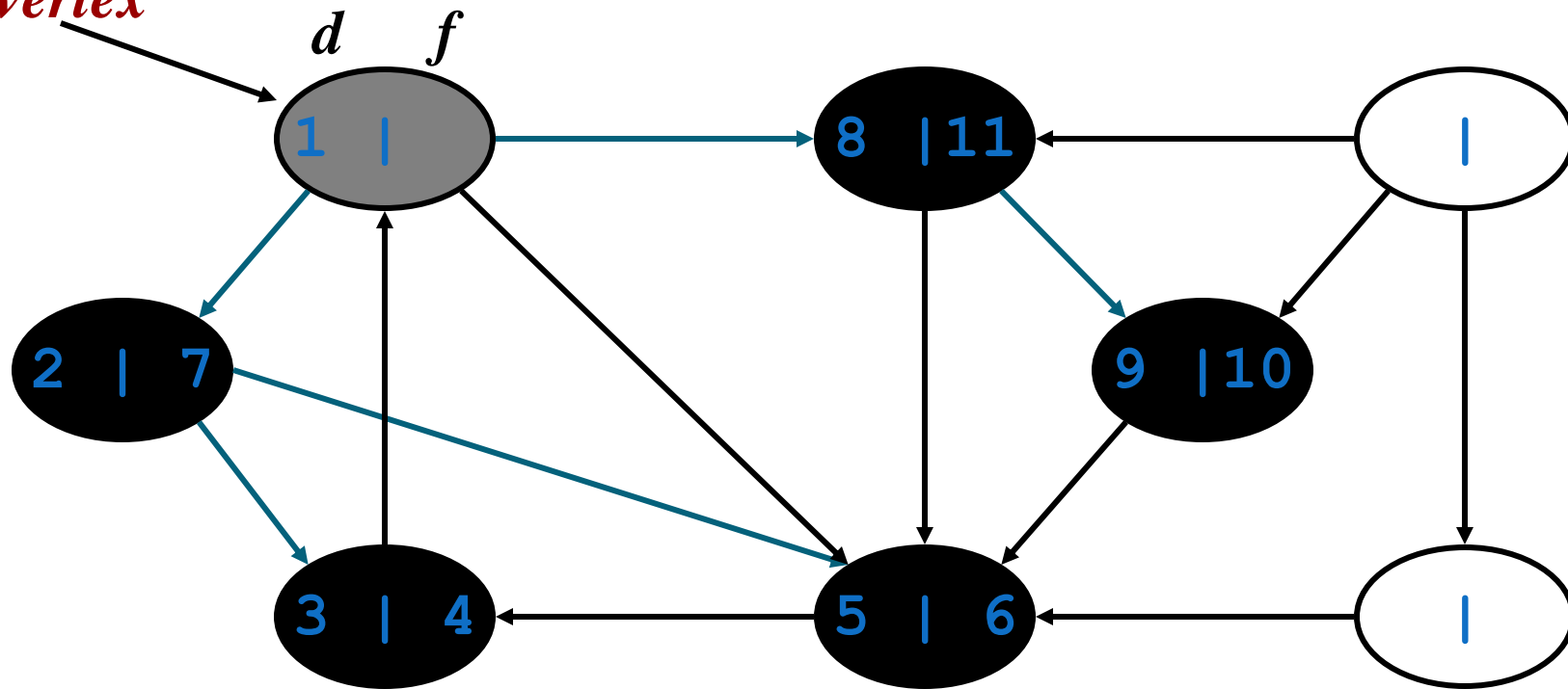
DFS Example

*source
vertex*



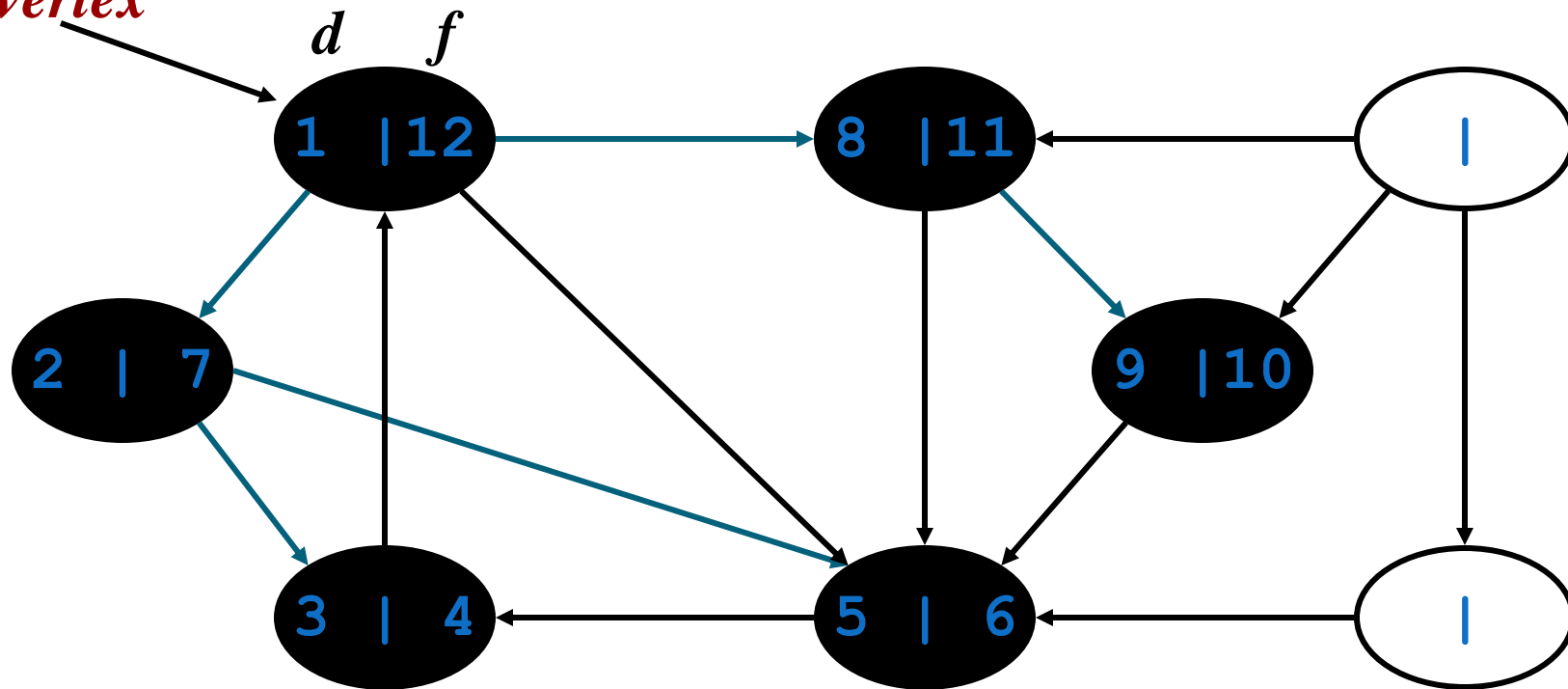
DFS Example

*source
vertex*



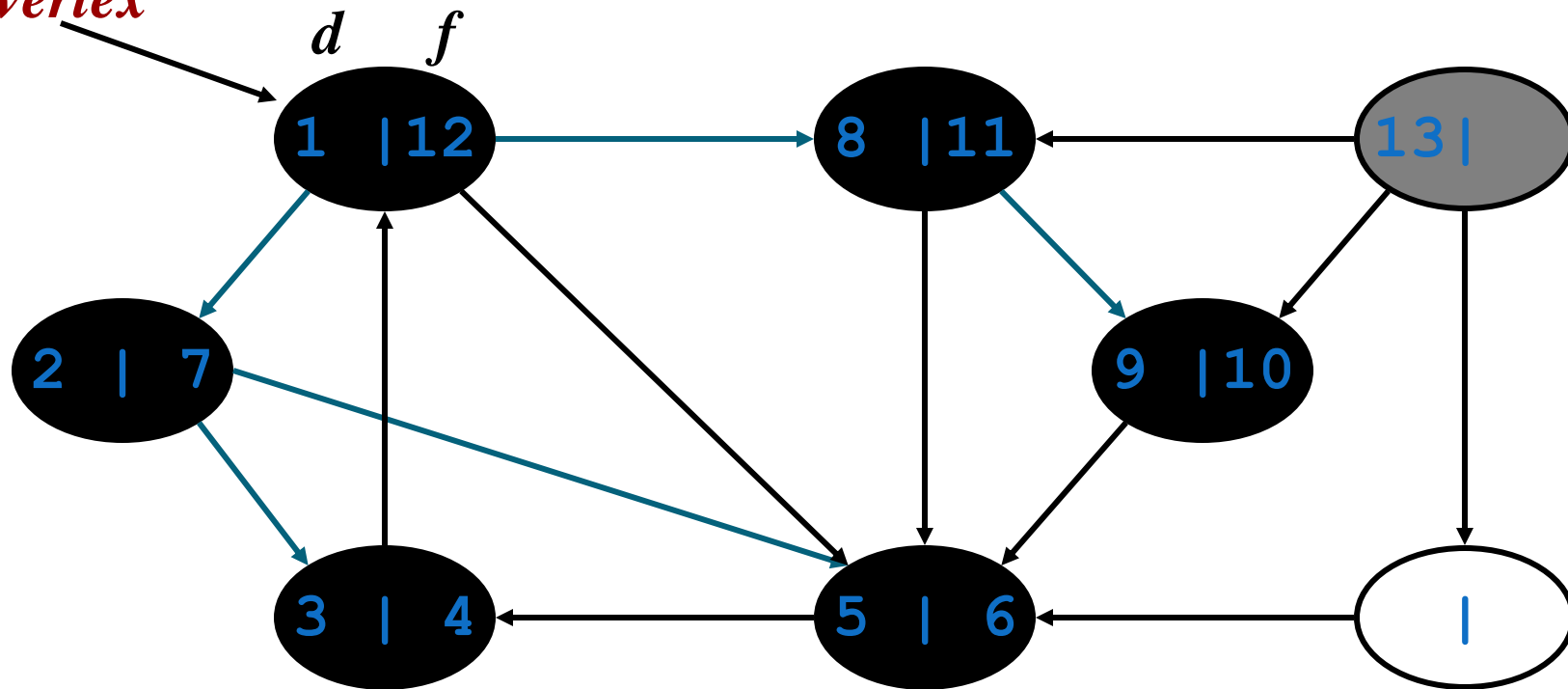
DFS Example

*source
vertex*



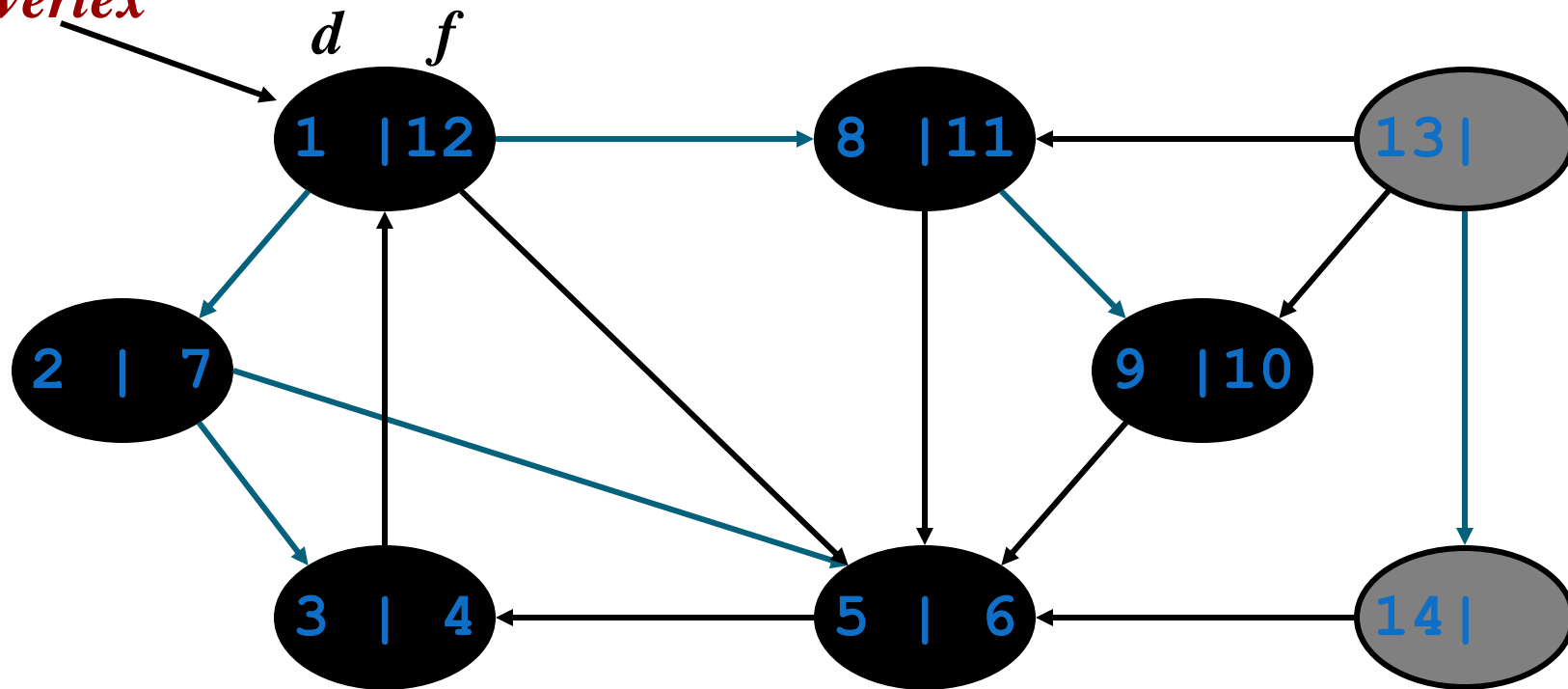
DFS Example

*source
vertex*



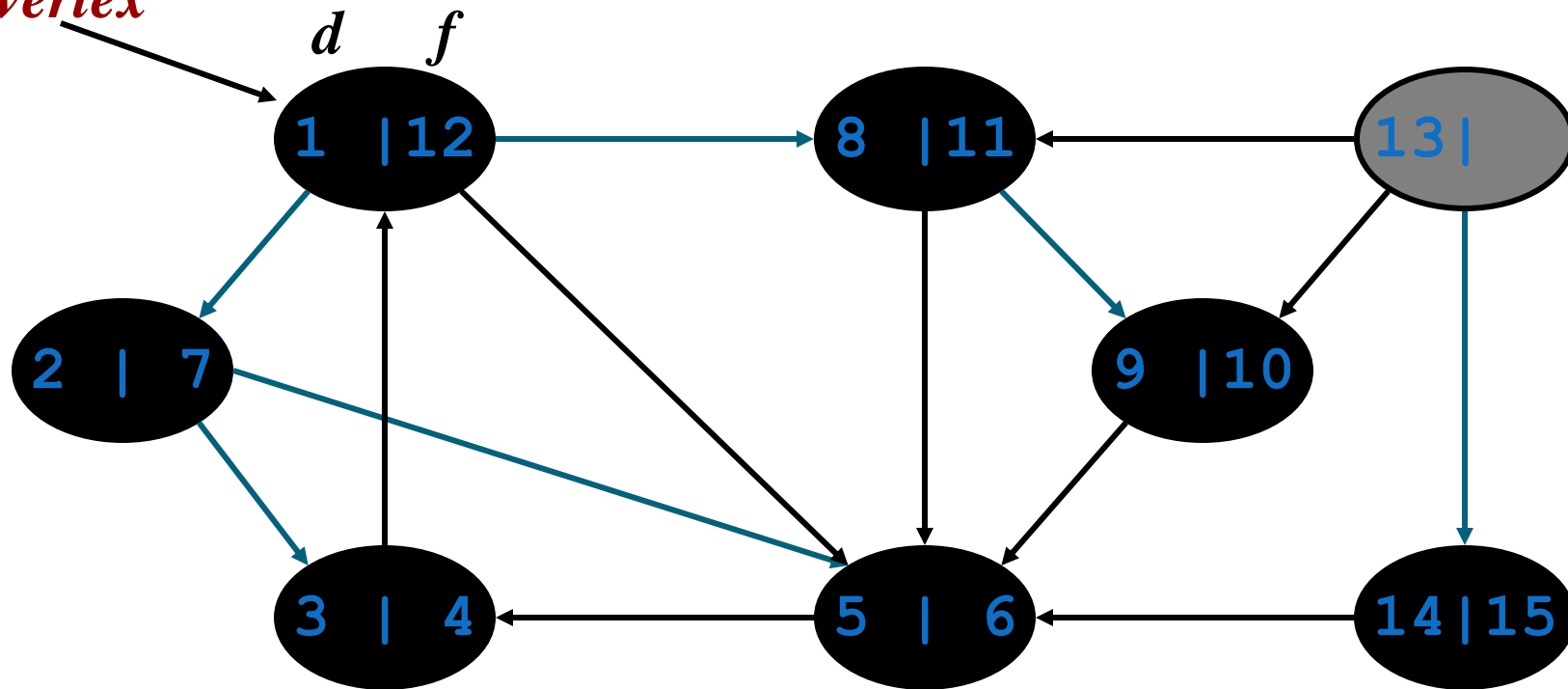
DFS Example

*source
vertex*



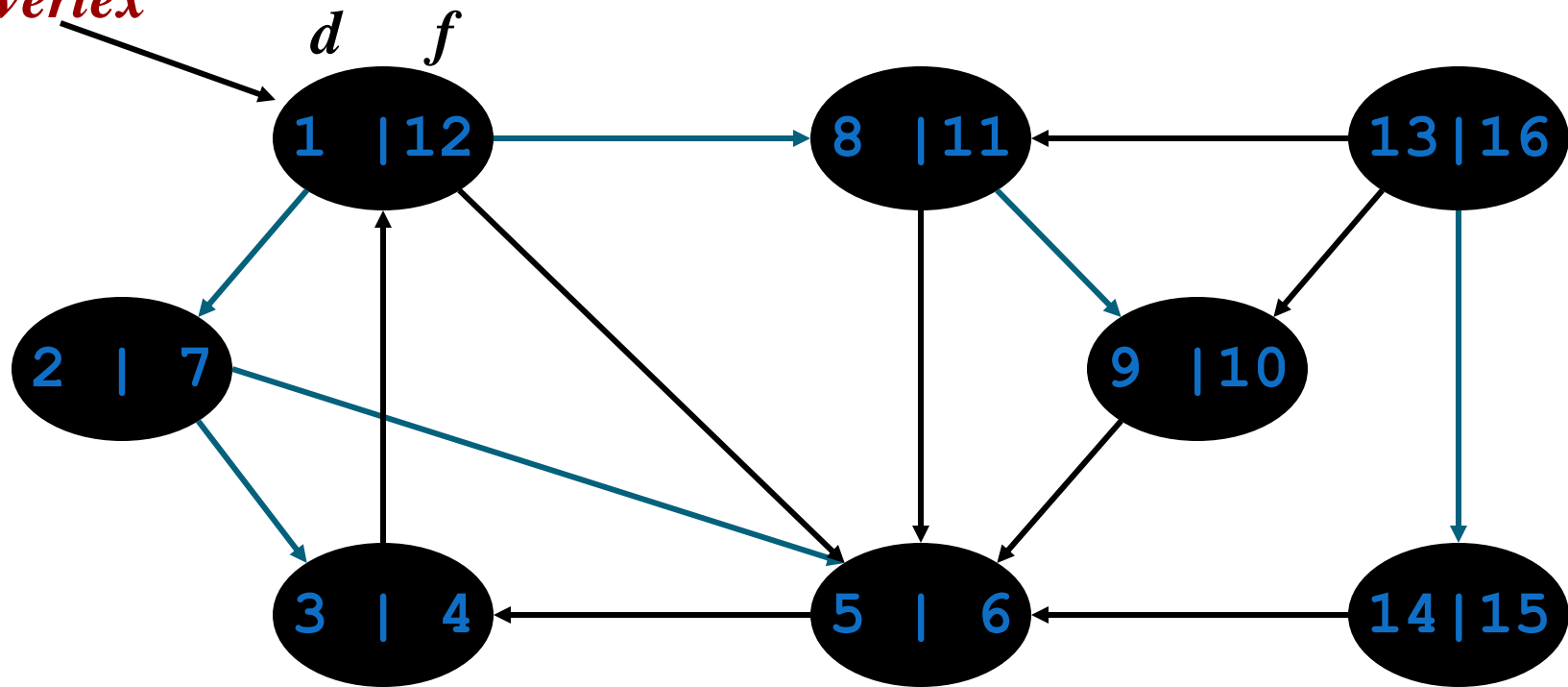
DFS Example

*source
vertex*

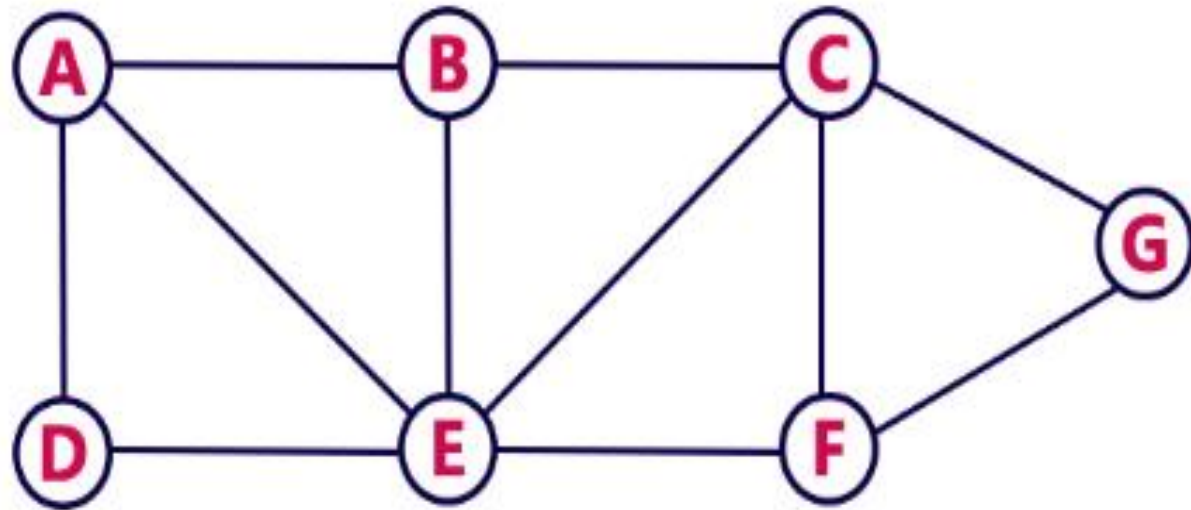


DFS Example

*source
vertex*

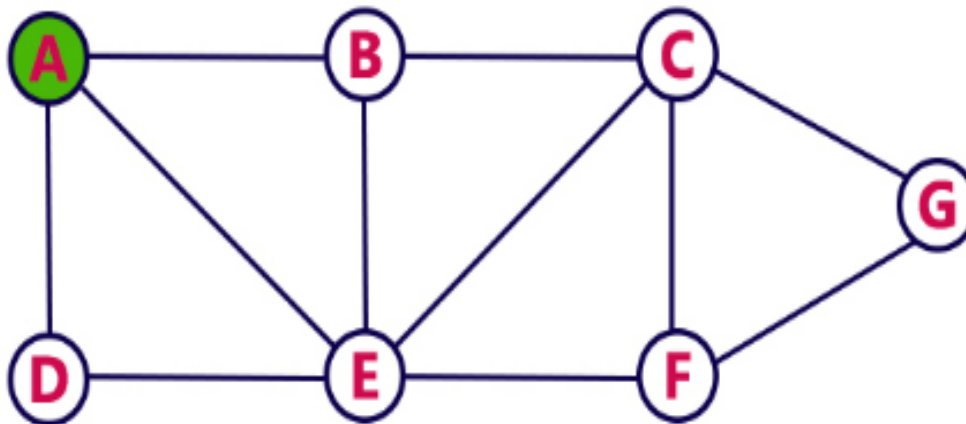


Consider the following example graph to perform DFS traversal



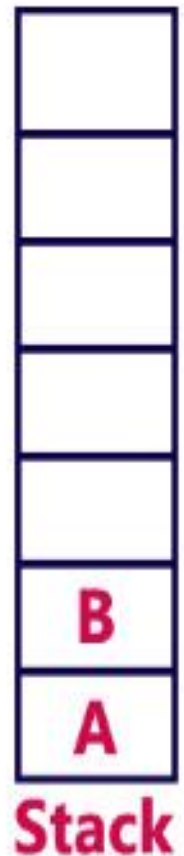
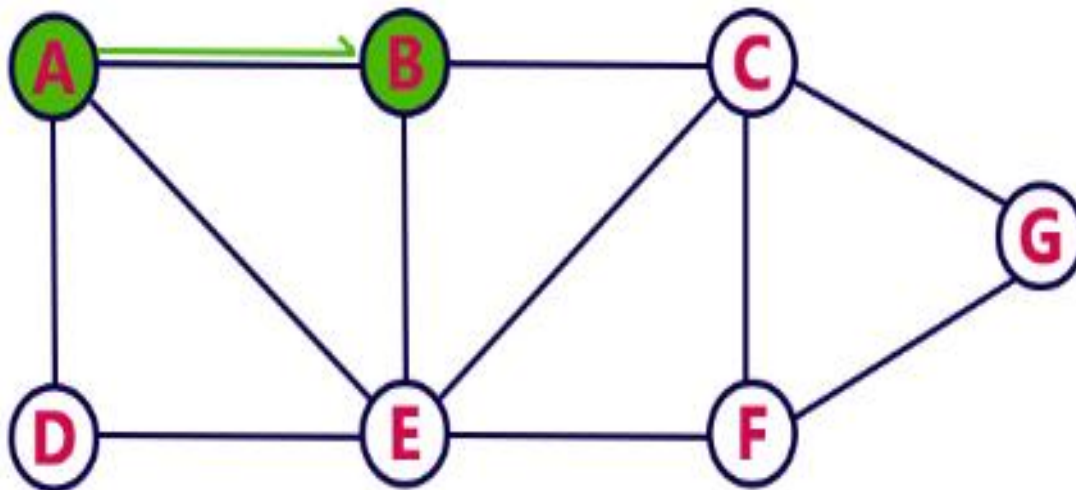
Step 1:

- Select the vertex **A** as starting point (visit **A**).
- Push **A** on to the Stack.



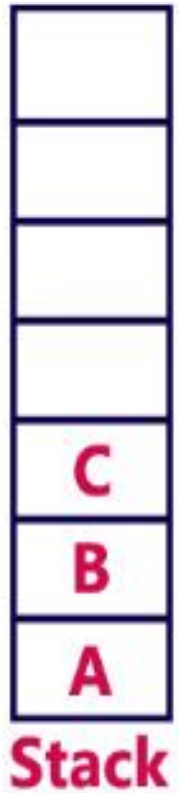
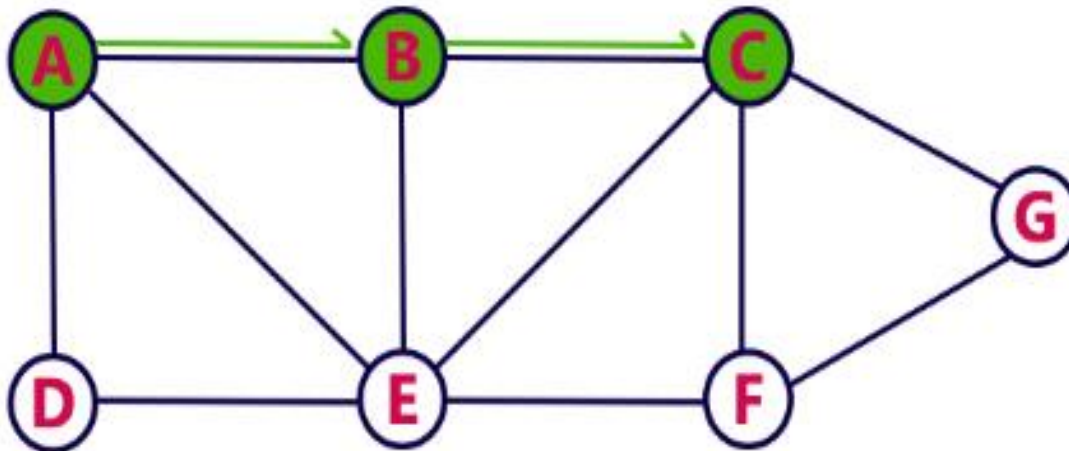
Step 2:

- Visit any adjacent vertex of **A** which is not visited (**B**).
- Push newly visited vertex B on to the Stack.



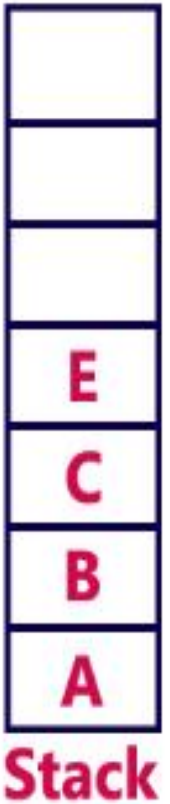
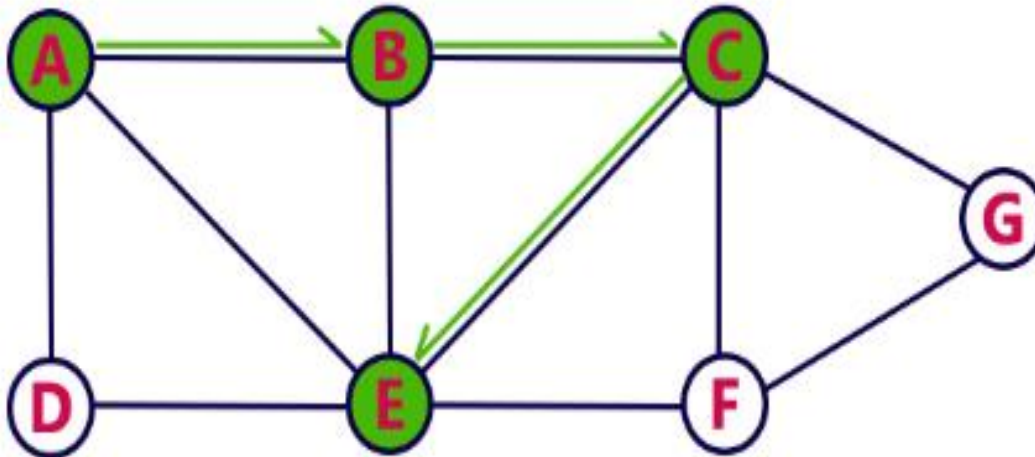
Step 3:

- Visit any adjacent vertex of **B** which is not visited (**C**).
- Push C on to the Stack.



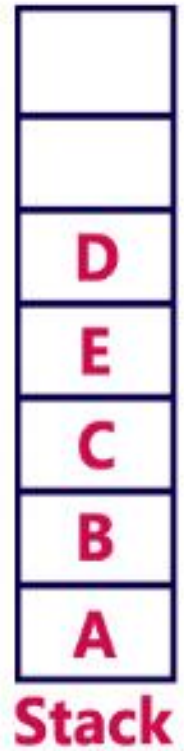
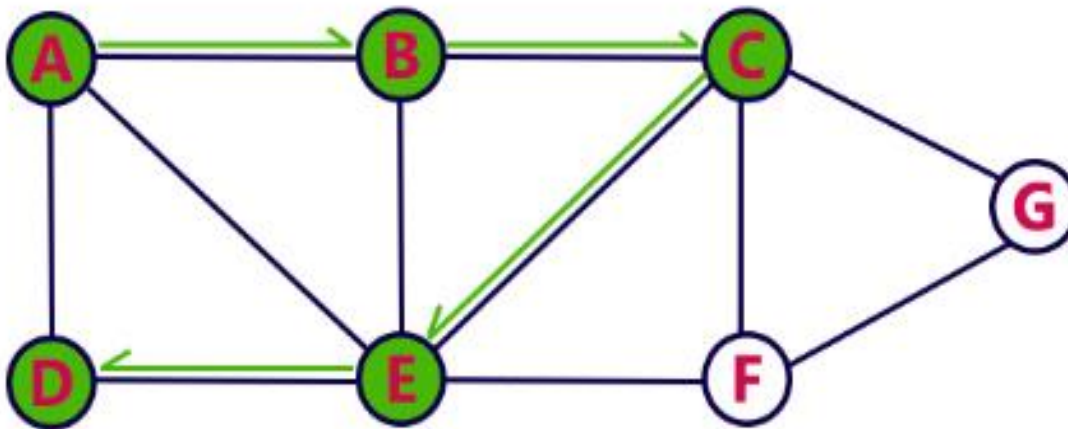
Step 4:

- Visit any adjacent vertex of **C** which is not visited (**E**).
- Push E on to the Stack



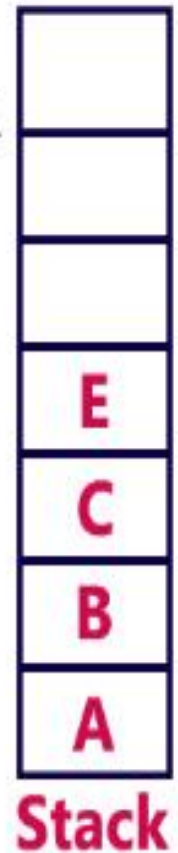
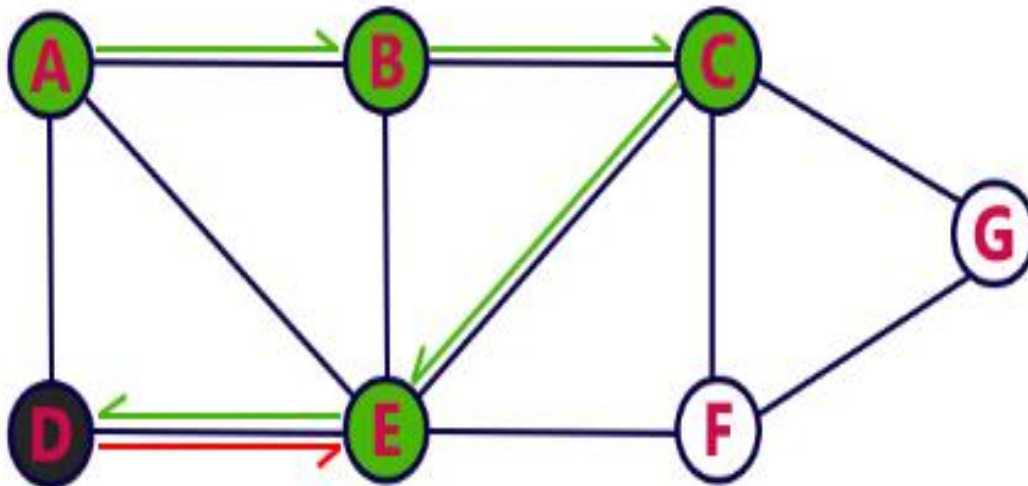
Step 5:

- Visit any adjacent vertex of **E** which is not visited (**D**).
- Push D on to the Stack



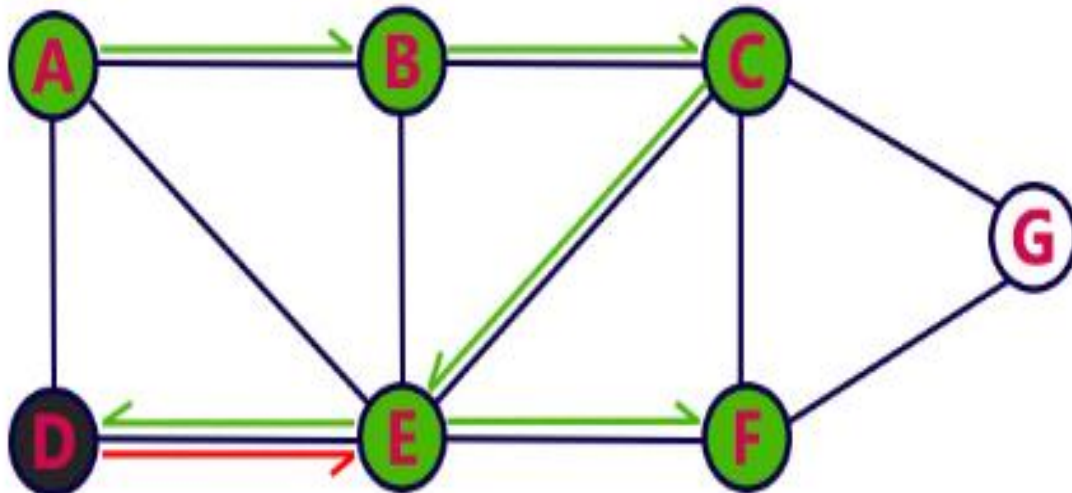
Step 6:

- There is no new vertex to be visited from D. So use back track.
- Pop D from the Stack.



Step 7:

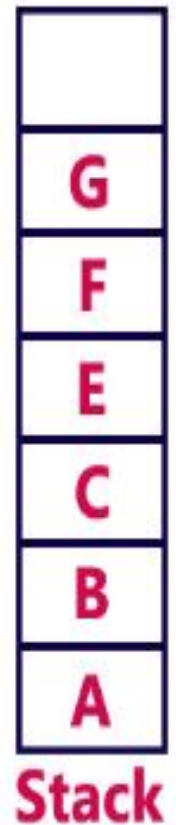
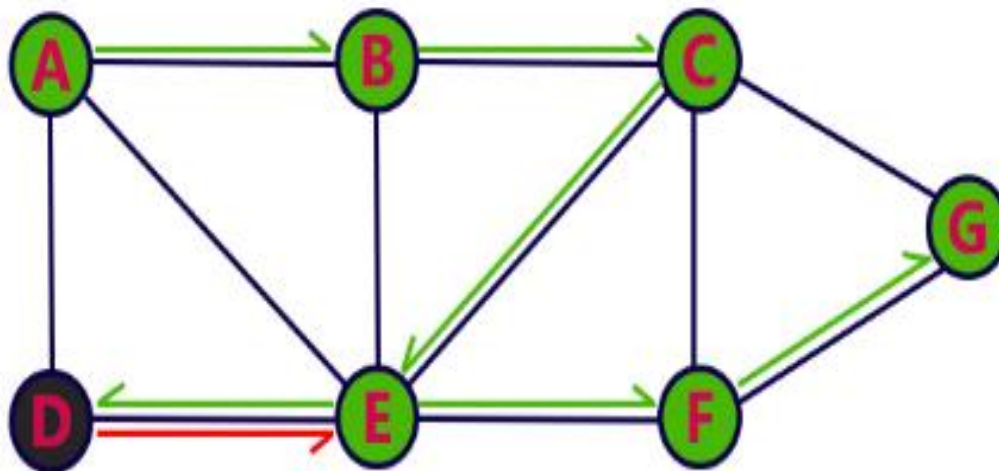
- Visit any adjacent vertex of **E** which is not visited (**F**).
- Push **F** on to the Stack.



Stack

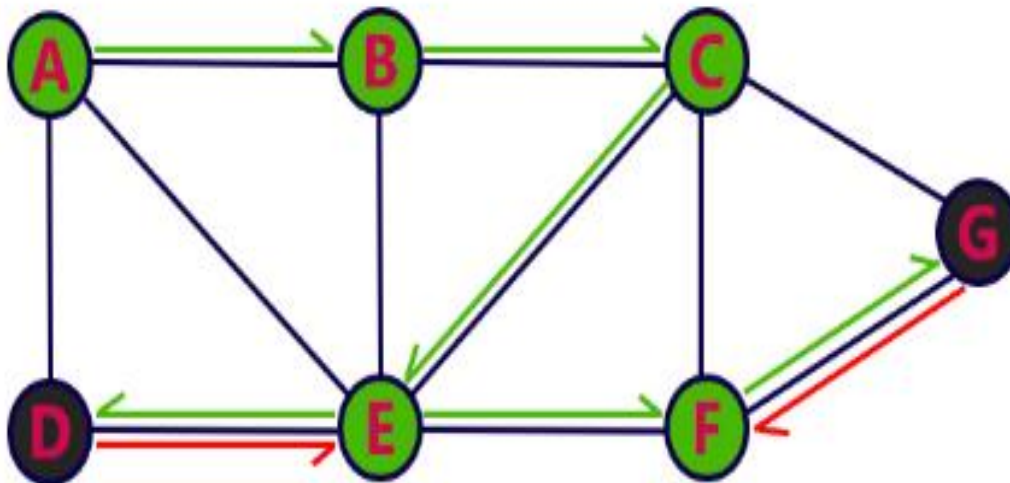
Step 8:

- Visit any adjacent vertex of **F** which is not visited (**G**).
- Push **G** on to the Stack.



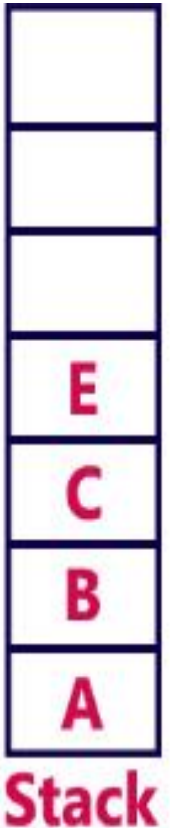
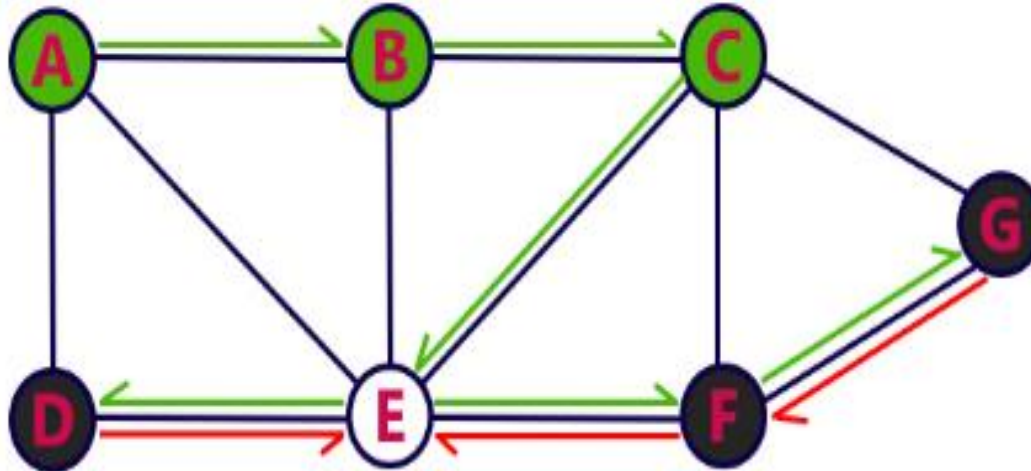
Step 9:

- There is no new vertex to be visited from G. So use back track.
- Pop G from the Stack.



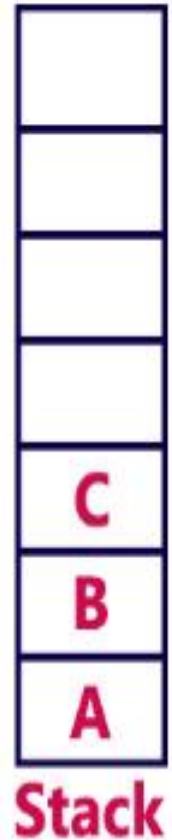
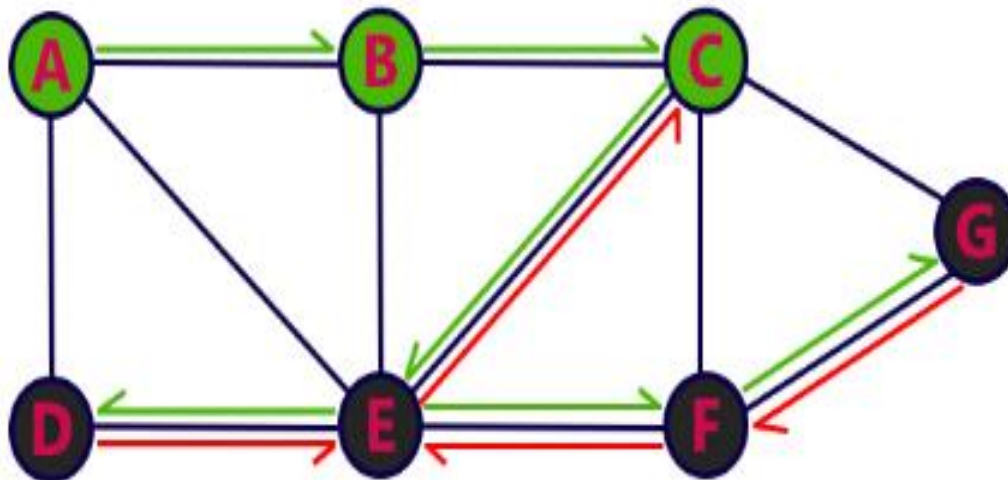
Step 10:

- There is no new vertex to be visited from F. So use back track.
- Pop F from the Stack.



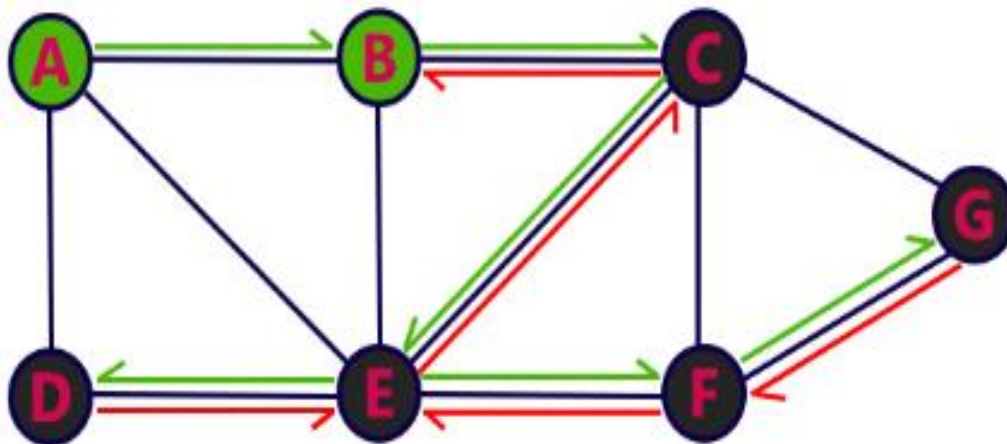
Step 11:

- There is no new vertex to be visited from E. So use back track.
- Pop E from the Stack.



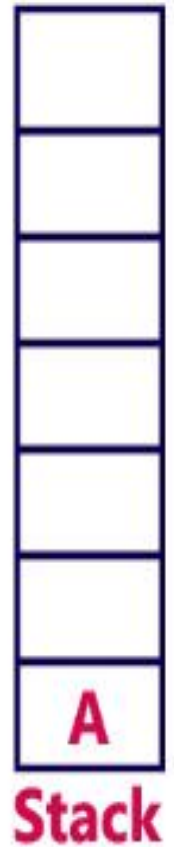
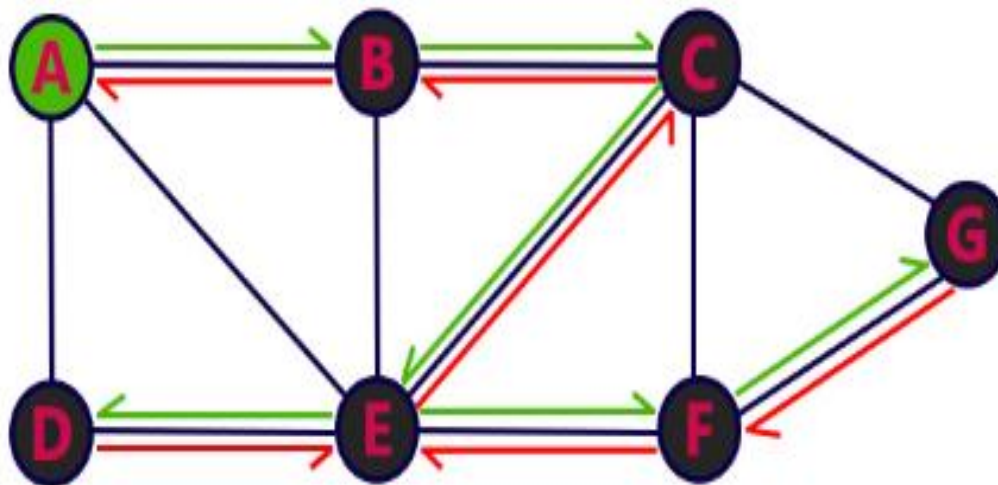
Step 12:

- There is no new vertex to be visited from C. So use back track.
- Pop C from the Stack.



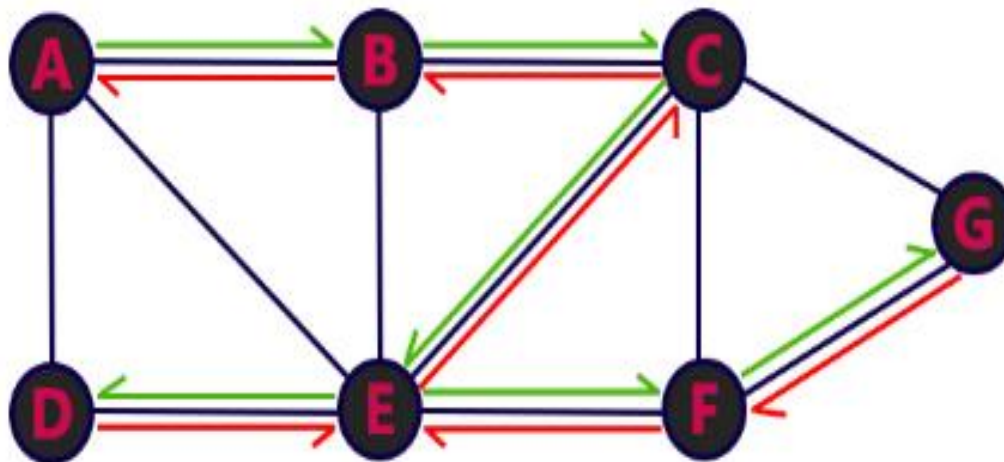
Step 13:

- There is no new vertex to be visited from B. So use back track.
- Pop B from the Stack.



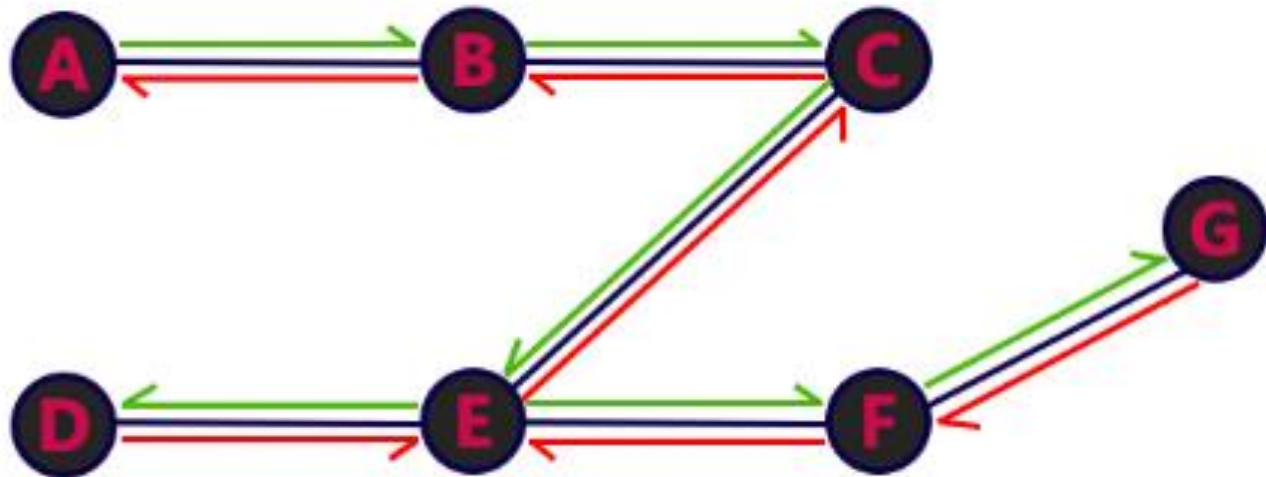
Step 14:

- There is no new vertex to be visited from A. So use back track.
- Pop A from the Stack.



Stack

- Stack became Empty. So stop DFS Traversal.
- Final result of DFS traversal is following spanning tree.



DFS: Algorithm

DFS(G)

for each vertex u in V ,

$\text{color}[u] = \text{white}$; $p[u] = \text{NIL}$

time=0;

for each vertex u in V

 if ($\text{color}[u] = \text{white}$)

 DFS-VISIT(u)

DFS: Algorithm (Cont.)

DFS-VISIT(u)

color[u]=gray;

time = time + 1;

d[u] = time;

for each v in Adj(u) do

if (color[v] = white)

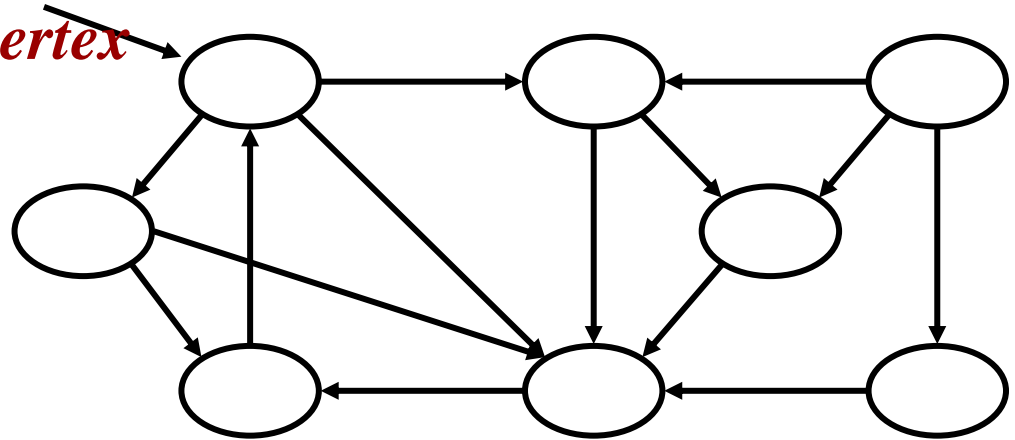
p[v] = u;

DFS-VISIT(v);

color[u] = black;

time = time + 1; f[u]= time;

*source
vertex*



DFS: Complexity Analysis

Initialization complexity is $O(V)$

DFS_VISIT is called exactly once for each vertex $O(V)$

And DFS_VISIT scans all the edges $\sum |Adj(u)| \rightarrow O(E)$

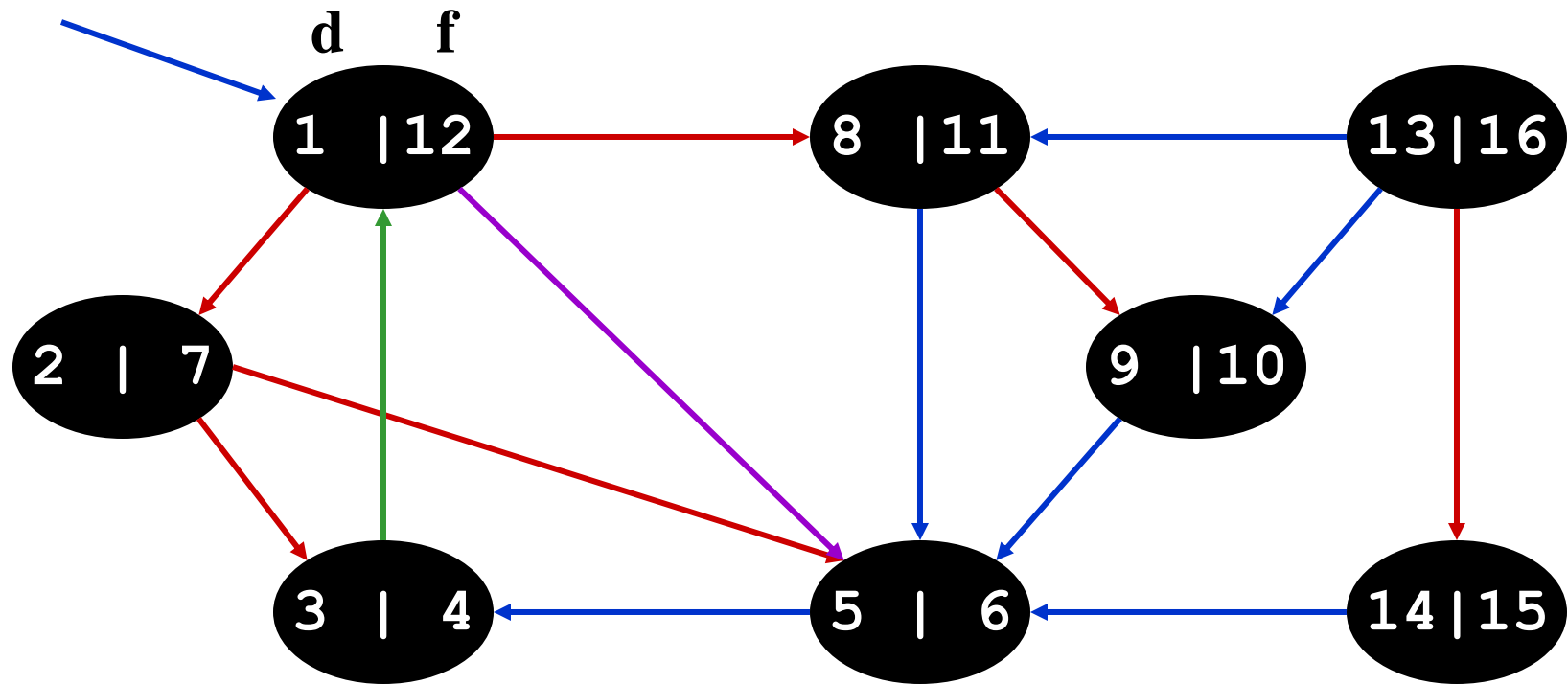
Overall complexity is $O(V + E)$

DFS: Kinds of edges

- DFS introduces an important distinction among edges in the original graph:
 - *Tree edge*: encounter new (white) vertex
 - *Back edge*: from descendent to ancestor
 - *Forward edge*: from ancestor to descendent
 - *Cross edge*: between a tree or subtrees
- Note: tree & back edges are important; most algorithms don't distinguish forward & cross

DFS Example

source
vertex

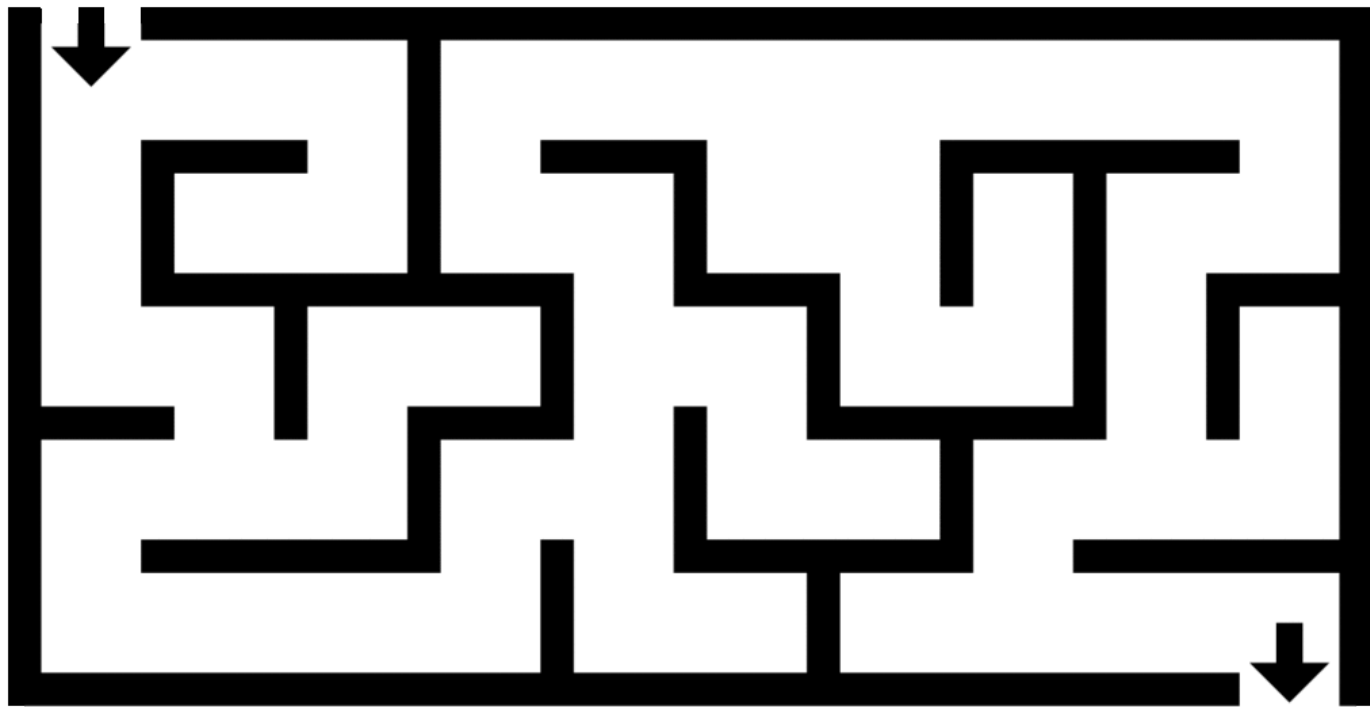


Tree edges **Back edges** **Forward edges** **Cross edges**

DFS: Application

- Topological Sort
- Simulation of games
- Scheduling events

Solving Maze Problem using DFS



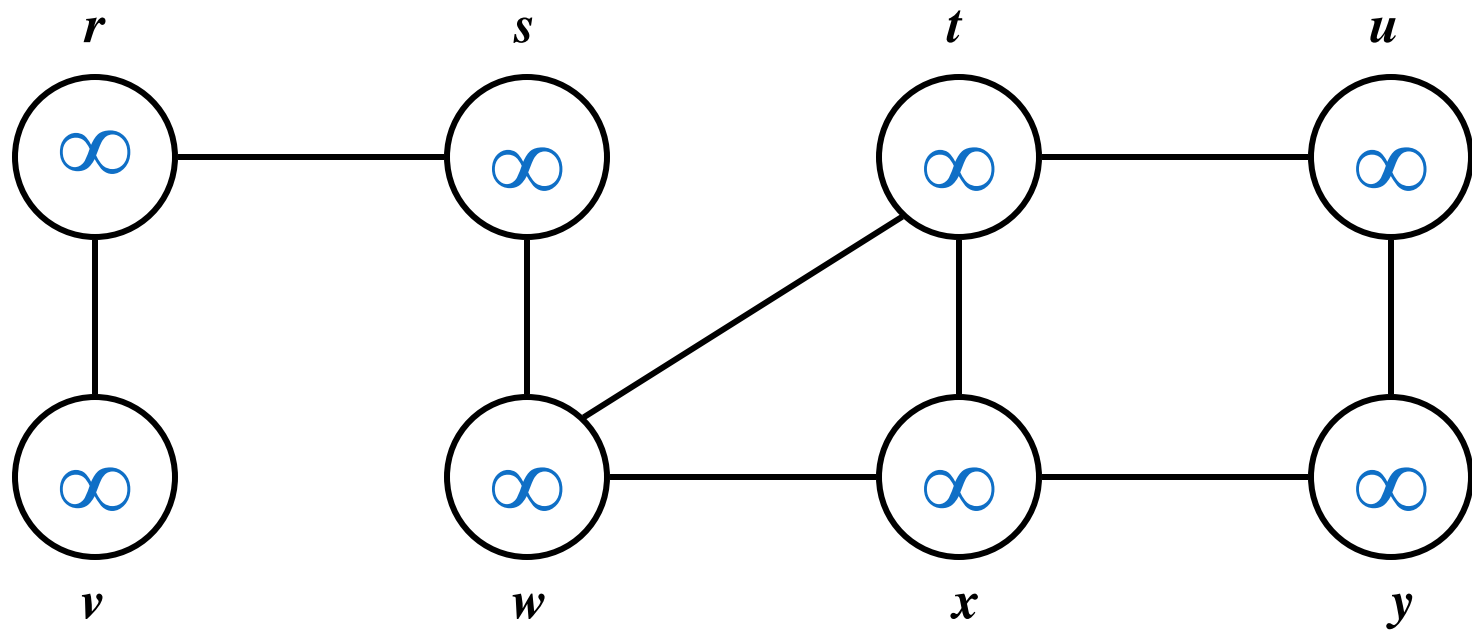
Breadth-first Search (BFS)

- Search for all vertices that are directly reachable from the root (called level 1 vertices)
- After mark all these vertices, visit all vertices that are directly reachable from any level 1 vertices (called level 2 vertices), and so on.
- Level k vertices are directly reachable from a level $k - 1$ vertices

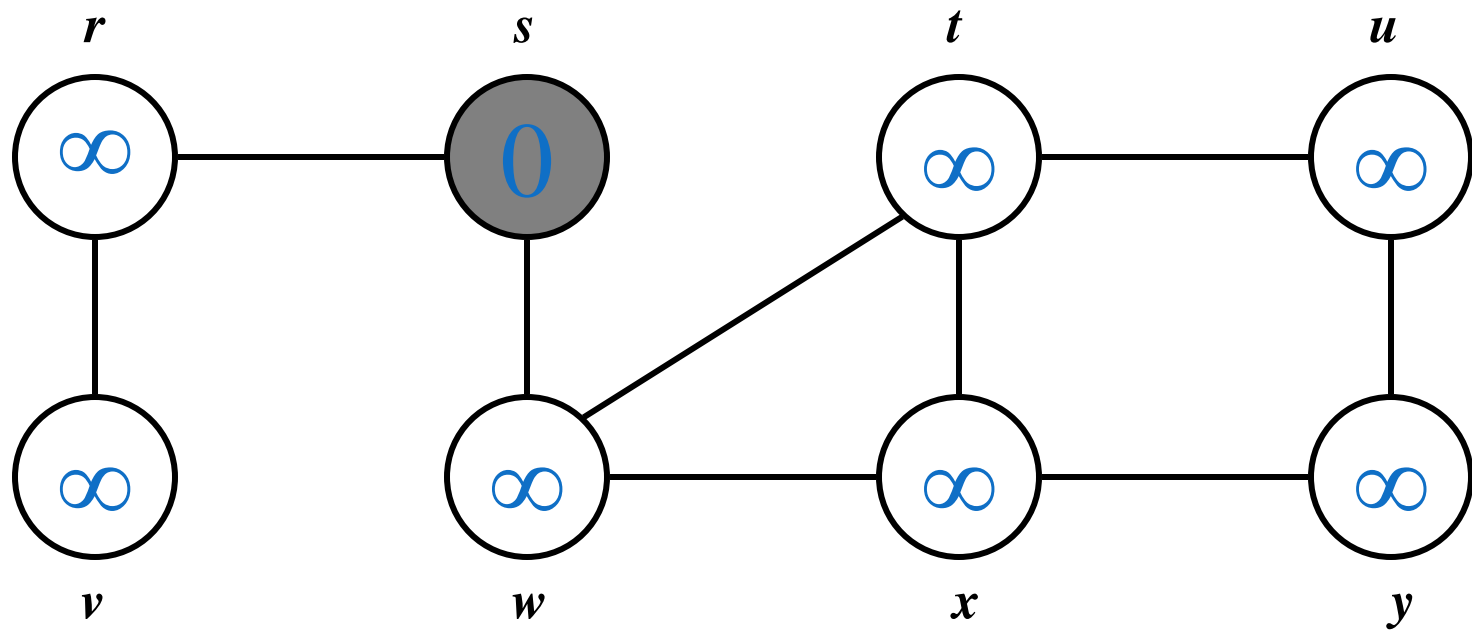
BFS: the Color Scheme

- White vertices have not been discovered
 - All vertices start out white
- Grey vertices are discovered but not fully explored
 - They may be adjacent to white vertices
- Black vertices are discovered and fully explored
 - They are adjacent only to black and gray vertices
- Explore vertices by scanning adjacency list of grey vertices

Example

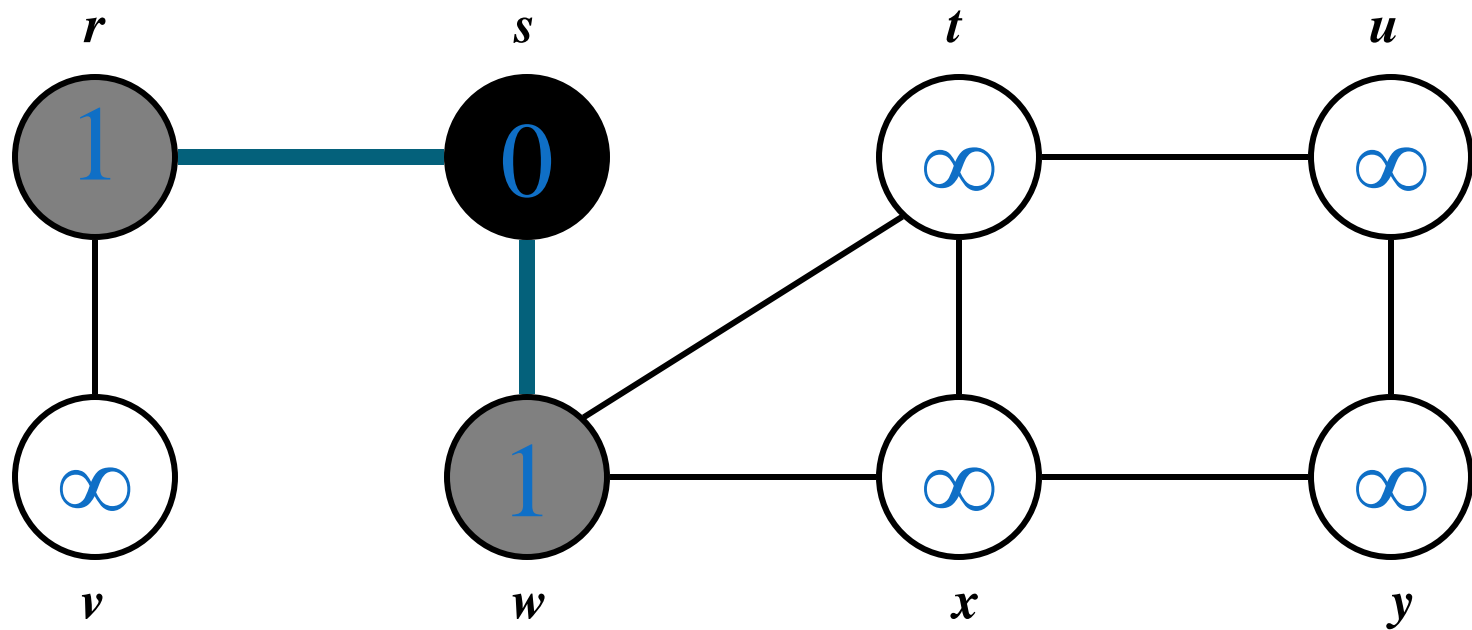


Example



Q : s

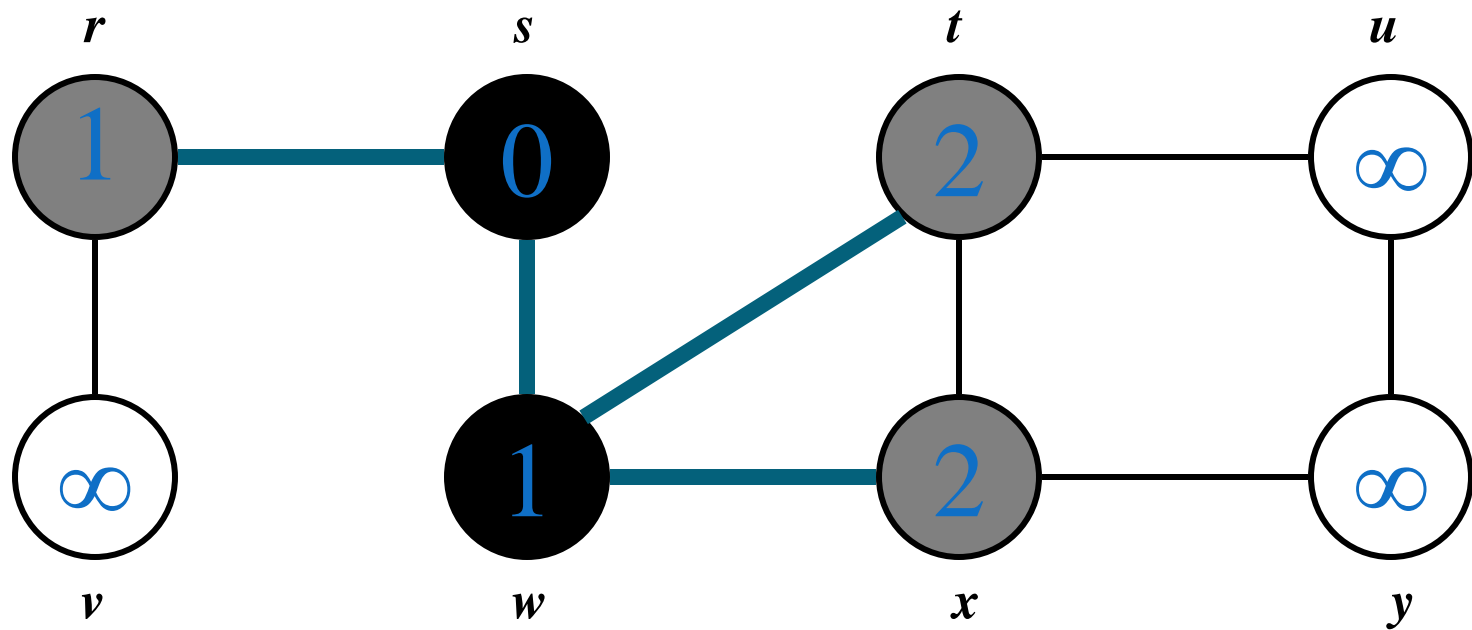
Example



Q :

w	r
-----	-----

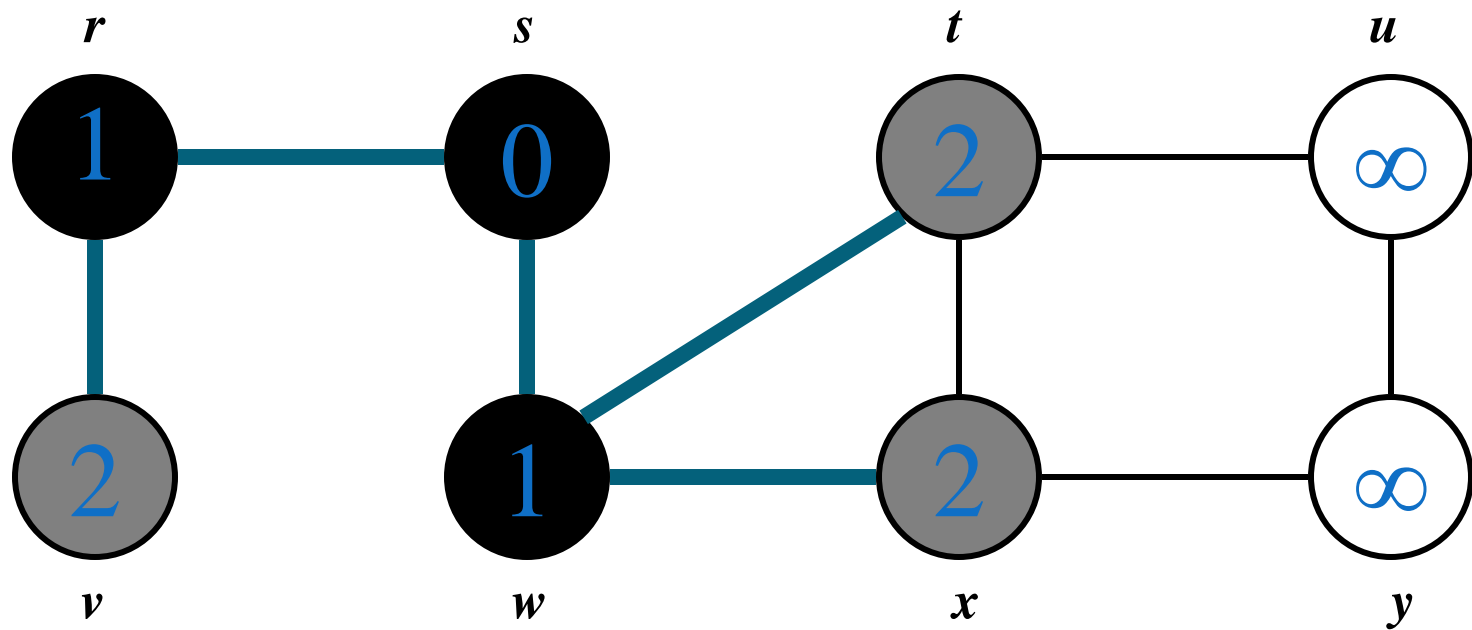
Example



Q :

r	t	x
-----	-----	-----

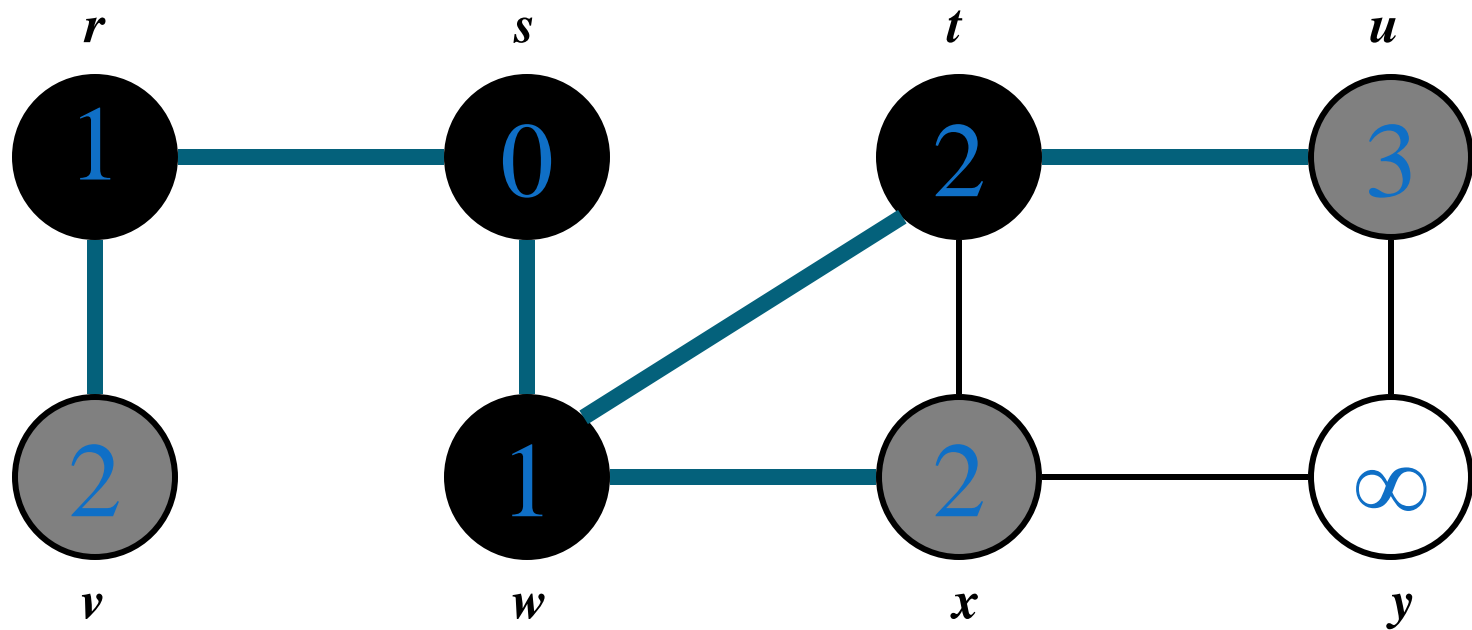
Example



Q :

t	x	v
-----	-----	-----

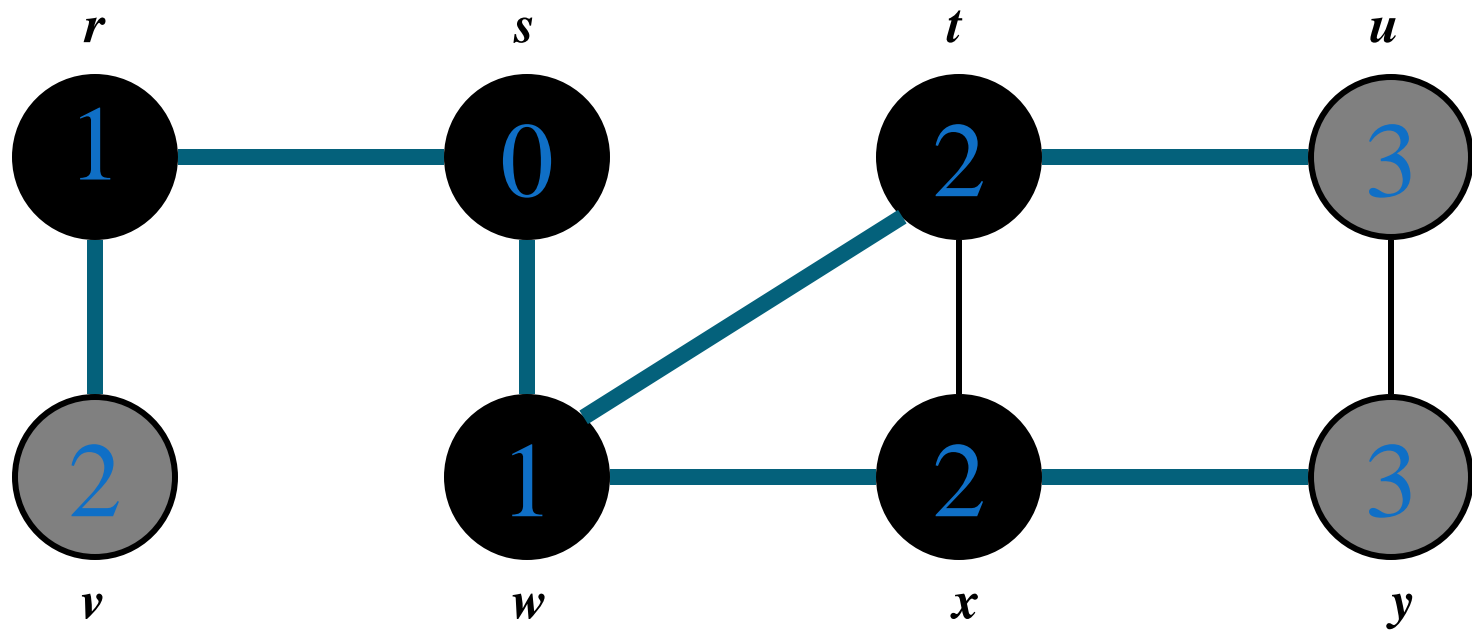
Example



Q :

x	v	u
-----	-----	-----

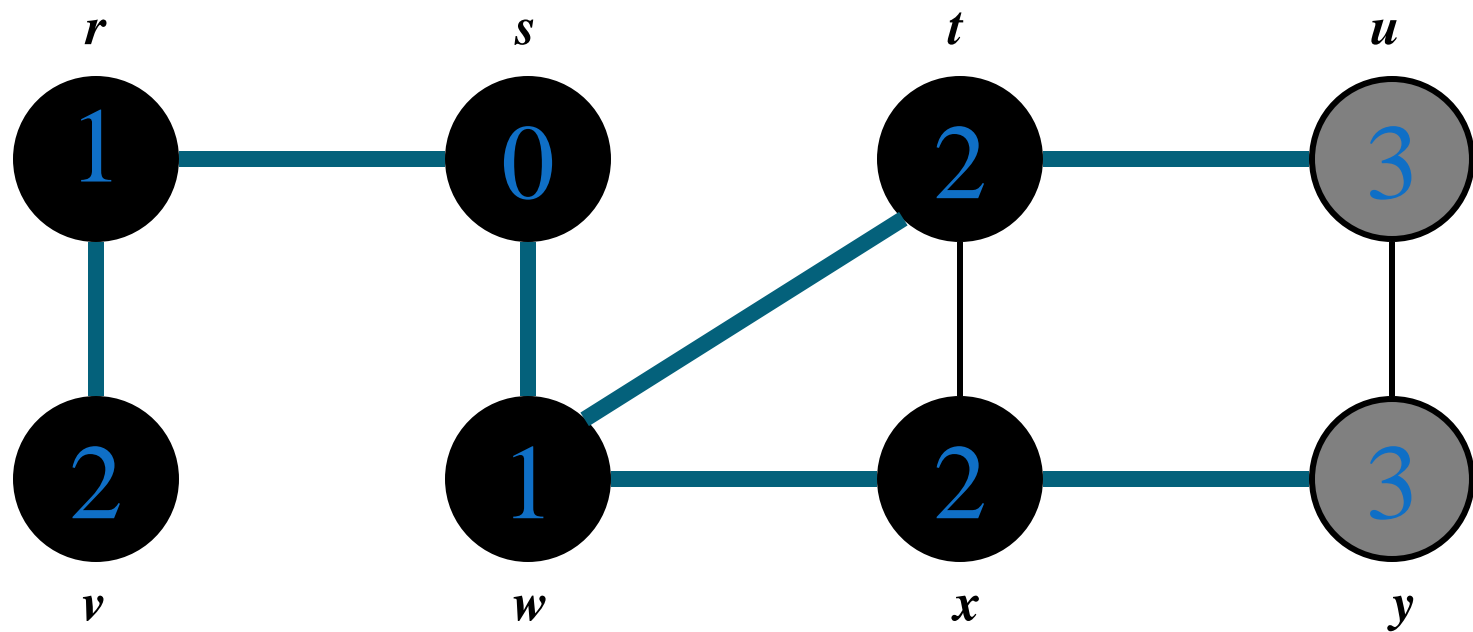
Example



Q :

v	u	y
-----	-----	-----

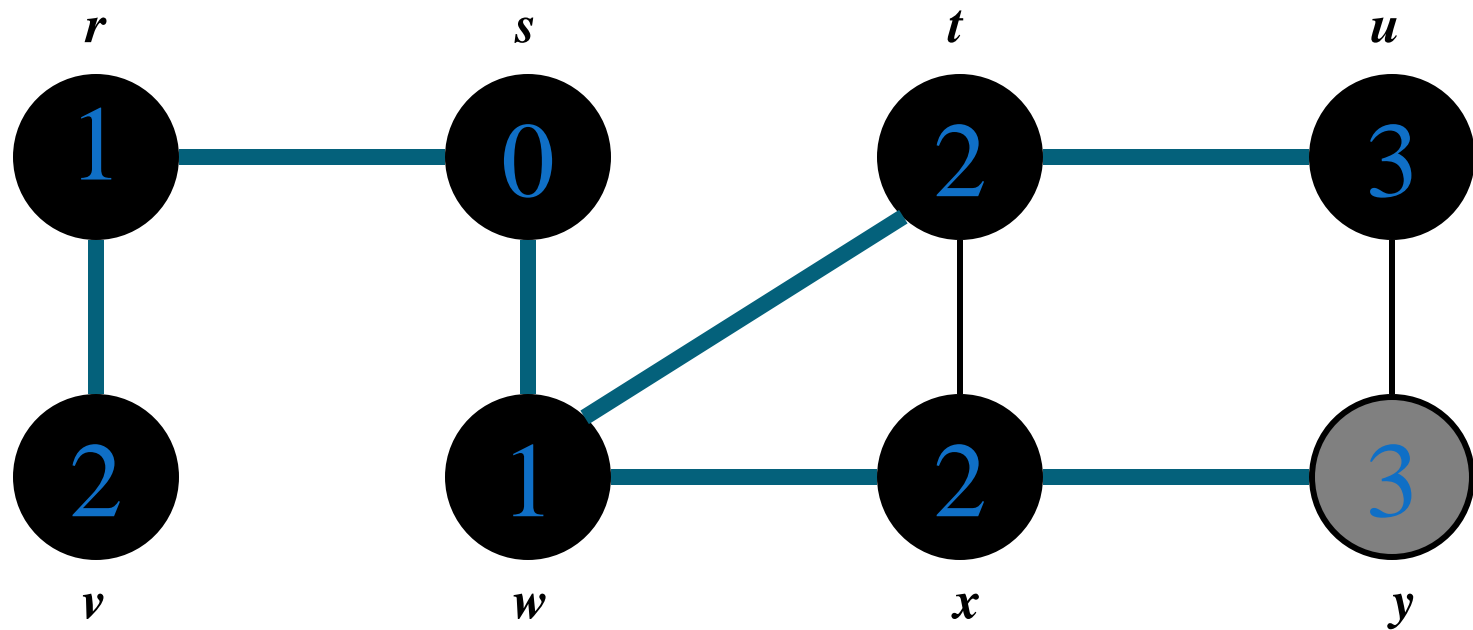
Example



Q :

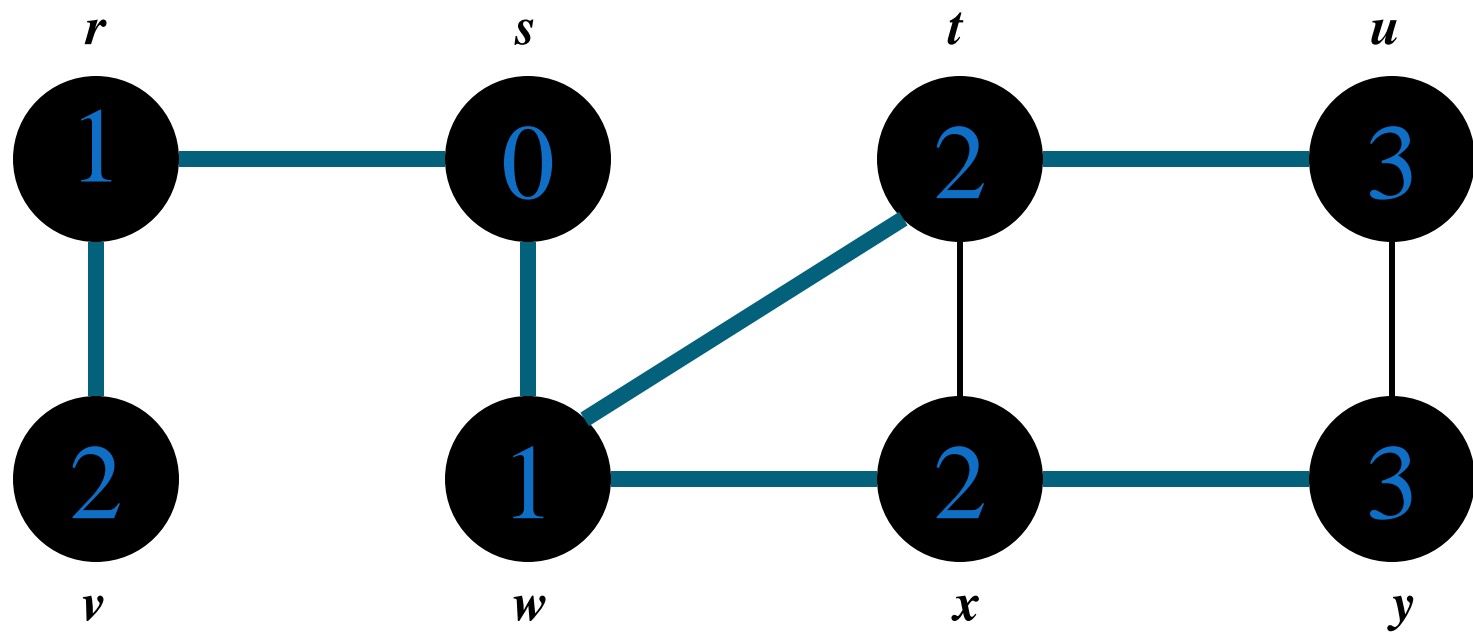
u	y
-----	-----

Example



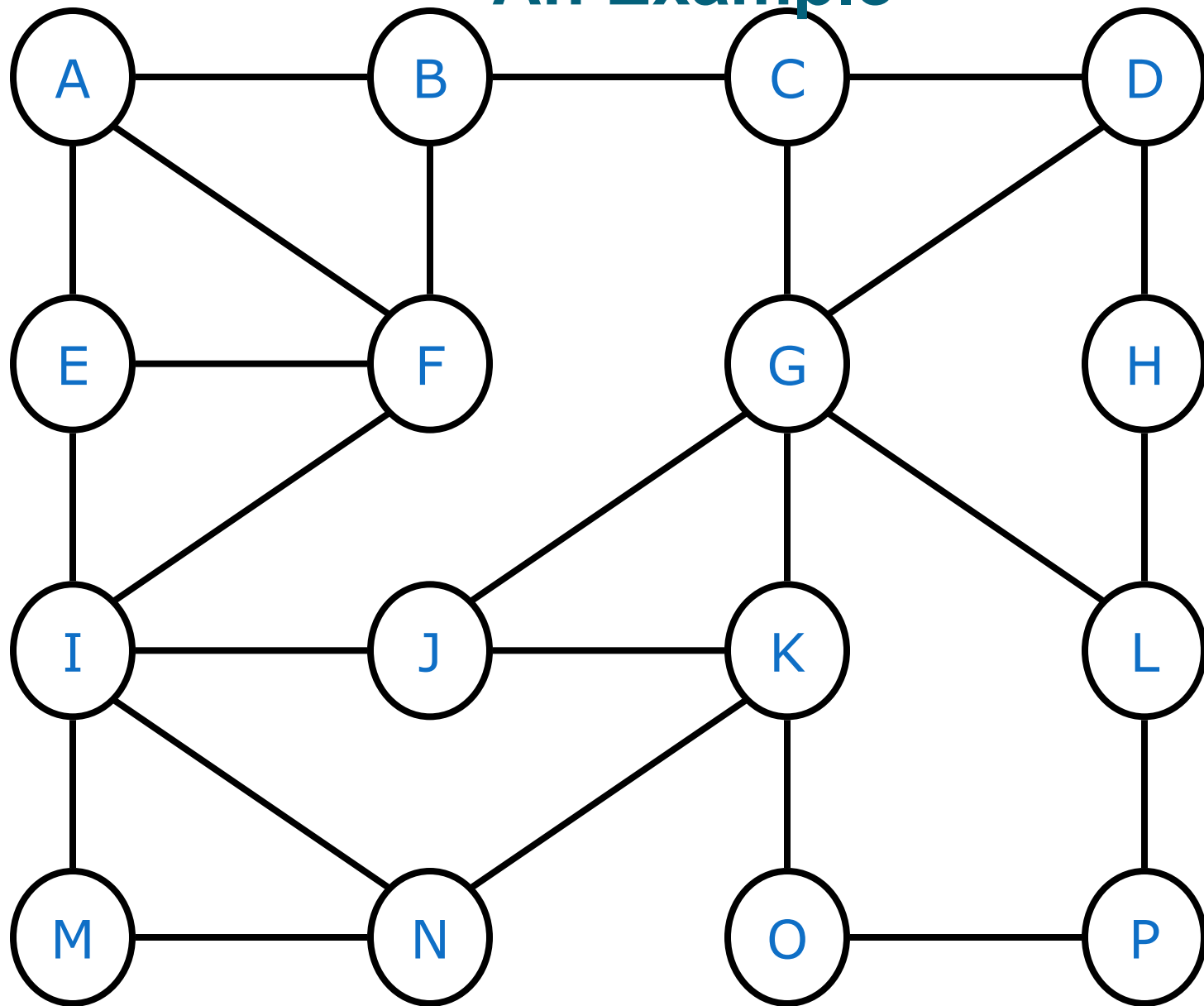
$Q:$ y

Example

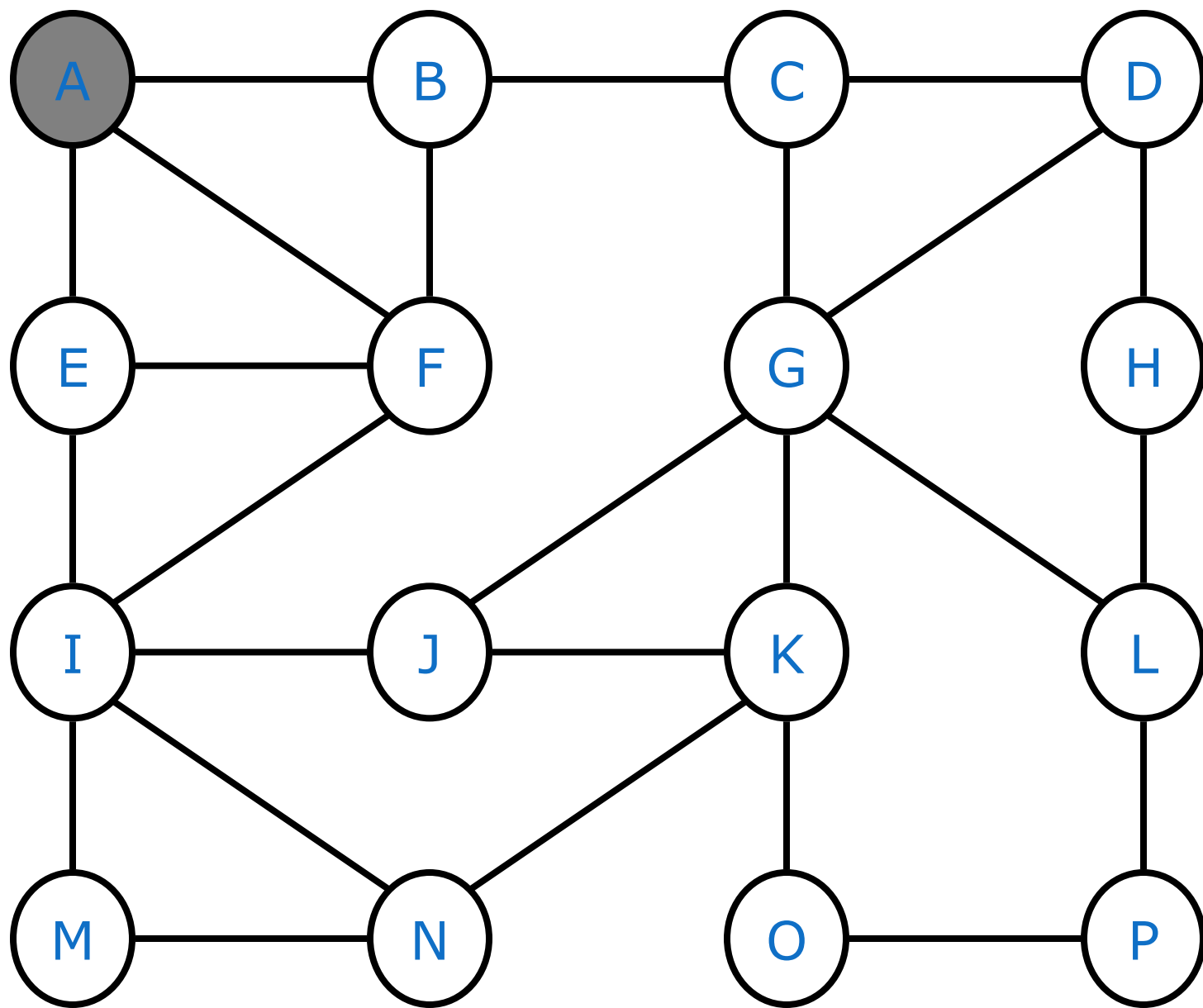


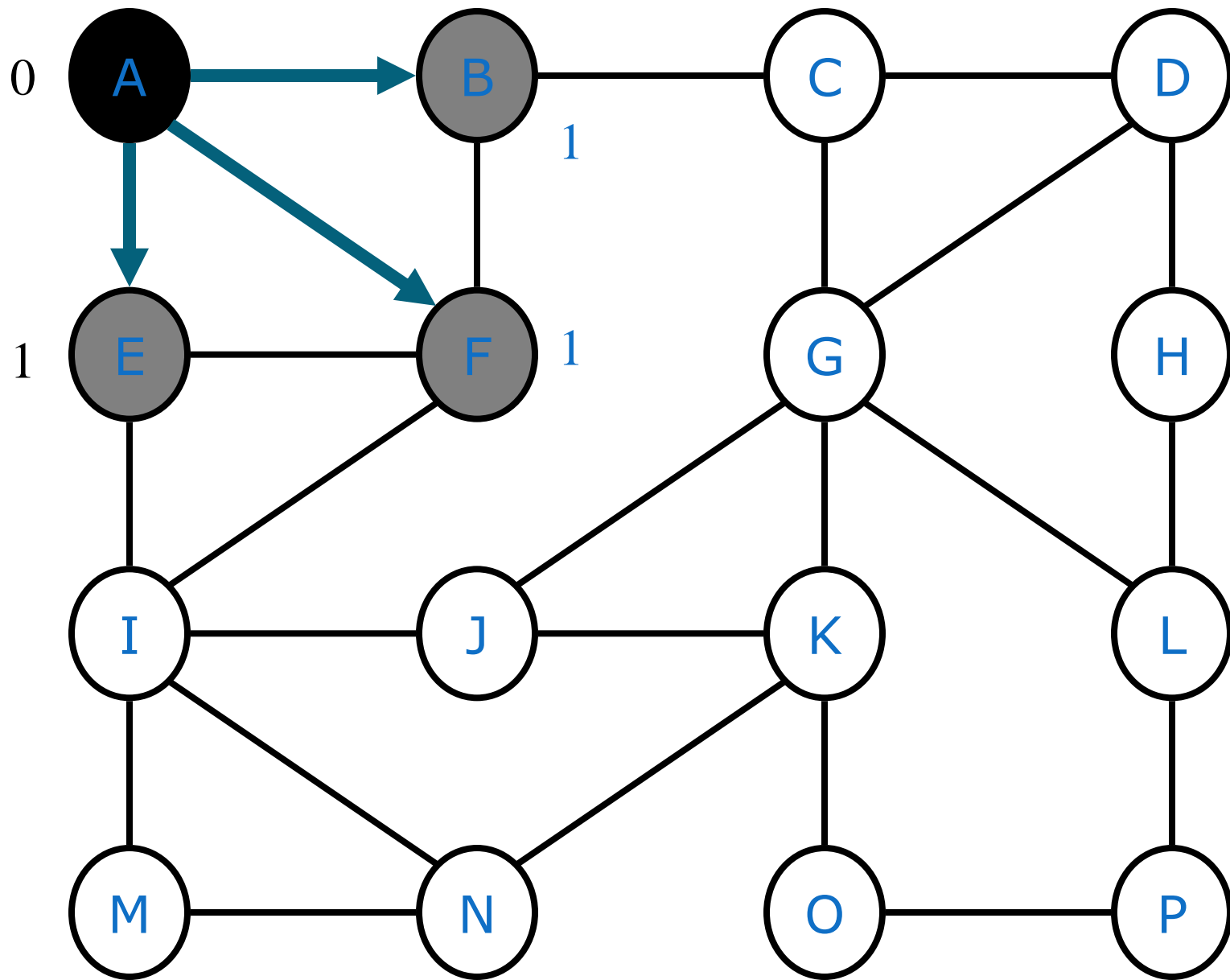
$Q: \emptyset$

An Example

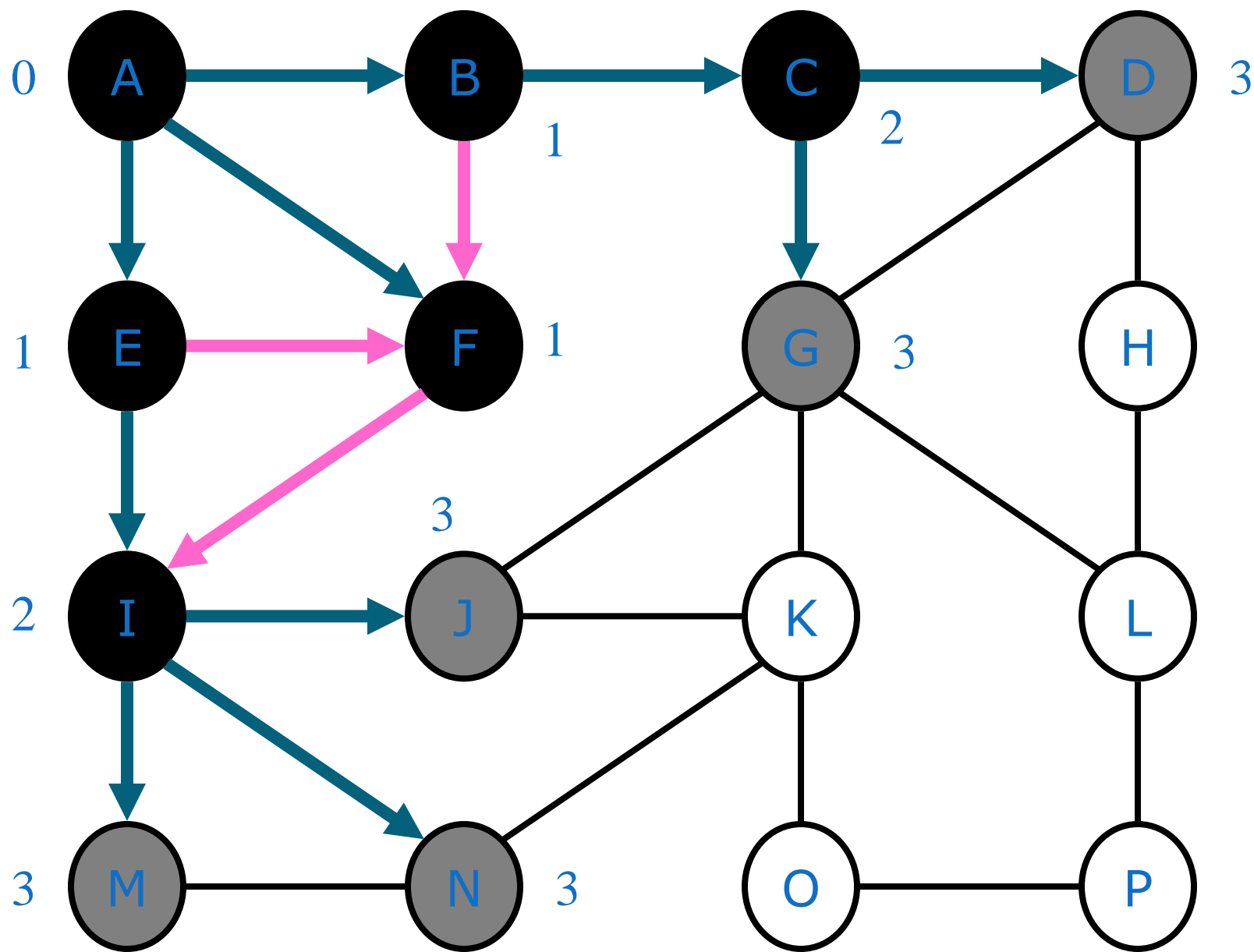


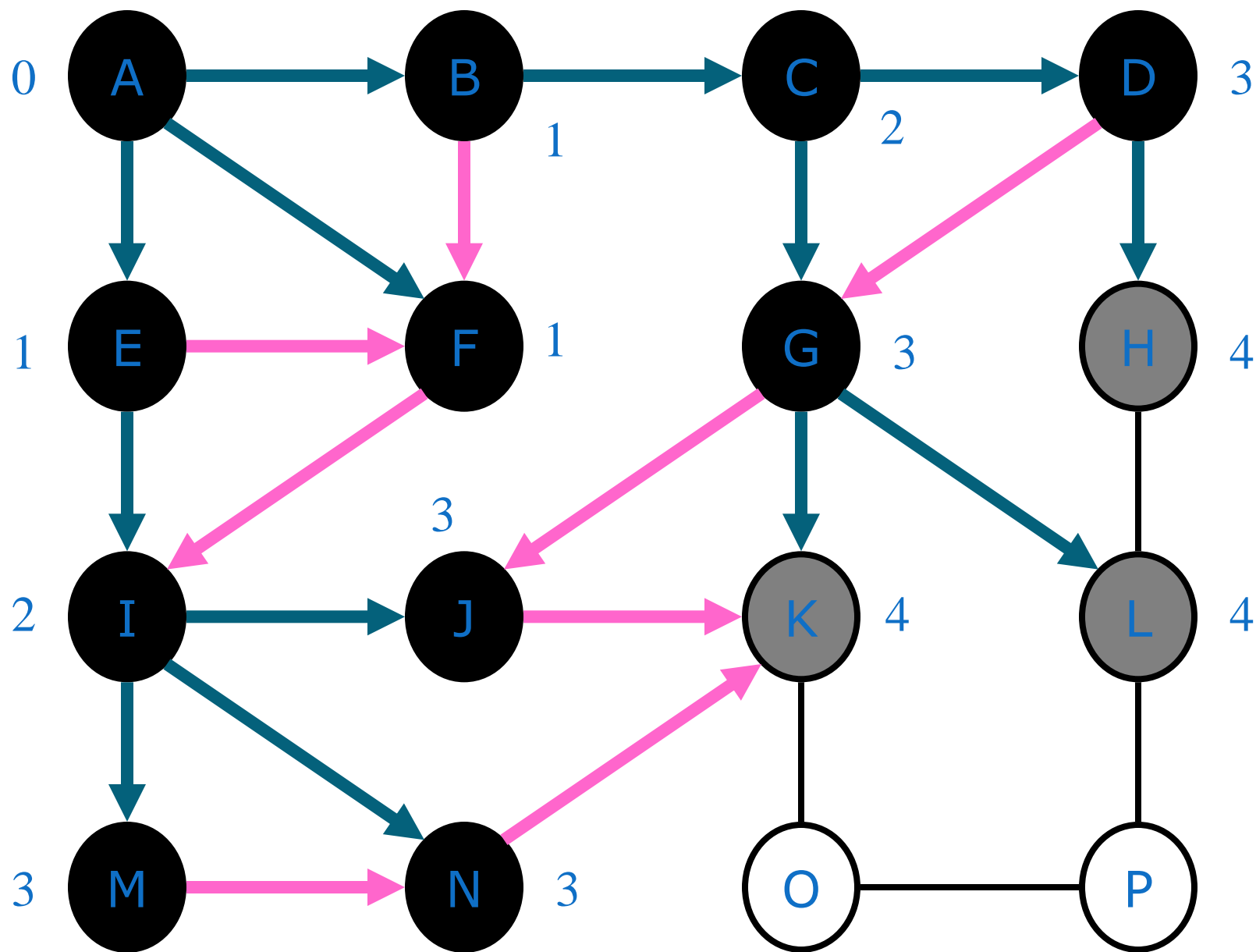
0

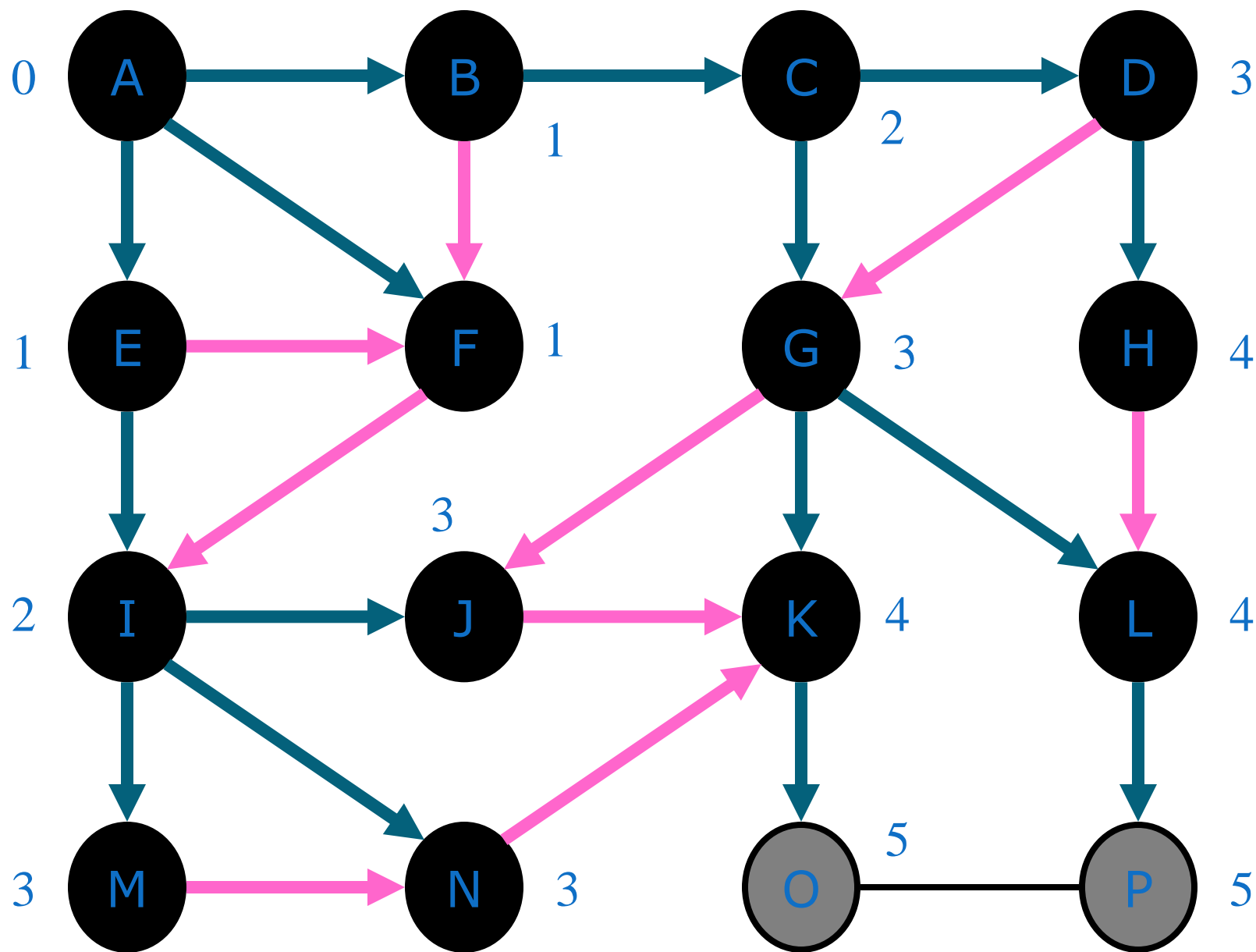


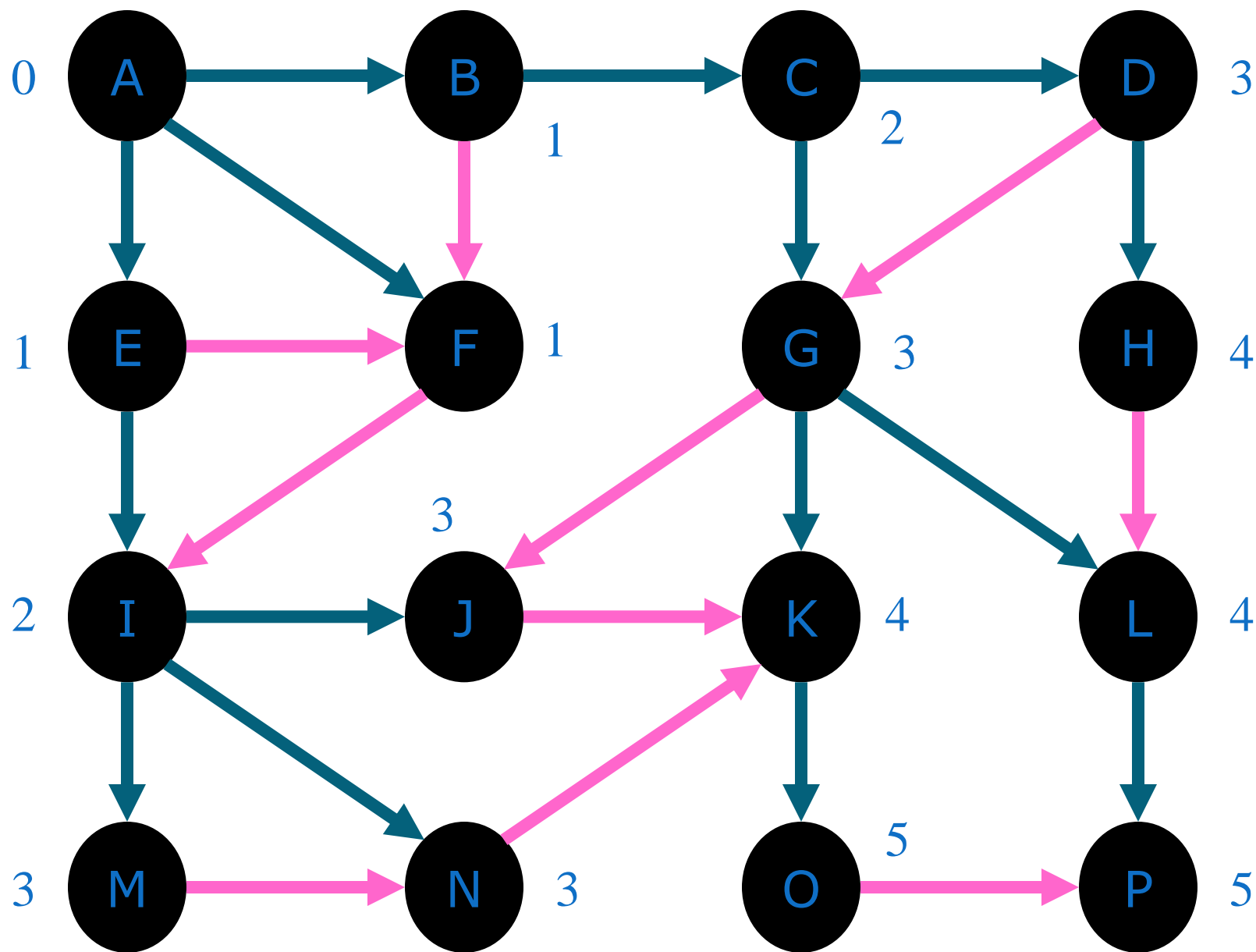


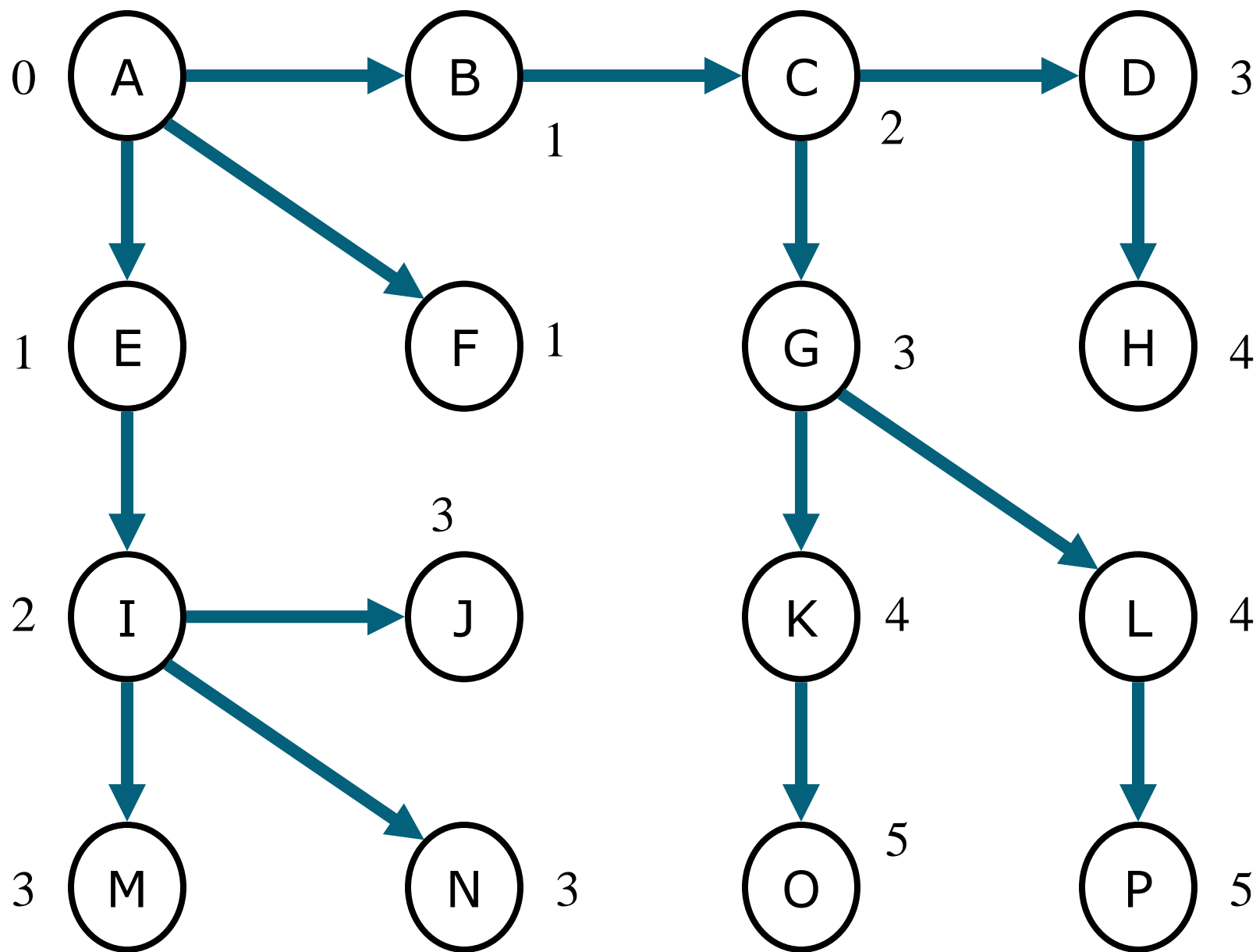












BFS: Algorithm

```
BFS(G, s)
for each vertex u in V - {s},
    color[u] = white;
    d[u] = infinity;
    p[u] = NIL
color[s] = GRAY;      d[s] = 0;      p[s] = NIL;      Q = empty queue
ENQUEUE(Q,s)
while (Q not empty)
    u = DEQUEUE(Q)
    for each v ∈ Adj[u]
        if color[v] = WHITE
            then color[v] = GREY
                d[v] = d[u] + 1; p[v] = u
                ENQUEUE(Q, v);
    color[u] = BLACK;
```

BFS: Complexity Analysis

- Queuing time is $O(V)$ and scanning all edges requires $O(E)$
- Overhead for initialization is $O(V)$
- So, total running time is $O(V+E)$

BFS: Application

- Shortest path problem
- GPS Navigation systems
- Broadcasting in Network
- Peer to Peer Network (BitTorrent)
- Parsing social graphs





END



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