Module 6

BackTracking N-Queen Problem

Backtracking

- Suppose you have to make a series of decisions, among various choices, where
 - You don't have enough information to know what to choose
 - Each decision leads to a new set of choices
 - Some sequence of choices (possibly more than one) may be a solution to your problem
- Backtracking is a methodical way of trying out various sequences of decisions, until you find one that "works"

Introduction

- Backtracking is used to solve problems in which a sequence of objects is chosen from a specified set so that the sequence satisfies some criterion.
- Backtracking is a modified depth-first search of a tree.
- Backtracking involves only a tree search.
- Backtracking is the procedure whereby, after determining that a node can lead to nothing but dead nodes, we go back ("backtrack") to the node's parent and proceed with the search on the next child.
- The term "backtrack" was coined by American mathematician D.
 H. Lehmer in the 1950s.

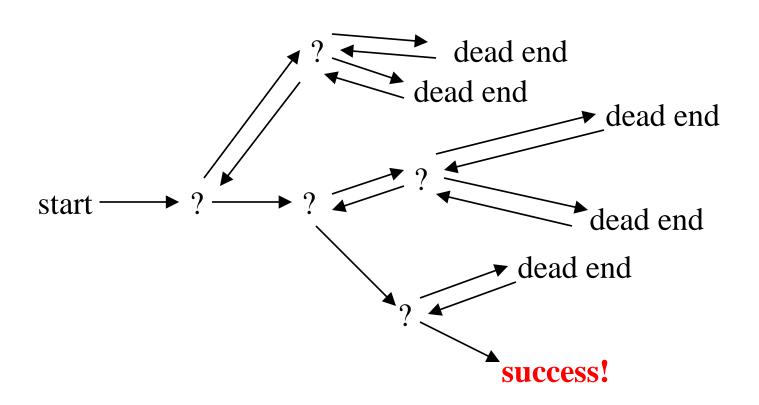
Introduction ...

- We call a node nonpromising if when visiting the node we determine that it cannot possibly lead to a solution. Otherwise, we call it promising.
- In summary, backtracking consists of
 - Doing a depth-first search of a state space tree,
 - Checking whether each node is promising, and, if it is nonpromising, backtracking to the node's parent.
- This is called pruning the state space tree, and the subtree consisting of the visited nodes is called the pruned state space tree.

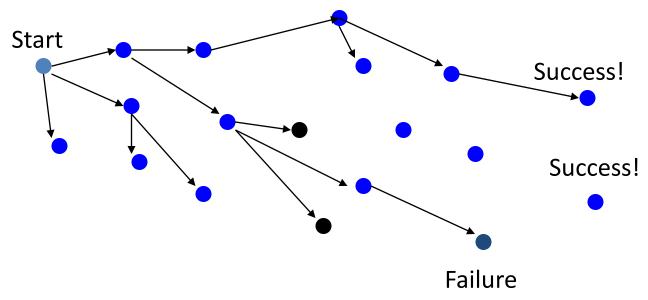
state space tree

- Construct the state space tree:
 - Root represents an initial state
 - Nodes reflect specific choices made for a solution's components.
 - Promising and nonpromising nodes
 - Leaves
- Explore the state space tree using depth-first search
- "Prune" non-promising nodes
 - dfs stops exploring subtree rooted at nodes leading to no solutions and...
 - "backtracks" to its parent node

Backtracking (animation)



Backtracking



Problem space consists of states (nodes) and actions (paths that lead to new states). When in a node can can only see paths to connected nodes

If a node only leads to failure go back to its "parent" node. Try other alternatives. If these all lead to failure then more backtracking may be necessary.

BACK TRACKING

- Backtracking is a general algorithm for finding all (or some) solutions to some computational problem, that incrementally builds candidates to the solutions, and abandons each partial candidate 'c' ("backtracks") as soon as it determines that 'c' cannot possibly be completed to a valid solution.
- Backtracking is an important tool for solving constraint satisfaction problems, such as crosswords, verbal arithmetic, Sudoku, and many other puzzles.

Control Abstraction

```
Algorithm Backtrack(k)
\begin{array}{c}23\\4\\5\\6\\7\\8\end{array}
    // This schema describes the backtracking process using
    // recursion. On entering, the first k-1 values
   // x[1], x[2], \ldots, x[k-1] of the solution vector
    //x[1:n] have been assigned. x[] and n are global.
         for (each x[k] \in T(x[1], \dots, x[k-1]) do
              if (B_k(x[1], x[2], \dots, x[k]) \neq 0) then
9
10
                   if (x[1], x[2], \dots, x[k]) is a path to an answer node
11
                        then write (x[1:k]);
12
                   if (k < n) then Backtrack(k + 1);
13
14
15
16
```

```
Algorithm \mathsf{IBacktrack}(n)
     // This schema describes the backtracking process.
   // All solutions are generated in x[1:n] and printed
\begin{array}{c} 4\\5\\6\\7\\8\\9 \end{array}
    // as soon as they are determined.
         k := 1:
         while (k \neq 0) do
              if (there remains an untried x[k] \in T(x[1], x[2], ...,
                   x[k-1]) and B_k(x[1],\ldots,x[k]) is true) then
10
11
                        if (x[1], \ldots, x[k]) is a path to an answer node
12
                             then write (x[1:k]);
13
                        k := k + 1; // Consider the next set.
14
15
              else k := k - 1; // Backtrack to the previous set.
16
17
18
```

N-Queens Problem

- Try to place N queens on an N * N board such that none of the queens can attack another queen.
- Remember that queens can move horizontally, vertically, or diagonally any distance.
- Let's consider the 8 queen example...

WHAT IS 8 QUEEN PROBLEM?

- The **eight queens puzzle** is the problem of placing eight chess queens on an 8×8 chessboard so that no two queens attack each other.
- Thus, a solution requires that no two queens share the same row, column, or diagonal.
- The eight queens puzzle is an example of the more general *n*-queens problem of placing *n* queens on an *n*×*n* chessboard, where solutions exist for all natural numbers *n* with the exception of *1, 2 and 3.*
- The solution possibilities are discovered only up to 23 queen.

Formulation:

States: any arrangement of 0 to 8 queens on the board

Initial state: 0 queens on

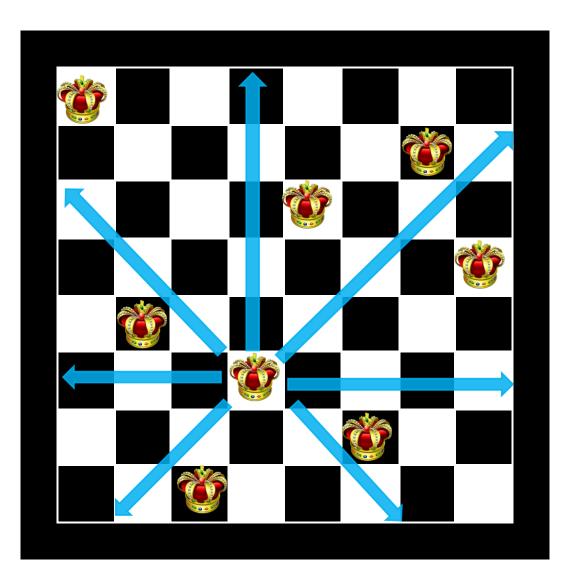
the board

Successor function: add

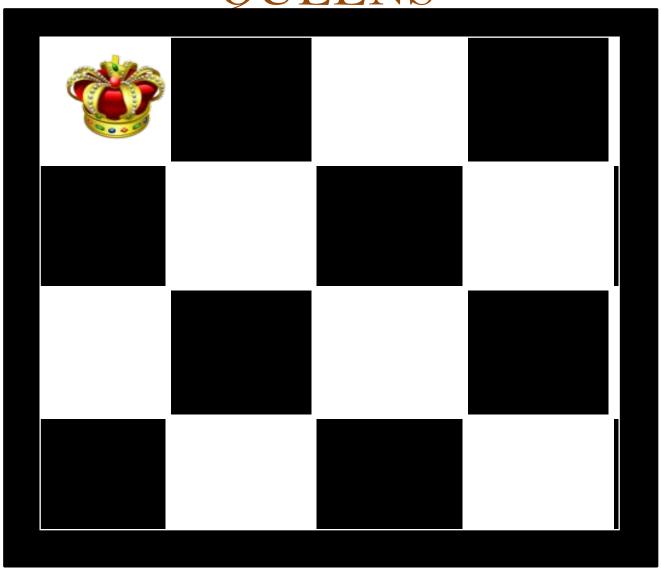
a queen in any square

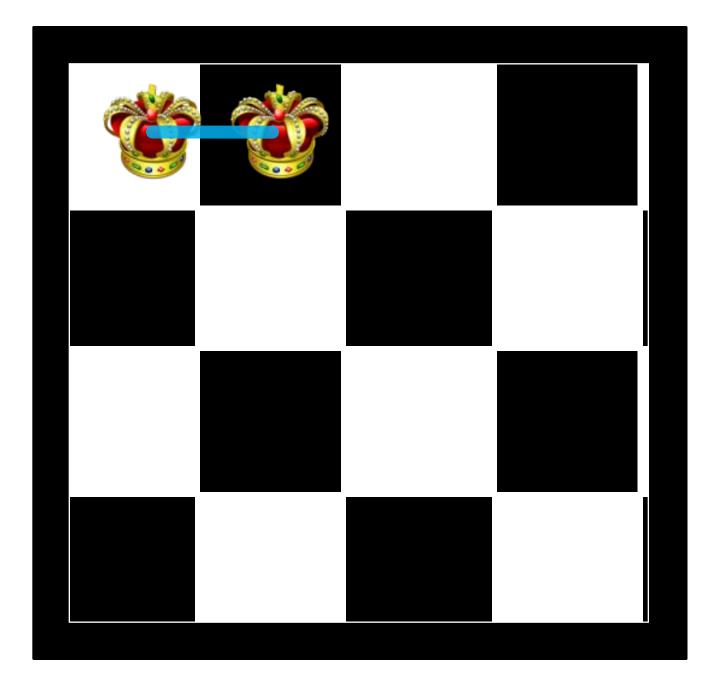
Goal test: 8 queens on

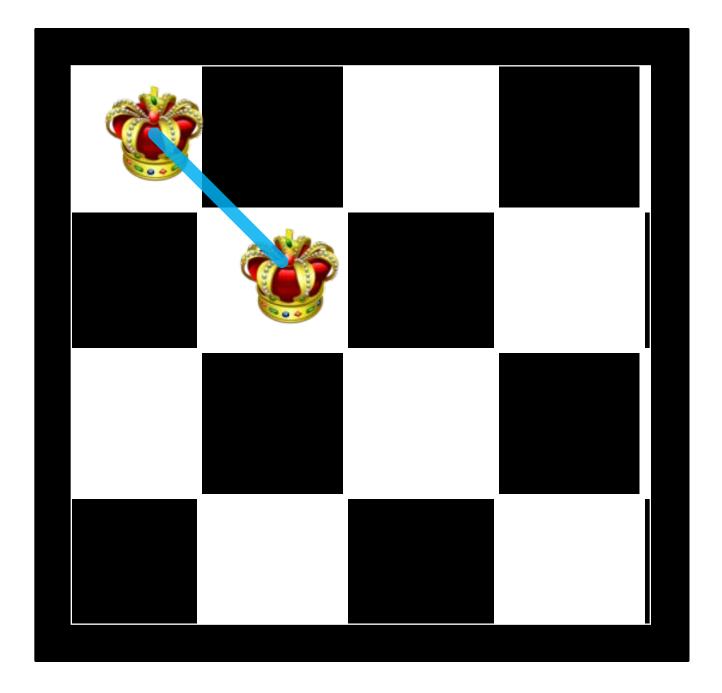
the board, none attacked

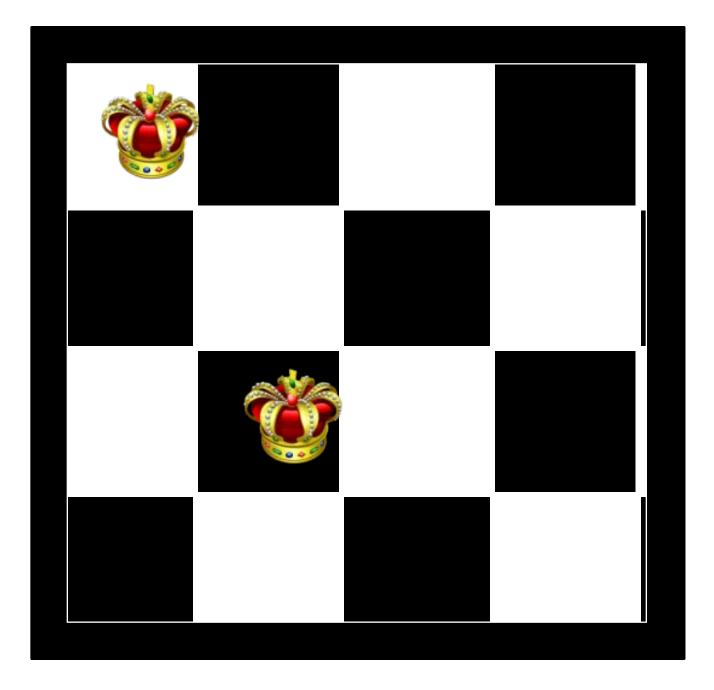


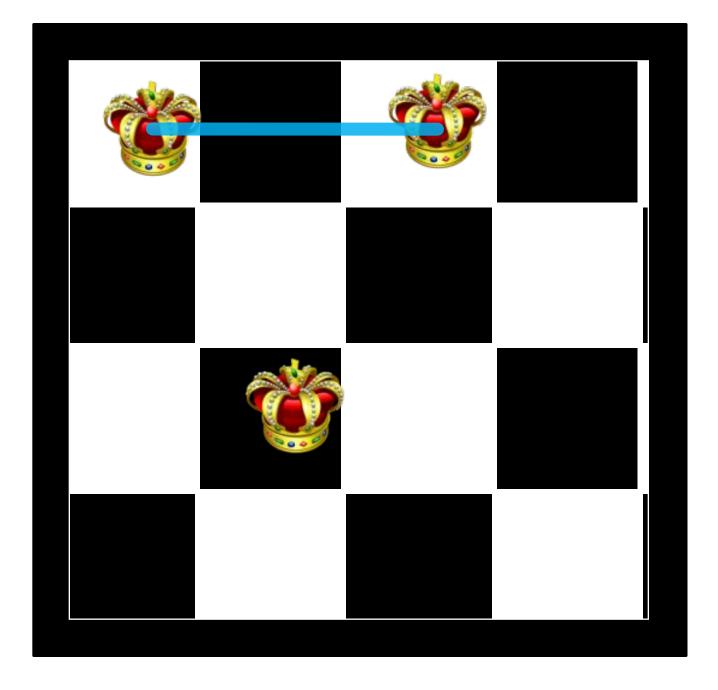
BACKTRACKING DEMO FOR 4 OUEENS

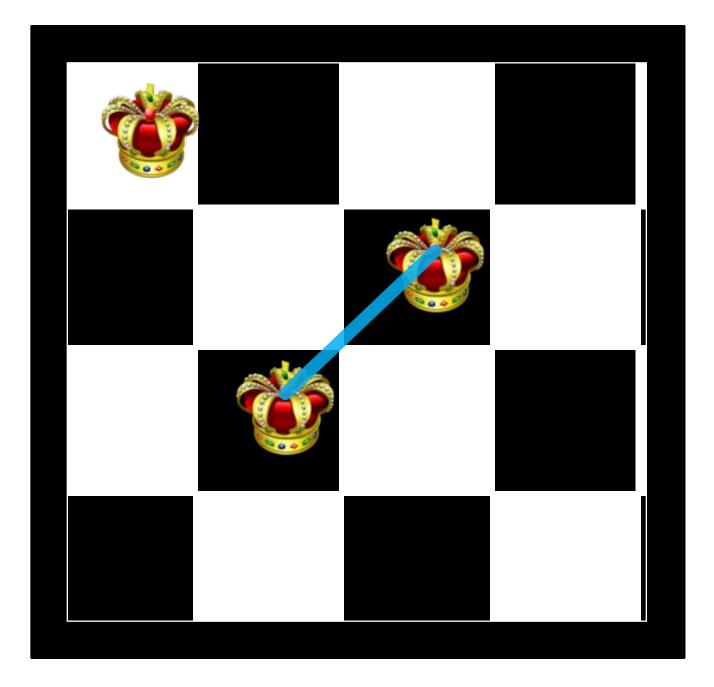


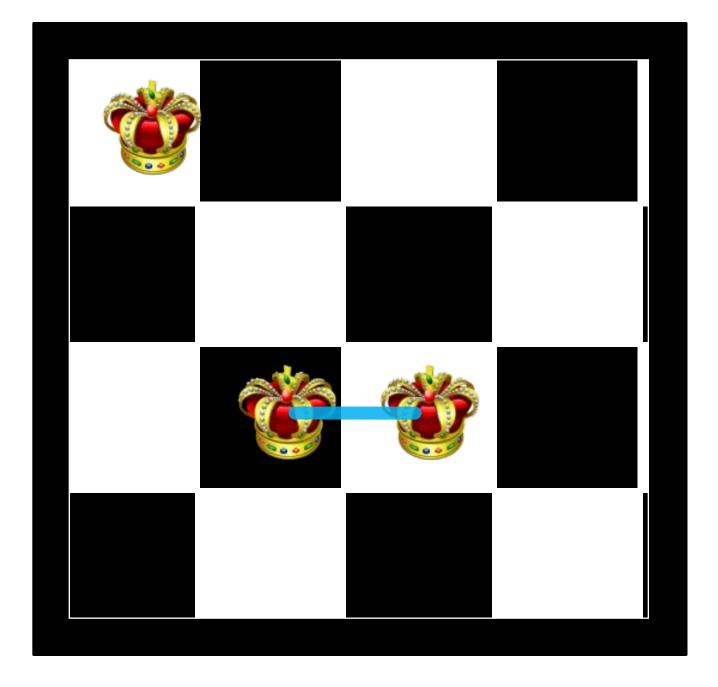


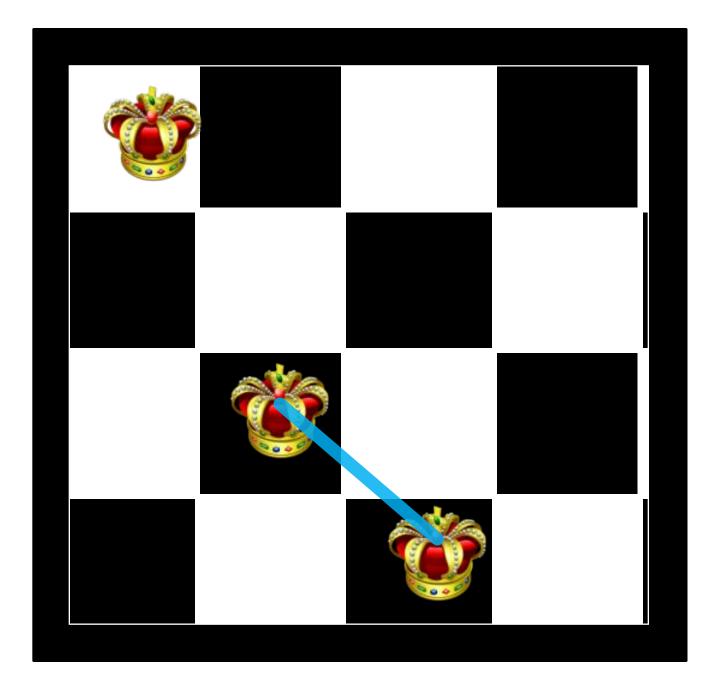


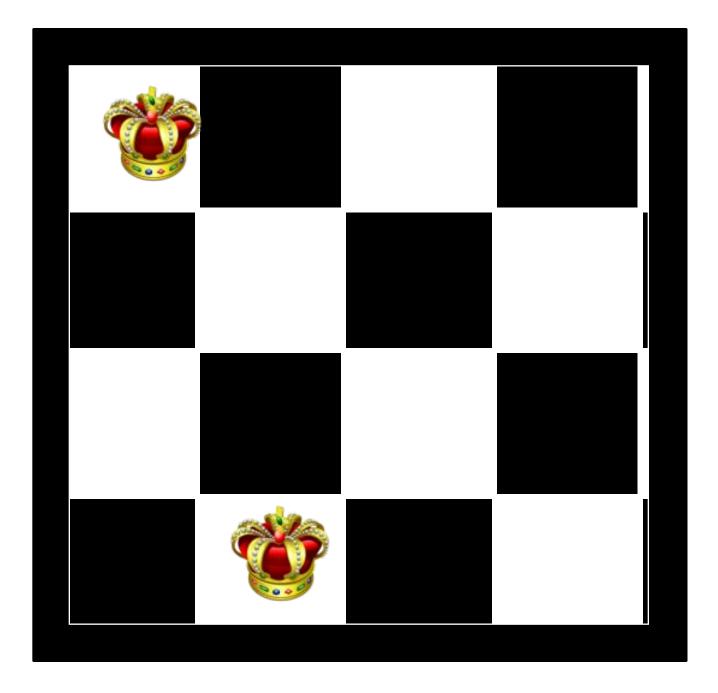


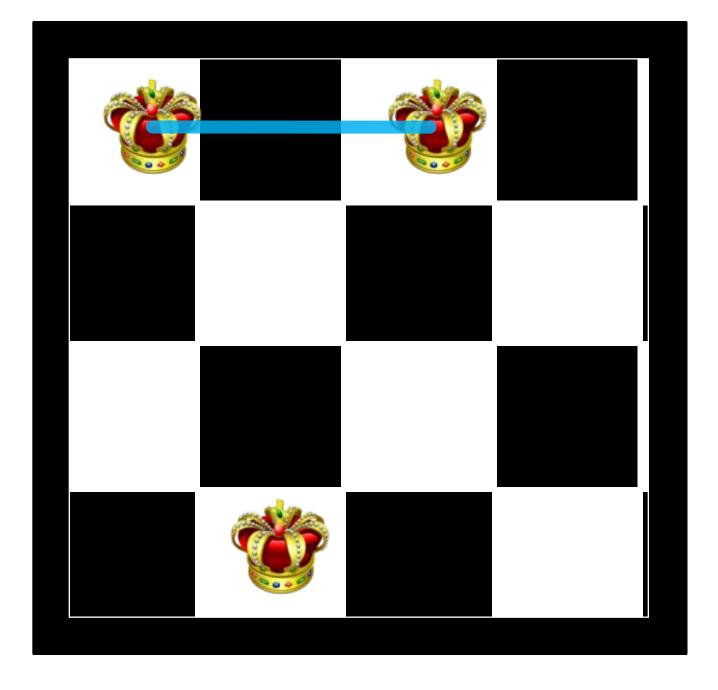


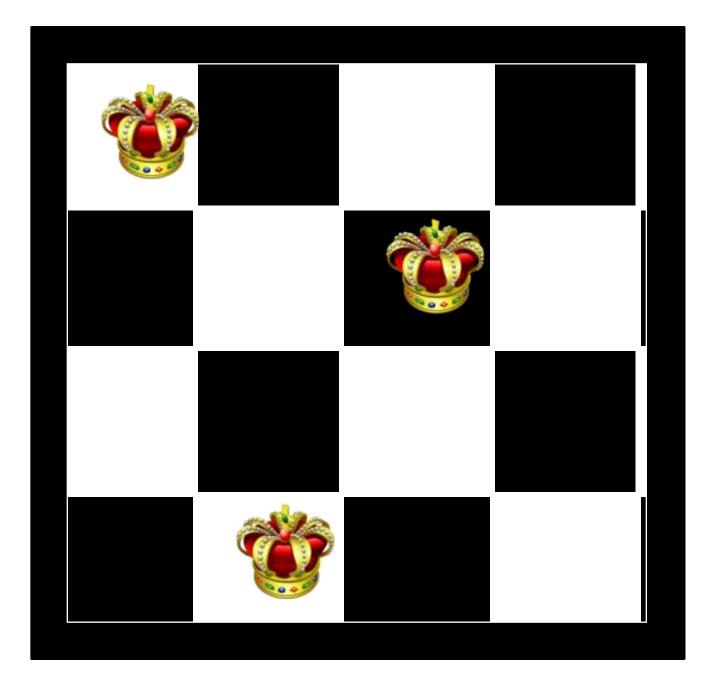


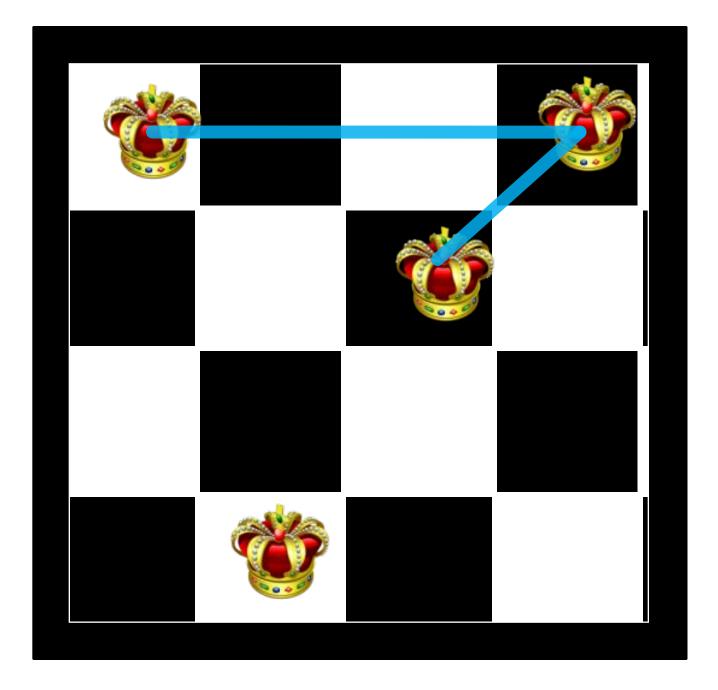


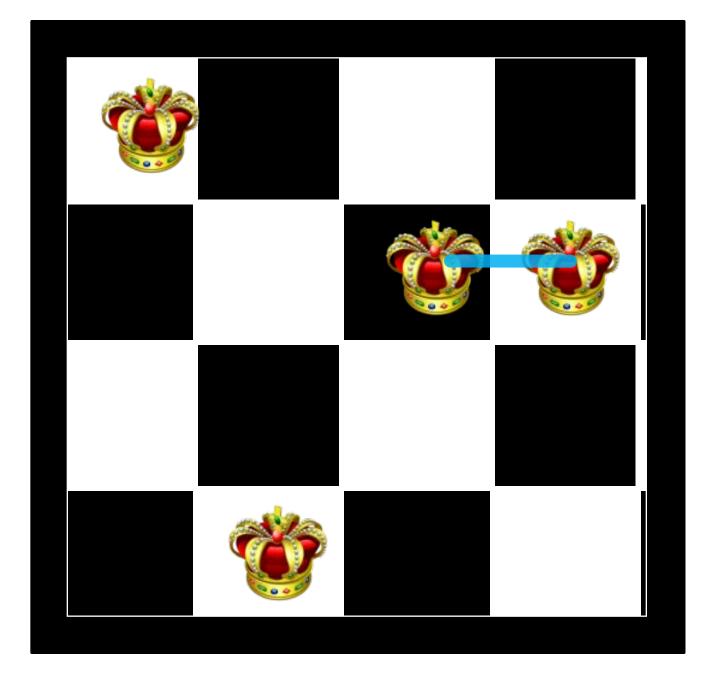


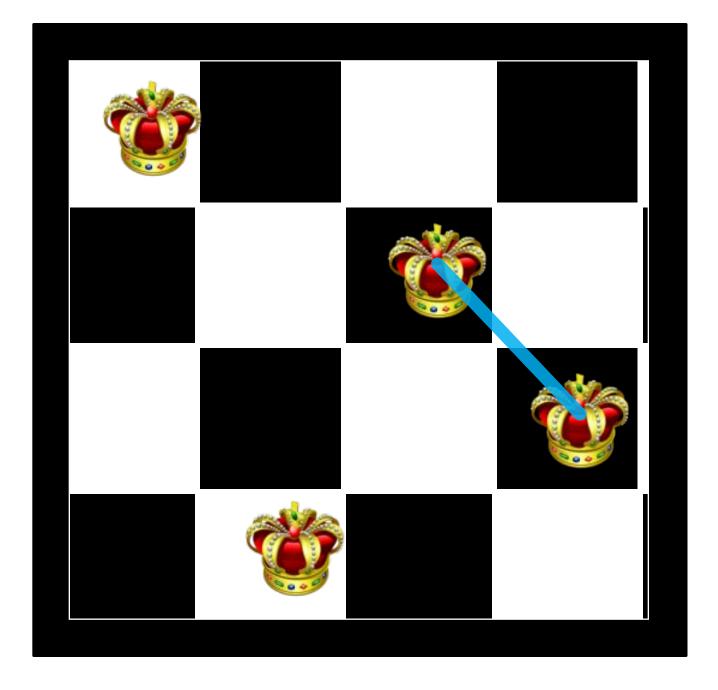


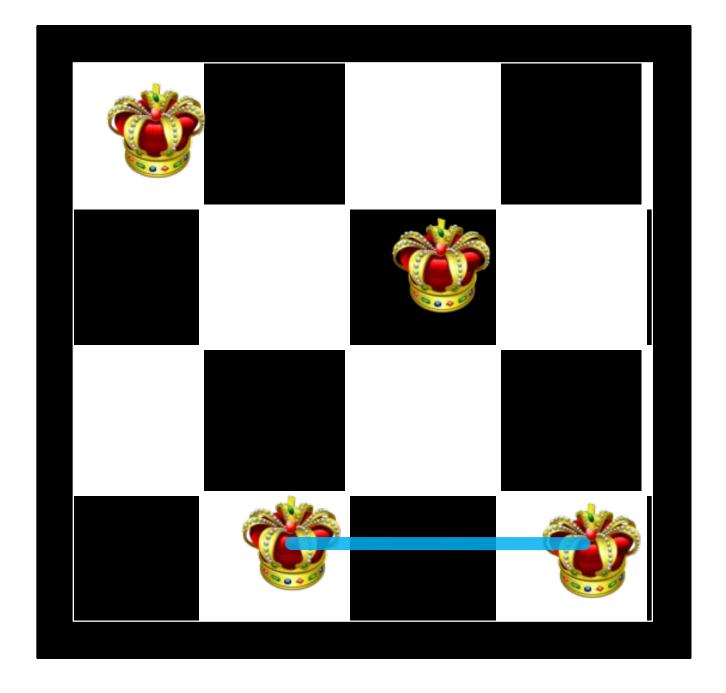


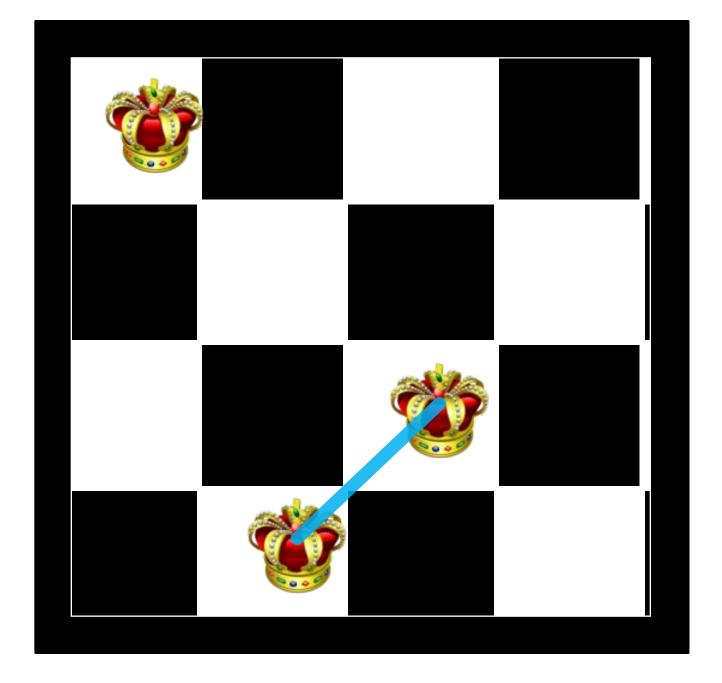


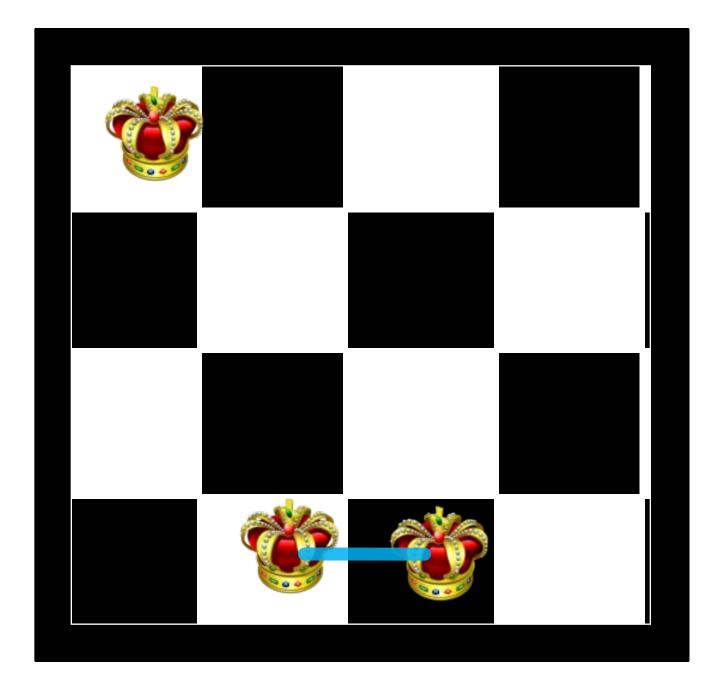


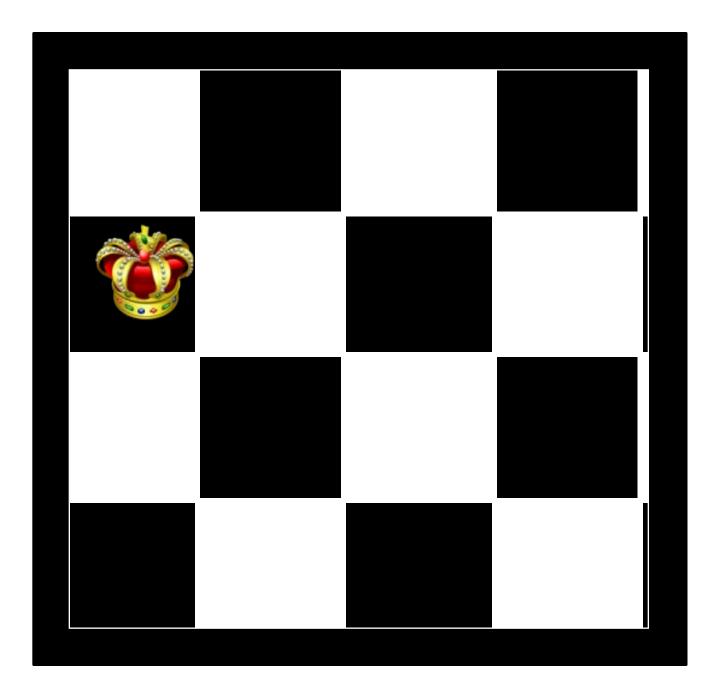


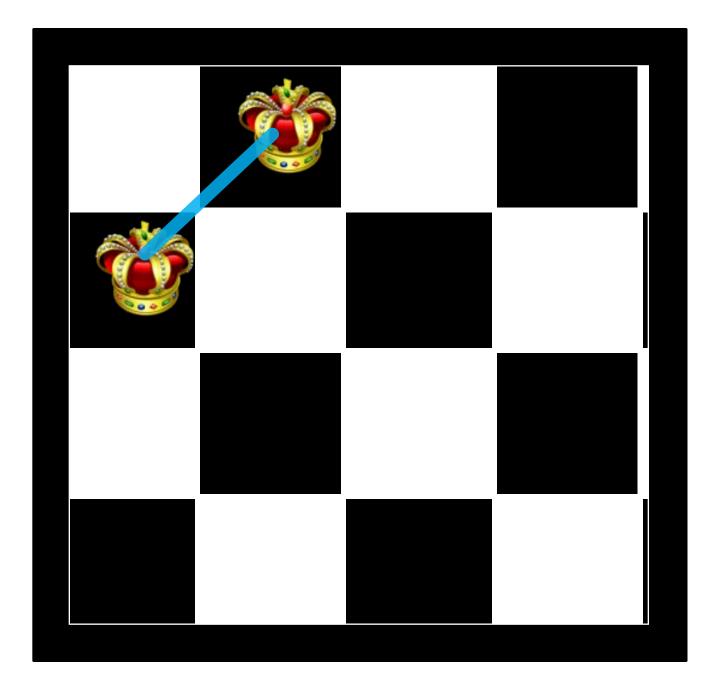


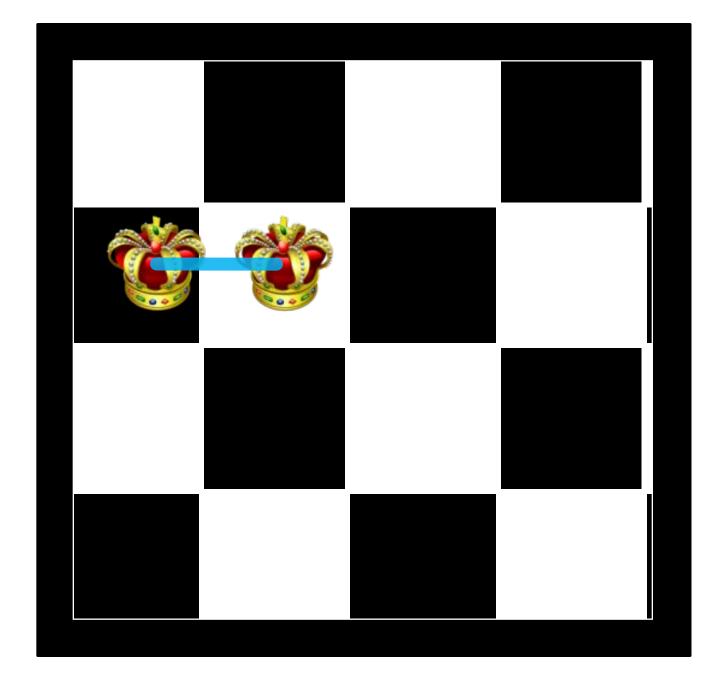


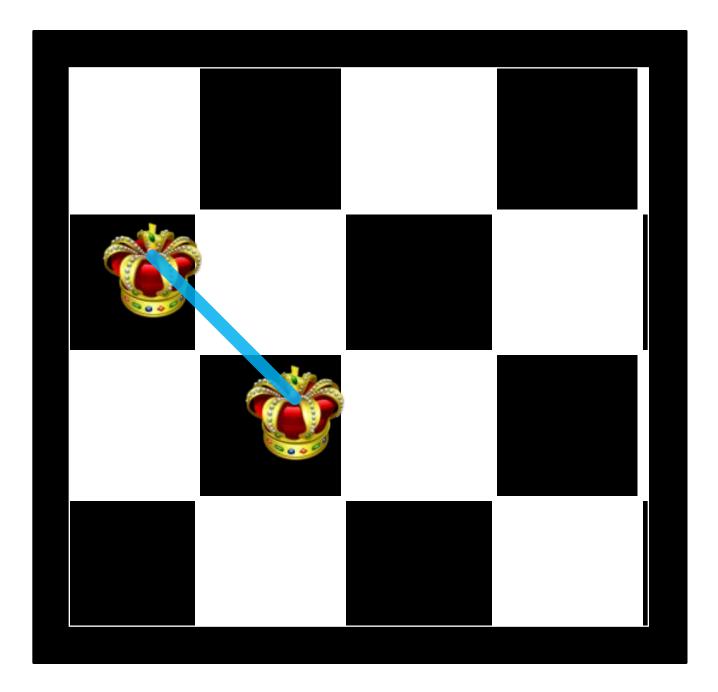


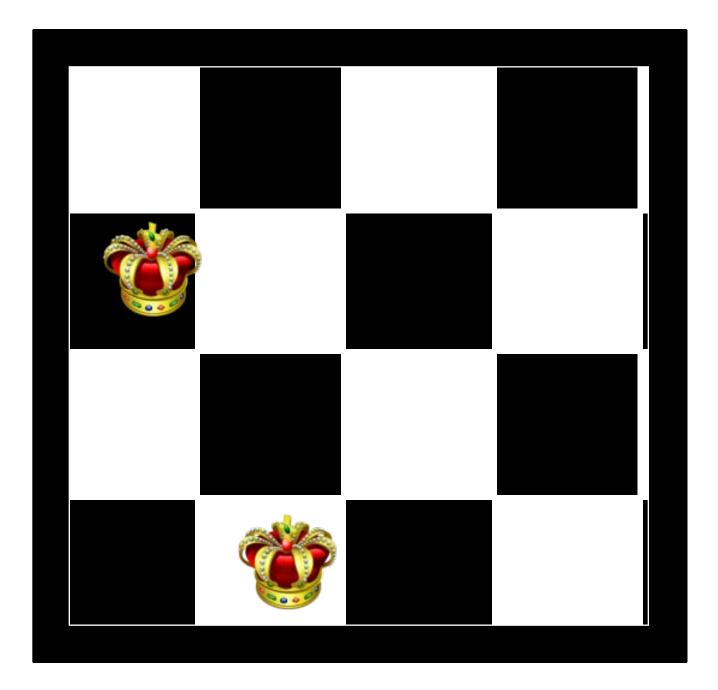


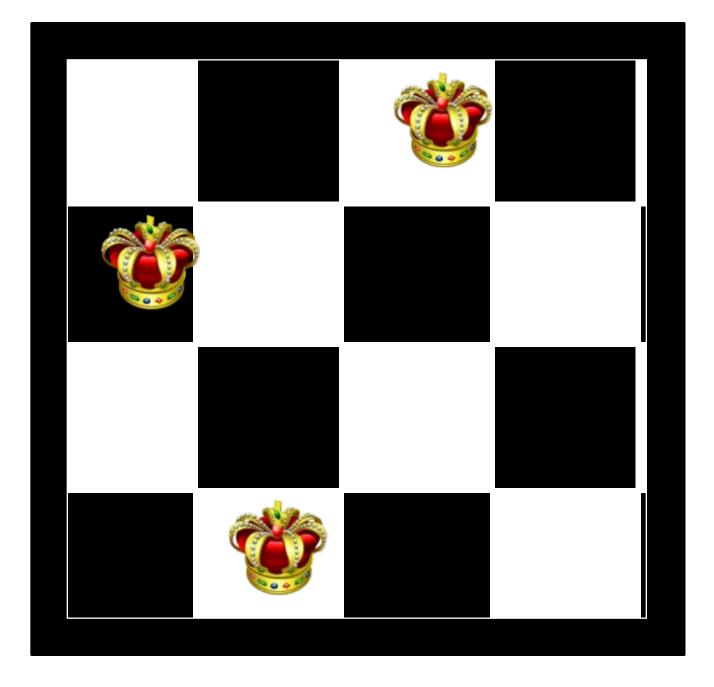


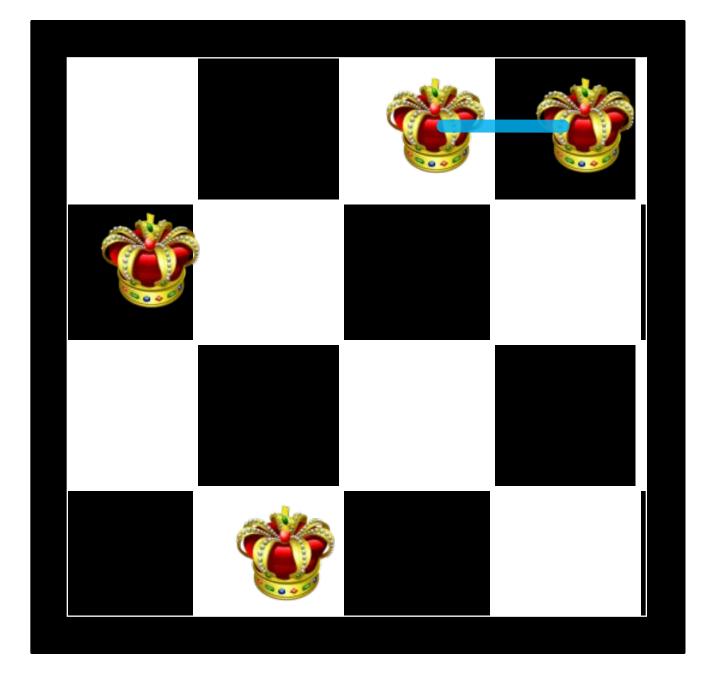


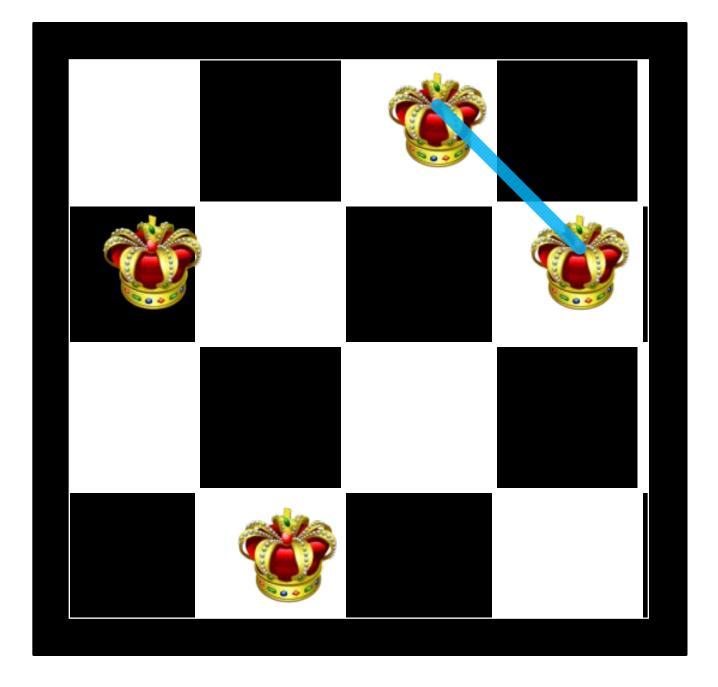
















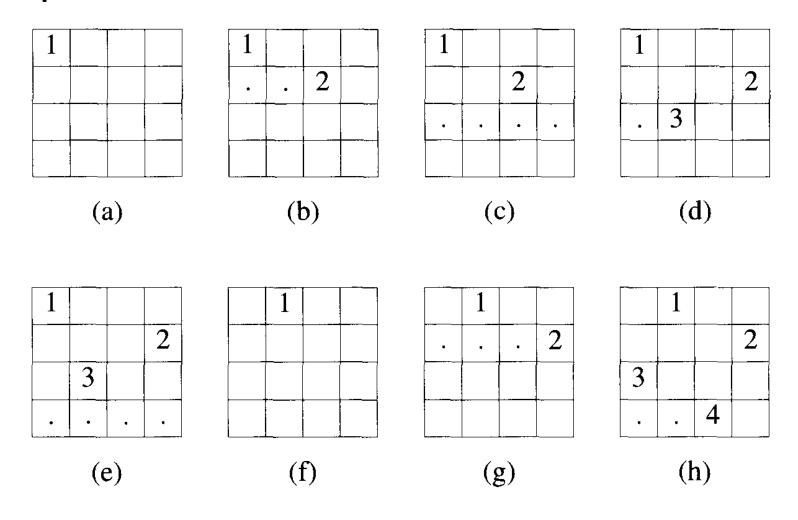
1 UNIQUE

SOLUTION

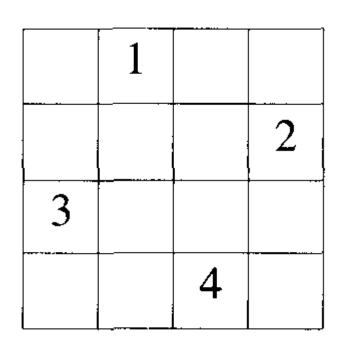




Example of a backtrack solution to the 4 -queens problem



Solutions of 4queen problems

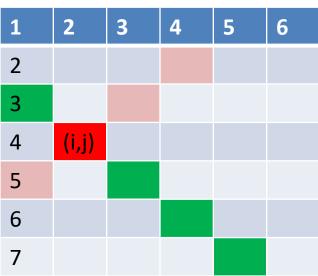


		1	
2			
			3
	4		

```
Algorithm NQueens(k, n)
    // Using backtracking, this procedure prints all
    // possible placements of n queens on an n \times n
    // chessboard so that they are nonattacking.
5
6
        for i := 1 to n do
             if Place(k, i) then
                 x[k] := i;
10
                 if (k = n) then write (x[1:n]);
11
                 else NQueens(k+1,n);
12
13
14
15
```

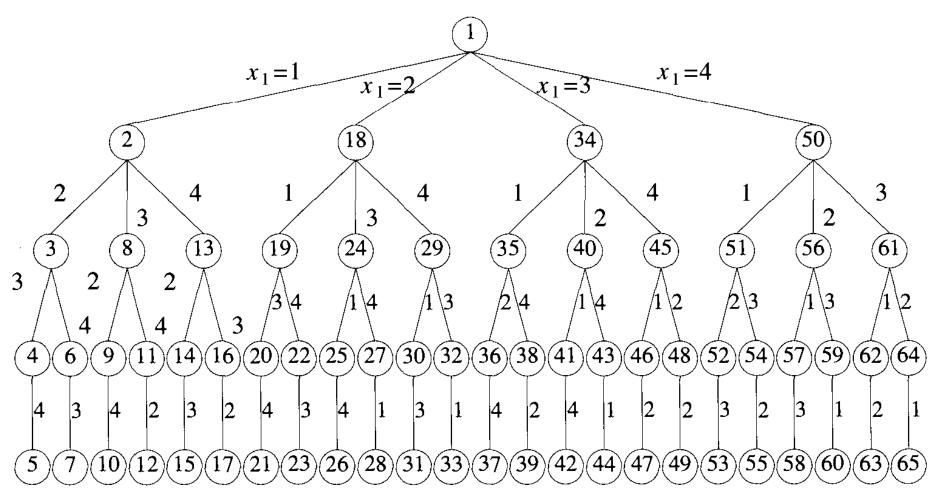
```
Algorithm Place(k, i)
   // Returns true if a queen can be placed in kth row and
   // ith column. Otherwise it returns false. x[] is a
   // global array whose first (k-1) values have been set.
   // Abs(r) returns the absolute value of r.
        for j := 1 to k-1 do
8
             if ((x[j] = i) // \text{Two in the same column})
                  or (\mathsf{Abs}(x[j]-i) = \mathsf{Abs}(j-k))
9
                      // or in the same diagonal
10
                 then return false;
11
12
        return true;
13
```

- To check whether they are on the same diagonal, let chessboard be represented by an array a[1..n][1..n].
- Every element with same diagonal that runs from upper left to lower right has same "row-column" value. E.g., consider the element a[4][2]. Elements a[3][1], a[5][3], a[6][4], a[7][5] and a[8][6] have row-column value 2.
- every element from same diagonal that goes from upper right to lower left has same "row+column" value. The elements a[1][5], a[2][4], a[3][3], a[5][1] have same "row+column" value as that of element a[4][2] which is 6.
- Hence two queens placed at (i,j) and (k,l) have same diagonal iff i j = k l or i + j
 = k + l
- i.e., j l = i k or j l = k i
- |j-l| = |i-k|

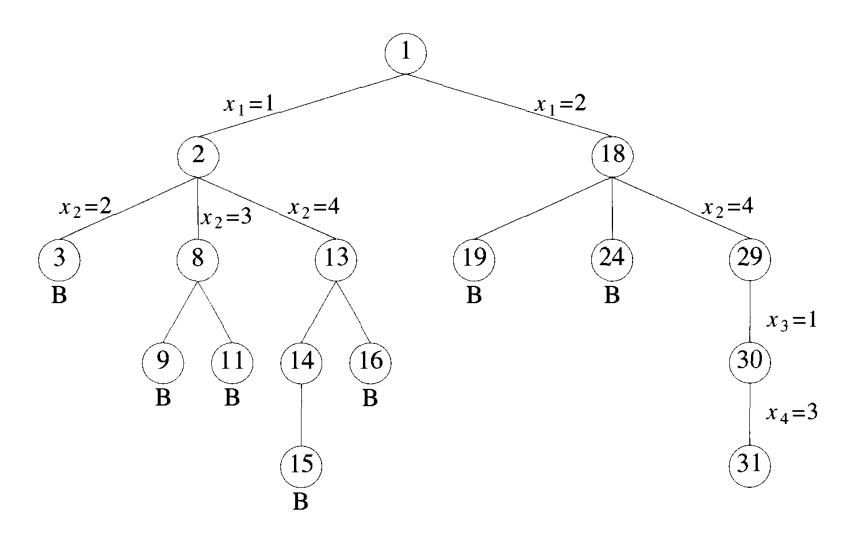


- State Space Tree: The tree organization of the solution space is referred to as the state space tree.
 - Each node in state space tree defines a problem state.
 - All paths from root to other nodes define state space of problem.
- Solution states are those problem states for which the path from root to s
 defines a tuple in solution space.
- Answer states are those solution states s for which path from root to s
 defines a tuple that is member of solution (satisfies implicit
 constraints).
- Live node: A node which has been generated and all of whose children are not yet been generated.
- E node: A live node whose children are currently been generated (node being expanded).
- Dead node: A generated node with all its children expanded

Tree Organization of the 4-queens solution space. Nodes are numbered as in depth first search



Portion of the tree is generated during backtracking



Counting Solutions

Order ("N")	Total Solutions	Unique Solutions	Exec time
1	1	1	< 0 seconds
2	0	0	< 0 seconds
3	0	0	< 0 seconds
4	2	1	< 0 seconds
5	10	2	< 0 seconds
6	4	1	< 0 seconds
7	40	6	< 0 seconds
8	92	12	< 0 seconds
9	352	46	< 0 seconds
10	724	92	< 0 seconds
11	2,680	341	< 0 seconds
12	14,200	1,787	< 0 seconds
13	73,712	9,233	< 0 seconds
14	365,596	45,752	0.2s

15	2,279,184	285,053	1.9 s
16	14,772,512	1,846,955	11.2 s
17	95,815,104	11,977,939	77.2 s
18	666,090,624	83,263,591	9.6 m
19	4,968,057,848	621,012,754	75.0 m
20	39,029,188,884	4,878,666,808	10.2 h
21	314,666,222,712	39,333,324,973	87.2 h
22	2,691,008,701,644	336,376,244,042	31.9
23	24,233,937,684,440	3,029,242,658,210	296 d
24	227,514,171,973,736	28,439,272,956,934	$\dot{5}$
25	2,207,893,435,808,352	275,986,683,743,434	$\dot{5}$
26	22,317,699,616,364,044	2,789,712,466,510,289	5

(s = seconds m = minutes h = hours d = days)

