Module 6

Branch and Bound-TSP

Branch and Bound (B&B)

- An enhancement of backtracking
 - Similarity
 - A state space tree is used to solve a problem.
 - Difference
 - The branch-and-bound algorithm does not limit us to any particular way of traversing the tree.
 - Used only for optimization problems (since the backtracking algorithm requires the using of DFS traversal and is used for non-optimization problems.)

Branch and bound

- A general algorithm for finding optimal solutions of various optimization problems.
- BFS like state space search in which the live nodes are maintained using a queue is called FIFO
- D-Search like state space search in which the live nodes are maintained using a stack is called LIFO.
- Bounding functions are used to avoid the generation of subtrees that do not contain an answer node.

Branch and Bound

The idea:

Set up a **bounding function**, which is used to compute a **bound** (for the value of the objective function) **at a node** on a state-space tree and determine **if it is promising**

- Promising (if the bound is better than the value of the best solution so far): expand beyond the node.
- Nonpromising (if the bound is no better than the value of the best solution so far): not expand beyond the node (pruning the state-space tree).

Travelling Salesman Problem(TSP)

 Given a directed graph G=(V,E), the TSP problem is to find a tour or cycle that begins from a node, covers all the nodes of the graph exactly once and returns back to that node.

Traveling Salesman Problem

- Construct the state-space tree:
 - A node = a vertex: a vertex in the graph.
 - A node that is not a leaf represents all the tours that start with the path stored at that node; each leaf represents a tour (or non-promising node).
 - Branch-and-bound: we need to determine a lower bound for each node
 - For example, to determine a lower bound for node [1, 2] means to determine a lower bound on the length of any tour that starts with edge 1—2.
 - Expand each promising node, and stop when all the promising nodes have been expanded. During this procedure, prune all the nonpromising nodes.
 - Promising node: the node's lower bound is less than current minimum tour length.
 - Non-promising node: the node's lower bound is NO less than current minimum tour length.

• end

Traveling Salesman Problem—Bounding Function 1

- Because a tour must leave every vertex exactly once, a lower bound on the length of a tour is b (lower bound) minimum cost of leaving every vertex.
 - The lower bound on the cost of leaving vertex v_1 is given by the minimum of all the nonzero entries in row 1 of the adjacency matrix.
 - **—** ...
 - The lower bound on the cost of leaving vertex v_n is given by the minimum of all the nonzero entries in row n of the adjacency matrix.
- Note: This is not to say that there is a tour with this length. Rather, it says that there can be no shorter tour.
- Assume that the tour starts with v1.

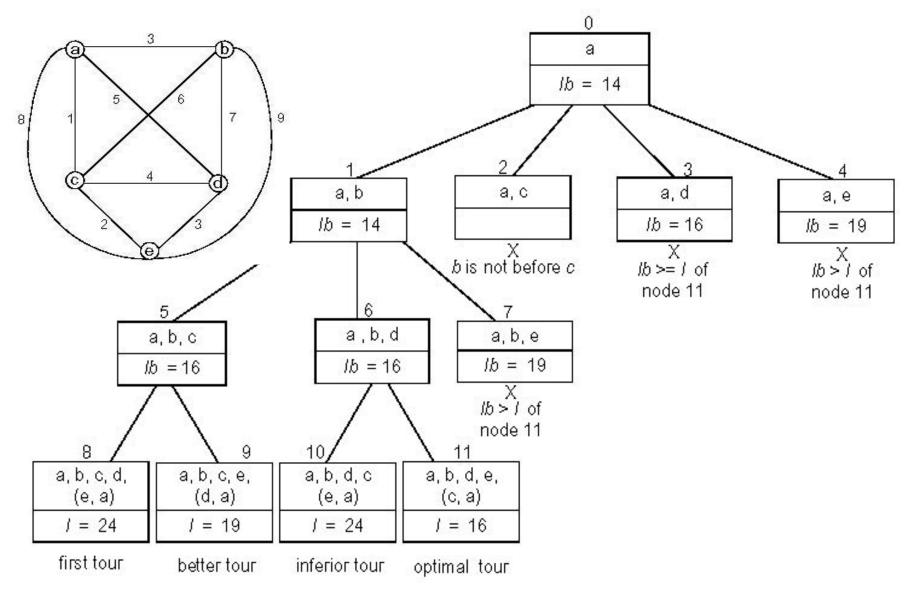
Traveling Salesman Problem—Bounding Function 2

- Because every vertex must be entered and exited exactly once, a lower bound on the length of a tour is the sum of the minimum cost of entering and leaving every vertex.
 - For a given edge (u, v), think of half of its weight as the <u>exiting cost of u</u>, and half of its weight as the <u>entering cost of v</u>.
 - The total length of a tour = the total cost of visiting(entering and exiting) every vertex exactly once.
 - The lower bound of the length of a tour = the lower bound of the total cost of visiting (entering and exiting) every vertex exactly once.

• Calculation:

- for each vertex, pick top two shortest adjacent edges (their sum divided by 2 is the lower bound of the total cost of entering and exiting the vertex);
- add up these summations for all the vertices.
- Assume that the tour starts with vertex a and that b is visited before c.
- The worst case complexity of TSP problem is O(n²2ⁿ).

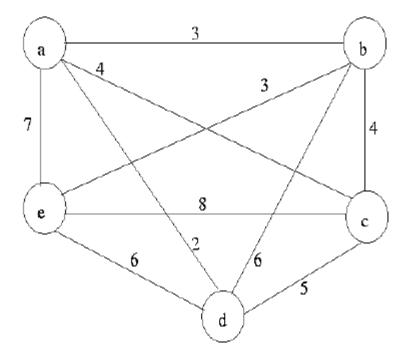
Traveling salesman example 2



 Suppose we have a graph with 4 nodes ie, n=4 then the different possibilities is shown in the state space tree S below:

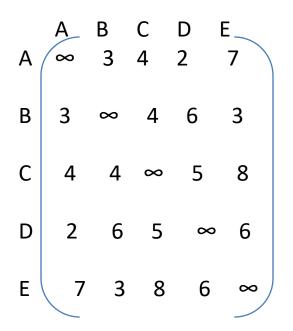
Problem

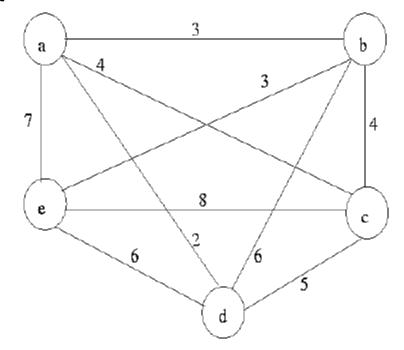
 Solve Travelling Salesman Problem using Branch and Bound Algorithm in the following graph-



Step-01:

Write the initial cost matrix and reduce it-





Rules

- To reduce a matrix, perform the row reduction and column reduction of the matrix separately.
- A row or a column is said to be reduced if it contains at least one entry '0' in it.

Row Reduction-

Consider the rows of the matrix one by one.

```
A B C D E
A ≈ 3 4 2 7
B 3 ≈ 4 6 3
C 4 4 ≈ 5 8
D 2 6 5 ≈ 6
E 7 3 8 6 ≈
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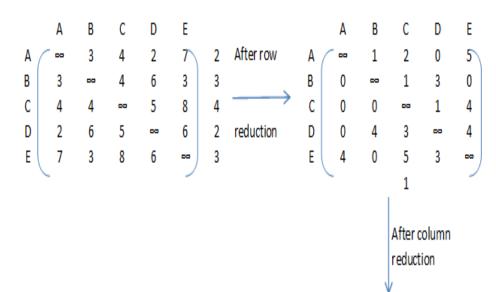
- If the row already contains an entry '0', then-There is no need to reduce that row.
- If the row does not contains an entry '0', then- Reduce that particular row.
- Select the least value element from that row.
- Subtract that element from each element of that row.
- This will create an entry '0' in that row, thus reducing that row.

Column Reduction-

- Consider the columns of above row-reduced matrix one by one.
 - If the column already contains an entry '0', then- There is no need to reduce that column.
 - If the column does not contains an entry '0', then-Reduce that particular column.
- Select the least value element from that column.
- Subtract that element from each element of that column.
- This will create an entry '0' in that column, thus reducing that column.

- Following this, we have-
- Reduce the elements of row-1 by 2.
- Reduce the elements of row-2 by 3.
- Reduce the elements of row-3 by 4.
- Reduce the elements of row-4 by 2.
- Reduce the elements of row-5 by 3.
- There is no need to reduce column-1.
- There is no need to reduce column-2.
- Reduce the elements of column-3 by 1.
- There is no need to reduce column-4.
- There is no need to reduce column-5.

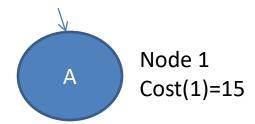
Performing this,
 we obtain the following
 row – column reduced matrix-



- Finally, the initial distance matrix is completely reduced.
- Now, we calculate the cost of node-1(A) by adding all the reduction elements.

Cost(1)= Sum of all reduction elements

$$= 2+3+4+2+3+1$$



Step-02:

- We consider all other vertices one by one.
- We select the best vertex where we can land upon to minimize the tour cost.

Choosing To Go To Vertex-B: Node-2 (Path A \rightarrow B)

- From the reduced matrix of step-01, M[A,B] = 1
- Set row-A and column-B to ∞
- Set M[B,A] = ∞

Now, resulting cost matrix is-

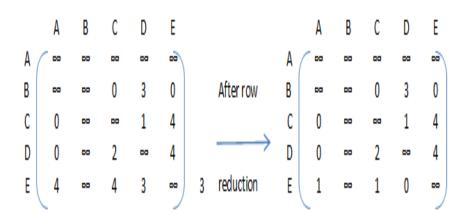
- Now, We reduce this matrix.
- Then, we find out the cost of node-02.

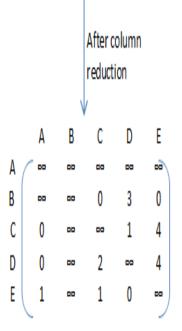
Row Reduction-

- We can not reduce row-1 as all its elements are ∞.
- There is no need to reduce row-2.
- There is no need to reduce row-3.
- There is no need to reduce row-4.
- Reduce the elements of row-5 by 3
- Performing this,
 we obtain the row-reduced matrix

Column Reduction-

- There is no need to reduce column-1.
- We can not reduce column-2 as all its elements are ∞.
- There is no need to reduce column-3.
- There is no need to reduce column-4.
- There is no need to reduce column-5
- Performing this,
 we obtain the column-reduced matrix





- Finally, the matrix is completely reduced.
- Now, we calculate the cost of node-2.

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Cost(2)= Cost(1) + Sum of reduction elements + M[A,B]
```

$$= 15 + 3 + 1$$

Choosing To Go To Vertex-C: Node-3 (Path A → C)

- From the reduced matrix of step-01, M[A,C] = 1
- Set row-A and column-C to ∞
- Set M[C,A] = ∞
- Now, resulting cost matrix is-

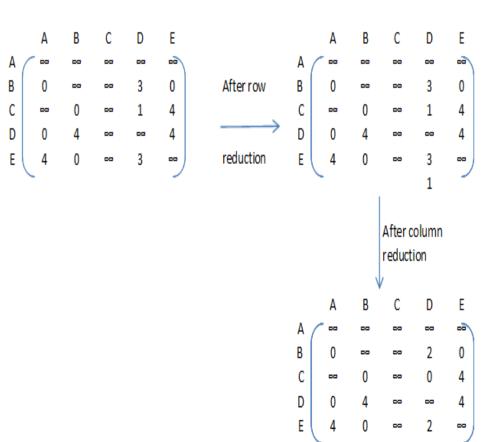
- Now,We reduce this matrix.
- Then, we find out the cost of node-03.

Row Reduction-

- We can not reduce row-1 as all its elements are ∞.
- There is no need to reduce row-2.
 row-3, row-4 and row-5.
- Thus, the matrix is already rowreduced.

Column Reduction-

- There is no need to reduce column-1 and column-2.
- We can not reduce column-3 as all its elements are ∞.
- There is no need to reduce column-4 and column 5.
- Thus, the matrix is already column reduced.
- Finally, the matrix is completely reduced.



- Now, we calculate the cost of node-3.
- Cost(3) = Cost(1) + Sum of reduction elements+ M[A,C]

$$= 15 + 1 + 1$$

Choosing To Go To Vertex-D: Node-4 (Path A → D)

- From the reduced matrix of step-01, M[A,D] = 0
- Set row-A and column-D to ∞
- Set M[D,A] = ∞
- Now, resulting cost matrix is-

- Now, We reduce this matrix.
- Then, we find out the cost of node-04.

Row Reduction-

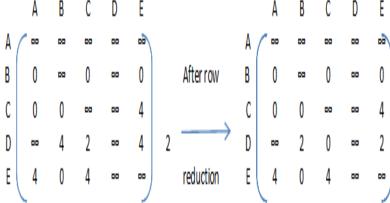
- We can not reduce row-1 as all its elements
- There is no need to reduce row-2,row 3.
- Reduce all the elements of row-4 by 2.
- There is no need to reduce row-5.
- Performing this, we obtain the row-reduced 0

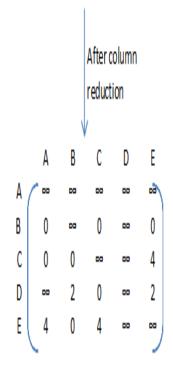
Column Reduction-

- There is no need to reduce column-1.
- There is no need to reduce column-2.
- There is no need to reduce column-3 and co
- We can not reduce column-4 as all its elements are ∞.
- Thus, the matrix is already column-reduced
- Finally, the matrix is completely reduced.
- Now, we calculate the cost of node-4.

Cost(4)= Cost(1) + Sum of reduction elements
+ M[A,D]
=
$$15 + 2 + 0$$

= 17





Choosing To Go To Vertex-D: Node-5 (Path A → E)

- From the reduced matrix of step-01, M[A,E] = 5
- Set row-A and column-E to ∞
- Set M[E,A] = ∞
- Now, resulting cost matrix is-

	Α	В	C	D	Ε			Α	В	С	D	Ε
Α	C	00	00	00	-5		Α	~ ~	00	00	00	-S
В	0	00	0	3	88	After row	В	0	00	0	2	
С	0	0	00	1			С	0	0	00	0	00
D	0	4	2	00		and column	D	0	4	2	00	00
Ε		0	4	3		reduction	Ε		0	4	2	•••
				1								

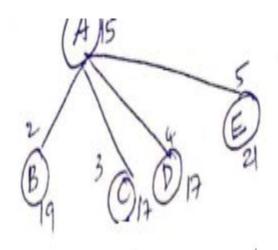
- Now, We reduce this matrix.
- Then, we find out the cost of node-05.

Cost(4)= Cost(1) + Sum of reduction elements
+
$$M[A,E]$$

= 15 + 1 +5 = 21

Thus, we have-

- Cost(2) = 19 (for Path A → B)
- Cost(3) = 17 (for Path A \rightarrow C)
- Cost(4) = 17 (for Path A → D)
- Cost(5) = 21 (for Path A \rightarrow E)



- We choose the node with the lowest cost.
- Since cost for node-3 is lowest, so we prefer to visit node-3.
- Thus, we choose node-3 i.e. path A → C.

Step-03:

- We explore the vertices B,D and E from node-3.
- We now start from the cost matrix at node-3 which is-Cost(3) = 17

Choosing To Go To Vertex-B: Node-6 (Path A \rightarrow C \rightarrow B)

- From the reduced matrix of step-02, M[C,B] = 0
- Set row-C and column-B to ∞
- Set M[B,A] = ∞
- Now, resulting cost matrix is-

- Now, We reduce this matrix.
- Then, we find out the cost of node-6.

• Perform row and column reduction, the matrix is completely reduced.

Now, we calculate the cost of node-5.
 Cost(6)= cost(3) + Sum of reduction elements + M[C,B]
 = 17 + 2 + 0
 = 19

Choosing To Go To Vertex-D: Node-7 (Path A \rightarrow C \rightarrow D)

- From the reduced matrix of step-02, M[C,D] = 0
- Set row-C and column-D to ∞
- Set M[D,A] = ∞
- Now, resulting cost matrix is-

- We reduce this matrix.
- Then, we find out the cost of node-7
- Cost(7)= cost(3) + Sum of reduction elements + M[C,D]

$$= 17 + 4 + 0$$

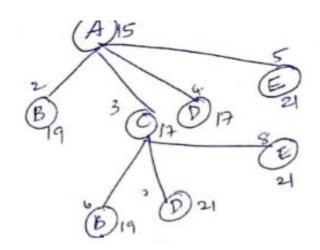
 $= 21$

Choosing To Go To Vertex-E: Node-8 (Path A \rightarrow C \rightarrow E)

- From the reduced matrix of step-02, M[C,E] = 4
- Set row-C and column-D to ∞
- Set M[E,A] = ∞
- Now, resulting cost matrix is-

	Α	В	С	D	Ε			Α	В	С	D	Ε
Α	C	00	00	00	-8		Α	~ ~~	00	00	00	∞3 ∕
В	0	00	00	2		After row	В	0	00	00	0	
С		00	00	00			С		00	00	00	
D	0	4	00	00		and column	D	0	4	00	00	
Ε		0	00	2		reduction	Е		0	00	0	∞)
				2								

- We reduce this matrix.
- Then, we find out the cost of node-8
- Cost(8)= cost(3) + Sum of reduction elements + M[C,E]
 = 17 + 2 + 4
 = 23



- Thus, we have-
- Cost(6) = 19 (for Path A \rightarrow C \rightarrow B)
- Cost(7) = 21 (for Path A \rightarrow C \rightarrow D)
- Cost(8) = 23 (for Path A \rightarrow C \rightarrow E)
- We choose the node with the lowest cost.
- Since cost for node-6 is lowest, so we prefer to visit node-6.
- Thus, we choose node-6 i.e. path $C \rightarrow B$.

Step-04:

- We explore vertex B from node-6.
- We start with the cost matrix at node-6 which is-Cost(6) = 25

Choosing To Go To Vertex-B: Node-9 (Path A \rightarrow C \rightarrow B \rightarrow D)

- From the reduced matrix of step-03, M[B,D] = 2
- Set row-B and column-D to ∞
- Set M[D,A] = ∞

•

• reduce this matrix, Then, we find out the cost of node-9 Cost(9) = cost(6) + Sum of reduction elements + M[B,D]= 19 + 6 + 2 = 27

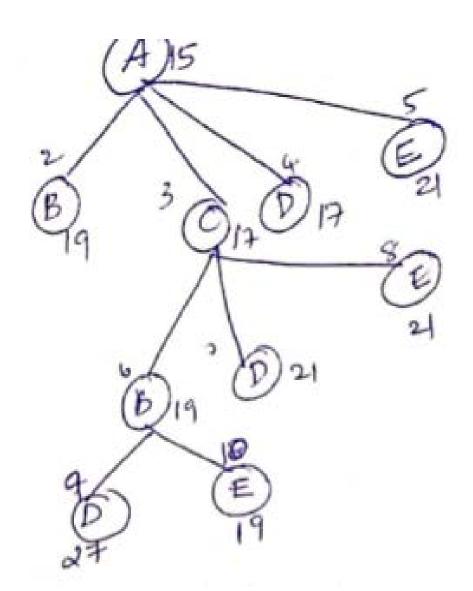
Choosing To Go To Vertex-B: Node-10 (Path A \rightarrow C \rightarrow B \rightarrow E)

- From the reduced matrix of step-03, M[B,E] = 0
- Set row-B and column-E to ∞
- Set M[E,A] = ∞

•

	Α	В	C	D	E			Α	В	С	D	Ε
Α	C	00	00	00	00		Α	·	00	00	00	60
В	0	00	00	2	0		В	00	00	00	00	
С		00	00	00	00	$\xrightarrow{\hspace*{1cm}}$	С	00	00	00	00	00
D	0	00	00	00	4		D	0	00	00	00	00
Ε	2	00	00	0	••		E	-	00	00	0	
	-							·				

• reduce this matrix, Then, we find out the cost of node-10 Cost(10) = cost(6) + Sum of reduction elements + M[B,E]= 19 +0 +0 = 19



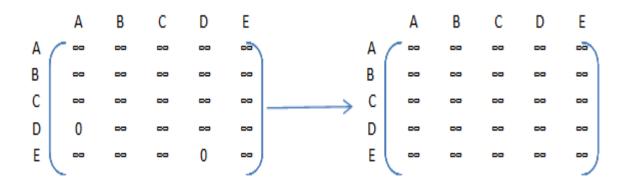
- Thus, we have-
- Cost(9) = 27 (for Path A \rightarrow C \rightarrow B \rightarrow D)
- Cost(10) = 19 (for Path A \rightarrow C \rightarrow B \rightarrow E)
- we choose the node with the lowest cost.
- Since cost for node-10 is lowest, so we prefer to visit node-10.
- Thus, we choose node-10 i.e. path B \rightarrow **E**.

Step-05:

Choosing To Go To Vertex-B: Node-11 (Path A \rightarrow C \rightarrow B \rightarrow E \rightarrow D)

- From the reduced matrix of step-03, M[E,D] = 0
- Set row-E and column-D to ∞
- Set M[D,A] = ∞

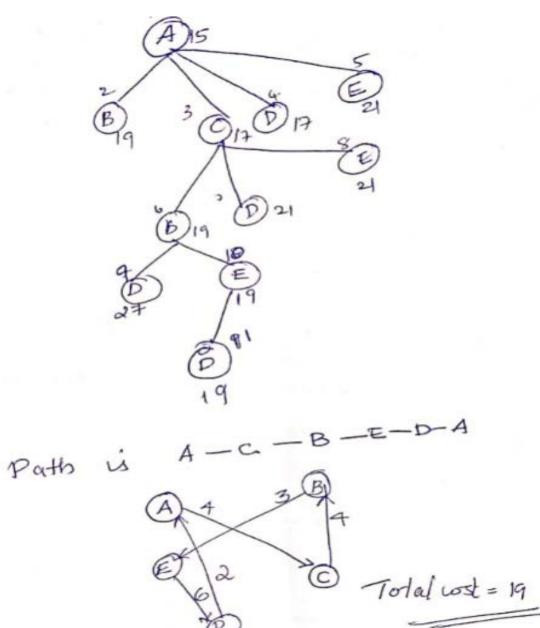
•



- Finally, the matrix is completely reduced.
- All the entries have become ∞.
- Now, we calculate the cost of node-11

Cost(11) = cost(10) + Sum of reduction elements + M[E,D]

$$= 19 + 0 + 0 = 19$$



- Thus,
- Optimal path is: $A \rightarrow C \rightarrow B \rightarrow E \rightarrow D \rightarrow A$
- Cost of Optimal path = 19

• END