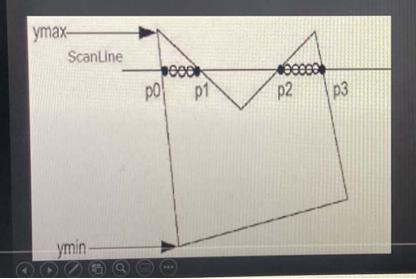
## Scanline Polygon filling Algorithm

Scanline filling is basically the filling up of polygons using horizontal lines or scanlines.

This algorithm works by intersecting scanlines with polygon edges and fills the polygon between pairs of intersections.



Step 1 – Find out the Ymin and Ymax from the given polygon.

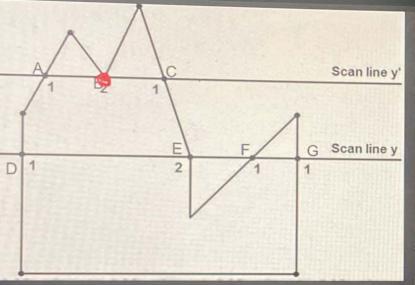
Step 2 – ScanLine intersects with each edge of the polygon from Ymin to Ymax. Name each intersection point of the polygon.

Example: consider previous figure, intersections are named as p0,p1,p2,p3

Step 3 – Sort the intersection point in the increasing order of X coordinate i.e. (p0,p1),(p1,p2),(p2,p3).

Step 4 – Fill all those pair of coordinates that are inside polygons and ignore the alternate pairs.

[ignore (p1,p2)]



### Scan line Y'

Intersection points:

A,B,C,Where B is a vertex and other ends of the 2 lines causes vertex B are on the same side of scan line, so take B two times .{A,B,B,C}

Pairs (A,B),(B,C)

#### Scan line Y

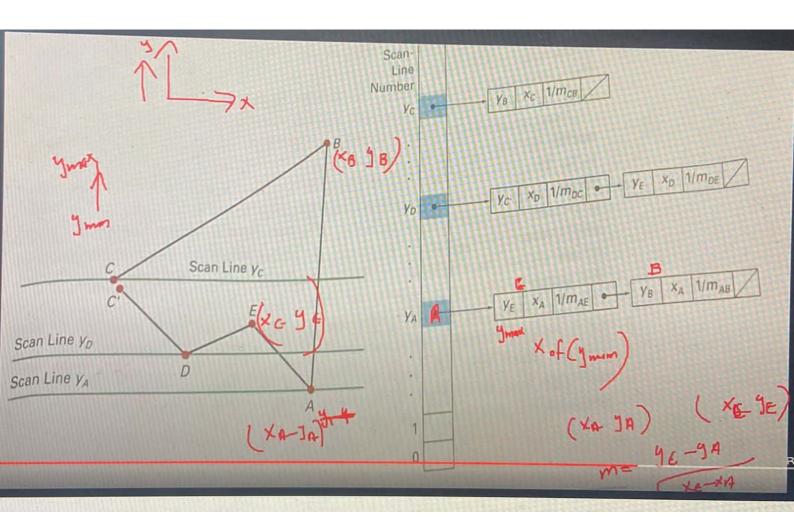
Intersection points:

D,E,F,G, Where E is a vertex and other ends of the 2 lines causes vertex E are on opposite side of scan line, so take E once . {D,E,F,G}

Pairs (D,E),(F,G)

### pecial cases of polygon vertices:

both lines intersecting at the vertex are on the same side of the scanline, consider it as two points. lines intersecting at the vertex are at opposite sides of the scanline, consider it as only one point.



To effectively perform a polygon fill, we can store the polygon boundary in a sorted edge table that contains all the information necessary to process the scan lines efficiently, Each entry in the table for a particular scan line contains the maximum y value for that edge, the x-intercept value (at the lower vertex) for the edge, and the inverse slope of the edge.

For each scan line, edges are in sorted order from left to right.

Next process the scan lines from the bottom of the polygon to its top, and produce an active edge list for each scan line crossing the polygon boundaries.

The active edge list for a scan line contains all edges crossed by that scan line, with iterative coherence calculations used to obtain the edge intersections.

# **Coherence Properties**

Coherence is simply that the properties of one part of a scene are related in some way to other parts of the scene so that the relationship can be used to reduce processing.

Slop of this polygon boundary can be expressed in terms of the scan line intersection coordinates:

Where, 
$$yk+1-yk=1$$
  
 $m = 1/(xk+1-xk)$ 

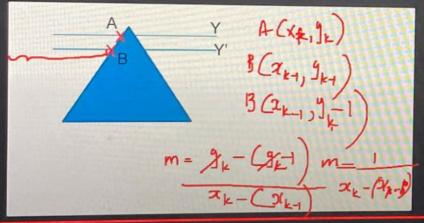
$$Xk+1=1/m+xk$$

$$(xk+1-xk)=1/m$$

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Adjacent scanlines are separated by a distance of 1, which means y difference is unity. y-y'=1

Using the properties of Coherence, after completing one scan line processing, we don't want to start from the beginning of the next scan line, instead, we can directly calculate the edge intersection point on the next scan line and proceed from that point.



In the given diagram, after processing scan line "y" start with "y", but here we don't want to start processing from the beginning of "y", instead we can directly find coordinate of intersection "B" using coherence property and start from that point of scan line "y", this will reduce complexity of algorithm.

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