Zackory Erickson

zackory@cmu.edu zackory.com Carnegie Mellon University Robotics Institute 5000 Forbes Avenue Pittsburgh, PA 15213

Current Positions

Assistant Professor, Carnegie Mellon University, Robotics Institute Sept 2021—present

Education

Ph.D., Robotics
Georgia Institute of Technology
Advisor: Charles C. Kemp

M.S., Computer Science
Georgia Institute of Technology
Advisor: Charles C. Kemp

B.S., Computer Science, Mathematics (double major)
University of Wisconsin-La Crosse

Honors and Awards

Undergraduate Research Grant, UW-La Crosse

NVIDIA Academic Hardware Grant 2022 "Adapting to Distribution Shift in Deformable Manipulation with Assistive Robots" **NVIDIA** Fellowship Finalist 2020 Best Student Paper Award, IEEE International Conference on Rehabilitation Robotics (ICORR) 2019 "Multidimensional Capacitive Sensing for Robot-Assisted Dressing and Bathing" Best Paper Award in Service Robotics Finalist, IEEE ICRA 2019 "Classification of Household Materials via Spectroscopy" 2016-2020 President's Fellowship, Georgia Tech 4th Heidelberg Laureate Forum 2016 Honorable Mention, NSF GRFP 2016 Strzelczyk Award 2016 Awarded to the top graduating senior in the College of Science and Health for academic achievement and service to the campus and community. MIT CONVERGE 2015 One of 18 prospective PhD students in the nation invited to tour MIT. 2015 Berkeley Engineering Preview Days One of 14 prospective PhD students nationwide invited to tour UC Berkeley. Grace Olwell Memorial Endowment Fund Scholarship 2015 **Xcel Energy Scholarship** 2015 John and Lois Storlie Scholarship in Computer Science 2014

2013

Scottish Rite Abbott Scholarship Dean's List, UW-La Crosse	2013 8 semesters
Mentoring	
PhD Students	
Yufei Wang, CMU, RI (co-advised with David Held)	2021-
Akhil Padmanabha, CMU, RI (co-advised with Carmel Majidi)	2021-
Angela Chen, CMU, MechE (co-advised with Melisa Orta Martinez)	2021-
$M.S.\ Students$	
Fukang Liu, CMU, MechE	2021-
Vaidehi Patil, CMU, RI	2021-
MRSD Project: Telepresence Mobile Manipulators, CMU, RI Students: Shivani Sivakumar, Jashkumar Diyora, Shruti Gangopadhyay, Prakhar Pradec Patel	2021- ep, Jigarkumar
Pratyusha Karnati, Georgia Tech, CS Current: Google X Robotics	2020-2021
Yijun (Esther) Gu, Georgia Tech, CS Current: PhD Student at Imperial College London	2019-2021
$Under graduate\ Students$	
Qin (Alicia) Wang, CMU, CS	2022-
Daphne Han, CMU, CB	2022-
Alexandra (Sasha) Wald, CMU, CS	2021-
Kavya Puthuveetil, Virginia Commonwealth University, BME	2021-
Samantha Mutiti, Georgia Tech, BME	2021
Holden Schaffer, Georgia Tech, CS	2020-2021
Siyan (Sylvia) Li, Georgia Tech, CS	2018-2019
Jiaqi (Julia) Chen, Georgia Tech, CS Current: PhD Student at ETH Zurich	2018
Katelyn Sosnowski, University of Arizona, BME Current: BME PhD Student at University of Arizona	2018
Mallak Taleb, University of Michigan, BME	2018
Bharat Srirangam, Georgia Tech, CS Current: Woot, Inc.	2018-2020
Eliot Xing, Georgia Tech, CE	2017-
Vamsee Gangaram, Georgia Tech, CS Current: Microsoft	2017-2020
Jong Hwa (Austin) Jang, Georgia Tech, CS	2017-2018
Maggie Collier, University of Alabama at Birmingham, BME	2017

Nathan Luskey, Georgia Tech, BME 2017 - 2018Current: MSCS student at CMU Teaching 16-741: Mechanics of Manipulation, CMU Fall 2022 16-887: Robotic Caregivers and Intelligent Physical Collaboration, CMU Spring 2022 Robotic Caregivers (BMED 4833/8813), Co-instructor, Georgia Tech Spring 2021 Robotic Caregivers (BMED 4803/8813), Co-developer and instructor, Georgia Tech Spring 2020 Invited Talks Robotic Caregiving and Human Interaction 16-311: Introduction to Robotics 2022 05-899: Special Topics in HCI: Accessibility 2021 Capacitive Servoing for Physically Assistive Robotics 4th Workshop on Proximity Perception in Robotics, IROS 2021 Robotic Caregivers—Sensing, Simulation, and Physical Human-Robot Interaction Carnegie Mellon University 2021 University of Pennsylvania 2021 Physics-based Cloth Simulation and Learning Towards Robotic Caregiving 2021 Workshop on Representing and Manipulating Deformable Objects, ICRA Robotic Caregivers—Recent Advances in Physics-based Simulation Medical Robotics Club, Georgia Tech 2021 Robot-Assisted Dressing Workshop on Smart and Robotic Homes, RESNA 2018 Multimodal Anomaly Detection Mathematics Colloquium, UW-La Crosse 2015 Academic Service Co-Chair — ICRA 2022 session on Physical HRI 2022 Area Chair — Conference on Robot Learning (CoRL) 2022 Associate Editor IEEE Conference on Robot and Human Interactive Communication (RO-MAN) 2021, 2022 T-RO, ICRA, IROS, RA-L, Humanoids, HRI, Sensors, RO-MAN, Science Robotics ICRA Workshop Organizer Learning for Caregiving Robots 2021 Seminar Organizer, Georgia Tech Life as a Professor: Student Advising and Recruiting 2020 Life as a Professor: Funding 101 2019 Life as a Professor: Starting a Start-Up 2018

Current: Robotics PhD student at CMU, NDSEG fellow

Panelist Graduate Intro to Robotics Research, Georgia Tech Summer Undergraduate Research Experience (SURE) Program, Georgia Tech	2018 2017–2019
RoboGrads (robotics graduate student organization), Georgia Tech Vice President for Robotics PhD President	2019–2020 2018–2019
Outreach	
RoboGrads, Vice President of Outreach, Georgia Tech Organized K-12 outreach events for over 30 robotics labs at Georgia Tech	2017–2018
Biomedical Robotics Club, Mentor, Georgia Tech Mentoring over 50 undergraduate students in how to research and build assistive devices and robots for people with impairments.	2016–2019
FIRST Lego League, Judge	2015-2021
CS Outreach & Diversity Club, UW–La Crosse Organizing CS and robotics events for K-12 students.	2015–2016
FIRST Robotics, Mentor, Central High School and Holmen High School	2012-2016
Peer-Reviewed Publications (Conferences and Journals)	
[1] Bodies Uncovered: Learning to Manipulate Real Blankets Around People via Phulations	ysics Sim-

IEEE Robotics and Automation Letters (RA-L), 2022 Kavya Puthuveetil, Charles C. Kemp, and Zackory Erickson

[2] Assistive VR Gym: Interactions with Real People to Improve Virtual Assistive Robots IEEE Conference on Robot and Human Interactive Communication (RO-MAN), 2020 Zackory Erickson*, Yijun Gu*, and Charles C. Kemp

[3] Multimodal Material Classification for Robots using Spectroscopy and High Resolution Texture Imaging

IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2020 Zackory Erickson, Eliot Xing, Bharat Srirangam, Sonia Chernova, and Charles C. Kemp

[4] Bodies at Rest: 3D Human Pose and Shape Estimation from a Pressure Image using Synthetic Data

IEEE Conference on Computer Vision and Pattern Recognition (CVPR), 2020 (Oral) Henry M. Clever, Zackory Erickson, Ariel Kapusta, Greg Turk, C. Karen Liu, and Charles C. Kemp

[5] Assistive Gym: A Physics Simulation Framework for Assistive Robotics IEEE International Conference on Robotics and Automation (ICRA), 2020 Zackory Erickson, Vamsee Gangaram, Ariel Kapusta, C. Karen Liu, and Charles C. Kemp

[6] Learning to Collaborate from Simulation for Robot-Assisted Dressing IEEE Robotics and Automation Letters (RA-L), 2020 Alexander Clegg, Zackory Erickson, Patrick Grady, Greg Turk, Charles C. Kemp, and C. Karen Liu

[7] Active Robot-Assisted Feeding with a General-Purpose Mobile Manipulator: Design, Evaluation, and Lessons Learned

Robotics and Autonomous Systems, 2020

Daehyung Park, Yuuna Hoshi, Harshal P. Mahajan, Ho Keun Kim, Zackory Erickson, Wendy A. Rogers, Charles C. Kemp

- [8] Multidimensional Capacitive Sensing for Robot-Assisted Dressing and Bathing IEEE International Conference on Rehabilitation Robotics (ICORR), 2019 (Best Student Paper) Zackory Erickson, Henry M. Clever, Vamsee Gangaram, Greg Turk, C. Karen Liu, and Charles C. Kemp
- [9] Classification of Household Materials via Spectroscopy IEEE Robotics and Automation Letters (RA-L), 2019 (Best Paper Award in Service Robotics Finalist at ICRA 2019) Zackory Erickson, Nathan Luskey, Sonia Chernova, and Charles C. Kemp
- [10] Personalized Collaborative Plans for Robot-Assisted Dressing via Optimization and Simulation

Autonomous Robots, 2019

Ariel Kapusta, Zackory Erickson, Henry M. Clever, Wenhao Yu, C. Karen Liu, Greg Turk, and Charles C. Kemp

- [11] Autonomous Tool Construction Using Part Shape and Attachment Prediction Robotics: Science and Systems (RSS), 2019 Lakshmi Nair, Nithin Srikanth, Zackory Erickson, Sonia Chernova
- [12] Deep Haptic Model Predictive Control for Robot-Assisted Dressing
 IEEE International Conference on Robotics and Automation (ICRA), 2018
 Zackory Erickson, Henry M. Clever, Greg Turk, C. Karen Liu, and Charles C. Kemp
- [13] Tracking Human Pose During Robot-Assisted Dressing using Single-Axis Capacitive Proximity Sensing

IEEE Robotics and Automation Letters (RA-L), 2018 Zackory Erickson, Maggie Collier, Ariel Kapusta, and Charles C. Kemp

- [14] 3D Human Pose Estimation on a Configurable Bed from a Pressure Image IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2018 Henry M. Clever, Ariel Kapusta, Daehyung Park, Zackory Erickson, Yash Chitalia, Charles C. Kemp
- [15] Semi-Supervised Haptic Material Recognition for Robots using Generative Adversarial Networks

Conference on Robot Learning (CoRL), 2017 Zackory Erickson, Sonia Chernova, and Charles C. Kemp

[16] What Does the Person Feel? Learning to Infer Applied Forces During Robot-Assisted Dressing

IEEE International Conference on Robotics and Automation (ICRA), 2017 Zackory Erickson, Alexander Clegg, Wenhao Yu, Greg Turk, C. Karen Liu, and Charles C. Kemp

- [17] Learning to Navigate Cloth using Haptics IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2017 Alexander Clegg, Wenhao Yu, Zackory Erickson, C. Karen Liu, and Greg Turk
- [18] A Multimodal Execution Monitor with Anomaly Classification for Robot-Assisted Feeding IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2017 Daehyung Park, Hokeun Kim, Yuuna Hoshi, Zackory Erickson, Ariel Kapusta, and Charles C. Kemp
- [19] Multimodal Execution Monitoring for Anomaly Detection During Robot Manipulation IEEE International Conference on Robotics and Automation (ICRA), 2016 Daehyung Park, Zackory Erickson, Tapomayukh Bhattacharjee, and Charles C. Kemp