Graph Algorithms-IV

SINGLE-SOURCE SHORTEST PATHS

Introduction

Generalization of BFS to handle weighted graphs

- ▶ Direct Graph G = (V, E), edge weight $fn ; w : E \rightarrow R$
- In BFS w(e)=I for all e ∈ E

Weight of path $p = v_1 \rightarrow v_2 \rightarrow ... \rightarrow v_k$ is

$$w(p) = \sum_{i=1}^{k-1} w(v_i, v_{i+1})$$

Shortest Path

Shortest Path = Path of minimum weight

$$\delta(u,v) = \begin{cases} \min\{\omega(p) : u \stackrel{p}{\leadsto} v\}; & \text{if there is a path from u to v,} \\ \infty & \text{otherwise.} \end{cases}$$

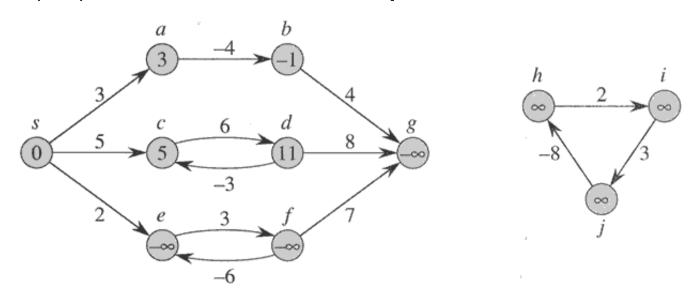
Shortest-Path Variants

Shortest-Path problems

- Single-source shortest-paths problem: Find the shortest path from s to each vertex v. (e.g. BFS)
- ▶ Single-destination shortest-paths problem: Find a shortest path to a given destination vertex t from each vertex v.
- Single-pair shortest-path problem: Find a shortest path from u to v for given vertices u and v.
- \blacktriangleright All-pairs shortest-paths problem: Find a shortest path from u to v for every pair of vertices u and v.

Negative-weight edges

- No problem, as long as no negative-weight cycles are reachable from the source
- ▶ Otherwise, we can just keep going around it, and get $w(s, v) = -\infty$ for all v on the cycle.



Relaxation

- ▶ Maintain d[v] for each $v \in V$
- ▶ d[v] is called shortest-path weight estimate

```
INIT(G, s)

for each v \in V do

d[v] \leftarrow \infty

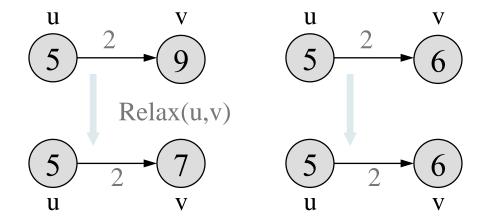
\pi[v] \leftarrow NIL

d[s] \leftarrow 0
```

Relaxation

RELAX(u, v) if d[v] > d[u]+w(u,v) then $d[v] \leftarrow d[u]+w(u,v)$ $\pi[v] \leftarrow u$

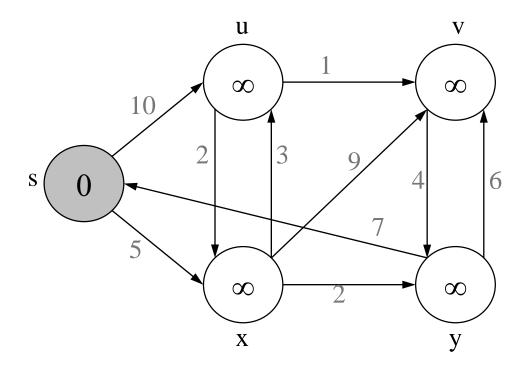
The process of relaxing an edge(u,v) consists of testing whether we can improve the shortest path to v found so far by going through u, If so, update v. d and d v. d

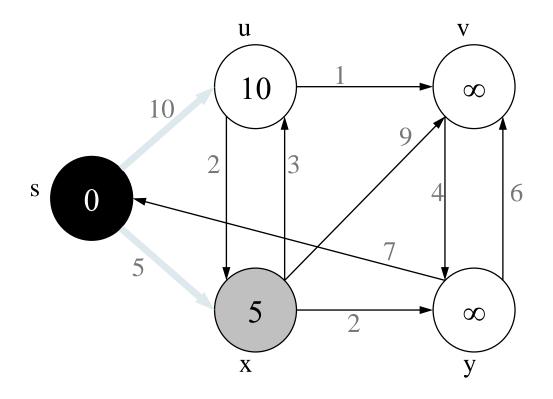


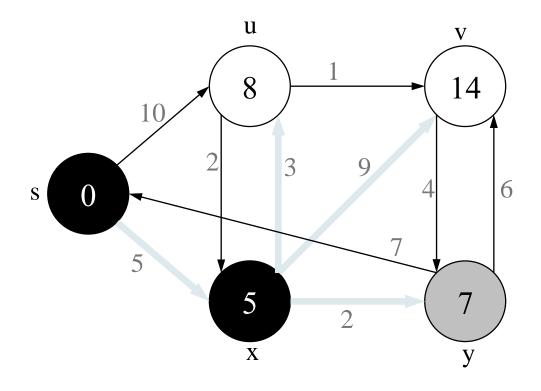
- Non-negative edge weight
- Like BFS: If all edge weights are equal, then use BFS, otherwise use this algorithm
- Use Q = priority queue keyed on d[v] values (note: BFS uses FIFO)

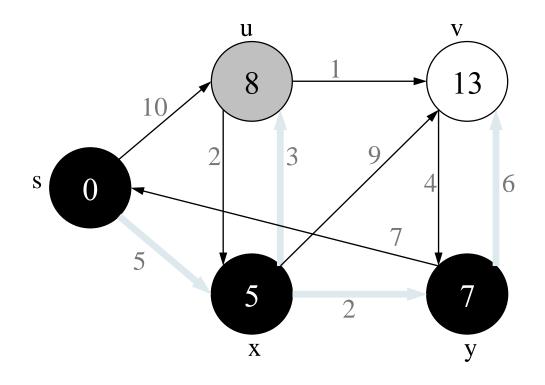
Total time: O(V+VlgV + ElgV) = O(ElgV)

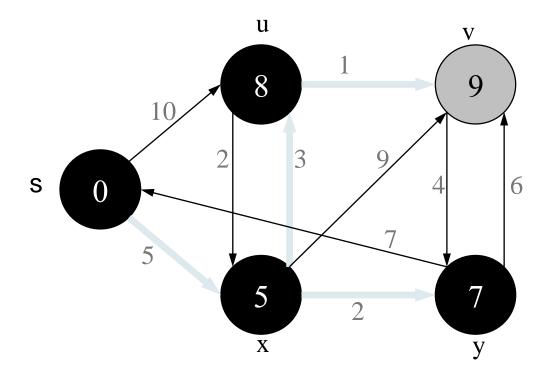
```
DIJKSTRA(G, s)
    INIT(G, s)
                               O(V)
   S←Ø
                           O(V) if Q is implemented as a
   Q←V[G]
                                  min-heap
                                                       Min-heap
    while Q #Ø do
                                                      operations:
       u←EXTRACT-MIN(Q)
                                   Takes O(IgV)
                                                       O(VlgV)
       S←S U {u}
       for each v \in Adj[u] do
                                      Executed O(E) times
                                                           O(ElgV)
          RELAX(u, v,w)
                                   Takes O(IqV)
```

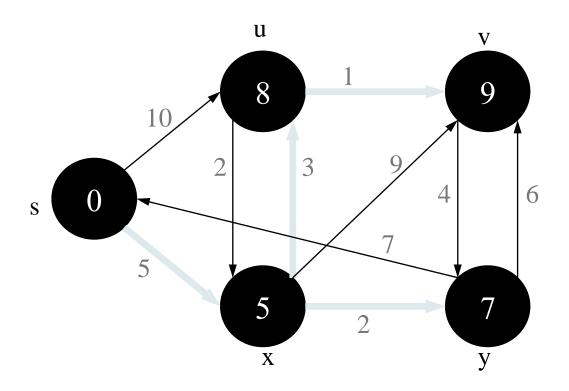












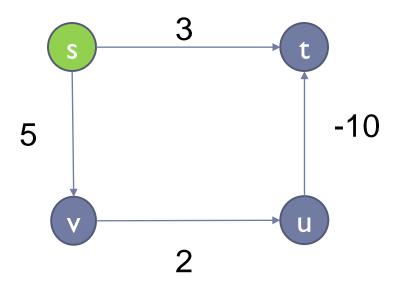
Observe:

- Each vertex is extracted from Q and inserted into S exactly once
- Each edge is relaxed exactly once
- S = set of vertices whose final shortest paths have already been determined
 - i.e., $S = \{v \in V: d[v] = \delta(s, v) \neq \infty \}$

- Similar to BFS algorithm: S corresponds to the set of black vertices in BFS which have their correct breadth-first distances already computed
- Greedy strategy: Always chooses the closest(lightest) vertex in Q = V-S to insert into S
- Relaxation may reset d[v] values

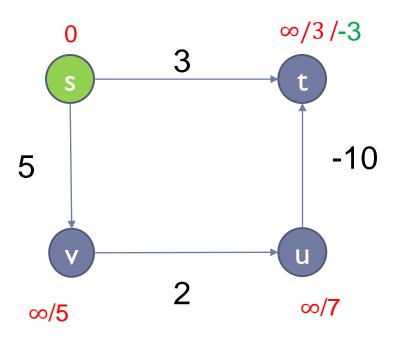
- Similar to Prim's MST algorithm: Both algorithms use a priority queue to find the lightest vertex outside a given set S
- Insert this vertex into the set
- Adjust weights of remaining adjacent vertices outside the set accordingly

Dijkstra's Algorithm-Disadvantages



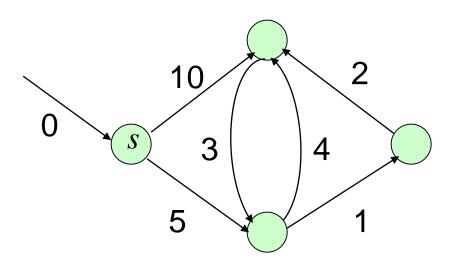
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Dijkstra's Algorithm-Disadvantages

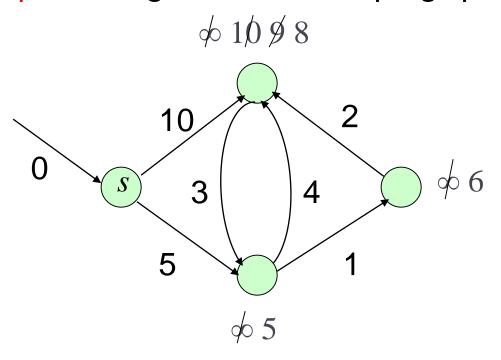


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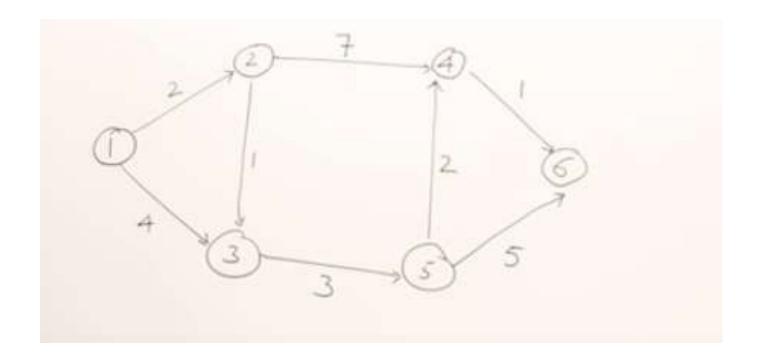
Example: Run algorithm on a sample graph



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Problem



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All-Pair Shortest Path

The Floyd-Warshall Algorithm

A recursive solution to the all-pairs shortest paths problem:

Let d_{ij}(k) be the weight of a shortest path from vertex i to vertex j with all intermediate vertices in the set {1,2,...,k}. A recursive definition is given by

$$d_{ij}^{(k)} = \begin{cases} w_{ij} & \text{if } k=0, \\ \min(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}) & \text{if } k \geq 1. \end{cases}$$

The matrix $D^{(n)}=(d_{ij}^{(n)})$ gives the final answer- $d_{ij}^{(n)}=\delta(i,j)$ for all i,j \in V-because all intermediate vertices are in the set {1,2,...,n}.

Computing the shortest-path weights bottom up:

```
FLOYD-WARSHALL(W)
\triangleright n \leftarrow rows[W]
▶ D<sup>(0)</sup> ← W
\blacktriangleright for k \longleftarrow I to n
         do
                 for i \leftarrow I to n
                          do for j \leftarrow I to n
                                   d_{ii}^{(k)} \leftarrow \min(d_{ii}^{(k-1)}, d_{ik}^{(k-1)} + d_{ki}^{(k-1)})
```

▶ return D⁽ⁿ⁾

