

# Weekly Homework 3

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CS 1675: Intro to Machine Learning

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**Problem 1.** Logistic regression model

- (a) See normalized data
- (b) N/A
- (c) See code
- (d) Miss-classification errors: Train = .295, Test = .4192

Confusion Matrix

Training		Testing	
273	93	79	52
66	107	55	43

Sensitivity: .5896

Specificity: .4526

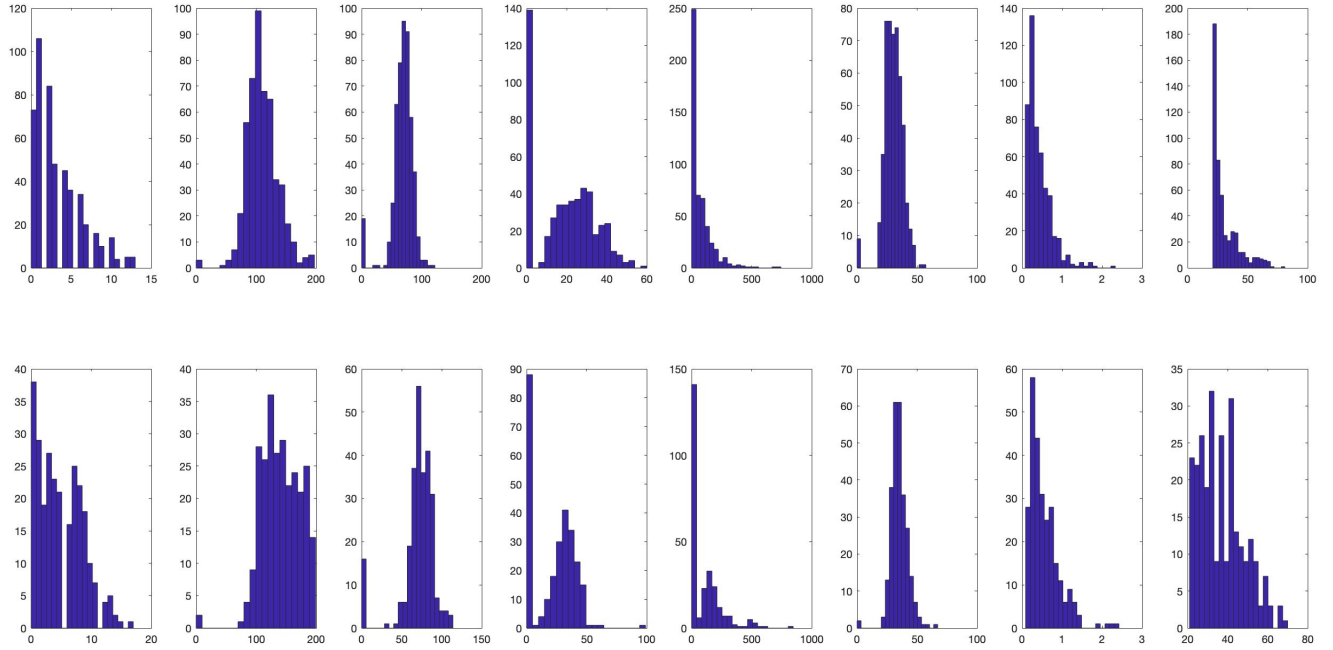
- (e) Experimenting with the learning rate and number of iterations yielded a test error that was consistently around 0.35. I also found that initializing the test weights produced more inconsistent results. The best miss-classification error I got for testing was .254 and for training it was .334 with 15,000 iterations.

**Problem 2.1.** Naive Bayes model: Exploratory data analysis

- (a) Histograms

Top row are attributes 1-8 with Class = 0

Bottom row are attributes 1-8 with Class = 1



(b) Attributes 1 & 5 have distributions similar to the Gamma distribution and attributes 2, 3, 4, 6, 7 & 8 have distributions similar to a normal distribution.

**Problem 2.2.** Learning of the Naive Bayes classifier

(a) See Code

(b) Parameters:

Class priors:  $p(y=0) = .65$ ,  $p(y=1) = .35$

Class Conditionals: Standard Deviation is in columns 1 & 3 and the Mean is listed in columns 2 & 4

Class 0		Class 1	
3.29	0	4.87	0
109.9	26.14	141.25	31.93
68.18	18.06	70.82	21.49
19.66	14.89	22.16	17.67
68.79	0	100.33	0
30.30	7.68	35.14	7.26
0.429	0	0.55	0
31.19	0	37.06	0

**Problem 2.3.** Classification with the Naive Bayes model

(a) See Code

(b) Mean classification error for training = .223 and testing = .205

### Confusion Matrix

Training		Testing	
294	80	142	28
45	120	19	40

Sensitivity: .89

Specificity: .59

(c) The Naive Bayes Algorithm had a significantly smaller miss-classification error (.205) than the Logistic Regression Algorithm (.419). This shows that for at least this data set, the Naive Bayes Algorithm worked better.

### **Problem 3.** ROC analysis

I was not able to get this to work properly. However, the underlying principle to this problem is to generate the value for  $p(y=1-x)$  for each point then pass the true value, the probabilities, and 1 to the ROC function and it does everything else.