<u>Stage 1: compressor curve</u> – rough test of the outlet flow rate against the compressor pressure for a range of 1 Bar to 3 Bars in steps of 0.5 Bar gauge. This will be used for comparison against the compressors used for calculations.

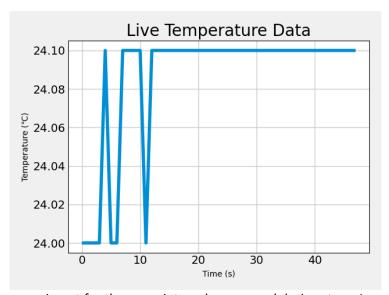
Compressor	Flowrate
Pressure (Bar)	
1	Χ
1.5	Χ
2	Χ
2.5	Χ
3	X

<u>Stage 2: Temperature and pressure testing with GY-68 BMP180</u> – measure the temperature and pressure variation within the robot for varying compressor pressures.

Install python if not already installed – install python by installing the pip package manager https://www.liquidweb.com/kb/install-pip-windows/

Modules – pyserial from https://pypi.org/project/pypi.org/project/pypi.org/project/pypi.org/project/matplotlib/, schedule from https://pypi.org/project/matplotlib/, schedule from https://pypi.org/project/schedule/

- 1. Attach the barometric pressure sensor within the robot
- 2. Run the BMP180withESP8266.ino file
- Run theBMP180Data.py script
 Python communicationpiarduino.py –port "COM4" –baudrate 115200 –outFile
 "2barResults.csv"
 - --port is the port for serial communication
 - --baudrate is the baudrate that the esp8266 is transferring data at
 - --outputFileName is the output filename, this is a csv file
- 4. End the test once the temperature curve has reached a steady equilibrium. This can be viewed by running the liveDataPlotter.py script Python liveDataPlotter.py –dataFile "2barResults.csv"



5. Repeat the experiment for the same intervals measured during stage 1