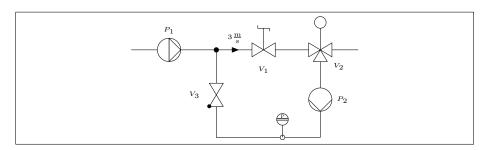
## Tikz P&ID circuit extension

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January 17, 2018

```
\usetikzlibrary { circuits }
   \usetikzlibrary { circuits .pid.ISO14617} \usetikzlibrary { positioning , calc }
6 \begin{tikzpicture}[
     circuit pid ISO14617,
     every info/.style=\{font=\langle tiny \}\}
    \dot{draw}(0,0) to [pump={displacement,name=P1,info=$P_1$}](2,0)
    to [branch={name=T1}](2.5,0)
to [flow direction=\{\text{speed}=3\}\](3,0)
   to [valve={name=V1,info'=$V_{1}$}](4,0)
to [three way valve={name=V2,info=belowright:$V_{2}$}](6,0);
    \label{eq:continuous_loss} $$ \operatorname{V2.south}$ to [pump={name=P2,info=\$P-2\$}]++(0,-2) $$
    to [measurementpoint=\{name=M1\}]++(-2,0)
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   to (\currentcoordinate - | T1)
    to [valve={nonreturn,info=$V_3$}](T1);
    \node[measurementdevice=localcontrol room, at=M1,measure=P]{};
    \node[turning actuator, at=V1]{};
    \node[automaticoperation, at=V2]{};
23 \end{tikzpicture}
```



Listing1: P&ID example code