	doc_1		doc_2		decision	id
cases	authors	M. A. Nabian H. Meidani	authors	Mohammad Amin Nabian Hadi Meidani	DUPLICATES 64	
	title	Adaptive Physics-Informed Neural Networks for Markov-Chain Monte Carlo	title	Adaptive Physics-Informed Neural Networks for Markov-Chain Monte Carlo		
	publication_date	2020-08-03 00:00:00	publication_date	2020-08-03 00:00:00		
	source	SupportedSources.SEMANTIC_SCHOLAR	source	SupportedSources.INTERNET_ARCHIVE		,
	journal	ArXiv	journal			
	volume	abs/2008.01604	volume			.
	doi		doi			.
	urls	https://www.semanticscholar.org/paper/eac719a1a9974241791bcaadc923be4741c89da9	urls	• https://web.archive.org/web/20200812132913/https://arxiv.org/pdf/2008.01604v1.pdf		64
	id	id1423807405709533101	id	id3504612614056425912		
	abstract	In this paper, we propose the Adaptive Physics-Informed Neural Networks (APINNs) for accurate and efficient simulation-free Bayesian parameter estimation via Markov-Chain Monte Carlo (MCMC). We specifically focus on a class of parameter estimation problems for which computing the likelihood function requires solving a PDE. The proposed method consists of: (1) constructing an offline PINN-UQ model as an approximation to the forward model; and (2) refining this approximate model on the fly using samples generated from the MCMC sampler. The proposed APINN method constantly refines this approximate model on the fly and guarantees that the approximation error is always less than a user-defined residual error threshold. We numerically demonstrate the performance of the proposed APINN method in solving a parameter estimation problem for a system governed by the Poisson equation.	abstract	In this paper, we propose the Adaptive Physics-Informed Neural Networks (APINNs) for accurate and efficient simulation-free Bayesian parameter estimation via Markov-Chain Monte Carlo (MCMC). We specifically focus on a class of parameter estimation problems for which computing the likelihood function requires solving a PDE. The proposed method consists of: (1) constructing an offline PINN-UQ model as an approximation to the forward model; and (2) refining this approximate model on the fly using samples generated from the MCMC sampler. The proposed APINN method constantly refines this approximate model on the fly and guarantees that the approximation error is always less than a user-defined residual error threshold. We numerically demonstrate the performance of the proposed APINN method in solving a parameter estimation problem for a system governed by the Poisson equation.		
	versions		versions			,