

cases	doc_1		doc_2		decision	id
					DUPLICATES	116
			authors	<ul style="list-style-type: none">Nir ShlezingerNariman FarsadYonina C. EldarAndrea J. Goldsmith		
	authors	<ul style="list-style-type: none">Nir ShlezingerNariman FarsadYonina C. EldarAndrea Goldsmith	title	Learned Factor Graphs for Inference from Stationary Time Sequences		
			publication_date	2021-12-24 00:00:00		
	title	Learned Factor Graphs for Inference From Stationary Time Sequences	source	SupportedSources.INTERNET_ARCHIVE		
	publication_date	2021-01-01 00:00:00	journal			
	source	SupportedSources.OPENALEX	volume			
	journal	IEEE Transactions on Signal Processing	doi			
	volume	70	urls	<ul style="list-style-type: none">https://web.archive.org/web/20200914212227/https://arxiv.org/pdf/2006.03258v1.pdf		
	doi	10.1109/tsp.2021.3139506	id	id1925174317138678977		
	urls	<ul style="list-style-type: none">https://openalex.org/W4285512363https://doi.org/10.1109/tsp.2021.3139506http://arxiv.org/pdf/2006.03258	abstract	The design of methods for inference from time sequences has traditionally relied on statistical models that describe the relation between a latent desired sequence and the observed one. A broad family of model-based algorithms have been derived to carry out inference at controllable complexity using recursive computations over the factor graph representing the underlying distribution. An alternative model-agnostic approach utilizes machine learning (ML) methods. Here we propose a framework that combines model-based algorithms and data-driven ML tools for stationary time sequences. In the proposed approach, neural networks are developed to separately learn specific components of a factor graph describing the distribution of the time sequence, rather than the complete inference task. By exploiting stationary properties of this distribution, the resulting approach can be applied to sequences of varying temporal duration. Learned factor graph can be realized using compact neural networks that are trainable using small training sets, or alternatively, be used to improve upon existing deep inference systems. We present an inference algorithm based on learned stationary factor graphs, which learns to implement the sum-product scheme from labeled data, and can be applied to sequences of different lengths. Our experimental results demonstrate the ability of the proposed learned factor graphs to learn to carry out accurate inference from small training sets for sleep stage detection using the Sleep-EDF dataset, as well as for symbol detection in digital communications with unknown channels.		
	id	id5872381892201788489	versions			
	abstract					
	versions					