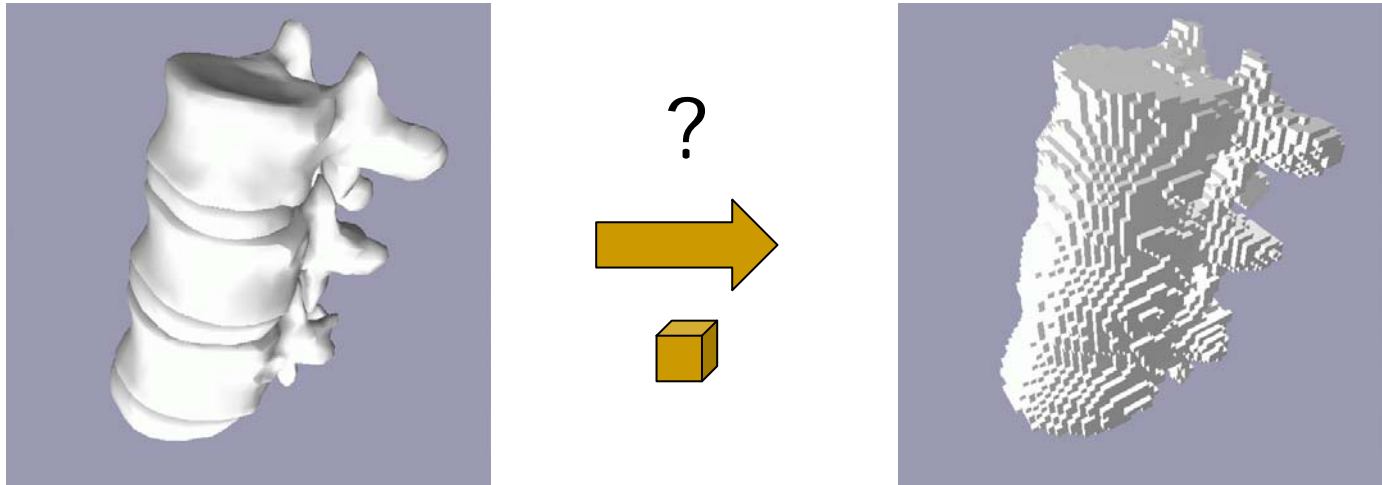


A Low Cost Antialiased Space Filled Voxelization Of Polygonal Objects

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Previous works

■ Objectives



- Transform a polygonal object into a set of voxel

Previous works

■ Objectives

- ❑ space filled voxelization
- ❑ take into account holes or tunnels (image)
- ❑ Decrease aliasing problems

Previous works

■ Objectives ...

- ❑ Fast computation (although not in real time),
- ❑ Low memory usage.
- ❑ Using this method on a personal computer without specific graphics hardware.

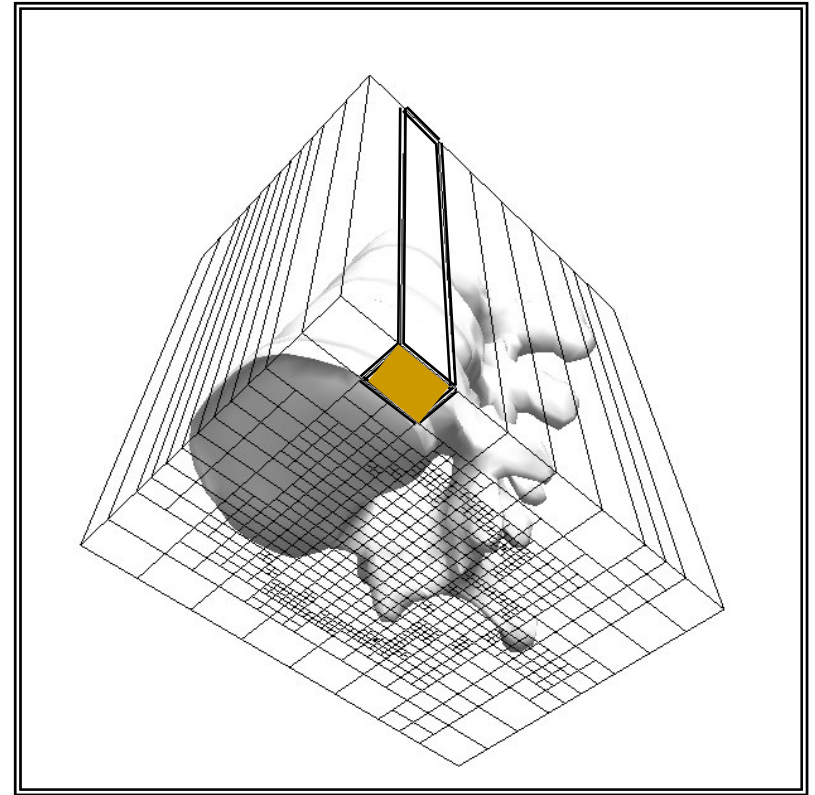
⇒ None of the existing methods matches all of our criteria

Our method

- based on an optimized raycasting through the faces of the polygonal object
- Two steps:
 - a space partitioning of the object faces
 - voxelization by raycasting through the space partitioned faces.

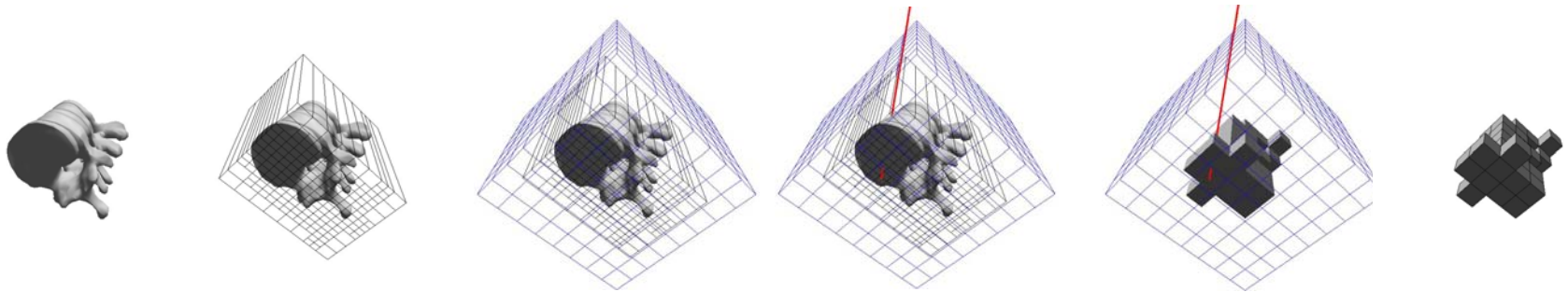
Space partitioning

1. Computation of the object bounding box
2. Subdivision of the bounding box as a quadtree of boxes
3. Each leaf of the quadtree contains a list of faces



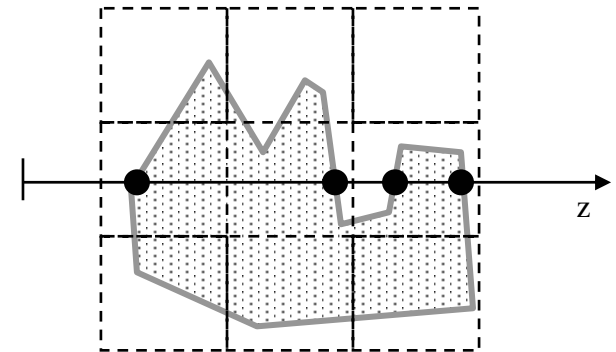
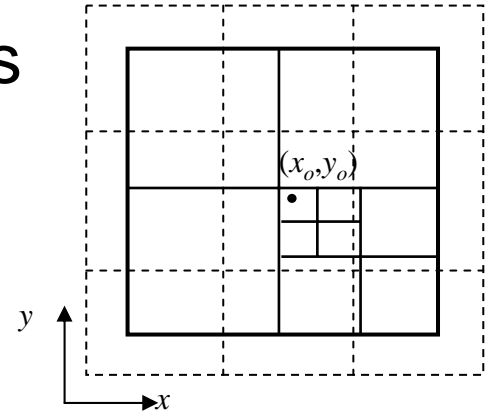
Voxelization

- Steps for the voxelization
 - ❑ Computation of a grid of voxels around the object
 - ❑ Raycasting
 - ❑ Inside/ outside determination



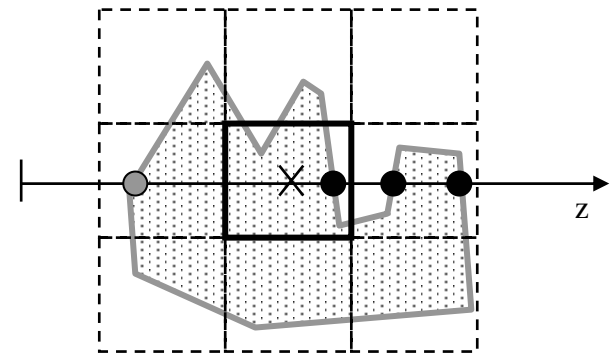
Voxelization- Raycasting

- 3D grid composed of $n \times m \times p$ cells
- Only $n \times m$ rays are cast
- For each ray
 - Detect the intersected leaf in the quadtree
 - Compute intersections between ray and faces contained in this list leaf
 - Fill a sorted list with z-intersection between the ray and faces.

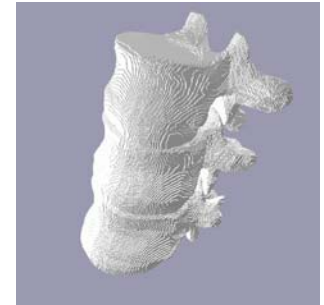
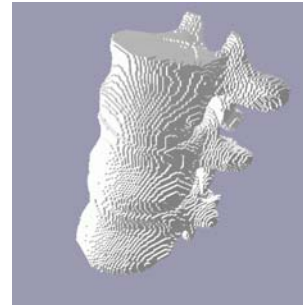
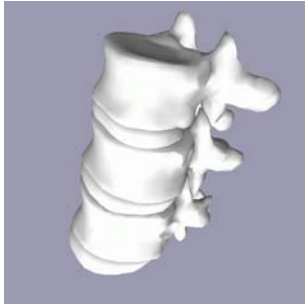


Voxelization- Inside/ outside determination

- For each voxel of the 3D Grid
 - ❑ Compute the z-coordinate of the center
 - ❑ Count the number of values in the sorted list that are greater than this z-coordinate
 - ❑ If this number is even
 - then the voxel is outside the object (0)
 - ❑ else
 - the voxel is inside the object (1)



Voxelization- Results

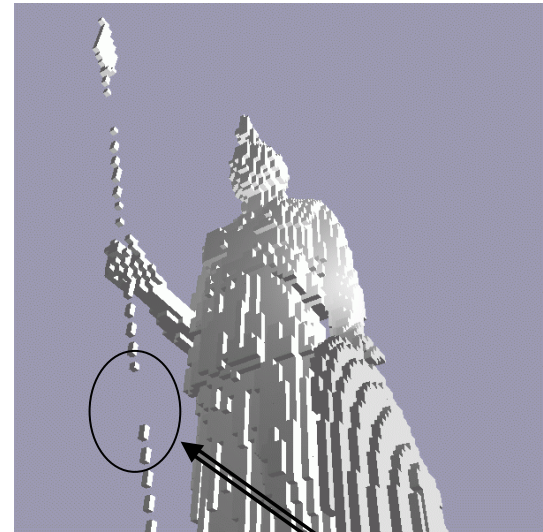


Resolution	64^3	128^3	256^3
Time (in sec.)	0,17	0,30	1

* Voxelization of polygonal object made of **10444** faces
Results obtained on an **Intel XEON 2.66 GHz with 512 Mo.**

Voxelization- Problems

- Voxelization of a polygonal object is a 3D sampling process
 - ⇒ aliasing problems (missing details, disconnected parts)



- Solution : oversampling

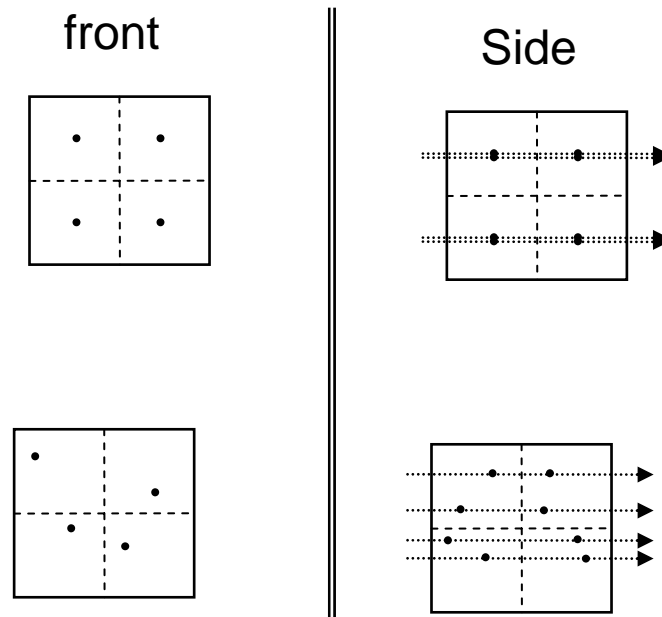
Lack of details

Antialiasing

- Instead of casting only one ray through a row of voxels, we cast several rays.
- Two solutions for oversampling

□ Uniform

□ Stochastic



Antialiasing

- Two ways for the oversampling process
 - Binary values
 - Grey level

Antialiasing- Results with binary values

**Polygonal
model**



**voxelization
without
antialiasing**



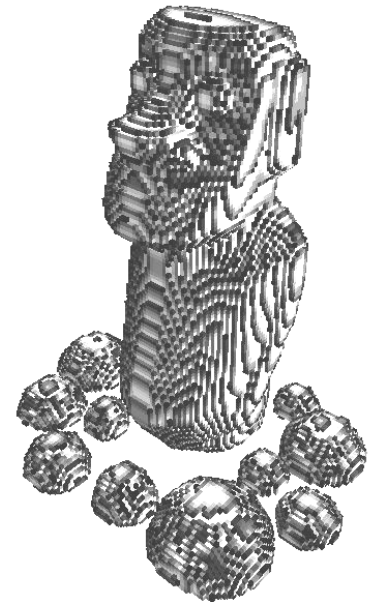
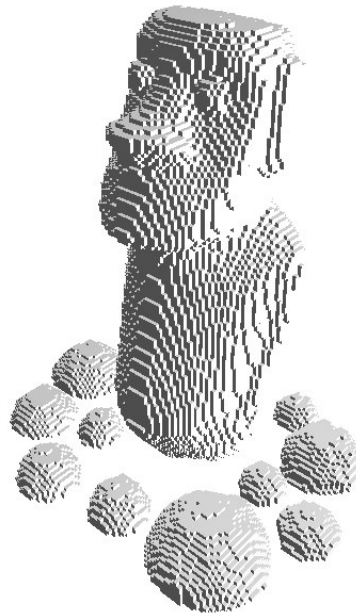
**uniform 2x2x2
oversampling**



**uniform 4x4x4
oversampling**



Antialiasing- Results with grey values



Antialiasing- Results with grey values

- Using the grey value for the marching cube

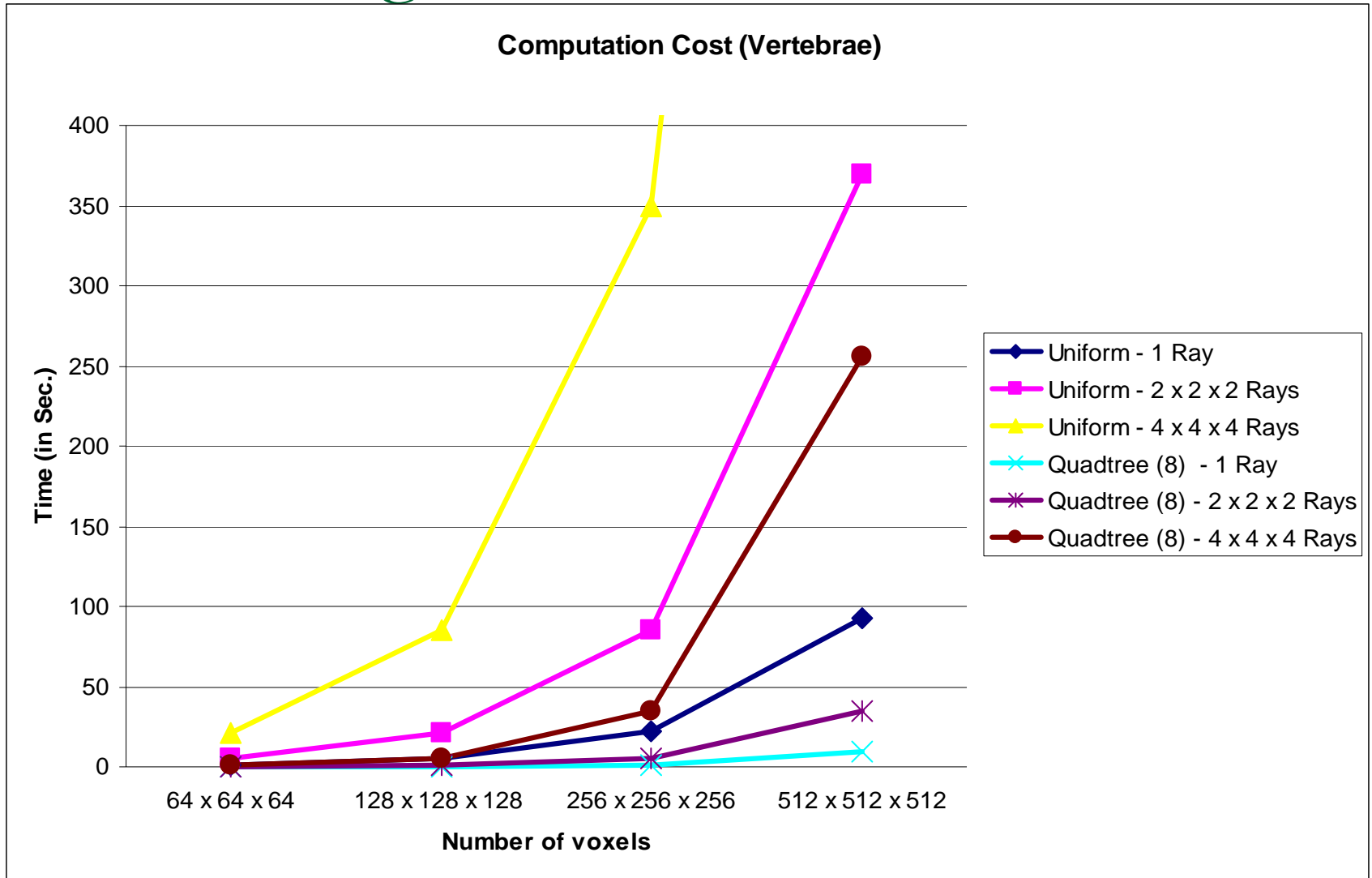


Marching Cubes with binary values



Marching Cubes with grey values

Antialiasing- Results



Conclusion

- voxelization method for polygonal objects based on an optimized raycasting.
- allows to fill the inner space of the object with voxels.
- Aliasing problems inherent to the sampling process of voxelization are tackled.
- Not real-time but fast enough to provide results within few seconds for polygonal objects made of several thousands of faces for large voxelizations such as 512^3 .

Future Works

- As our method is based on a raycasting, it can be easily extended to the voxelization of other object (implicit surfaces, nurbs or analytic objects)
- Take into account polygonal objects that are not correctly closed, with missing faces.
- Compute adaptively the voxels in an octree.

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