

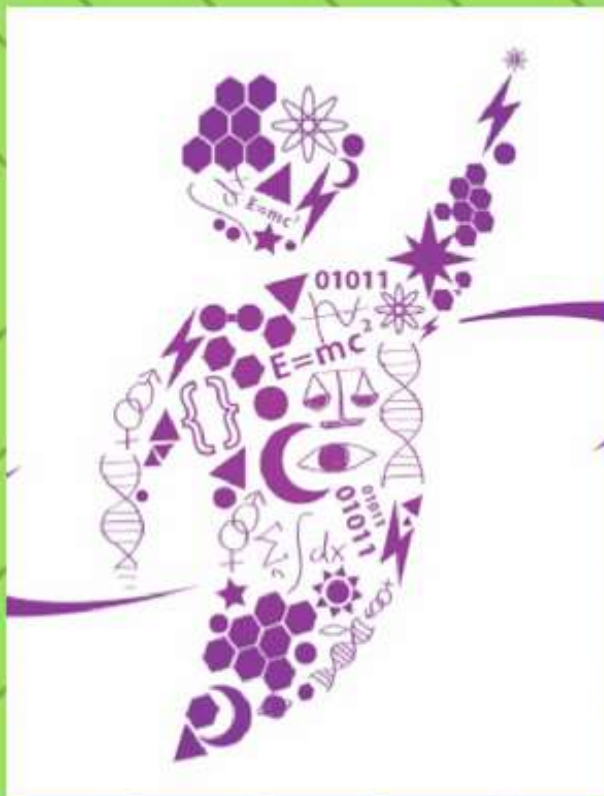
PAKET 5

PELATIHAN ONLINE

2019

**SMA
FISIKA**

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PEMBAHASAN PAKET 5

1. Gunakan aturan rantai

$$\begin{aligned}a &= -kv^2 \\ \frac{dv}{dt} &= -kv^2 \\ \int \frac{dv}{v^2} &= - \int k dt \\ \frac{1}{v_0} - \frac{1}{v} &= -kt \\ v &= \frac{v_0}{v_0 kt + 1}\end{aligned}$$

Percepatan merupakan turunan pertama dari kecepatan

$$a = \frac{dv}{dt} = -\frac{v_0^2 k}{(v_0 kt + 1)^2}$$

(a)

2. Sesuai dengan pembahasan sebelumnya

$$v = \frac{v_0}{v_0 kt + 1}$$

(b)

3. Posisi merupakan integral dari kecepatan terhadap waktu

$$s = \int v dt = \int \frac{v_0}{v_0 kt + 1} dt = \frac{1}{k} \ln(v_0 kt + 1)$$

(d)

4. Gunakan aturan rantai dalam menurunkan persamaan $y(x) = \sin^3 4x \tan^2 3x$

$$\begin{aligned}u &= \sin^3 4x \\ v &= \tan^2 3x\end{aligned}$$

$$\frac{dy}{dx} = \frac{d}{dx}(uv) = v \frac{du}{dx} + u \frac{dv}{dx} = 6\sin^2 4x \tan 3x (\sin 4x \sec^2 3x + 2 \tan 3x \cos 4x)$$

(c)

5. Gunakan aturan rantai dalam menurunkan persamaan $y(x) = e^{\sec x} \sin^2 x$

$$\begin{aligned}u &= e^{\sec x} \\ v &= \sin^2 x\end{aligned}$$

$$\frac{dy}{dx} = \frac{d}{dx}(uv) = v \frac{du}{dx} + u \frac{dv}{dx}$$

Turunan untuk $e^{\sec x}$. Gunakan manipulasi

$$\ln u = \sec x$$

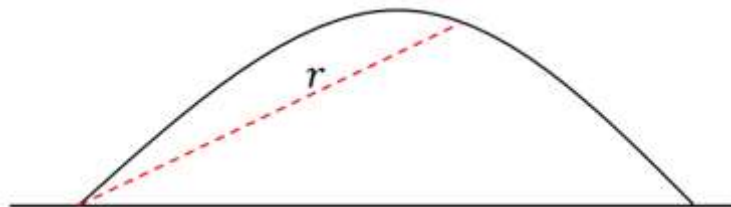
$$\begin{aligned}\frac{d}{dx} \frac{d}{du} (\ln u) &= \frac{d}{dx} \frac{d}{du} (\sec x) \\ \frac{du}{dx} \frac{1}{u} &= \sec x \tan x \\ \frac{du}{dx} &= e^{\sec x} \sec x \tan x\end{aligned}$$

Turunan untuk $\sin^2 x$

$$\begin{aligned}\frac{dv}{dx} &= 2 \sin x \cos x = \sin 2x \\ \frac{dy}{dx} &= v \frac{du}{dx} + u \frac{dv}{dx} = e^{\sec x} (\sin 2x + \sin x \tan^2 x)\end{aligned}$$

(a)

6. Perhatikan gambar dibawah ini



Besar r tidak boleh berkurang tiap waktu, harus semakin besar.

$$\begin{aligned}x &= v_0 \cos \theta t \\ y &= v_0 \sin \theta t - \frac{1}{2} g t^2 \\ r^2 = x^2 + y^2 &= (v_0 \cos \theta t)^2 + \left(v_0 \sin \theta t - \frac{1}{2} g t^2 \right)^2 = v_0^2 t^2 - v_0 \sin \theta g t^3 + \frac{1}{4} g^2 t^4 \\ \frac{dr}{dt} &> 0 \text{ agar objek semakin jauh (tidak mendekat).}\end{aligned}$$

$$\begin{aligned}\frac{d}{dt} r^2 &= 2r \frac{dr}{dt} > 0 \\ \frac{d}{dt} r^2 &= 2v_0^2 t - 3v_0 \sin \theta g t^2 + g^2 t^3 > 0 \\ 2v_0^2 - 3v_0 \sin \theta g t + g^2 t^2 &> 0\end{aligned}$$

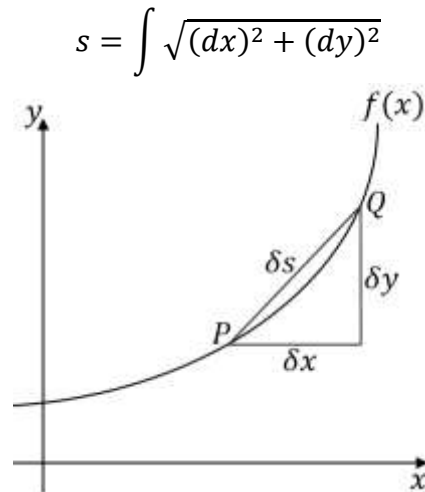
Agar $\frac{dr}{dt} > 0$ dapat terwujud, maka persamaan diatas harus mempunyai akar yang real.

$$\begin{aligned}D &= b^2 - 4ac > 0 \\ (3v_0 \sin \theta g t)^2 - 4(g^2 t^2)(2v_0^2) &> 0 \\ \sin^2 \theta &< \frac{8}{9} \\ \theta &< \arcsin \sqrt{\frac{8}{9}}\end{aligned}$$

(a)

7. Berikut merupakan persamaan matematika panjang kurva

$$(ds)^2 = (dx)^2 + (dy)^2$$



$$s = \int \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$$

Persamaan gerak parabola

$$x = v_0 \cos \theta t$$

$$y = v_0 \sin \theta t - \frac{1}{2} g t^2$$

$$\frac{dx}{dt} = v_0 \cos \theta$$

$$\frac{dy}{dt} = v_0 \sin \theta - g t$$

$$ds = \sqrt{(v_0 \cos \theta)^2 + (v_0 \sin \theta - g t)^2} dt = v_0 \cos \theta \sqrt{1 + \left(\tan \theta - \frac{g t}{v_0 \cos \theta}\right)^2} dt$$

Asumsikan substitusi integralnya

$$\tan \theta - \frac{g t}{v_0 \cos \theta} \equiv \tan \varphi$$

$$\frac{d}{d\varphi} \left(\tan \theta - \frac{g t}{v_0 \cos \theta} \right) = \sec^2 \varphi$$

$$\frac{dt}{d\varphi} = -\frac{v_0 \sec^2 \varphi \cos \theta}{g}$$

$$ds = -\frac{v_0^2 \cos^2 \theta \sec^2 \varphi}{g} \sqrt{1 + \tan^2 \varphi} d\varphi = -\frac{v_0^2 \cos^2 \theta}{g} \sec^3 \varphi d\varphi$$

$$s = -\frac{v_0^2 \cos^2 \theta}{g} \int \sec^3 \varphi d\varphi$$

Menghitung integral $\sec^3 \varphi$

$$\int \sec^3 \varphi d\varphi = \int \sec^2 \varphi \sec \varphi d\varphi$$

Gunakan metode parsial

$$dv = \sec^2 \varphi d\varphi$$

$$u = \sec \varphi$$

$$\int \sec^3 \varphi d\varphi = \int \sec^2 \varphi \sec \varphi d\varphi = \sec \varphi \tan \varphi - \int \tan^2 \varphi \sec \varphi d\varphi$$

$$\tan^2 \varphi \sec \varphi = \sin^2 \varphi \sec^3 \varphi = (1 - \cos^2 \varphi) \sec^3 \varphi = \sec^3 \varphi - \sec \varphi$$

$$\int \sec^3 \varphi d\varphi = \int \sec^2 \varphi \sec \varphi d\varphi = \sec \varphi \tan \varphi - \int (\sec^3 \varphi - \sec \varphi) d\varphi$$

$$2 \int \sec^3 \varphi d\varphi = \sec \varphi \tan \varphi + \int \sec \varphi d\varphi = \sec \varphi \tan \varphi + \ln(\sec \varphi + \tan \varphi)$$

$$\int \sec^3 \varphi d\varphi = \frac{1}{2} \sec \varphi \tan \varphi + \frac{1}{2} \ln(\sec \varphi + \tan \varphi)$$

Kita mengetahui bahwa

$$\tan \theta - \frac{gt}{v_0 \cos \theta} \equiv \tan \varphi$$

$$\sec \varphi = \frac{\sqrt{v_0^2 - 2v_0 \sin \theta gt + g^2 t^2}}{v_0 \cos \theta}$$

$$\sec \varphi \tan \varphi = \frac{(v_0 \sin \theta - gt) \sqrt{v_0^2 - 2v_0 \sin \theta gt + g^2 t^2}}{v_0^2 \cos^2 \theta}$$

$$\ln(\sec \varphi + \tan \varphi) = \ln \left(\frac{\sqrt{v_0^2 - 2v_0 \sin \theta gt + g^2 t^2}}{v_0 \cos \theta} + \tan \theta - \frac{gt}{v_0 \cos \theta} \right)$$

Maka, panjang kurva lintasan

$$s = -\frac{v_0^2 \cos^2 \theta}{g} (\sec \varphi \tan \varphi + \ln(\sec \varphi + \tan \varphi)) \Big|_{t=0}^{t=\frac{v_0 \sin \theta}{g}}$$

$$\sec \varphi \tan \varphi \Big|_{t=0}^{t=\frac{v_0 \sin \theta}{g}} = -\sec^2 \theta$$

$$\ln(\sec \varphi + \tan \varphi) \Big|_{t=0}^{t=\frac{v_0 \sin \theta}{g}} = -\ln \left(\frac{1 + \sin \theta}{\cos \theta} \right)$$

$$s = -\frac{v_0^2 \cos^2 \theta}{g} (\sec \varphi \tan \varphi + \ln(\sec \varphi + \tan \varphi)) \Big|_{t=0}^{t=\frac{v_0 \sin \theta}{g}}$$

$$= \frac{v_0^2}{g} \left(\sin \theta + \cos^2 \theta \ln \left(\frac{1 + \sin \theta}{\cos \theta} \right) \right)$$

Untuk mencari besar θ agar s maksimal adalah harus memenuhi $\frac{ds}{d\theta} = 0$

$$\frac{ds}{d\theta} = 0 = \frac{d}{d\theta} \left(\sin \theta + \cos^2 \theta \ln \left(\frac{1 + \sin \theta}{\cos \theta} \right) \right)$$

Differensial

$$\ln \left(\frac{1 + \sin \theta}{\cos \theta} \right) = \ln(1 + \sin \theta) - \ln(\cos \theta)$$

$$\frac{d}{d\theta} \left(\ln \left(\frac{1 + \sin \theta}{\cos \theta} \right) \right) = \frac{d}{d\theta} \ln(1 + \sin \theta) \frac{d(1 + \sin \theta)}{d(1 + \sin \theta)} - \frac{d}{d\theta} \ln(\cos \theta) \frac{d(\cos \theta)}{d(\cos \theta)}$$

$$\frac{d}{d\theta} \left(\ln \left(\frac{1 + \sin \theta}{\cos \theta} \right) \right) = \frac{\cos \theta}{1 + \sin \theta} + \tan \theta$$

$$\begin{aligned} \frac{ds}{d\theta} &= \cos \theta - 2 \cos \theta \sin \theta \ln \left(\frac{1 + \sin \theta}{\cos \theta} \right) + \cos^2 \theta \left(\frac{\cos \theta}{1 + \sin \theta} + \tan \theta \right) = 0 \\ 1 &= \sin \theta \ln \left(\frac{1 + \sin \theta}{\cos \theta} \right) \end{aligned}$$

(a)

8. Sesuai di pembahasan sebelumnya

$$L = \frac{v_0^2}{g} \left(\sin \theta + \cos^2 \theta \ln \left(\frac{1 + \sin \theta}{\cos \theta} \right) \right)$$

(e)

9. Untuk memudahkan pengerjaan, akan dilakukan manipulasi persamaan

$$\begin{aligned} \frac{x^2 - 14}{x^2 + 16} &= 1 - \frac{30}{x^2 + 16} \\ \int \frac{x^2 - 14}{x^2 + 16} dx &= \int dx - \int \frac{30}{x^2 + 16} dx \\ x &= 4 \tan \varphi \\ dx &= 4 \sec^2 \varphi d\varphi \\ \int \frac{x^2 - 14}{x^2 + 16} dx &= x - \frac{30}{4} \int d\varphi = x - \frac{15}{2} \arctan \left(\frac{x}{4} \right) + c \end{aligned}$$

(d)

10. Tinjau gerak parabola

$$\begin{aligned} x &= \frac{v^2 \sin 2\theta}{g} \\ t &= \frac{2v \sin \theta}{g} \end{aligned}$$

Tinjau gerak miring

$$\begin{aligned} v &= g \sin \varphi t \\ x &= \frac{v^2}{2a} = \frac{v^2}{2g \tan \varphi} \end{aligned}$$

Objek 1 dan objek 2 masing-masing menempuh x yang sama

$$\begin{aligned} \frac{v^2 \sin 2\theta}{g} &= \frac{v^2}{2g \tan \varphi} \\ \tan \varphi &= \frac{1}{2 \sin 2\theta} \end{aligned}$$

Objek 1 dan objek 2 masing-masing menempuh t yang sama

$$\frac{2v \sin \theta}{g} = \frac{v}{g \sin \varphi}$$
$$2 \sin \theta = \frac{1}{\sin \varphi}$$

Dengan 2 persamaan diatas dapat diselesaikan untuk masing-masing sudut

$$\sin \theta = \sqrt{\frac{3 + \sqrt{13}}{8}}$$
$$\theta = \arcsin \sqrt{\frac{3 + \sqrt{13}}{8}}$$

(a)

11. Sesuai persamaan sebelumnya

$$\sin \varphi = \sqrt{\frac{2}{3 + \sqrt{13}}}$$
$$\varphi = \arcsin \sqrt{\frac{2}{3 + \sqrt{13}}}$$

(b)

12. Gunakan sifat logaritma

$$\log_7 3x = \frac{\ln 3x}{\ln 7}$$
$$\int \log_7 3x \, dx = \frac{1}{\ln 7} \int \ln 3x \, dx$$

Lakukan metode parsil

$$u = \ln 3x$$
$$\frac{du}{dx} = \frac{1}{x}$$
$$dv = dx$$
$$\int \log_7 3x \, dx = \frac{1}{\ln 7} \left(x \ln 3x - \int dx \right) = \frac{1}{\ln 7} (x \ln 3x - x) + c$$

(a)

13. Persamaan geraknya

$$y = v_0 \sin \theta \, t - \frac{1}{2} g t^2$$
$$x = v_0 \cos \theta \, t$$

Subtitusikan persamaan x pada persamaan y

$$0 = \frac{1}{2} g \frac{x^2}{v_0^2} \tan^2 \theta - x \tan \theta + \frac{1}{2} g \frac{x^2}{v_0^2} + y$$

Namun, kita memerlukan satu nilai θ yang real, maka $D = 0$ untuk $x = d$ dan $y = d$

$$b^2 - 4ac = 0$$

$$(x \tan \theta)^2 - 4 \left(\frac{1}{2} g \frac{x^2}{v_0^2} \tan^2 \theta \right) \left(\frac{1}{2} g \frac{x^2}{v_0^2} + y \right) = 0$$

$$v_0^4 - 2gdv_0^2 - g^2d^2 = 0$$

$$v_0 = \sqrt{gd(1 + \sqrt{2})}$$

(c)

14. Untuk mendapatkan nilai θ , substitusikan kecepatan awal pada persamaan sebelumnya untuk $x = d$ dan $y = d$

$$0 = \frac{1}{2} g \frac{x^2}{v_0^2} \tan^2 \theta - x \tan \theta + \frac{1}{2} g \frac{x^2}{v_0^2} + y$$

$$0 = \frac{1}{2} g \frac{d^2}{gd(1 + \sqrt{2})} \tan^2 \theta - d \tan \theta + \frac{1}{2} g \frac{d^2}{gd(1 + \sqrt{2})} + d$$

$$\tan \theta = 1 + \sqrt{2}$$

$$\theta = \arctan(1 + \sqrt{2})$$

(c)

15. Ketinggian maksimum dicapai saat $v_y = 0$

$$v_y = v_0 \sin \theta - gt$$

$$t = \frac{v_0 \sin \theta}{g}$$

$$y = v_0 \sin \theta \left(\frac{v_0 \sin \theta}{g} \right) - \frac{1}{2} g \left(\frac{v_0 \sin \theta}{g} \right)^2 = \frac{v_0^2 \sin^2 \theta}{2g}$$

$$y = \frac{gd(1 + \sqrt{2})}{2g} \left(\frac{1 + \sqrt{2}}{\sqrt{4 + 2\sqrt{2}}} \right)^2 \approx 1,03d$$

(c)