

Interactive Appearance Prediction for Cloudy Beverages

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Abstract

Juice appearance is important to consumers, so digital juice with a slider that varies a production parameter or changes juice content is useful. It is however challenging to render juice with scattering particles quickly and accurately. As a case study, we create an appearance model that provides the optical properties needed for rendering of unfiltered apple juice. This is a scattering medium that requires volume path tracing as the scattering is too much for single scattering techniques and too little for subsurface scattering techniques. We investigate techniques to provide a progressive interactive appearance prediction tool for this type of medium. Our renderings are validated by qualitative and quantitative comparison with photographs. Visual comparisons using our interactive tool enable us to estimate the apple particle concentration of a photographed apple juice.

Categories and Subject Descriptors (according to ACM CCS): I.3.7 [Computer Graphics]: Three-Dimensional Graphics and Realism—

1. Introduction

Quoting a food science article: “the visual appearance of a cloudy drink is a decisive factor for consumer accep-



Figure 1: *Cloudy apple juice photographed and rendered using our appearance model. In the model, apple particle concentration (1.0 g/L) and days the apples were stored (4) were selected to match the photograph.*

tance” [Bev02]. We therefore believe that appearance prediction is highly relevant in the beverage industry of the future. It is important to predict the visual effect of a production parameter being modified, so that production parameters may be optimized without negative impact on the visual quality of the product. An appearance model also potentially enables analysis of product properties using camera sensors.

The cloudy part of a beverage typically consists of oil droplets or fruit flesh. We use Lorenz-Mie theory to go from a particle size distribution of fruit flesh particles, for example, to the scattering properties that we would use in a volume rendering [FCJ07]. Once the scattering properties are available, there are many ways to render the medium. However, in the case of a cloudy beverage, the scattering is neither low enough for single scattering techniques nor high enough for subsurface scattering techniques. We thus use full volume path tracing [Rus88], which quite accurately predicts the appearance of milk [FCJ12].

The complex refractive indices ($n = n' + i n''$) of host liquid and particle inclusions are required as input for the Lorenz-Mie theory. In many cases, these parameters depend to some degree on production parameters. In addition, the concentration of particles is often a production parameter. This enables us to build appearance models that are parameterized by production parameters. As a case study, we build such an appearance model for apple juice.

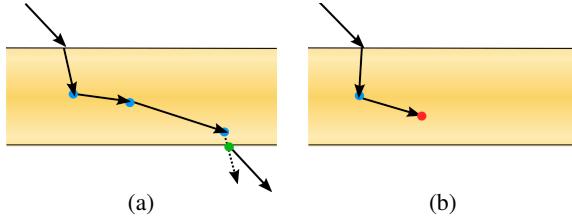


Figure 2: The scattering process using shadow rays. Each shadow ray has a sampled direction (sampled with the Henyey-Greenstein phase function) and length (from an exponential distribution of average σ_t). In (a), the random walk exits the material and continues path tracing. In (b), the last ray is absorbed and the random path discarded.

average over the color bands of the beam transmittance $T_r = e^{-\sigma_{a,glass}s}$, where s is the distance traveled through the glass medium, is then the probability that the path continues through the glass without being terminated.

The cloudy beverage is also considered a specular material, but it also contains light scattering particles. When a ray passes through this medium (either by refracting into it or by internal reflection), we perform a volumetric scattering process as illustrated in Figure 2. This is done by a stochastic walk inside the medium based on the scattering properties (scattering and extinction coefficients, σ_s and σ_t , and asymmetry parameter, g) that we obtain from the Lorenz-Mie theory. At each step of the walk, we use the scattering albedo σ_s/σ_t in a Russian roulette as the probability of the path surviving without being absorbed. We discard the whole walk if the ray is absorbed. If the ray is not absorbed, we sample the distance to the next scattering event using $s = \ln(-\xi)/\sigma_t$, where $\xi \in [0, 1]$ is a uniform random variable. If s is beyond the surface of the medium, the next scattering event is interaction with the surface in the usual way. If not, we sample a new scattering direction using the Henyey-Greenstein phase function [PH10] (which is a function of g). To improve efficiency, we randomly pick one RGB components when performing the scattering process, and all tracings inside the medium are done with shadow rays using the distance to the next scattering event as the maximum trace distance.

4. Materials

To capture a reference photograph, we set up a scene consisting of a drinking glass with unfiltered apple juice placed on a neutral white surface with a neutral white background. The glass was illuminated by a large diffuse light source at a 45° angle. We used a standard digital single-lens reflex (DSLR) camera with a 50 mm lens. The light source was a Bowens BW3370 100W Unilite, which is a compact fluorescent light source with a correlated color temperature (CCT) of 6400 K. This is fairly close to the equal energy point (E with $x = y = 1/3$) in the chromaticity diagram, which is

	4 days	9.5 days peeled	9.5 days	27 days
0.0 g/L	0.1333	0.1337	0.1508	0.2015
0.1 g/L	0.0480	0.0649	0.1025	0.1741
0.2 g/L	0.0411	0.0657	0.1048	0.1753
0.5 g/L	0.0368	0.0689	0.1072	0.1755
1.0 g/L	0.0363	0.0687	0.1055	0.1731
2.0 g/L	0.0416	0.0563	0.0858	0.1519

Table 2: RMSE for a patch of color in the lower part of the glass. We note a minimum error around the 0.5-1.0 g/L concentration and 4 days storage time.

also the reference white point of the CIE RGB color space. We thus model our light source as being purely white, and convert the spectral optical properties obtained from our appearance model to CIE RGB using the RGB color matching functions reported by Stockman and Sharpe [SS00].

The apple juice is an unfiltered press juice from Orskov Foods with a sugar content of 10 g per 100 ml. We estimated $X = 11.25$ as the juice also contains pectin, organic acids, and salts in addition to the sugar [GL06], and with this X we get n'_{host} equal to one previously measured for regular pressed cloudy apple juice [BGL07].

5. Results

We performed two sets of comparisons, one qualitative in Figures 1 and 3 and one quantitative in Table 2. All comparisons show the converged result after 5000 accumulated frames. On a qualitative visual comparison, the photograph matches most closely the rendering with concentration in the 0.5-1.0 g/L range and a storage time of 4 days. For the quantitative comparison, we compare a patch of color on the lower part of the glass. As a metric, we use the RMSE of the color bands on the patch. The quantitative result places the concentration between 0.5 g/L and 1.0 g/L, slightly leaning towards the latter and confirming our qualitative comparison. Strong highlights in the glass are due to rays getting trapped due to total internal reflection.

Our implementation of the method, based on OptiX [PBD*10], runs progressively on the GPU, with an average frame rate of 12 frames per second on an NVIDIA GeForce 780 Ti card. This enables us to get nearly converged results in less than 10 minutes. A visual comparison of the main liquid is possible within a minute (~600 frames), while caustics from the juice take much longer to converge.

6. Discussion

By combining existing techniques in our framework, we enable interactive testing of the influence of different production parameters on the appearance of a cloudy beverage. Our case study enables approximate simulation of the appearance

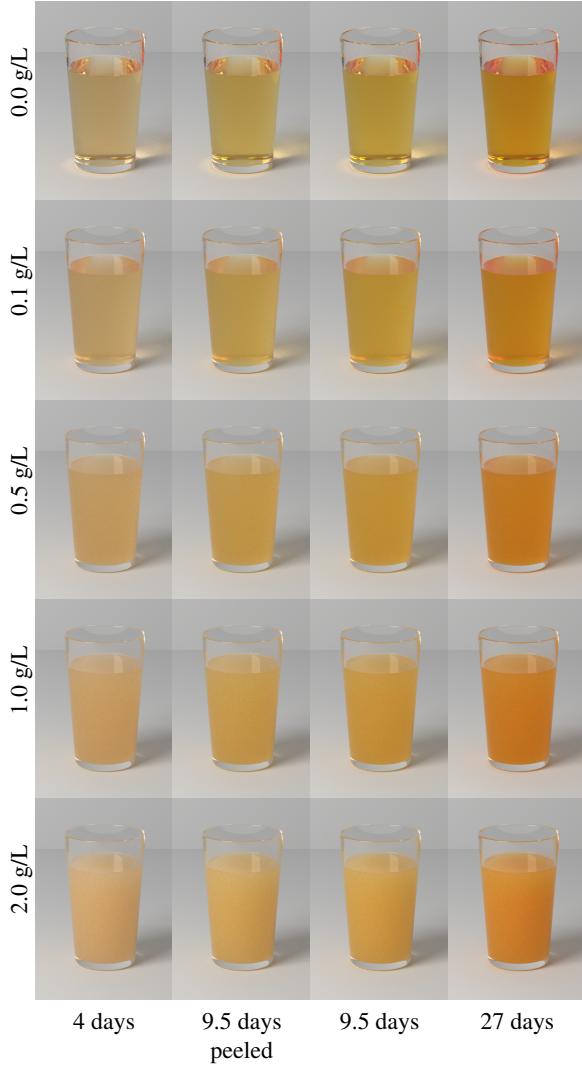


Figure 3: Visual comparison of our renderings varying two parameters: particle concentration and apple storage time.

of cloudy apple juice during production. However, we cannot match the photograph perfectly, and can thus only give a rough estimate of the parameters. As a possible future step, we want to improve precision by better estimating scene geometry, camera parameters, and lighting environment.

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