



- 1) Connect everything as shown on the diagram
- 2) Start the Net Server. Wait until it's booted up (~30 sec.).
- 3) Start the robot (just flick the switch).
- 4) Start the Operator Control Unit.
- 5) Open two terminals and type the following commands:

#### TERMINAL 1

```
ssh robot@dfki-robot (password: nifti)  
roslaunch nifti_launchers user_teleop_only.launch
```

#### TERMINAL 2

```
export ROS_MASTER_URI=http://dfki-robot:11311  
roslaunch nifti_gui nifti_gui_ugv.launch
```