Scientific Computation

Spring, **2019**

Lecture 17

- Consider 'wave,' $f(x) = e^{ikx}$
- and its derivative, $f' = ike^{ikx}$
- Finite difference approximation of f':

$$f_{i+1} = e^{ik(x+h)}$$

$$f_{i-1} = e^{ik(x-h)}$$

$$\frac{(f_{i+1} - f_{i-1})}{2h} = \frac{e^{ikh} - e^{-ikh}}{2h} e^{ikx}$$

$$\frac{(f_{i+1} - f_{i-1})}{2h} = i \left[\frac{\sin(kh)}{h}\right] e^{ikx}$$

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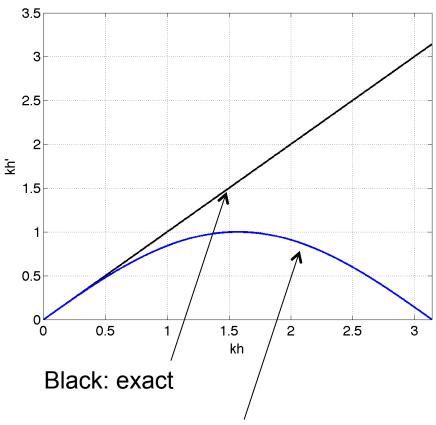
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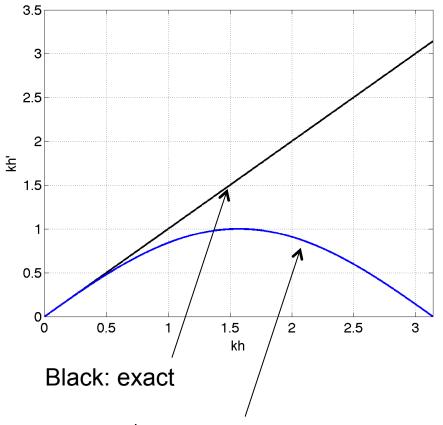
• Compare 'modified wavenumber,' $\underline{\sin(kh)}$ to kh



 FD only accurate for low wavenumbers (long waves)

Blue: 2nd-order finite difference

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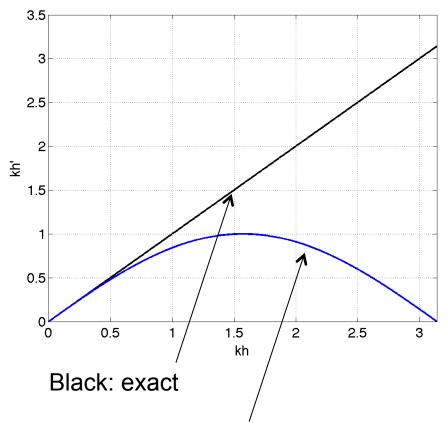
- FD only accurate for low wavenumbers (long waves)
- 1% error when khpprox0.39

$$kh = \frac{2\pi h}{\lambda}$$

$$\lambda/h \approx 16$$

Blue: 2nd-order finite difference

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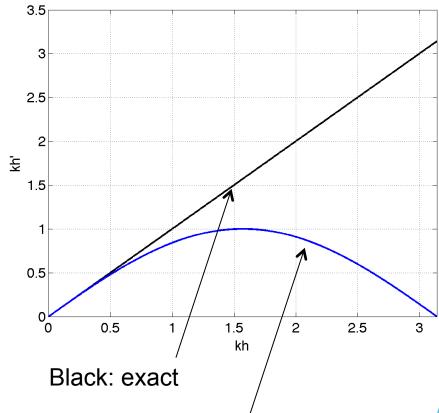
- FD only accurate for low wavenumbers (long waves)
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- So, need ~16 points/wavelength for ~1 % error
- Spectral (Fourier): >2 points/ wavelength, exact

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Blue: 2nd-order finite difference

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Exercise: What is modified wavenumber for 2nd derivative?:

$$f_i'' = \frac{(f_{i+1} - 2f_i + f_{i-1})}{h^2}$$

FD schemes with better resolution?

- Think about time marching:
 - Explicit Euler has poor stability properties
 - Implicit Euler: much better stability, but requires matrix inversion → more expensive
- Explicit finite difference: $f_i' = \frac{(f_{i+1} f_{i-1})}{2h}$
- Or 'implicit' finite difference stencils:

$$\beta f'_{i-2} + \alpha f'_{i-1} + f'_i + \alpha f'_{i+1} + \beta f'_{i+2} =$$

$$c \frac{f_{i+3} - f_{i-3}}{6h} + b \frac{f_{i+2} - f_{i-2}}{4h} + a \frac{f_{i+1} - f_{i-1}}{2h}$$

- Now have a system of equations (a banded matrix)
- Lots of coefficients to play with!

Designing your FD stencil

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- First think about truncation error:
 - Taylor series + lots of algebra →

2nd **order**:
$$a + b + c = 1 + 2\alpha + 2\beta$$

4th order:
$$a + 2^2b + 3^2 = \frac{4!}{2!}(\alpha + 2^2\beta)$$

6th order:
$$a + 2^4b + 3^4c = \frac{6!}{4!}(\alpha + 2^4\beta)$$

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Highest possible accuracy: 10th order:

$$\alpha = \frac{1}{2}, \beta = \frac{1}{20}, a = \frac{17}{12}, b = \frac{101}{150}, c = \frac{1}{100}$$

But is this the best scheme?

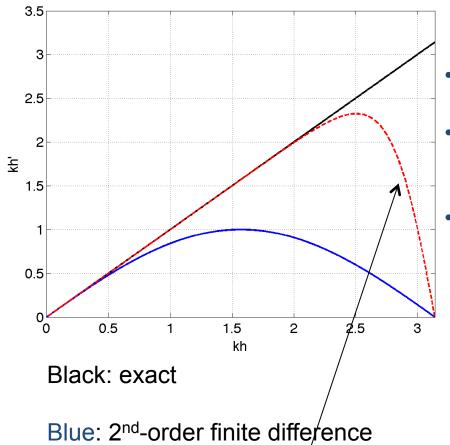
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$$c \frac{f_{i+3} - f_{i-3}}{6h} + b \frac{f_{i+2} - f_{i-2}}{4h} + a \frac{f_{i+1} - f_{i-1}}{2h}$$

• Same approach as before, $f(x) = e^{ikx}$ $f_{i+1} = e^{ik(x+h)}$

gives the general modified wavenumber:

$$kh' = \frac{a\sin(kh) + (b/2)\sin(2kh) + (c/3)\sin(3kh)}{1 + 2\alpha\cos(kh) + 2\beta\cos(2kh)}$$



- Previous result for 2nd order FD
- 10th order ~ 3 points/wavelength for 1% error
- But can we do better?

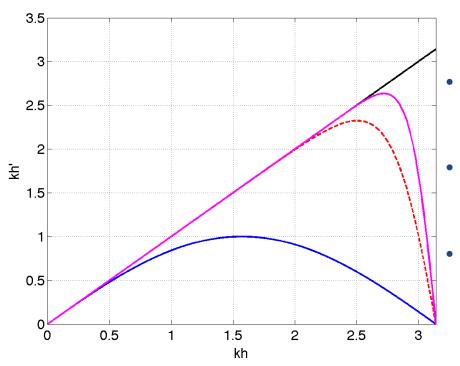
Red: 10th-order finite difference

- 4th order schemes have three free constants
- Can impose constraints on modified wavenumber:

• e.g.:
$$kh'(2.2) = 2.2$$
 $kh'(2.3) = 2.3$ $kh'(2.4) = 2.4$

Then,

$$\alpha = 0.5771439, \beta = 0.0896406, a = 1.3025166, b = 0.99335500, c = 0.03750245$$



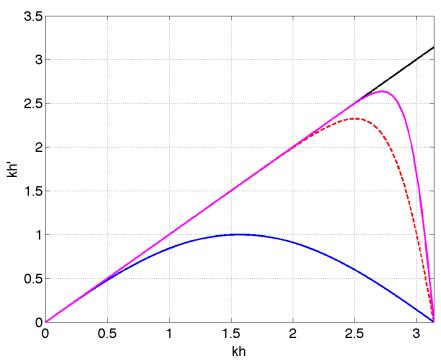
- 10th order ~ 3 points/wavelength for 1% error
- 4th order ~ 2.5 points/wavelength for 1% error
- Order of accuracy isn't everything!

Black: exact

Blue: 2nd-order

Red: 10th-order

Magenta: Optimised, 4th order



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10th order ~ 3 points/wavelength for 1% error

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- Notes on cost: operation counts
 - 2nd order FD: N mult + N add
 - 4th order implicit FD: pentadiagonal linear system,
 - 7N mult + 7N add
- Spectral (Fourier): ~Nlog₂N Key question: which method requires least time for desired accuracy?

• Spectral-like scheme requires solution of $\mathbf{A}\mathbf{x}=\mathbf{b}$ and \mathbf{A} is a pentadiagonal matrix:

- In general, np.linalg.solve(A,b)
- But this isn't very efficient
 - Requires excessive memory (storing the zeros in A)
 - Requires excessive operations (again due to the zeros)

- Can build sparse banded matrix using scipy.diags
- First construct diagonals:

```
#RHS
a = 1.3025166
b = 0.9935500
c = 0.03750245

#LHS
ag = 0.5771439
bg = 0.0896406

#Construct A
zv = np.ones(N)
agv = ag*zv[1:]
bgv = bg*zv[2:]
```

Then construct sparse matrix, A:

and use scipy.sparse.linalg.spsolve

- This would solve the memory issue
- But it is still possible to do better with efficiency

- scipy.linalg has a solver specifically for banded matrices: scipy.linalg.solve_banded (actually a Fortran routine from Lapack)
- This is a little tricky to use
 - Need to provide matrix in "matrix diagonal ordered form"

$$A_b[u + i - j, j] == A[i,j]$$

- A_b is a 2-D array required as input to solve_banded
- u, is the number of non-zero diagonals above the main diagonal (2 for our pentadiagonal matrix)
- Now we (nearly) have the "best" approach for our problem
 - Need to modify our method for the top two and bottom two rows in the matrix (i=0,1,N-2,N-1)

Boundary modifications

At i=1 and i=N-2, we switch to a (8th-order) tridiagonal scheme:

$$\alpha = \frac{3}{8}$$
. $\beta = 0$, $a = \frac{1}{6}(\alpha + 9)$,
 $b = \frac{1}{15}(32\alpha - 9)$, $c = \frac{1}{10}(-3\alpha + 1)$.

And at i=0,N-1, we switch to "one-sided" schemes:

$$f'_{0} + \alpha f'_{1} = \frac{1}{h} \left(af_{0} + bf_{1} + cf_{2} + df_{3} \right) \qquad \alpha = 3, \quad a = -\frac{17}{6}, \quad b = \frac{3}{2},$$

$$f'_{N-1} + \alpha f'_{N-2} = -\frac{1}{h} \left(af_{N-1} + bf_{N-2} + cf_{N-3} + df_{N-4} \right) \qquad c = \frac{3}{2}, \quad d = -\frac{1}{6}. \quad \text{(fourth order)}$$

This works for *periodic* functions where the RHS can be evaluated using these schemes. For general functions, we would have to modify the scheme at i=3,N-2 as well

Final notes on finite-difference methods

Advantages of quasi-spectral FD schemes

- 'Competitive' efficiency: depends on desired accuracy, aim for 1e-6 error or smaller for scientific applications
- Low memory usage (relative to explicit FD and Fourier) second key question: how much memory is available? Is there a performance gain from using less memory? (low space complexity)

Disadvantages

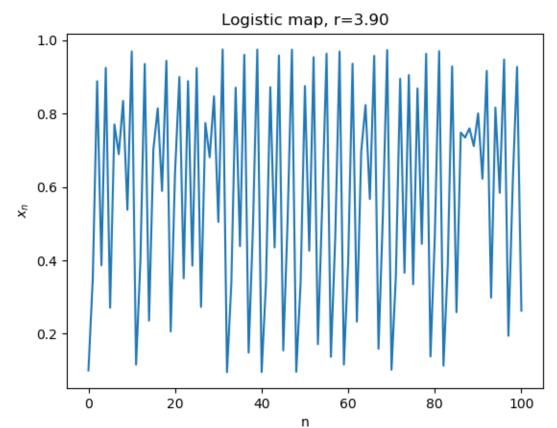
- Global (like spectral)
- Difficult to apply to complex geometries

(More) data analysis

- Fourier (energy or power) spectra are a good place to start with stationary data
 - If the length of the data is sufficiently large
 - And the sampling rate (i.e. Δx or Δt) is sufficiently small

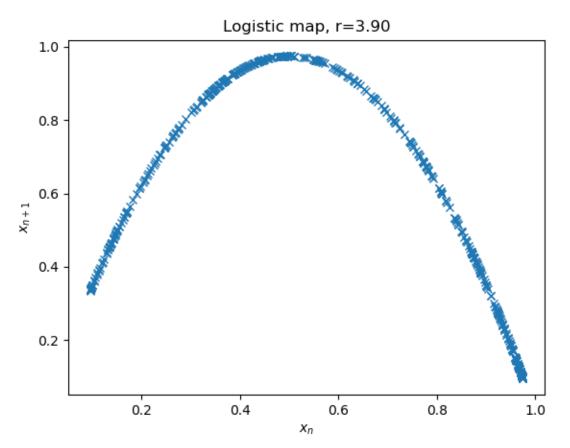
(More) data analysis

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- What can we do with this data?
- FFT won't work data is not smooth
- Three basic options:
 - Compare peaks to peaks
 - Or troughs to troughs
 - Or peaks to troughs
- Let's try the 3rd option

Logistic map

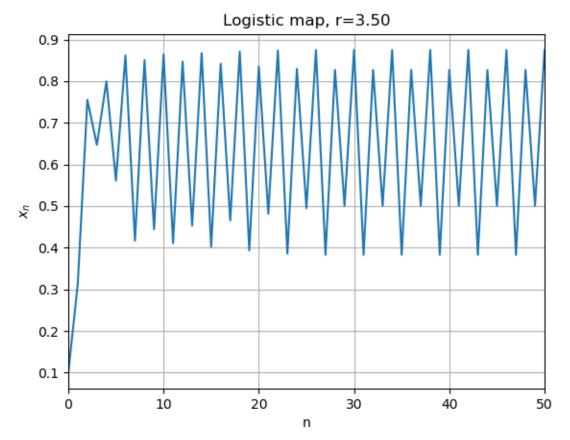


- There is clear "structure" within the data!
- The logistic map is:

$$x_{n+1} = rx_n \left(1 - x_n \right)$$

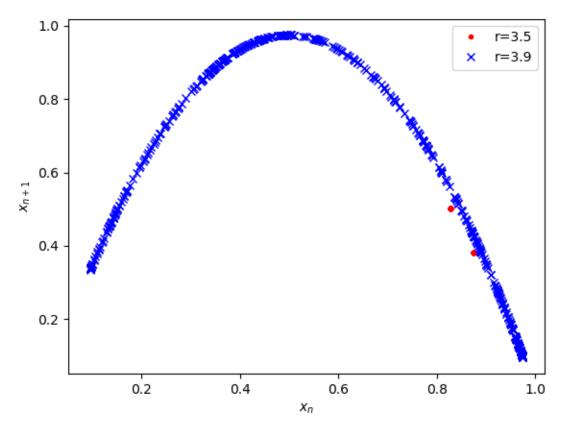
- The parameter, r, controls the dynamics.
 - For smaller r, simple periodic behavior
 - For r=3.9, chaotic behavior
 - As time increases, more and more points on the parabola will be visited in an irregular order

Logistic map



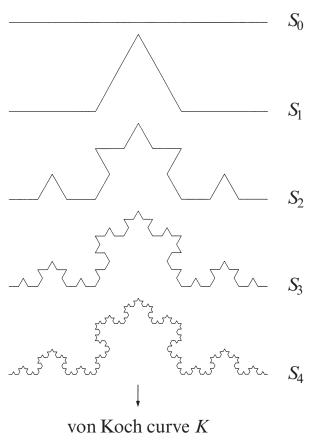
- At r=3.5, there are period-2 oscillations
- $\mathbf{x}_{n+4} = \mathbf{x}_n$
- When characterizing a solution, we need to think about the set of points visited (after discarding the initial transient)
- And in particular, the dimension of this set

Logistic map



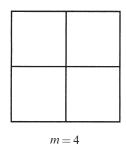
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 We borrow from the study of fractals where there is a similarity or fractal dimension

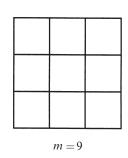


- An example: the Koch snowflake
 - Each "iteration", the "curve" is broken up into 4 smaller copies of itself. The length of each copy is 1/3 of the original
 - What is the dimension of this curve?

 We borrow from the study of fractals where there is a similarity or fractal dimension



r=2

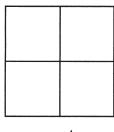


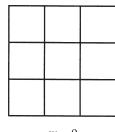
r = 3

m = number of copies r = scale factor

- A simpler example: A square.
 - Break a square into 4 smaller copies (m=4) the sides of each copy have been scaled down by a factor of 2 (r=2)
 - With m=9, we have r=3
 - And the dimension is d = log(m)/log(r)=2
 - For the Koch snowflake, m=4, r=3, d=log(4)/log(3)=1.261...

 We borrow from the study of fractals where there is a similarity or fractal dimension





m = number of copies r = scale factor

$$m = 4$$

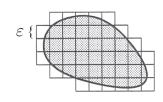
 $r = 2$

$$m = 9$$
 $r = 3$

How do we compute the fractal dimension given data?

One approach is to compute the *box dimension*:





$$N(\varepsilon) \propto \frac{L}{\varepsilon}$$

$$N(\varepsilon) \propto \frac{A}{\varepsilon^2}$$

Construct m-dimensional cubes with edge-length, ϵ , find the number of cubes needed to cover the set of points in the solution, $N(\epsilon)$

We expect: $N(\varepsilon) \propto 1/\varepsilon^d$. where d is the box dimension Imperial College

- In practice, the box dimension is not used it's computation is too expensive for large high-dimensional sets
- The correlation dimension is often used instead
- We collect n m-dimensional points "visited" during a process after discarding the effect of the initial condition: $\{x_i, i = 1, ..., n\}$
- The correlation sum, $C(\epsilon)$ is: (total number of pairs of points within distance ϵ)/(Total number of distinct pairs)

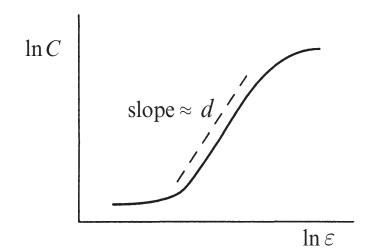
$$C(\epsilon) = \frac{2}{n(n-1)} \sum_{i=1}^{n} \sum_{j=i+1}^{n} H(\epsilon - ||\mathbf{x}_i - \mathbf{x}_j||)$$

- Here, H, is the Heaviside function, H(z)=0 if z<=0, H(z)=1 if z>0
- $||\mathbf{x}_i \mathbf{x}_i||$ is the Euclidian distance (for m-dimensional x)
- For points falling on a fractal-like structure, we expect: $C(\epsilon) \sim \epsilon^D$

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Generically, we expect:



- At small ϵ , few if any pairs within ϵ of each other
- At large ϵ , almost all pairs within ϵ
- Often some trial-and-error is needed to choose a good range of ε
- Straightforward to compute for logistic map using scipy.spatial.distance.pdist

1. Compute solution:

```
for i in range(N):
    x[i+1] = r*x[i]*(1-x[i])
```

2. Discard influence of initial condition:

```
y = x[N//2:]
n = y.size
```

3. Split into two vectors (m=2) and collect in n x m matrix

```
y1 = y[:-1:2]
y2 = y[1::2]
A = np.vstack([y1,y2]).T
```

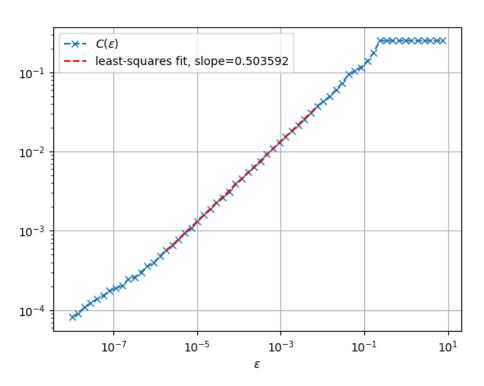
4. pdist will then compute all n(n-1)/2 distances:

```
D = pdist(A)
```

5. Now just need to pass these distances through Heaviside function for a range of ϵ ...

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D = D[D<eps[i]] #Discard distances larger than eps. Assumes eps[i+1]<eps[i]
C[i] = D.size #Size of new D is Correlation sum (without m*(m-1)/2 scaling)</pre>



- Results for r=3.5699456 are shown, m=8000
- 1st 15 and last 20 points have been discarded for best fit calculation, fractal dimension is estimated as 0.5 (for this value of r)
- Estimate computed using np.polyfit