Programming Technologies: BlueZ Programming

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Assignment 1

Implementar una aplicación con BlueZ para detectar dispositivos bluetooth vía Linux OS. Una vez detectados, entonces imprimir en la terminal bash:

- Clase del dispositivo.
- Dirección Bluetooth.

Listing 1: Detecting Bluetooth Devices

```
#include <stdio.h>
   #include <stdlib.h>
   #include <unistd.h>
   #include <sys/socket.h>
  #include <bluetooth/bluetooth.h>
   #include <bluetooth/hci.h>
   #include <bluetooth/hci_lib.h>
   int main(int argc, char **argv)
10
       inquiry_info *ii = NULL;
       int max_rsp, num_rsp;
       int dev_id, sock, len, flags;
       int i;
       char addr[19] = { 0 };
       char name [248] = \{ 0 \};
       dev_id = hci_get_route(NULL);
       sock = hci_open_dev( dev_id );
       if (dev_id < 0 || sock < 0) {</pre>
           perror("opening socket");
           exit(1);
       }
       len = 8;
       max\_rsp = 255;
       flags = IREQ_CACHE_FLUSH;
       ii = (inquiry_info*)malloc(max_rsp * sizeof(inquiry_info));
       num_rsp = hci_inquiry(dev_id, len, max_rsp, NULL, &ii, flags);
       if ( num_rsp < 0 ) perror("hci_inquiry");</pre>
       for (i = 0; i < num_rsp; i++) {</pre>
           ba2str(&(ii+i)->bdaddr, addr);
           memset(name, 0, sizeof(name));
           if (hci_read_remote_name(sock, &(ii+i)->bdaddr, sizeof(name),
               name, 0) < 0)
           strcpy(name, "[unknown]");
           printf("%s %s\n", addr, name);
       }
       free( ii );
       close( sock );
       return 0;
```

```
45 }
```

Assignment 2

Implementar una aplicación *Cliente-Servidor* para comunicar vía Bluetooth el ATmegaX (Arduino) con Linux OS: Servidor Arduino/Cliente Linux.

Listing 2: BlueZ RFComm Client

```
#include <stdio.h>
   #include <unistd.h>
   #include <sys/socket.h>
   #include <bluetooth/bluetooth.h>
  #include <bluetooth/rfcomm.h>
   int main(int argc, char **argv)
       struct sockaddr_rc addr = { 0 };
       int s, status;
10
       char dest[18] = "01:23:45:67:89:AB";
       // allocate a socket
       s = socket(AF_BLUETOOTH, SOCK_STREAM, BTPROTO_RFCOMM);
15
       // set the connection parameters (who to connect to)
       addr.rc_family = AF_BLUETOOTH;
       addr.rc_channel = (uint8_t) 1;
       str2ba( dest, &addr.rc_bdaddr );
       // connect to server
       status = connect(s, (struct sockaddr *) &addr, sizeof(addr));
       // send a message
       if ( status == 0 ) {
           status = write(s, "hello!", 6);
       if ( status < 0 ) perror("uh oh");</pre>
       close(s);
       return 0;
```