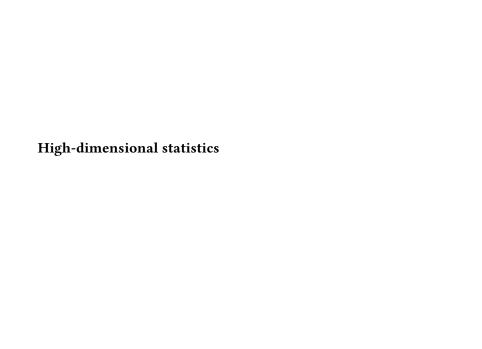
# Lecture 4 Global testing in high-dimensions

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Aldo Solari University of Milano-Bicocca Statistical Inference II PhD in Economics and Statistics





## Classical theory

- It concerns the behaviour when the *sample size*  $n \to \infty$
- Suppose  $Y_1,\ldots,Y_n\stackrel{i.i.d.}{\sim} Y_n$  with mean  $\mu=\mathbb{E}(Y)$  and finite variance  $\Sigma=\mathbb{V}\mathrm{ar}(Y)$
- Law of large numbers: the sample mean  $\hat{\mu}_n = \frac{1}{n} \sum_{i=1}^n Y_i$  converges in probability to  $\mu$
- Central limit theorem: the rescaled deviation  $\sqrt{n}(\hat{\mu}_n \mu)$  converges in distribution to a centered Gaussian with covariance matrix  $\Sigma$
- Consistency of maximum likelihood estimation
- Etc.

Suppose that we are given n=1000 samples from a statistical model in m=500 dimensions

Will theory that requires  $n \to \infty$  with the dimension m remaining fixed provide useful predictions?

## High-dimensional data

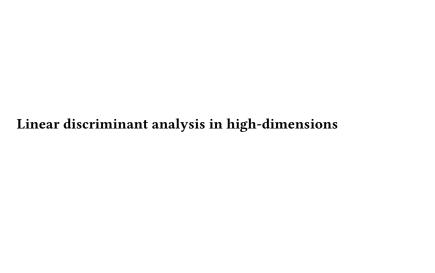
 The data sets arising in many parts of modern science have a "high-dimensional flavor", with *m* on the same order as, or possibly larger than *n*

$$m \gg n$$

- Classical "large n, fixed m" theory fails to provide useful predictions
- Classical methods can break down dramatically in high-dimensional regimes

#### Reference

Wainwright (2019) High-Dimensional Statistics: A Non-Asymptotic Viewpoint Cambridge University Press



#### Two classes

- Hypothesis testing can be used to determine whether an observed vector  $x = (x_1, \dots, x_m)^\mathsf{T} \in \mathbb{R}^m$  has been drawn from one of two possible densities  $f_A \equiv P(X|Y=A)$  and  $f_B \equiv P(X|Y=B)$ , corresponding to two possible classes A and B
- Consider testing  $H_A: X_A \sim f_A$  vs  $H_B: X_B \sim f_B$ , where  $X_A \equiv (X|Y=A)$  and  $X_B \equiv (X|Y=B)$
- When these two distributions are known, then the Neyman-Pearson lemma says that the optimal decision rule is based on thresholding the log-likelihood ratio

$$\log \frac{f_B(x)}{f_A(x)}$$

- By testing  $H_A$  vs  $H_B$  and  $H_B$  vs  $H_A$  the conclusion is that the observed data x is consistent with A ( $H_B$  rejected), with B ( $H_A$  rejected), with both (no rejections), or with neither (both rejected)

### Classification problem

- Let's turn to the classification problem involving the allocation of the observed unit *x* to one of two classes *A* and *B*
- For a Bayesian analysis suppose that the prior probabilities are  $\pi_A \equiv P(Y=A)$  and  $\pi_B \equiv P(Y=B)$  with  $\pi_A + \pi_B = 1$ . Then the posterior probabilities satisfy

$$\frac{P(Y=B|X=x)}{P(Y=A|X=x)} = \frac{\pi_B}{\pi_A} \frac{f_B(x)}{f_A(x)}$$

giving the class with the higher posterior probability

- As a special case, suppose that the two classes are distributed as multivariate Gaussians  $X_A \sim N(\mu_A, I_m)$  and  $X_B \sim N(\mu_B, I_m)$ , with  $\pi_A = \pi_B = 1/2$ 

# Optimal decision

The optimal decision rule is to threshold the log-likelihood ratio

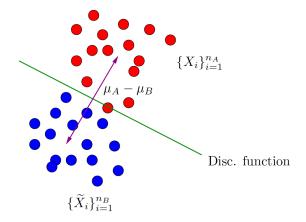
$$\Psi(x) = \langle \mu_A - \mu_B, \left(x - \frac{\mu_A + \mu_B}{2}\right) \rangle$$

where  $\langle x, z \rangle = x^{\mathsf{T}} z = \sum_{j=1}^{m} x_j z_j$  denotes the Euclidean inner product in  $\mathbb{R}^m$ 

- If  $\Psi(x) > 0$  then classify *A*, otherwise *B*
- Error probability of the optimal rule:

$$\operatorname{Err}(\Psi) = \frac{1}{2} P(\Psi(X_A) < 0) + \frac{1}{2} P(\Psi(X_B) \ge 0) = \Phi\left(-\frac{\gamma}{2}\right)$$

where  $\gamma = \|\mu_A - \mu_B\|_2$ ,  $\|\mu\|_2 = \sqrt{\mu^T \mu}$ , and  $\Phi$  is the cdf of a standard normal variable



$$\langle \mu_A - \mu_B, \left( x - \frac{\mu_A + \mu_B}{2} \right) \rangle = 0$$

source: Wainwright

# Linear Discriminant Analysis

- Fisher's LDA: uses the plug-in principle based on  $n_A$  samples from class A and  $n_B$  samples from class B

$$\hat{\Psi}(x) = \langle \hat{\mu}_A - \hat{\mu}_B, x - \frac{\hat{\mu}_A + \hat{\mu}_B}{2} \rangle$$

- Error probability of LDA (is itself a random variable)

$$\operatorname{Err}(\hat{\Psi}) = \frac{1}{2} P(\hat{\Psi}(X_A) < 0) + \frac{1}{2} P(\hat{\Psi}(X_B) \ge 0)$$

- Classical theory: if  $(n_A, n_B) \to \infty$  and m remains fixed, then  $\hat{\mu}_A \overset{prob.}{\to} \mu_A$ ,  $\hat{\mu}_B \overset{prob.}{\to} \mu_B$  and the asymptotic error probability is  $\operatorname{Err}(\hat{\Psi}) \overset{prob.}{\to} \operatorname{Err}(\Psi) = \Phi(-\gamma/2)$ 

# **High-Dimensional Theory**

- What happens if  $(n_A, n_B, m) \to \infty$  with
  - $m/n_A \rightarrow \delta$  with  $\delta > 0$
  - $m/n_B \rightarrow \delta$
  - $\|\mu_A \mu_B\|_2 \to \gamma > 0$
- Kolmogorov (1960) showed that

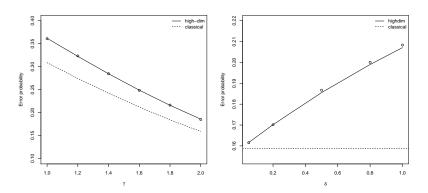
$$\operatorname{Err}(\hat{\Psi}) \stackrel{prob.}{\to} \Phi\left(-\frac{\gamma^2}{2\sqrt{\gamma^2 + 2\delta}}\right)$$

- If  $m/n \to 0$ , then the asymptotic error probability is  $\Phi(-\gamma/2)$  as is predicted by classical theory
- If  $m/n \to \delta > 0$ , then the asymptotic error probability is strictly larger than  $\Phi(-\gamma/2)$

The error probability of  $\hat{\Phi}$ , for the finite triple

$$(m, n_A, n_B) = (400, 800, 800)$$

is better described by the classical  $\Phi(-\gamma/2)$ , or the high-dimensional analog  $\Phi(-\gamma^2/(2\sqrt{\gamma^2+2\delta}))$ ?



circles correspond to the empirical error probabilities, averaged over 10 trials

# What can help us in high dimensions?

- An important fact is that high-dimensional phenomena are unavoidable
- If the ratio m/n stays bounded strictly above zero, then it is not possible to achieve the optimal classification rate
- Our only hope is that the data is endowed with some form of low-dimensional structure

- What is the underlying cause of the inaccuracy of the prediction for the LDA in high-dimensions?
- The squared Euclidean error

$$\|\hat{\mu} - \mu\|_2^2 = \sum_{j=1}^m (\hat{\mu}_j - \mu_j)^2$$

concentrates sharply around m/n, i.e. for  $t \in (0,1)$ 

$$P\left(\left|\|\hat{\mu}-\mu\|_2^2 - \frac{m}{n}\right| \ge \frac{m}{n}t\right) = P\left(\left|\frac{1}{m}\sum_{j=1}^m Z_j^2 - 1\right| \ge t\right) \le 2e^{-\frac{mt^2}{8}}$$

where  $Z_j = \sqrt{n}(\hat{\mu}_j - \mu_j) \sim N(0, 1)$ ; for the upper bound see Wainwright (2019), Example 2.11

## Sparsity

- Suppose that the *m*-vector  $\mu$  is *sparse*, with only *s* of its *m* entries being nonzero, for some sparsity parameter  $s \ll m$
- If sparsity holds, we can obtain a better estimator by thresholding the sample means

$$\tilde{\mu}_j = \hat{\mu}_j \mathbb{1}\{|\hat{\mu}_j| > \lambda\}$$

where

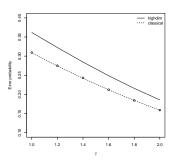
$$\lambda = \sqrt{\frac{2\log m}{n}}$$

#### Thresholded mean

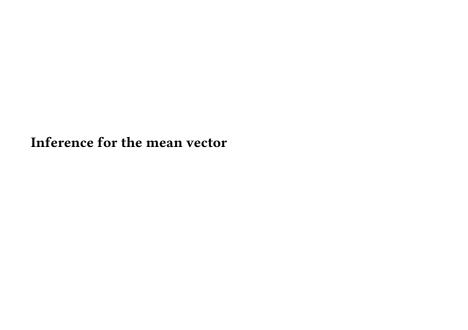
Suppose to replace  $\hat{\mu}$  by the thresholded mean  $\tilde{\mu}$ , then

$$ilde{\Psi}( extbf{ extit{x}}) = \langle ilde{\mu}_{ extit{A}} - ilde{\mu}_{ extit{B}}, extit{ extit{x}} - rac{ ilde{\mu}_{ extit{A}} + ilde{\mu}_{ extit{B}}}{2} 
angle$$

approaches the optimal  $\operatorname{Err}(\Psi)$  if  $\log {m \choose s}/n \to 0$ . For s=5:



circles correspond to the empirical error probabilities, averaged over 10 trials



- Random sample of *n* observations from  $y \sim N_m(\mu, \Sigma)$ 

$$\left( egin{array}{c} y_1 \ dots \ y_m \end{array} 
ight) \sim N_m \left( \left( egin{array}{ccc} \mu_1 \ dots \ \mu_m \end{array} 
ight), \left[ egin{array}{ccc} \sigma_1^2 & \sigma_{12} & \cdot & \sigma_{1m} \ \sigma_{21} & \sigma_2^2 & \cdot & \sigma_{2m} \ \cdot & \cdot & \cdot & \cdot \ \sigma_{m1} & \cdot & \cdot & \sigma_m^2 \end{array} 
ight] 
ight)$$

- The parameter of interest is  $\mathbb{E}(y) = \mu$ , where  $\mu_j = 0$  means "no effect" and  $\mu_i \neq 0$  means "effect" in the *j*th component
- The nuisance parameter is the variance/covariance matrix  $\mathbb{V}ar(y) = \Sigma$

#### Three questions

- 1. Detecting effects: There is at least one  $\mu_j$  different from o?
- 2. Counting effects: How many  $\mu_i$  are different from o?
- 3. *Identifying effects*: Which  $\mu_i$  are different from o?

## Global null hypothesis

Testing the global null hypothesis aims at detecting any effect

$$H_0: \mu = 0$$
, i.e.  $\bigcap_{j=1}^{m} {\{\mu_j = 0\}}$   
 $H_1: \mu \neq 0$ , i.e.  $\bigcup_{j=1}^{m} {\{\mu_j \neq 0\}}$ 

One-sided alternative

$$H_0: \bigcap_{j=1}^{m} {\{\mu_j = 0\}}$$
 $H_1: \bigcup_{j=1}^{m} {\{\mu_j > 0\}}$ 

#### MaxT and SumT

- For simplicity, assume  $\Sigma = I_m$  and n = 1 and consider the one-sided alternative
- $T_j = y_j \sim N(\mu_j, 1)$  for  $j = 1, \dots, m$
- $(T_1,\ldots,T_m)' \stackrel{H_0}{\sim} N_m(0,I_m)$
- MaxT

$$T_{\max} = \max(T_1, \ldots, T_m)$$

- SumT

$$T_{\text{sum}} = \sum_{i=1}^{m} T_i$$

#### MaxT

– The critical value  $t_{1-\alpha}$  of  $T_{\text{max}}$  is

$$P_0(T_{\text{max}} \geq t_{1-\alpha}) = \alpha$$

where  $t_{1-\alpha}$  is the  $1-\alpha$  quantile of the distribution of the maximum of m independent standard normal variables

$$\int_{t_{1-\alpha}}^{\infty} m\phi(y)\Phi(y)^{m-1}dy = \alpha$$

where  $\phi$  and  $\Phi$  are the density and cdf of N(0,1)

# Critical value approximation

– We can replace  $t_{1-\alpha}$  by  $z_{1-\frac{\alpha}{m}}$ 

$$P_{0}(T_{\max} \geq z_{1-\frac{\alpha}{m}}) = P_{0}\left(\bigcup_{j=1}^{m} \{T_{j} \geq z_{1-\frac{\alpha}{m}}\}\right)$$

$$\leq \sum_{j=1}^{m} P_{0}(T_{j} \geq z_{1-\frac{\alpha}{m}}) = m\frac{\alpha}{m} = \alpha$$

– The union bound might seem crude, but with independent  $T_j$ s the size of the test is very near  $\alpha$ 

$$P_0(T_{\text{max}} \ge z_{1-\frac{\alpha}{m}}) = 1 - \prod_{j=1}^m P_0(T_j < z_{1-\frac{\alpha}{m}})$$
$$= 1 - \left(1 - \frac{\alpha}{m}\right)^m \stackrel{m \to \infty}{\to} 1 - e^{-\alpha}$$

For  $\alpha = 0.05$ ,  $1 - e^{-\alpha} = 0.0487$ 

# Magnitude of the critical value

– How large is the threshold  $z_{1-\frac{\alpha}{n}}$ ? For large m

$$\begin{array}{lcl} z_{1-\frac{\alpha}{m}} & \approx & \sqrt{2\log m} - \frac{\log(2\log m) + \log 2\pi}{2\sqrt{2\log m}} \\ \\ & \approx & \sqrt{2\log m} \end{array}$$

with no dependence on  $\alpha$ 

# Needle in a haystack problem

$$H_0: \mu_j = 0 \text{ for all } j = 1, \dots, m$$
  
 $H_1: \mu_j = c_m > 0, \mu_k = 0 \text{ for } k \neq j$ 

– What is the limiting power of the MaxT test?

$$\lim_{m\to\infty} P_1(T_{\max} > z_{1-\frac{\alpha}{m}})$$

It depends on the limiting ratio

$$\lim_{m \to \infty} \frac{c_m}{\sqrt{2\log m}} \le 1$$

where  $c_m$  is the value of the single non-zero mean, which depends on m

Two cases:

- Assume without loss of generality that  $\mu_1 = c_m$ . Suppose  $c_m > (1 + \epsilon) \sqrt{2 \log m}$ . Then, for  $m \to \infty$ 

$$P_1(T_{\max} > z_{1-\frac{\alpha}{m}}) \ge P_1(T_1 > z_{1-\frac{\alpha}{m}}) = P(N(0,1) > z_{1-\frac{\alpha}{m}} - c) \to 1$$

- Suppose  $c_m < (1-\epsilon)\sqrt{2\log m}$ . Then for  $m\to\infty$ 

$$\begin{array}{lcl} \mathrm{P}_{1}(T_{\max}>z_{1-\frac{\alpha}{m}}) & \leq & \mathrm{P}(T_{1}>z_{1-\frac{\alpha}{m}}) + \mathrm{P}(\max_{j>1}T_{j}>z_{1-\frac{\alpha}{m}}) \\ \\ & = & \mathrm{P}(N(0,1)>z_{1-\frac{\alpha}{m}}-c) + \mathrm{P}(\max_{j>1}T_{j}>z_{1-\frac{\alpha}{m}}) \\ \\ & \to & 0+(1-e^{-\alpha}) \end{array}$$

and the MaxT test has no power

#### SumT

$$T_{\text{sum}} = \sum_{j=1}^{m} T_j \sim N(\sum_{j=1}^{m} \mu_j, m)$$

- 
$$\frac{T_{\text{sum}}}{\sqrt{m}}\stackrel{H_0}{\sim} \textit{N}(0,1); \frac{T_{\text{sum}}}{\sqrt{m}}\stackrel{H_1}{\sim} \textit{N}(\theta_{\textit{m}},1)$$
 with

$$\theta_m = \frac{\sum_{j=1}^m \mu_j}{\sqrt{m}}$$

but if  $\theta_m \to 0$  when  $m \to \infty$ , then  $T_{\text{sum}}$  has no power

– By the Neyman-Pearson lemma,  $T_{\rm sum}$  is the UMP test for

$$H_0: \mu_j = 0 \text{ for all } j$$

$$H_1: \mu_j = c_m > 0$$
 for all  $j$ 

where  $\theta_m = \sqrt{m}c_m$ , but if  $c_m = \frac{1}{m}$  the UMP test has no power

## Comparison

#### - Few strong effects:

 $m^{1/4}$  of the  $\mu_j$ s are equal to  $\sqrt{2\log m}$ , the rest o. E.g. when  $m=10^6$ ,  $m^{1/4}\approx 36$  and  $\sqrt{2\log m}\approx 5.3$ . In this setting  $T_{\rm max}$  has full power, but  $T_{\rm sum}$  has no power because

$$\theta_m = \frac{m^{1/4}\sqrt{2\log m}}{\sqrt{m}} \to 0$$

#### - Small, distributed effects:

 $\sqrt{2m}$  of the  $\mu_j$ s are equal to 3, the rest o.

The  $T_{\rm sum}$  has (almost) full power, but  $T_{\rm max}$  has no power because when m is large it's very likely that the largest  $y_j$  value comes from a null  $\mu_j$ 

#### MinP

- Let  $p_i = 1 \Phi(T_i)$  be the *j*th *p*-value
- $-p_1,\ldots,p_m \stackrel{i.i.d.}{\sim} U(0,1)$  under  $H_0$
- The MinP test is based on the minimum *p*-value

$$p_{\min} = \min(p_1, \ldots, p_m) \stackrel{H_0}{\sim} \text{Beta}(1, m)$$

- The MinP test rejects  $H_0$  if  $p_{\min} \leq 1 - (1 - \alpha)^{\frac{1}{m}}$  and has size  $\alpha$ :

$$P_{0}(p_{\min} \leq 1 - (1 - \alpha)^{\frac{1}{m}}) = 1 - P_{0}\left(\bigcap_{i=1}^{m} \{p_{i} > 1 - (1 - \alpha)^{\frac{1}{m}}\}\right)$$
$$= 1 - [(1 - \alpha)^{\frac{1}{m}}]^{m} = \alpha$$

#### Simes test

- $-p_1,\ldots,p_m\stackrel{i.i.d.}{\sim}U(0,1)$  under  $H_0$
- Sort the *p*-values

$$p_{(1)} \leq p_{(2)} \leq \ldots \leq p_{(m)}$$

- The null distribution of *j*th ordered *p*-value is

$$p_{(j)} \stackrel{H_0}{\sim} \text{Beta}(j, m - j + 1)$$

- The Simes test *p*-value

$$p_{s} = \min_{j=1,\dots,m} \left\{ p_{(j)} \frac{m}{j} \right\} \stackrel{H_0}{\sim} U(0,1)$$

- It rejects  $H_0$  if

$$\exists j: p_{(j)} \leq \frac{\alpha j}{m}$$

#### Fisher combination

- $-p_1,\ldots,p_m \stackrel{i.i.d.}{\sim} U(0,1)$  under  $H_0$
- Fisher's method of combining *p*-values

$$T_{\rm f} = \sum_{j=1}^{m} 2\log\left(\frac{1}{p_j}\right) \stackrel{H_0}{\sim} \chi_{2m}^2$$

# Higher criticism

- Empirical cdf 
$$\hat{F}_m(t) = \frac{\sum_{j=1}^m \mathbb{1}\{p_j \leq t\}}{m}$$
 for  $t \in [0, 1]$ .

- Since  $p_1, \ldots, p_m \stackrel{i.i.d.}{\sim} U(0, 1)$  under  $H_0$ , then

$$m\hat{F}_m(t) \stackrel{H_0}{\sim} \text{Binomial}(m, t)$$

- The higher criticism test is

$$T_{\text{hc}} = \sup_{t \in [0,1]} \frac{\ddot{F}_m(t) - t}{\sqrt{t(1-t)/m}}$$

or equivalently

$$T_{
m hc} = \max_{j=1,...,m} \sqrt{m} \frac{(i/m) - p_{(i)}}{\sqrt{p_{(i)}(1 - p_{(i)})}}$$

- For  $m \to \infty$ ,  $b_m T_{hc} - c_m$  converges weakly to the standard Gumbel distribution, where  $b_m = \sqrt{2 \log \log m}$  and

Gumbel distribution, where 
$$b_m = \sqrt{2 \log \log m}$$
 and  $c_m = \frac{1}{2} (\log \log \log (m) - 4\pi)$ 

- For any fixed  $\alpha$  and  $m \to \infty$ , its critical value is

for some a > 0, e.g. a = 1.08 for  $m \approx 10^6$  and  $\alpha = 0.05$ 

$$c_m = \frac{1}{2}(\log \log \log(m) - 4\pi)$$
  
For any fixed  $\alpha$  and  $m \to \infty$ , its critical value is

 $t_{1-\alpha} \approx (1+a)\sqrt{2\log\log m}$ 

#### Mixture distribution

– We assume that our samples follow a mixture of N(0,1) and  $N(\mu,1)$  distributions

$$H_0: y_j \stackrel{i.i.d}{\sim} N(0,1)$$
 $H_1: y_j \stackrel{i.i.d}{\sim} \pi_0 N(0,1) + \pi_1 N(\mu,1)$ 

where  $\pi_1 = 1 - \pi_0$ 

- To carry out asymptotic analysis, we must specify the dependence scheme of  $\pi_1 = \pi_1(m)$  and  $\mu = \mu(m)$  on m:

$$\pi_1 = \mathbf{m}^{-\beta} \qquad \frac{1}{2} < \beta < 1$$
 
$$\mu = \sqrt{2r \log \mathbf{m}} \qquad 0 < r < 1$$

– The needle in a haystack problem:  $\beta = 1$  and r = 1; small distributed effects:  $\beta = 1/2$ 

#### Threshold curve

Consider the following threshold curve for *r* 

$$\rho_{\mathrm{hc}}(\beta) = \left\{ \begin{array}{cc} \beta - \frac{1}{2} & \text{if } \frac{1}{2} < \beta \leq \frac{3}{4} \\ (1 - \sqrt{1 - \beta})^2 & \text{if } \frac{3}{4} \leq \beta \leq 1 \end{array} \right.$$

– If  $r > \rho_{hc}(\beta)$  the Neyman-Pearson optimal test achieves

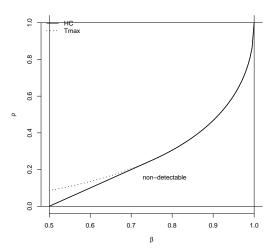
$$P_0(\text{Type I Error}) + P_1(\text{Type II Error}) \rightarrow 0$$

The Higher Criticism is asymptotically equivalent to the optimal test without knowledge of  $\pi_1$  and/or  $\mu$ 

- If  $r < \rho_{hc}(\beta)$  then for any test

$$\liminf_{m \to \infty} P_0(\text{Type I Error}) + P_1(\text{Type II Error}) \ge 1$$

# Detectable region



## High-dimensional linear model

$$y = X\beta + \varepsilon$$

with response vector y, design matrix  $X_{n \times m}$ , vector of parameters  $\beta$ , gaussian errors  $\varepsilon \sim N_n(0, \sigma^2 I_n)$  and m > n

- For testing  $H_0$ :  $\beta = 0$ , the global test of Goeman (2006)

$$T_{\rm g} = y'XX'y$$

− In low dimensions m < n, the F statistic is  $\propto y'X(X'X)^{-1}X'y$ 

#### Reference

Goeman et al. (2006) Testing against a high dimensional alternative JRSSB