

Flexible Inference for fMRI Data

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Big Data - Big Knowledge

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Joint work with

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Outline

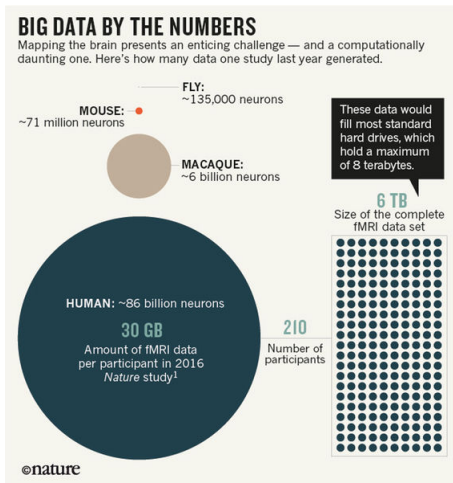
① Introduction

② Cluster-based Inference

③ All-Resolutions Inference

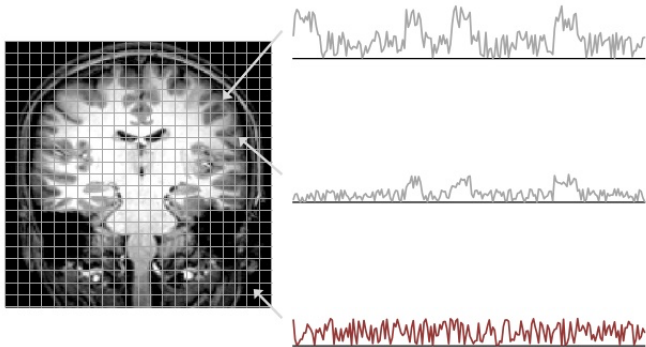
④ Discussion

Big brain



Source: Landhuis (2017)

Brain activity



- Brain activity is measured on a 3D grid of voxels
- Voxel = $3\text{mm} \times 3\text{mm} \times 3\text{mm}$ cube

Go/No-go data

Task

- Go: press a button when you see an happy face 😊
- No-go: hold when you see a neutral face 😐

High-dimensional data

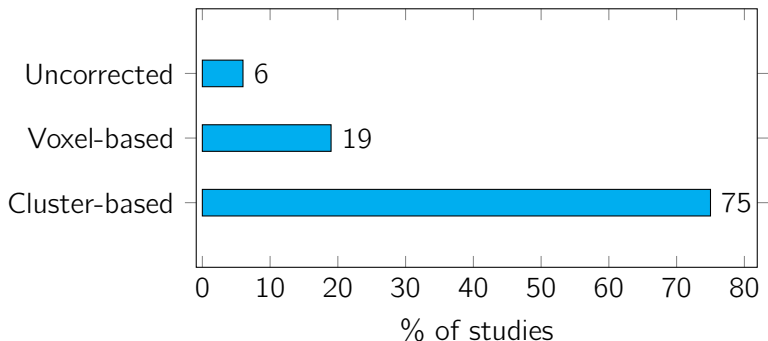
- $n = 34$ subjects
- $m = 225212$ voxels

Test statistics

- Null hypothesis: Go = No-go
- A test statistic Z is computed for each voxel

Standard approaches

Woo et al. (2014) survey *



* 814 fMRI studies published in 2010 and 2011 from Cerebral Cortex, Nature, Nature Neuroscience, NeuroImage, Neuron, PNAS, and Science

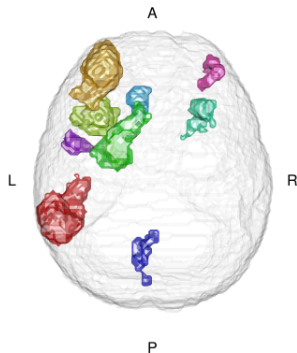
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Cluster-based inference

- Cluster-based inference is **data-driven**: clusters are both defined and tested with the same data
- Issues with circular analysis solved by **random field theory**
- Two steps:
 - ① **Cluster definition**: Z -threshold
e.g. cluster = contiguous voxels with $Z > 3.2$
 - ② **Cluster significance**: α -threshold
e.g. a cluster is significant if RFT p -value $< 5\%$

Significant clusters



9 significant clusters with $Z > 3.2$ and $\alpha = 5\%$

Low spatial resolution

- **Discovering a cluster** means that

“there exists at least one active voxel in the cluster”

and not that

“all the voxels in the cluster are active”

- **Spatial specificity paradox**: the larger the detected cluster, the less information we have on the location of the activation
- No information on the **% of activation** of each cluster

Low spatial resolution

<i>cluster</i>	<i>size</i>	<i># active</i>	<i>% active</i>
A	2191	?	?
B	1835	?	?
C	1400	?	?
D	698	?	?
E	421	?	?
F	304	?	?
G	245	?	?
H	232	?	?
I	187	?	?

Notation

- $B = \{1, 2, \dots, m\}$: brain, collection of m voxels
- $S \subseteq B$: voxel set. A cluster C is a particular case
- $\mathcal{S} = \{S : S \subseteq B\}$ with $|\mathcal{S}| = 2^m$: collection of all voxel sets
- $A \subseteq B$: (unknown) set of truly active voxels

Parameter of interest

- $a(S) = |A \cap S|$: # of truly active voxels in S
- $\pi(S) = a(S)/|S|$: % of truly active voxels in S

Cluster null hypothesis

- Given a pre-specified cluster forming Z -threshold (e.g. $Z > 3.2$), we obtain a collection of candidate clusters \mathcal{C}
- Both the number of clusters $|\mathcal{C}|$ and each cluster $C \in \mathcal{C}$ are random quantities, because are determined by the data
- Cluster null hypothesis

$$H_C : \pi(C) = 0$$

Rejecting H_C implies $\pi(C) > 0$, at least one active voxel in C

- However, the null hypotheses are random

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Proposed approach: ARI

- Rather than testing random hypotheses, we propose a more classical approach
- Construct simultaneous lower bounds $\underline{\pi}(S)$ for the parameter of interest $\pi(S)$ satisfying

$$P(\text{for all } S \in \mathcal{S} : \underline{\pi}(S) \leq \pi(S)) \geq 1 - \alpha$$

- The bound is valid for all S , and therefore for one or more selected S , regardless of how they were selected

Confidence bounds

Based on Goeman and Solari (2011), Meijer et al. (2016) and Rosenblatt et al. (2017) showed that

$$\underline{\pi}(S) = \min \left\{ 0 \leq k \leq |S| : \min_{1 \leq i \leq |S|-k} \frac{h}{i} p_{(i+k:S)} > \alpha \right\} / |S|$$

where $p_{(i:S)}$ is the i th smallest p -value in S and

$$h = \max \left\{ i \in \{0, \dots, m\} : i p_{(m-i+j:B)} > j\alpha, \text{ for } j = 1, \dots, i \right\}$$

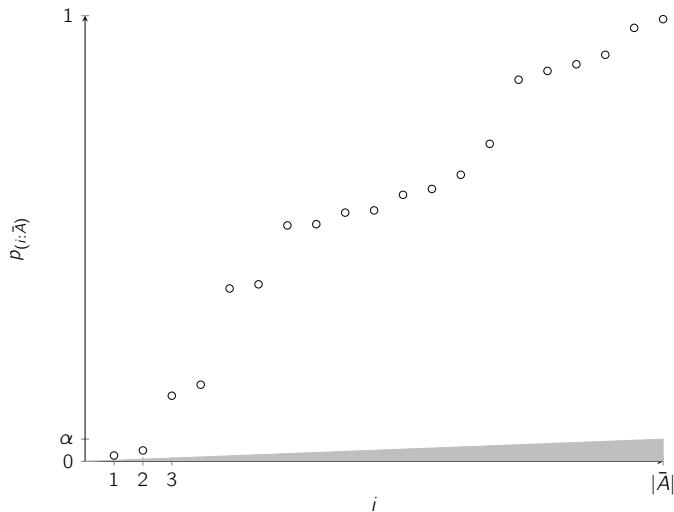
Assumption: Simes inequality

For the set $\bar{A} = B \setminus A$ of all non-active voxels, we assume the Simes inequality

$$P \left(\bigcap_{i=1}^{|\bar{A}|} \left\{ p_{(i:\bar{A})} > \frac{i\alpha}{|\bar{A}|} \right\} \right) \geq 1 - \alpha$$

- It has been shown to hold for independent p -values, and under various conditions implying non-negative correlations between p -values, one of which is the PRDS condition
- For instance, Simes inequality is necessary for the Benjamini and Hochberg (1995) procedure
- Nichols and Haysaka (2003) suggested that PRDS, and therefore the Simes inequality, is plausible for brain maps

Simes inequality



Computation time

- Sorting the p -values: linearithmic $O(m \log m)$
- Computing h (only once): linearithmic $O(m \log m)$
- Computing $\underline{\pi}(S)$: linear in S
- With $m = 225212$ takes seconds

ARI: quantify and localize

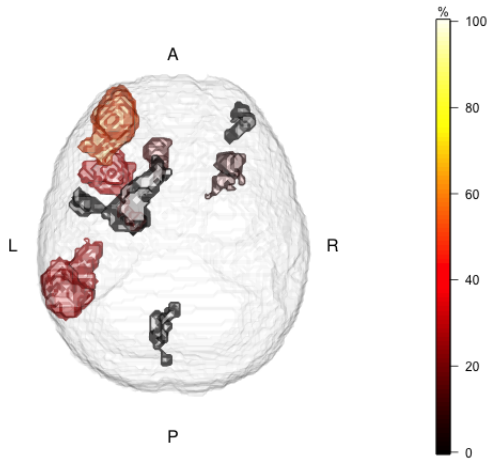
- 1 **quantify** the activation of each cluster
- 2 **localize** the source of the activation within the cluster:
a “drill-down” from discovered clusters to sub-clusters

Quantify

<i>cluster</i>	<i>size</i>	$\# \text{ active}$ $\underline{a}(C)$	$\% \text{ active}$ $\underline{\pi}(C)$
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A	2191	624	29 %
B	1835	847	46 %
C	1400	454	32 %
D	698	0	0 %
E	421	25	6 %
F	304	33	11 %
G	245	0	0 %
H	232	0	0 %
I	187	0	0 %

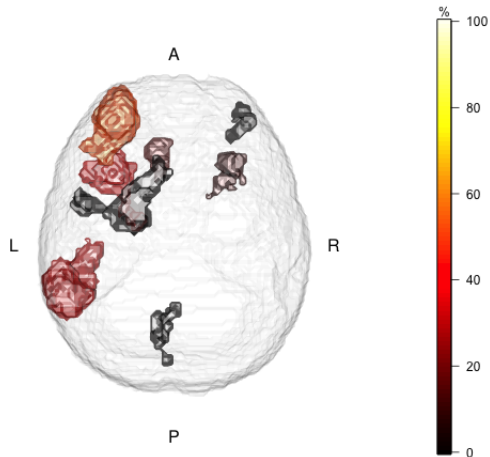
Quantify



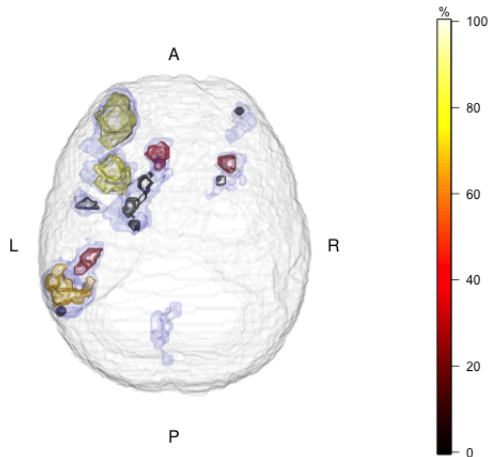
Localize

<i>cluster</i>	<i>threshold</i>	<i>size</i>	<i># active</i>	<i>% active</i>
A	$Z > 3.2$	2191	624	29 %
1	$Z > 4$	405	267	66 %
2	$Z > 4$	133	31	23 %
3	$Z > 4$	6	0	0 %
B	$Z > 3.2$	1835	847	46 %
1	$Z > 4$	963	826	86 %
C	$Z > 3.2$	1400	454	32%
1	$Z > 4$	583	449	77 %
2	$Z > 4$	4	0	0 %
3	$Z > 4$	1	0	0 %
⋮				

Localize



Localize






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Discussion

- ARI brings unprecedented flexibility to the analysis of fMRI data
- With ARI, users can iterate the process of
 - ① choosing regions in any way, also after seeing the data
 - ② quantify the % of activation
 - ③ refine the regionswithout compromising the validity of the inference
- ARI is implemented in R package `homme1`

References

-  Goeman JJ and Solari (2011)
Multiple Testing for Exploratory Research
Statistical Science, 26:584?597
-  Meijer RS, Krebs TJP, Solari A and Goeman JJ (2016)
Simultaneous Control of All Discovery Proportions by an Extension of Hommel's Method
Arxiv
-  Rosenblatt JD, Finos L, Weeda WW, Solari A and Goeman JJ (2017)
All-Resolutions Inference for Brain Imaging
Submitted