

Tarea 02

Ecualización de imagen

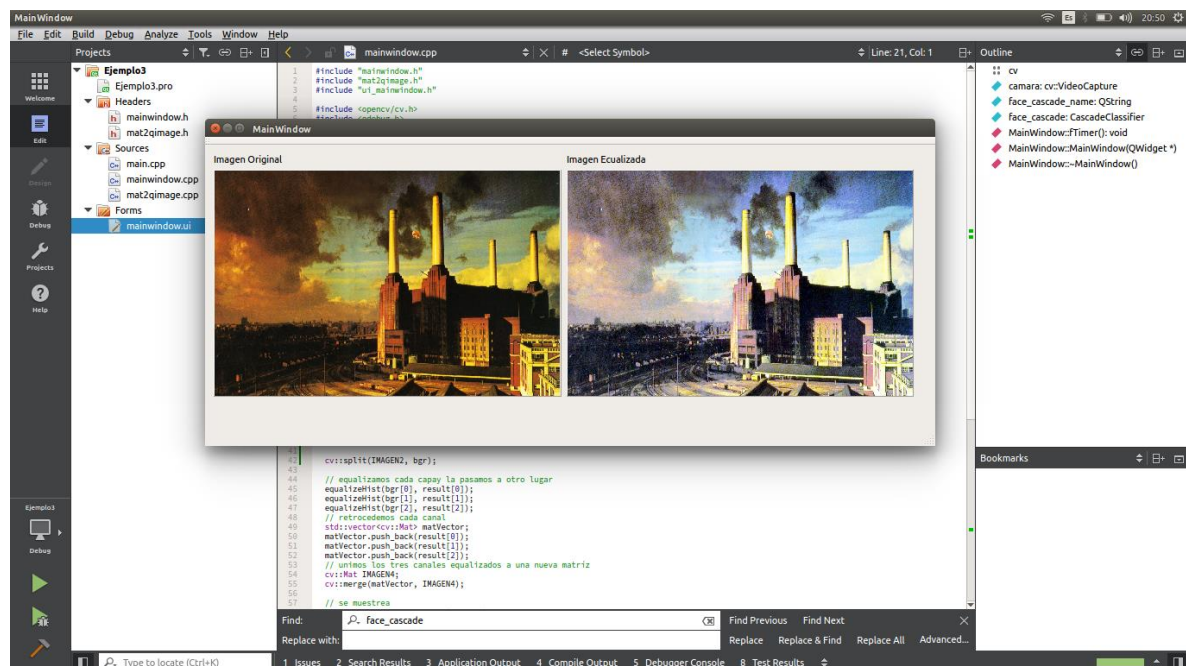
Aldo Alejandro Vargas Meza

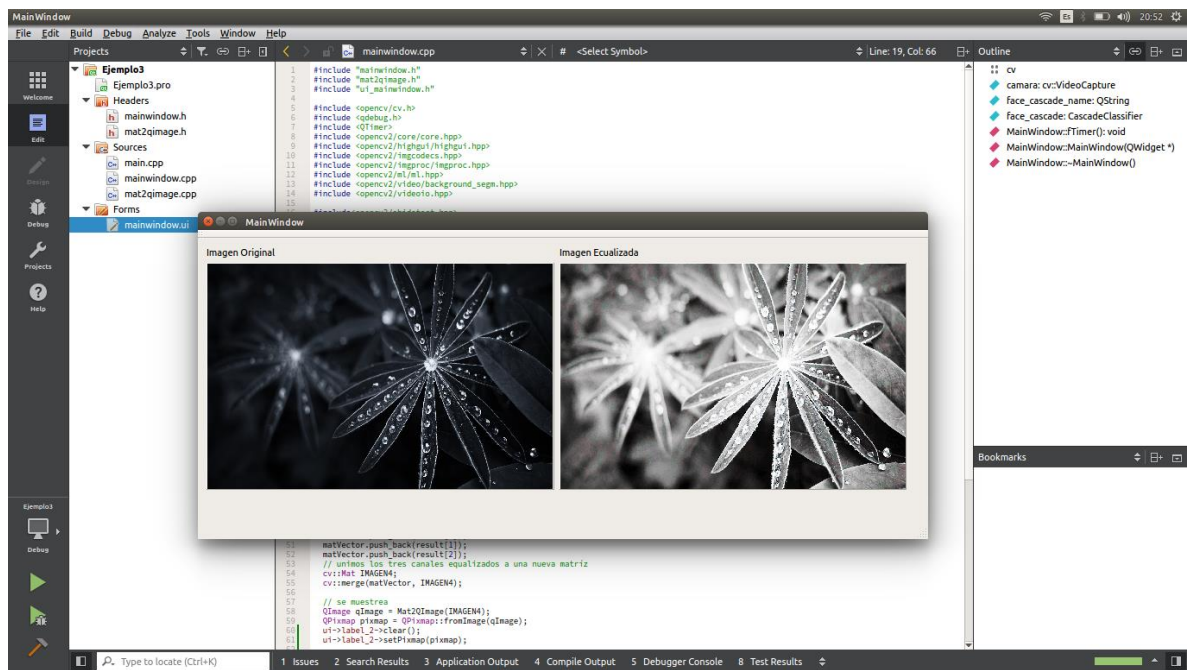
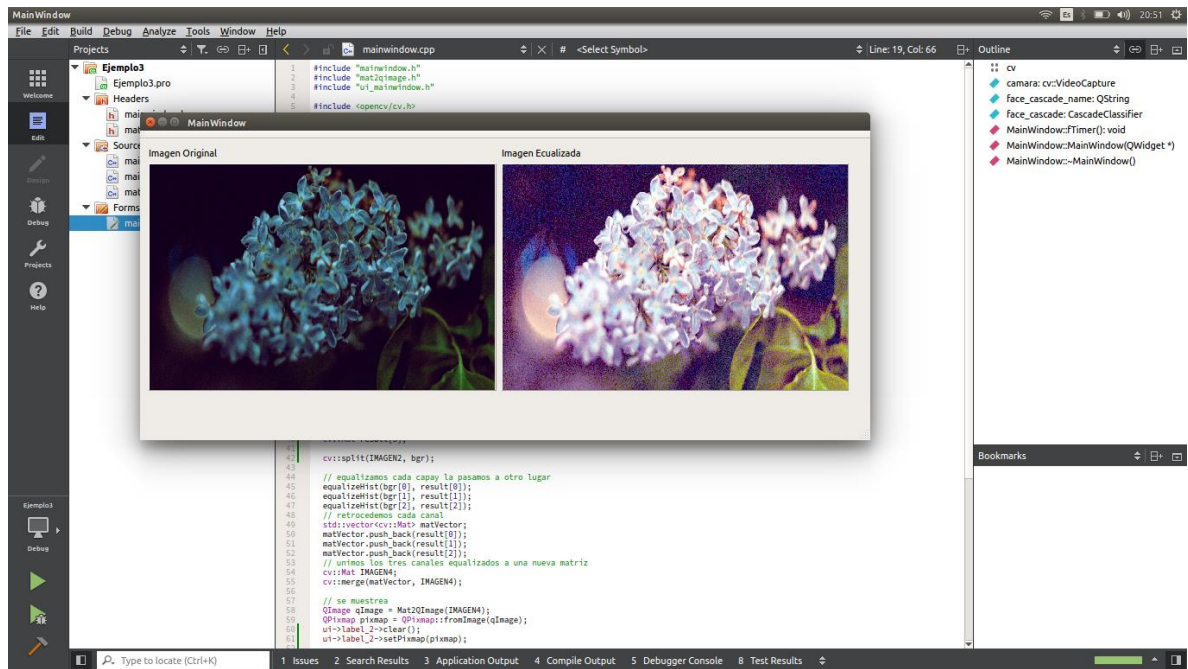
13/10/2017



La tarea consiste en tratar las capas que componen a una imagen, para poder resaltar los bordes mas sutiles. Con esto, se busca encontrar diferentes patrones que en la imagen original es mas complicado.

Introducción





Desarrollo:

conclusión:

Códigos

```
/* Librerías y archivos incluidos */
#include "mainwindow.h"
#include "mat2qimage.h"
#include "ui_mainwindow.h"

#include <opencv/cv.h>
#include <qdebug.h>
#include <QTimer>
#include <opencv2/core/core.hpp>
#include <opencv2/highgui/highgui.hpp>
#include <opencv2/imgcodecs.hpp>
#include <opencv2/imgproc/imgproc.hpp>
#include <opencv2/ml/ml.hpp>
#include <opencv2/video/background_segm.hpp>
#include <opencv2/videoio.hpp>

#include <opencv2/objdetect.hpp>

/* MACROS */
#define IP 0
#define IMG_ADD "/home/aldo/Imágenes/Wallpapers/1505520401699.jpg"
#define CASCADE "../haarcascade_frontalface_alt2.xml"

using namespace cv;

QString face_cascade_name = QString(CASCADE);
CascadeClassifier face_cascade;

MainWindow::MainWindow(QWidget *parent)
    : QMainWindow(parent), ui(new Ui::MainWindow) {
    ui->setupUi(this);

    if (!face_cascade.load(face_cascade_name.toUtf8().constData())) {
        qDebug() << "Error al cargar el detector de rostros";
    }

    QTimer *cronometro = new QTimer(this);
    connect(cronometro, SIGNAL(timeout()), this, SLOT(fTimer()));
    cronometro->start(30);

    if (!camara.isOpened()) camara.open(IP);
```

```

}

MainWindow::~MainWindow() { delete ui; }

void MainWindow::fTimer() {
    /* Matrices para Imagen */
    Mat IMAGEN;
    Mat IMAGEN2;
    Mat IMAGEN3;
    Mat IMAGEN4;

    Mat GRIS;
    Mat rgb[3];
    Mat result[3];

    /* Lectura de Imagen */
    IMAGEN = cv::imread(IMG_ADD);
    /* Ajuste de dimension */
    cv::resize(IMAGEN, IMAGEN2, Size(400, 300), 0, 0, 0);

    cv::split(IMAGEN2, rgb);

    /* Ecuacion y guardado por capas */
    equalizeHist(rgb[0], result[0]);
    equalizeHist(rgb[1], result[1]);
    equalizeHist(rgb[2], result[2]);

    std::vector<cv::Mat> matVector;
    matVector.push_back(result[0]);
    matVector.push_back(result[1]);
    matVector.push_back(result[2]);

    /* Union de 3 canales en la matriz */
    cv::merge(matVector, IMAGEN4);

    /* Impresion en Etiquetas */
    QImage qImage = Mat2QImage(IMAGEN4);
    QPixmap pixmap = QPixmap::fromImage(qImage);
    ui->label_2->clear();
    ui->label_2->setPixmap(pixmap);

    QImage qImage1 = Mat2QImage(IMAGEN2);
    QPixmap pixmap1 = QPixmap::fromImage(qImage1);
    ui->label->clear();
    ui->label->setPixmap(pixmap1);
}

#ifdef MAINWINDOW_H
#define MAINWINDOW_H

#include <QMainWindow>

```

```

namespace Ui {
class MainWindow;
}

class MainWindow : public QMainWindow
{
    Q_OBJECT

public:
    explicit MainWindow(QWidget *parent = 0);
    ~MainWindow();

public slots:

    void fTimer();
private slots:

private:
    Ui::MainWindow *ui;
};

#endif // MAINWINDOW_H

#-----
#
# Project created by QtCreator 2017-08-18T16:20:48
#
#-----

QT += core gui

greaterThan(QT_MAJOR_VERSION, 4): QT += widgets

TARGET = pencv_videoio
TEMPLATE = app

# The following define makes your compiler emit warnings if you use
# any feature of Qt which as been marked as deprecated (the exact warnings
# depend on your compiler). Please consult the documentation of the
# deprecated API in order to know how to port your code away from it.
DEFINES += QT_DEPRECATED_WARNINGS

# You can also make your code fail to compile if you use deprecated APIs.
# In order to do so, uncomment the following line.
# You can also select to disable deprecated APIs only up to a certain version of Qt.
#DEFINES += QT_DISABLE_DEPRECATED_BEFORE=0x060000   # disables all the APIs deprecated before Qt
6.0.0

SOURCES += \
    main.cpp \
    mainwindow.cpp \

```

mat2qimage.cpp

HEADERS += \
 mainwindow.h \
 mat2qimage.h

FORMS += \
 mainwindow.ui

INCLUDEPATH += /usr/local/include/opencv2

LIBS += -L/usr/local/lib -lopencv_core -lopencv_imgcodecs -lopencv_highgui -opencv_videoio

CONFIG += link_pkgconfig

PKGCONFIG += opencv