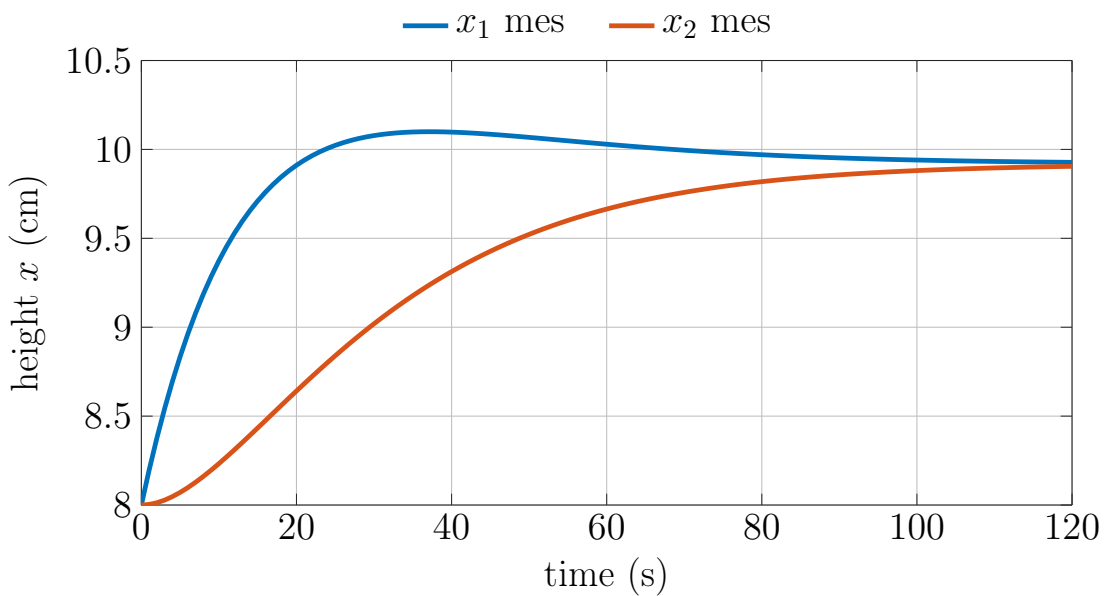


FL - x with state measure



FL - model u with state measure

