

Implementación de Métodos de Aprendizaje Automatizado en problemas colisionales

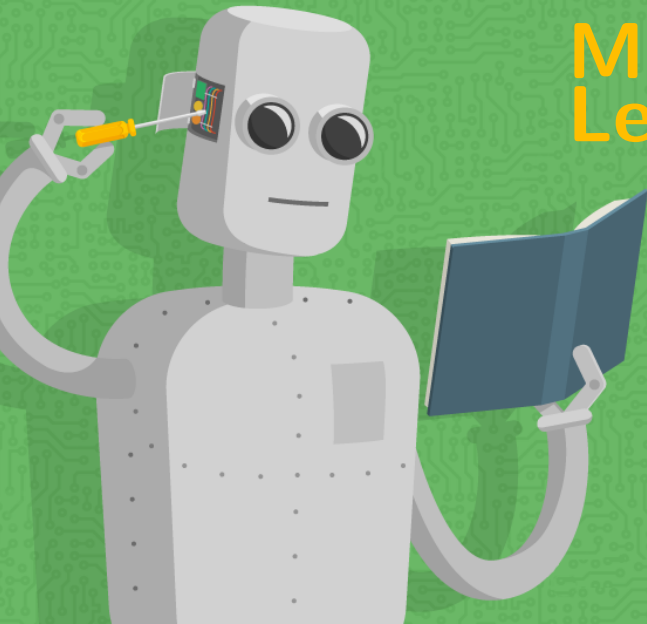


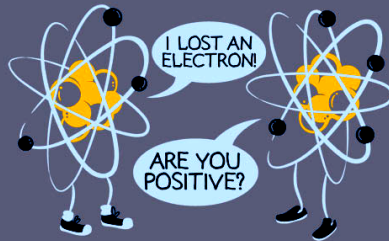
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1 de Septiembre – Buenos Aires

Machine Learning





Método de Inversión Depurada (DIM)

$$T_{fi} = |\langle \psi_f | V | \psi_i \rangle|^2$$

Método de Inversión Depurada (DIM)

¿Cómo
conocemos V ?

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$$\left[-\frac{1}{2} \frac{\partial^2}{\partial r^2} + \frac{l(l+1)}{2r^2} + \mathbf{V}_{nl}(r) \right] \varphi_{nl}(r) = E_{nl} \varphi_{nl}(r)$$

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$$\mathbf{V}_{nl}(r) = \frac{1}{2} \frac{\varphi_{nl}''(r)}{\varphi_{nl}(r)} - \frac{l(l+1)}{2r^2} + E_{nl}$$

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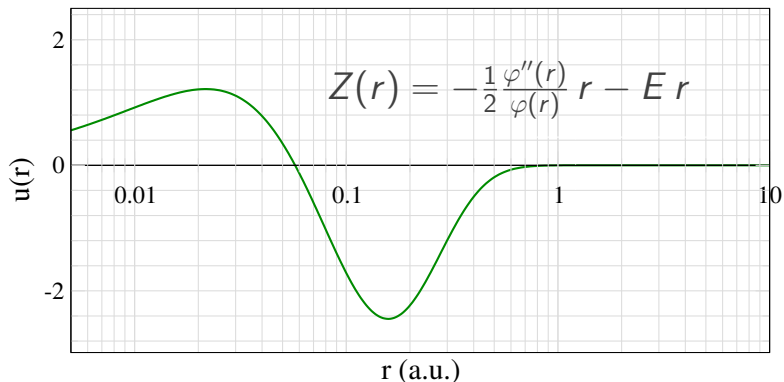
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$$\left[-\frac{1}{2} \frac{\partial^2}{\partial r^2} + \frac{l(l+1)}{2r^2} - \frac{\mathbf{Z}_{nl}(\mathbf{r})}{r} \right] \varphi_{nl}(r) = E_{nl} \varphi_{nl}(r)$$

$$\mathbf{Z}_{nl}(\mathbf{r}) = -\frac{1}{2} \frac{\varphi_{nl}''(r)}{\varphi_{nl}(r)} r + \frac{l(l+1)}{2r} - E_{nl} r$$

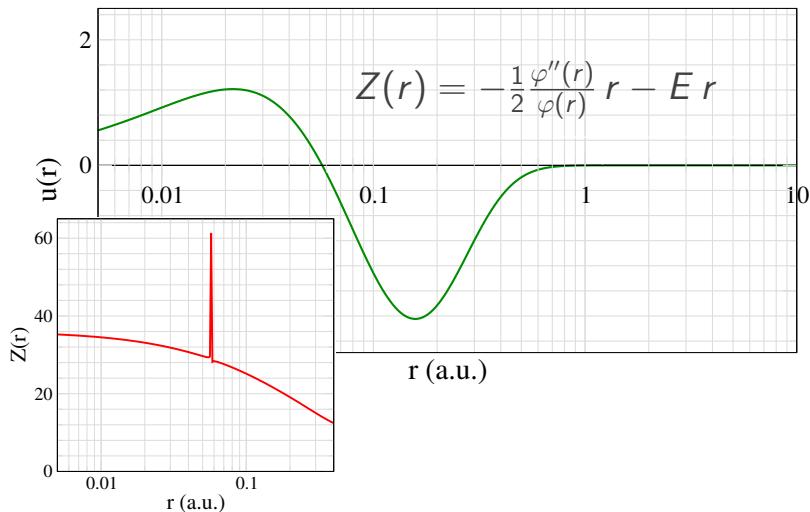
Houston, we have a problem!

2s Kr



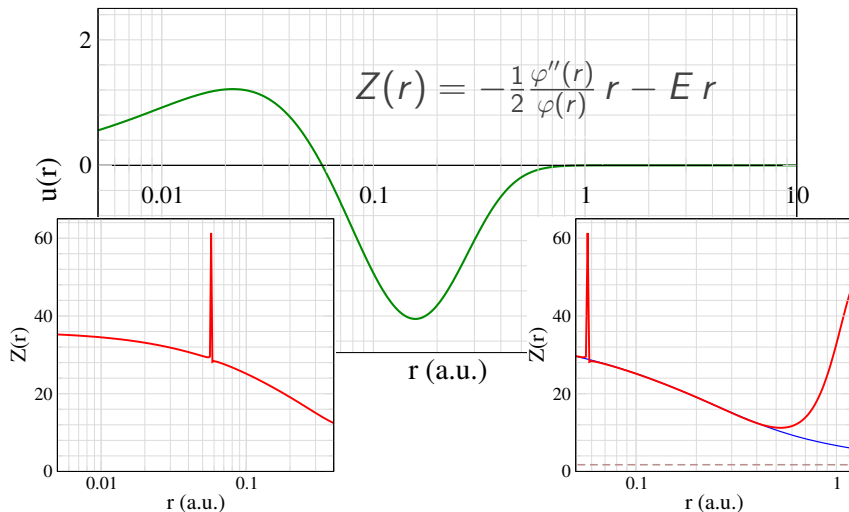
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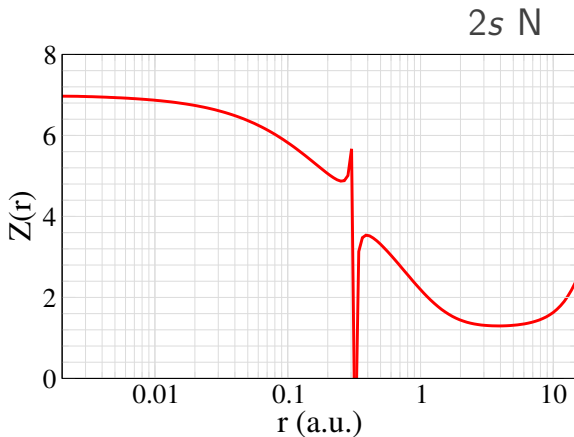


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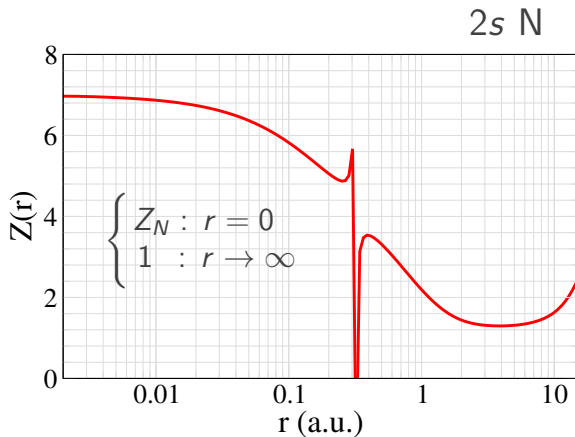
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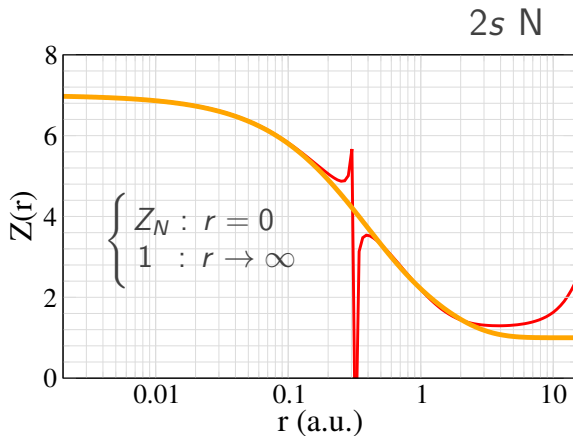
Depuración



Depuración

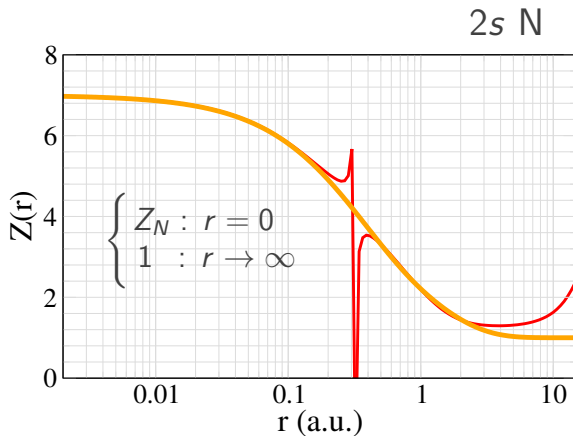


Depuración



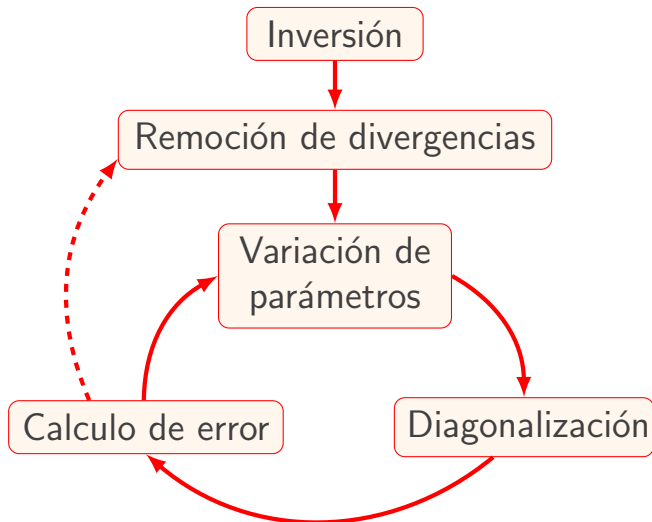
$$Z(r) = 1 + \sum_j \alpha_j e^{-\beta_j r}$$

Depuración



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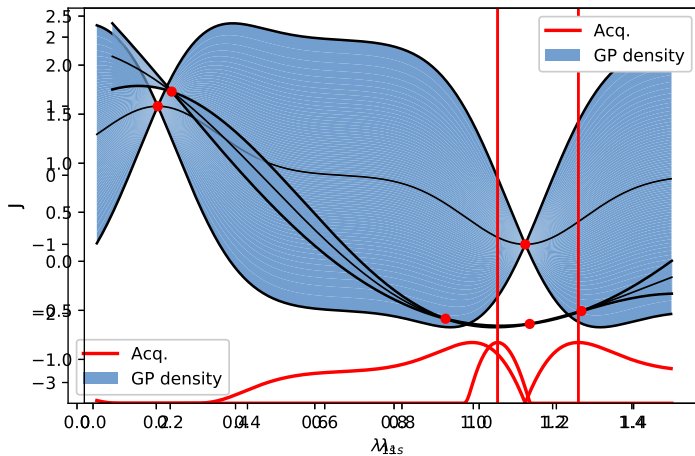
Procedimiento



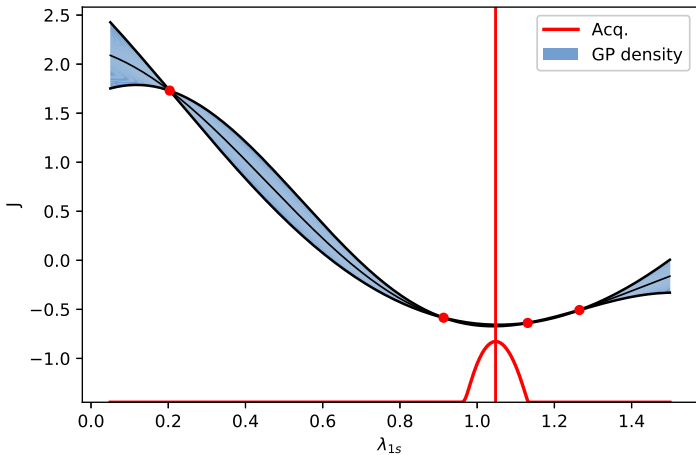


Optimización Bayesiana

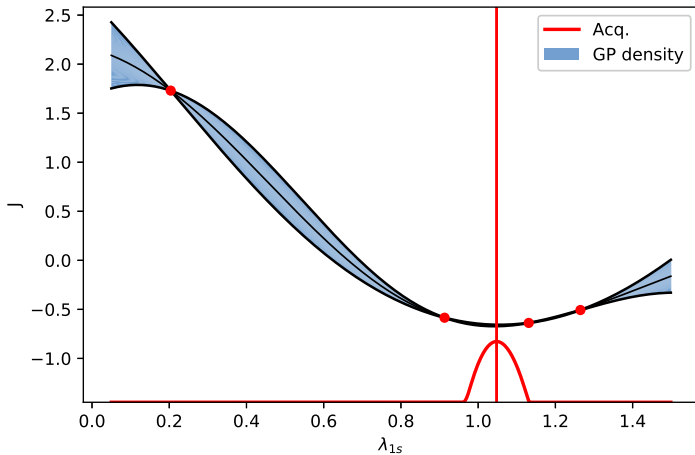
Gaussian Process



Gaussian Process



Gaussian Process



Gaussian Process

