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```
In [16]: import pandas as pd
import numpy as np
from tqdm import tqdm

from sklearn.metrics import accuracy_score
from sklearn.metrics import precision_score
from sklearn.metrics import recall_score

In [17]: !ls
```

README.md solution.ipynb

Используем набор данных партий игр в крестики нолики (tic-tac-toe). Целью является показать победил ли игрок ходивший первым.

Проведем бинаризацию признаков.

Out[20]:

	0_b	0_o	0_x	1_b	1_0	1_x	2_b	2 _o	2_x	3_b	•••	6_b	6_o	6_x	7_b	7_o	7_x	8_b	8_o	8_x	target
0	0	0	1	0	0	1	0	0	1	0		0	0	1	0	1	0	0	1	0	1
1	0	0	1	0	0	1	0	0	1	0		0	1	0	0	0	1	0	1	0	1
2	0	0	1	0	0	1	0	0	1	0		0	1	0	0	1	0	0	0	1	1
3	0	0	1	0	0	1	0	0	1	0		0	1	0	1	0	0	1	0	0	1
4	0	0	1	0	0	1	0	0	1	0		1	0	0	0	1	0	1	0	0	1

5 rows × 28 columns

Разделим исходные данные на обучающую и контрольную подвыборки в отношении 7:3.

```
In [21]: from sklearn.model_selection import train_test_split
    df_train, df_test = train_test_split(df, test_size=0.3)
    len(df_train), len(df_test)
```

Out[21]: (670, 288)

```
In [22]: X_train, y_train = df_train.drop(['target'], axis=1), df_train['target']
X_test, y_test = df_test.drop(['target'], axis=1), df_test['target']
```

В предложенной реализации удобно разделить объекты из негативного и позитивного контекстовю

```
In [23]: X_train_pos = np.array(X_train[y_train == 1])
X_train_neg = np.array(X_train[y_train == 0])
```

Для настройки уровня влияния поддержки и достоверности введем вспомогательный коэффициент.

```
In [50]: RECALL_RATIO = 0.35
```

Реализуем предложенный простой вариант алгоритма.

```
In [51]: def print_apc(metrics) :
             print('accuracy {}'.format(metrics[0]))
             print('precision {}'.format(metrics[1]))
             print('recall {}'.format(metrics[2]))
         def get_impact_baseline(obj, X):
             impact = 0
             for x in X:
                 common_ids = (obj == x)
                 closure_power = np.sum(np.all(obj[common_ids] == X[:, common_ids], axis=1)) - 1
                 assert(closure_power >= 0)
                 impact += closure_power
             return impact
         def apply baseline():
             y_pred = np.zeros(len(X_test), dtype=np.int32)
             for i, test_obj in tqdm(enumerate(np.array(X_test)), position=0):
                 positive impact = get impact baseline(test obj, X train pos)
                 negative_impact = get_impact_baseline(test_obj, X_train_neg)
                 y_pred[i] = (positive_impact * RECALL_RATIO > negative_impact)
             accuracy = accuracy_score(y_test, y_pred)
             precision = precision_score(y_test, y_pred)
             recall = recall_score(y_test, y_pred)
             return accuracy, precision, recall
```

Усовершенствуем алгоритм.

Нормализуем величину поддержки/влияния на размер контекста.

recall 0.9027027027027027

Положим вес(weight) каждого замыкания пропорционально размеру пересечения.

Введем параметр weight_power.

Итоговый вес будет вычисляться как степенная функция от веса(weight) с показателем weight_power.

```
In [55]: RECALL RATIO = 0.8
         def get_impact(obj, X, weight_power):
             impact = 0
             for x in X:
                 common ids = (obj == x)
                 weight = np.sum(common_ids) / len(common_ids)
                 closure_power = np.sum(np.all(obj[common_ids] == X[:, common_ids], axis=1)) - 1
                 assert(closure_power >= 0)
                 impact += closure_power * (weight**weight_power)
             impact /= len(X)
             return impact
         def apply(weight power):
             y_pred = np.zeros(len(X_test), dtype=np.int32)
             for i, test_obj in tqdm(enumerate(np.array(X_test)), position=0):
                 positive_impact = get_impact(test_obj, X_train_pos, weight_power)
                 negative_impact = get_impact(test_obj, X_train_neg, weight_power)
                 y_pred[i] = (positive_impact * RECALL_RATIO > negative_impact)
             accuracy = accuracy_score(y_test, y_pred)
             precision = precision score(y test, y pred)
             recall = recall_score(y_test, y_pred)
             return accuracy, precision, recall
```

```
In [56]: accuracy, precision, recall = apply(5)
    print("acc : {}, precision : {}, recall : {}".format(accuracy, precision, recall))

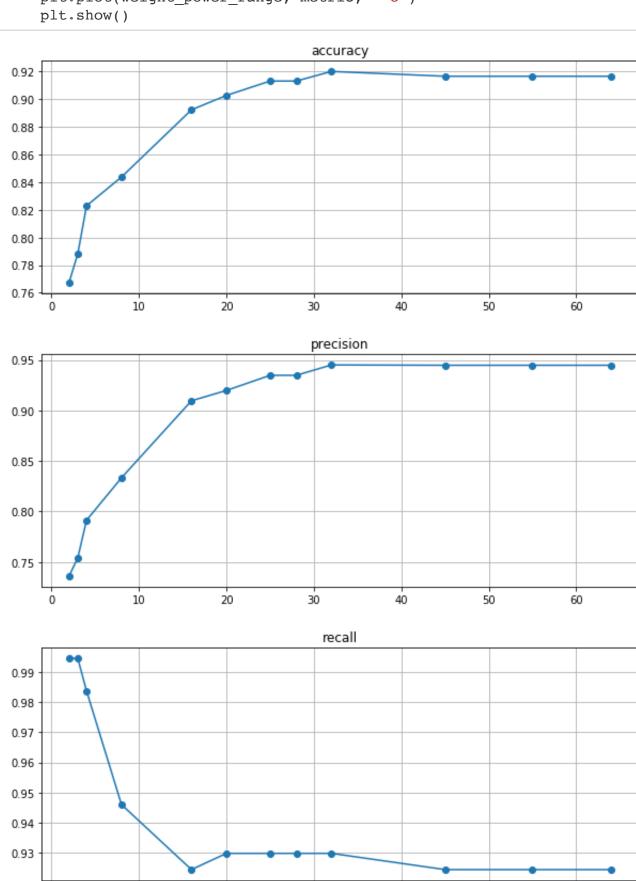
288it [00:05, 50.62it/s]
    acc : 0.8333333333333334, precision : 0.8071748878923767, recall : 0.972972972972973
```

Результат заметно лучше по всем метрикам.

Подберем оптимальный параметр weight_power.

```
In [57]: weight_power_range = [2, 3, 4, 8, 16, 20, 25, 28, 32, 45, 55, 64]
         accuracy_all, precision_all, recall_all = [], [], []
         for weight_power in weight_power_range:
             accuracy, precision, recall = apply(weight_power)
             accuracy_all.append(accuracy)
             precision all.append(precision)
             recall_all.append(recall)
         288it [00:05, 48.93it/s]
         288it [00:05, 50.57it/s]
         288it [00:05, 53.08it/s]
         288it [00:05, 53.61it/s]
         288it [00:05, 51.93it/s]
         288it [00:05, 54.33it/s]
         288it [00:05, 51.56it/s]
         288it [00:05, 52.48it/s]
         288it [00:05, 50.89it/s]
         288it [00:05, 51.51it/s]
         288it [00:05, 52.76it/s]
         288it [00:05, 52.55it/s]
         import matplotlib.pyplot as plt
In [61]:
          %matplotlib inline
```

```
In [62]: metrics = (accuracy_all, precision_all, recall_all)
    names = ("accuracy", "precision", "recall")
    for name, metric in zip(names, metrics):
        plt.figure(figsize=(10,4))
        plt.grid(True)
        plt.title(name)
        plt.plot(weight_power_range, metric, '-o')
        plt.show()
```



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При данной точности измерений, оптимальной точкой примем weight_power=32

```
In [64]: accuracy, precision, recall = apply(32)
    print("acc : {}, precision : {}, recall : {}".format(accuracy, precision, recall))

288it [00:05, 53.27it/s]
    acc : 0.920138888888888, precision : 0.945054945054945, recall : 0.9297297297297298
```