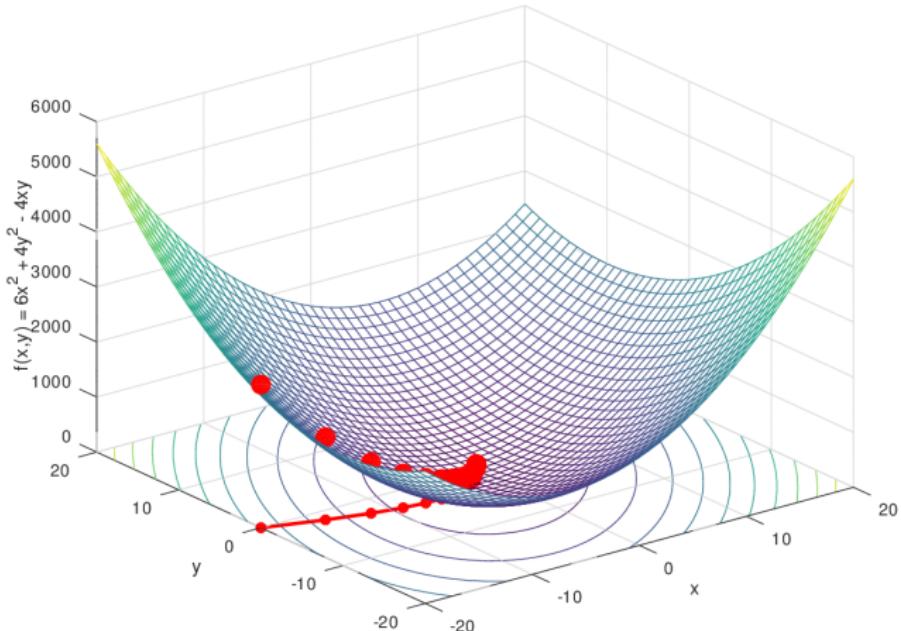


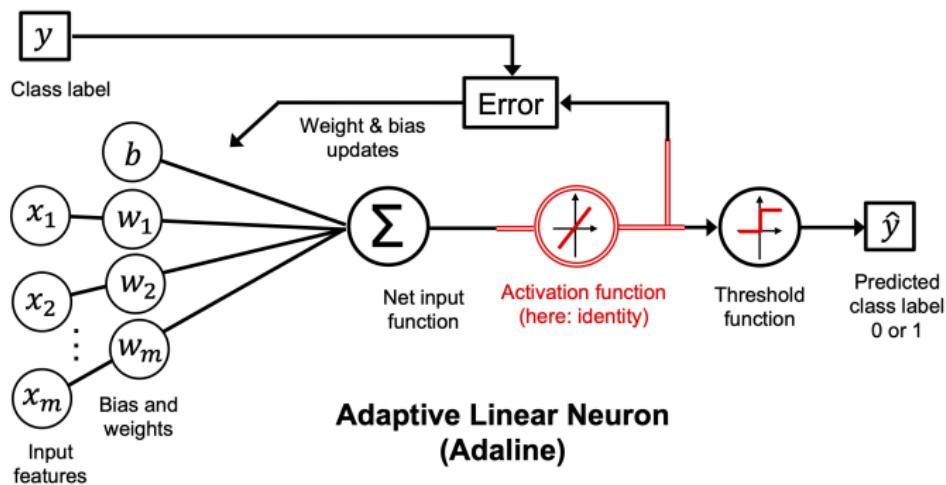
# Gradient Descent

**Recall:** Gradient Descent ...



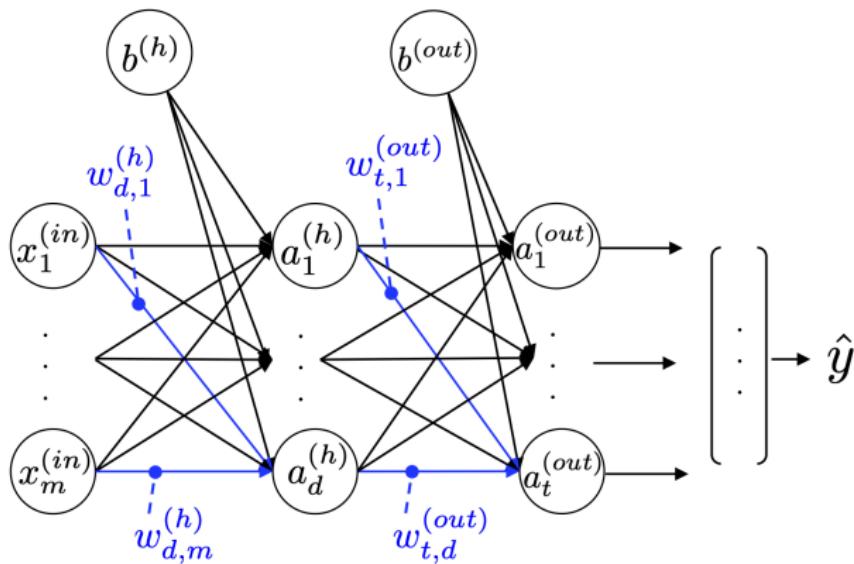
# Logistic Regression

Recall: Logistic Regression . . .



# Neural Network Architecture

**Idea:** Layer this architecture . . .



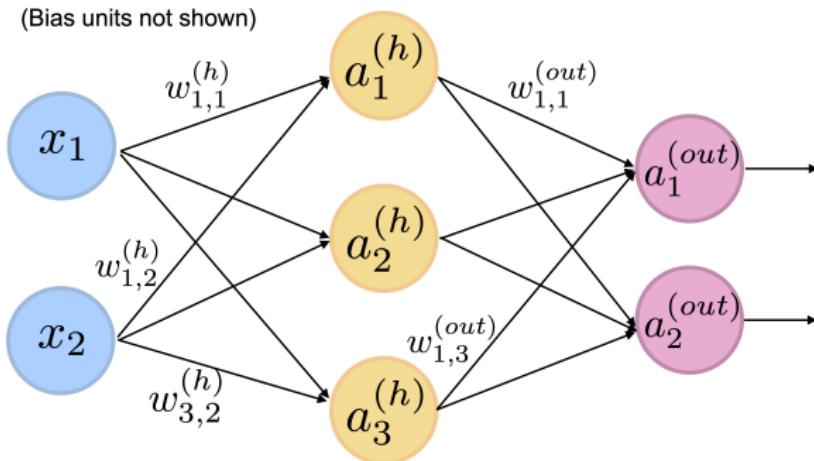
Data input  
("input layer"  $in$ )

1<sup>st</sup> layer  
(hidden layer  $h$ )

2<sup>nd</sup> layer  
(output layer  $out$ )

# Neural Network Architecture

**Idea:** Meaning?



- ▶ There are other activation functions
- ▶ What awaits at the end?

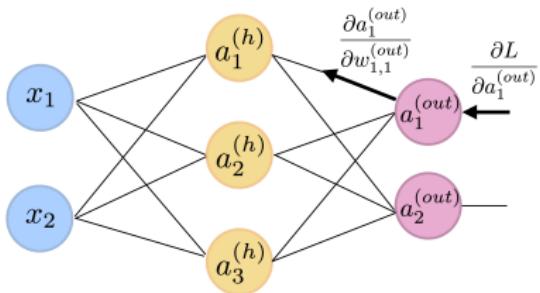
# Back Propagation

A loss function ...

$$L(\mathbf{W}, \mathbf{b}) = \frac{1}{n} \sum_{i=1}^n \frac{1}{t} \sum_{j=1}^t (y_j^{[i]} - a_j^{(out)[i]})^2$$

We need:

$$\frac{\partial}{\partial w_{j,l}^{(l)}} = L(\mathbf{W}, \mathbf{b})$$



Gradient for output layer weight:

$$\frac{\partial L}{\partial w_{1,1}^{(out)}} = \frac{\partial L}{\partial a_1^{(out)}} \cdot \frac{\partial a_1^{(out)}}{\partial w_{1,1}^{(out)}}$$

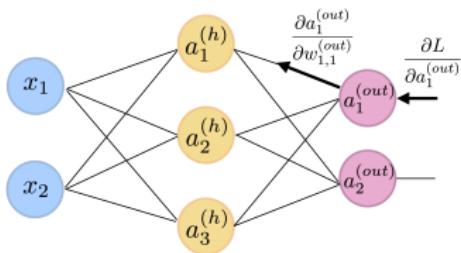
# Chain Rule

Given a *composition* of functions, the derivative is:

$$\frac{dF}{dx} = \frac{d}{dx} F(x) = \frac{d}{dx} f(g(h(u(v(x))))) = \frac{df}{dg} \cdot \frac{dg}{dh} \cdot \frac{dh}{du} \cdot \frac{du}{dv} \cdot \frac{dv}{dx}$$

In our case, this means:

$$\frac{\partial L}{\partial w_{1,1}^{(out)}} = \frac{\partial L}{\partial a_1^{(out)}} \cdot \frac{\partial a_1^{(out)}}{\partial z_1^{(out)}} \cdot \frac{\partial z_1^{(out)}}{\partial w_{1,1}^{(out)}}$$



Gradient for output layer weight:

$$\frac{\partial L}{\partial w_{1,1}^{(out)}} = \frac{\partial L}{\partial a_1^{(out)}} \cdot \frac{\partial a_1^{(out)}}{\partial w_{1,1}^{(out)}}$$

# Breaking apart the Chain Rule

$$\frac{\partial L}{\partial a_1^{(out)}} = \frac{\partial}{\partial a_1^{(out)}} (y_1 - a_1^{(out)})^2 = 2(a_1^{(out)} - y)$$

The next term is the derivative of the logistic sigmoid activation function that we used in the output layer:

$$\begin{aligned} \frac{\partial a_1^{(out)}}{\partial z_1^{(out)}} &= \frac{\partial}{\partial z_1^{(out)}} \frac{1}{1 + e^{z_1^{(out)}}} = \dots = \left( \frac{1}{1 + e^{z_1^{(out)}}} \right) \left( 1 - \frac{1}{1 + e^{z_1^{(out)}}} \right) \\ &= a_1^{(out)} (1 - a_1^{(out)}) \end{aligned}$$

Lastly, we compute the derivative of the net input with respect to the weight:

$$\frac{\partial z_1^{(out)}}{\partial w_{1,1}^{(out)}} = \frac{\partial}{\partial w_{1,1}^{(out)}} a_1^{(h)} w_{1,1}^{(out)} + b_1^{(out)} = a_1^{(h)}$$

Putting all of it together, we get the following:

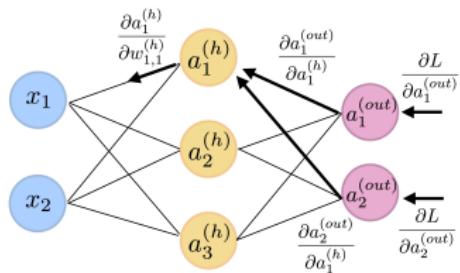
$$\frac{\partial L}{\partial w_{1,1}^{(out)}} = \frac{\partial L}{\partial a_1^{(out)}} \cdot \frac{\partial a_1^{(out)}}{\partial z_1^{(out)}} \cdot \frac{\partial z_1^{(out)}}{\partial w_{1,1}^{(out)}} = 2(a_1^{(out)} - y) \cdot a_1^{(out)} (1 - a_1^{(out)}) \cdot a_1^{(h)}$$

We then use this value to update the weight via the familiar stochastic gradient descent update with a learning rate of  $\eta$ :

$$w_{1,1}^{(out)} := w_{1,1}^{(out)} - \eta \frac{\partial L}{\partial w_{1,1}^{(out)}}$$

It gets more complicated . . .

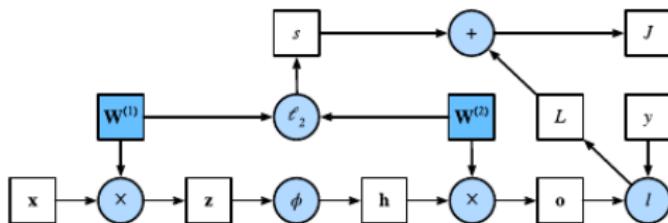
# Deeper into Backprop



Gradient for hidden layer weight:

$$\begin{aligned}\frac{\partial L}{\partial w_{1,1}^{(h)}} &= \frac{\partial L}{\partial a_1^{(out)}} \cdot \frac{\partial a_1^{(out)}}{\partial a_1^{(h)}} \cdot \frac{\partial a_1^{(h)}}{\partial w_{1,1}^{(h)}} \\ &\quad + \frac{\partial L}{\partial a_2^{(out)}} \cdot \frac{\partial a_2^{(out)}}{\partial a_1^{(h)}} \cdot \frac{\partial a_1^{(h)}}{\partial w_{1,1}^{(h)}}\end{aligned}$$

Computational graphs are key . . .



**Idea:** You backprop along the computational graph . . .