Attention via $\log \sum \exp$ energy

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Overview

 $\log \sum exp\ framework$

 $\log \sum exp \ examples$

 $\log \sum \exp$ graphical models

 $\log \sum \exp$ spatio-temporal model

Renormalised mixture models

$\log \sum \exp \text{ energy}$

We consider energy functions that map a set of parents $\{v_p \in \mathbb{R}^{d_p} : p \in P\}$ to a set of children $\{v_c \in \mathbb{R}^{d_c} : c \in C\}$.

Each energy function defines a similarity function (with parameters θ) that measures agreement between a parent and child vector:

$$\sin_{\theta}(\mathbf{v}_c, \mathbf{v}_p) : \mathbb{R}^{d_c} \times \mathbb{R}^{d_p} \to \mathbb{R}.$$

The $\log \sum$ exp energy function is then given by:

$$E(\{\mathbf{v}_c\}, \{\mathbf{v}_p\}, \theta) = -\sum_{c \in C} \ln \left(\sum_{p \in P} \exp \left(\operatorname{sim}_{\theta}(\mathbf{v}_c, \mathbf{v}_p) \right) \right).$$

$\log \sum \exp$ derivatives

We define attention as:

$$\alpha_{c,p} = \operatorname{softmax}_p \big(\operatorname{sim}_{\theta}(\mathbf{\textit{v}}_c, \mathbf{\textit{v}}_p) \big) = \frac{\exp \big(\operatorname{sim}_{\theta}(\mathbf{\textit{v}}_c, \mathbf{\textit{v}}_p) \big)}{\sum_{p' \in P} \exp \big(\operatorname{sim}_{\theta}(\mathbf{\textit{v}}_c, \mathbf{\textit{v}}_{p'}) \big)}.$$

The derivatives with are then given by:

$$-\frac{\partial E}{\partial \mathbf{v}_{c}} = \sum_{p \in P} \alpha_{c,p} \frac{\partial \operatorname{sim}_{\theta}(\mathbf{v}_{c}, \mathbf{v}_{p})}{\partial \mathbf{v}_{c}},$$

$$-\frac{\partial E}{\partial \mathbf{v}_{p}} = \sum_{c \in C} \alpha_{c,p} \frac{\partial \operatorname{sim}_{\theta}(\mathbf{v}_{c}, \mathbf{v}_{p})}{\partial \mathbf{v}_{p}},$$

$$-\frac{\partial E}{\partial \theta} = \sum_{c \in C} \sum_{p \in P} \alpha_{c,p} \frac{\partial \operatorname{sim}_{\theta}(\mathbf{v}_{c}, \mathbf{v}_{p})}{\partial \theta}.$$

$\log \sum \exp$ derivatives

The gradient of the energy function can be interpreted as an expected value over a discrete distribution $\alpha_{c,p} = P(p \mid c)$:

$$-\frac{\partial E}{\partial \mathbf{v}_c} = \mathbb{E}_{p \sim P(p|c)} \left[\frac{\partial \text{sim}_{\theta}(\mathbf{v}_c, \mathbf{v}_p)}{\partial \mathbf{v}_c} \right]$$
(1)

While the child gradient is an exact expectation under $P(p \mid c)$, the parent gradient does not correspond exactly to an expectation under $P(c \mid p)$; it is instead proportional to it through Bayes rule.

$\log \sum \exp$ graphical models

We consider a single set of N nodes $\mathbf{v} = \{\mathbf{v}_i : i \in \{1, 2, ..., N\}\}$, where each node $\mathbf{v}_i \in \mathbb{R}^{d_i}$, and M energy functions $\{E_m : m \in \{1, 2, ..., M\}\}$.

Each E_m has a similarity function $\operatorname{sim}_m(\cdot)$ with parameters θ_m and defines a subset of nodes acting as *children* $C_m \subseteq \{1, 2, \dots, N\}$ and a subset acting as *parents* $P_m \subseteq \{1, 2, \dots, N\}$, which may overlap.

$$E_mig(\{m{v}_c\},\{m{v}_p\}, heta_mig) = -\sum_{c\in C_m} \ln\Bigl(\sum_{p\in P_m} \exp\bigl(\sin_m(m{v}_c,m{v}_p)\bigr)\Bigr).$$

The full energy is the sum over all energy functions:

$$E(\{\mathbf{v}_i\}, \{\theta_m\}) = \sum_{m=1}^{M} E_m(\{\mathbf{v}_c\}, \{\mathbf{v}_p\}, \theta_m).$$

$\log \sum$ exp expectation maximisation

Expectation Step:

▶ Perform gradient descent on each v_i to find the optimal latent states:

$$\mathbf{v}_i^* = \arg\min_{\mathbf{v}_i} E(\{\mathbf{v}_i\}, \{\theta_m\}).$$

Maximisation Step:

▶ Given the updated \mathbf{v}_{i}^{*} , take a gradient step on each θ_{m} :

$$\theta_{m} = \theta_{m} - \eta \frac{\partial E}{\partial \theta_{m}} \Big|_{\mathbf{v}_{i}^{*}}.$$

log ∑ exp framework

```
class Energy:
    def similarity(self, *args):
        raise NotImplementedError
    def __call__(self, *args):
        # energy function
        sim_matrix = self.similarity(*args)
        return -sum(logsumexp(sim_matrix, axis=1))
dx = grad(energy)(x, y)
```

Gaussian Mixture Model

We define a set of child nodes $\{x_i\}_{i=1}^N$ and parent means $\{\mu_k\}_{k=1}^K$. The covariance matrices $\{\Sigma_k\}_{k=1}^K$ are treated as parameters $\theta_k = \Sigma_k$ (note that we could have also included means in the similarity parameters).

The similarity function is given by:

$$\operatorname{sim}_k(\mathbf{x}_i, \boldsymbol{\mu}_k) = -\frac{1}{2}(\mathbf{x}_i - \boldsymbol{\mu}_k)^{\top} \boldsymbol{\Sigma}_k^{-1}(\mathbf{x}_i - \boldsymbol{\mu}_k).$$

The energy function is:

$$E^{\mathrm{GMM}} = -\sum_{i=1}^{N} \ln \left(\sum_{k=1}^{K} \exp \left(\sin_k(\mathbf{x}_i, \boldsymbol{\mu}_k) \right) \right).$$

The similarity function can be interpreted as the log probability of x_i under the conditional Gaussian distribution $\mathcal{N}(\mu_k, \Sigma_k)$, up to a normalization constant.

Gaussian Mixture Model

The gradient for μ_k is given by:

$$-\frac{\partial \boldsymbol{E}^{\mathrm{GMM}}}{\partial \boldsymbol{\mu}_{k}} = \sum_{i=1}^{N} \underbrace{\operatorname{softmax}_{k} (\operatorname{sim}(\boldsymbol{x}_{i}, \boldsymbol{\mu}_{k}))}_{\alpha_{i,k}} \boldsymbol{\Sigma}_{k}^{-1} (\boldsymbol{x}_{i} - \boldsymbol{\mu}_{k}).$$

Solving for zero gives the fixed point update for μ_k :

$$\mu_k = \frac{\sum_{i=1}^N \alpha_{i,k} x_i}{\sum_{i=1}^N \alpha_{i,k}}.$$

Hopfield Attention

We define a set of child nodes $\{x_i\}_{i=1}^N$, each $x_i \in \mathbb{R}^d$, and a set of parent memory vectors $\{\boldsymbol{m}_{\mu}\}_{\mu=1}^K$, each $\boldsymbol{m}_{\mu} \in \mathbb{R}^d$.

The energy function is given by:

$$\mathrm{sim}ig(m{x}_i,m{m}_\muig) = m{x}_i^ opm{m}_\mu.$$
 $E^\mathrm{Hopfield} = -\sum_{i=1}^N \mathrm{In}\Big(\sum_{j=1}^K \mathrm{exp}ig(m{x}_i^ opm{m}_\muig)\Big).$

The gradients are:

$$\alpha_{i,\mu} = \operatorname{softmax}_{\mu}(\mathbf{x}_i^{\top} \mathbf{m}_{\mu}).$$

$$-\frac{\partial E}{\partial \mathbf{m}_{\mu}} = \sum_{i=1}^{N} \alpha_{i,\mu} \, \mathbf{x}_{i}, \quad -\frac{\partial E}{\partial \mathbf{x}_{i}} = \sum_{\mu=1}^{K} \alpha_{i,\mu} \, \mathbf{m}_{\mu},$$



Slot Attention

We define a set of child (token) nodes $\{x_j\}_{j=1}^N$ and a set of parent (slot) nodes $\{\mu_i\}_{i=1}^S$. The parameters θ consist of two projection matrices \boldsymbol{W}_K and \boldsymbol{W}_Q .

The energy function is:

$$\operatorname{sim}(\mathbf{x}_j, \boldsymbol{\mu}_i) = (\mathbf{W}_K \mathbf{x}_j)^\top (\mathbf{W}_Q \boldsymbol{\mu}_i).$$

$$E^{\mathrm{Slot}} = -\sum_{j=1}^{N} \ln \left(\sum_{i=1}^{S} \exp \left(\sin(\mathbf{x}_{j}, \boldsymbol{\mu}_{i}) \right) \right).$$

The gradients are:

$$\alpha_{j,i} = \operatorname{softmax}_i (\operatorname{sim}(\mathbf{x}_j, \boldsymbol{\mu}_i)).$$

$$-\frac{\partial E}{\partial \boldsymbol{\mu}_i} = \sum_{i=1}^N \alpha_{j,i} \; \boldsymbol{W}_Q^\top \boldsymbol{W}_K \; \boldsymbol{x}_j, \quad -\frac{\partial E}{\partial \boldsymbol{x}_j} = \sum_{i=1}^S \alpha_{j,i} \; \boldsymbol{W}_K^\top \boldsymbol{W}_Q \; \boldsymbol{\mu}_i.$$



Self-Attention

We define a set of nodes $\{x_i\}_{i=1}^N$, where each x_i serves as both a child (query) and a parent (key). The parameters θ consist of projection matrices \boldsymbol{W}^Q and \boldsymbol{W}^K , forming:

$$\mathbf{q}_i = \mathbf{W}^Q \mathbf{x}_i, \quad \mathbf{k}_i = \mathbf{W}^K \mathbf{x}_i.$$

The energy function is:

$$\sin(\mathbf{x}_c, \mathbf{x}_p) = \mathbf{q}_c^{\top} \mathbf{k}_p.$$

$$E^{\mathrm{SA}} = -\sum_{c=1}^{N} \ln \left(\sum_{p=1}^{N} \exp(\mathbf{q}_c^{\top} \mathbf{k}_p) \right).$$

The gradients are:

$$\alpha_{c,p} = \operatorname{softmax}_{p}(\boldsymbol{q}_{c}^{\top}\boldsymbol{k}_{p}).$$

$$-\frac{\partial E}{\partial \boldsymbol{x}_{i}} = \underbrace{\sum_{p=1}^{N} \alpha_{i,p} \boldsymbol{W}^{Q\top} \boldsymbol{W}^{K} \boldsymbol{x}_{p}}_{\text{Child side}} + \underbrace{\sum_{c=1}^{N} \alpha_{c,i} \boldsymbol{W}^{K\top} \boldsymbol{W}^{Q} \boldsymbol{x}_{c}}_{\text{Parent side}}.$$

Linear Mixture Model

We define a set of child nodes $\{x_i\}_{i=1}^N$ and a set of parent nodes $\{z_k\}_{k=1}^K$. The parameters $\theta = \{(\boldsymbol{A}_k, \boldsymbol{b}_k, \boldsymbol{\Sigma}_k)\}_{k=1}^K$ define a linear mapping:

$$\mathbf{x}_i = \mathbf{A}_k \mathbf{z}_k + \mathbf{b}_k + \epsilon, \quad \epsilon \sim \mathcal{N}(\mathbf{0}, \mathbf{\Sigma}_k).$$

The energy function is:

$$egin{aligned} \sin_k(\mathbf{x}_i, \mathbf{z}_k) &= -rac{1}{2}(\mathbf{x}_i - \mathbf{A}_k \mathbf{z}_k - \mathbf{b}_k)^{ op} \mathbf{\Sigma}_k^{-1}(\mathbf{x}_i - \mathbf{A}_k \mathbf{z}_k - \mathbf{b}_k). \ E^{\mathrm{LM}} &= -\sum_{i=1}^N \ln\Bigl(\sum_{k=1}^K \exp\bigl(\sin_k(\mathbf{x}_i, \mathbf{z}_k)\bigr)\Bigr). \end{aligned}$$

Note this is the energy function for the switching linear dynamical system (SLDS) model, and our simple latent attention (SLA) model.

Linear Mixture Model

The attention weights are:

$$\alpha_{i,k} = \operatorname{softmax}_k(\operatorname{sim}_k(\mathbf{x}_i, \mathbf{z}_k)).$$

The gradient w.r.t. x_i is:

$$-\frac{\partial E}{\partial \mathbf{x}_i} = \sum_{k=1}^K \alpha_{i,k} \mathbf{\Sigma}_k^{-1} (\mathbf{x}_i - \mathbf{A}_k \mathbf{z}_k - \mathbf{b}_k).$$

The fixed-point update for x_i is:

$$\mathbf{x}_{i}^{*} = \sum_{k=1}^{K} \alpha_{i,k} \left(\mathbf{A}_{k} \mathbf{z}_{k} + \mathbf{b}_{k} \right).$$

Non-Linear Mixture Model

We define a set of child nodes $\{\mathbf{z}_i\}_{i=1}^N$ and a set of parent nodes $\{\mathbf{z}_k\}_{k=1}^K$. The parameters $\boldsymbol{\theta} = \{\boldsymbol{A}_k, \boldsymbol{b}_k, \sigma\}$ define a non-linear mapping:

$$f(\mathbf{z}_k) = \sigma(\mathbf{A}_k \mathbf{z}_k + \mathbf{b}_k),$$

where $\sigma(\cdot)$ is a non-linearity.

The similarity function is:

$$\sin_k(\mathbf{x}_i, \mathbf{z}_k) = -\frac{1}{2} ||\mathbf{x}_i - f(\mathbf{z}_k)||^2.$$

The energy function is:

$$E^{\mathrm{NL}} = -\sum_{i=1}^{N} \ln \Bigl(\sum_{k=1}^{K} \exp \bigl(\mathrm{sim}_{k}(\mathbf{x}_{i}, \mathbf{z}_{k}) \bigr) \Bigr).$$

Non-Linear Mixture Model: Gradients

The attention weights are:

$$\alpha_{i,k} = \operatorname{softmax}_k(\operatorname{sim}_k(\mathbf{x}_i, \mathbf{z}_k)).$$

The gradient w.r.t. x_i is:

$$-\frac{\partial E}{\partial \mathbf{x}_i} = \sum_{k=1}^K \alpha_{i,k} (\mathbf{x}_i - f(\mathbf{z}_k)).$$

The gradient w.r.t. \mathbf{z}_k is:

$$-\frac{\partial E}{\partial \mathbf{z}_k} = \sum_{i=1}^N \alpha_{i,k} \frac{\partial f(\mathbf{z}_k)}{\partial \mathbf{z}_k} (\mathbf{x}_i - f(\mathbf{z}_k)).$$

Note these are these are predictive coding updates, weighted by the attention $\alpha_{i,k}$.

Kronecker $\log \sum \exp$

We define a single set of child nodes $\{x_i\}_{i=1}^N$ and two sets of parents:

$$\{\mathbf{z}_k\}_{k=1}^K, \quad \{\mathbf{u}_\ell\}_{\ell=1}^L.$$

We combine these factors *multiplicatively* via a *Kronecker* structure, giving a single $\log \sum \exp \text{ term over all pairs } (k, \ell)$.

Similarity: For each child x_i and each parent pair (k, ℓ) , define

$$\operatorname{sim}(\mathbf{x}_i; \mathbf{z}_k, \mathbf{u}_\ell) = \operatorname{sim}_{\mathbf{z}}(\mathbf{x}_i, \mathbf{z}_k) + \operatorname{sim}_{\mathbf{u}}(\mathbf{x}_i, \mathbf{u}_\ell),$$

$$E^{\mathrm{Kron}} = -\sum_{i=1}^{N} \ln \left(\sum_{k=1}^{K} \sum_{\ell=1}^{L} \exp \left(\operatorname{sim}(\boldsymbol{x}_{i}; \boldsymbol{z}_{k}, \boldsymbol{u}_{\ell}) \right) \right).$$

Kronecker log ∑ exp

The resulting attention is now a joint softmax over all parent pairs:

$$\begin{aligned} &\alpha_{i,k,\ell} = \operatorname{softmax}_{k,\ell} \big(\operatorname{sim}(\boldsymbol{x}_i; \boldsymbol{z}_k, \boldsymbol{u}_\ell) \big) \\ &= \frac{\exp \big(\operatorname{sim}(\boldsymbol{x}_i; \boldsymbol{z}_k, \boldsymbol{u}_\ell) \big)}{\sum_{k'=1}^K \sum_{\ell'=1}^L \exp \big(\operatorname{sim}(\boldsymbol{x}_i; \boldsymbol{z}_{k'}, \boldsymbol{u}_{\ell'}) \big)}. \end{aligned}$$

Gradients: For a child x_i ,

$$-\frac{\partial E}{\partial \mathbf{x}_i} = \sum_{k=1}^K \sum_{\ell=1}^L \alpha_{i,k,\ell} \frac{\partial}{\partial \mathbf{x}_i} \sin(\mathbf{x}_i; \mathbf{z}_k, \mathbf{u}_\ell).$$

Similarly, for a parent z_k :

$$-\frac{\partial E}{\partial \mathbf{z}_{k}} = \sum_{i=1}^{N} \sum_{\ell=1}^{L} \alpha_{i,k,\ell} \frac{\partial}{\partial \mathbf{z}_{k}} \operatorname{sim}_{\mathbf{z}}(\mathbf{x}_{i}, \mathbf{z}_{k}),$$

Kronecker $\log \sum \exp (\text{Discrete Case})$

Setup: We define a single discrete child variable $\mathbf{x} \in \{1, \dots, D\}$ and two discrete parent variables:

$$\mathbf{z} \in \{1, \dots, K\}, \quad \mathbf{u} \in \{1, \dots, L\}.$$

The parameters $\theta \in \mathbb{R}^{D \times K \times L}$ represent a joint categorical distribution.

Energy We define a single similarity function that depends on all three variables:

$$\sin(x,z,u)=\ln\theta_{x,z,u}.$$

$$E^{\mathrm{Kron}} = -\sum_{i=1}^{N} \ln \left(\sum_{k=1}^{K} \sum_{\ell=1}^{L} \exp \left(\sin(x_i, z_k, u_\ell) \right) \right).$$

Kronecker $\log \sum \exp (\text{Discrete Case})$

Tensor Attention: This induces a joint softmax over both parent variables:

$$\alpha_{i,k,\ell} = \frac{\exp(\operatorname{sim}(x_i, z_k, u_\ell))}{\sum_{k'=1}^K \sum_{\ell'=1}^L \exp(\operatorname{sim}(x_i, z_{k'}, u_{\ell'}))}.$$

Interpretation:

- Parent variables (z_k, u_ℓ) conspire to jointly explain child variables x_i .
- ▶ The attention $\alpha_{i,k,\ell}$ generalizes categorical mixture models to factorial structures.

Multi $\log \sum \exp$

We define a set of child nodes $\{x_i\}_{i=1}^N$ and a set of parent nodes $\{z_k\}_{k=1}^K$. Each parent k is associated with multiple similarity terms, indexed by different factors.

Similarity functions: Each similarity term contributes independently to the energy function:

$$sim_1(\mathbf{x}_i, \mathbf{z}_k), \quad sim_2(\mathbf{x}_i, \mathbf{z}_k), \quad \ldots, \quad sim_M(\mathbf{x}_i, \mathbf{z}_k).$$

Energy function:

$$E^{\mathrm{Multi}} = -\sum_{i=1}^{N} \ln \left(\sum_{k=1}^{K} \exp \left(\sum_{m=1}^{M} \sin_{m}(\mathbf{x}_{i}, \mathbf{z}_{k}) \right) \right).$$

Here, all similarity terms are summed before the softmax, leading to a *joint* mixture model over multiple factors.



Multi $\log \sum \exp$

The resulting attention weight is:

$$\alpha_{i,k} = \operatorname{softmax}_k \left(\sum_{m=1}^M \operatorname{sim}_m(\mathbf{x}_i, \mathbf{z}_k) \right).$$

With gradients:

$$-\frac{\partial E}{\partial \mathbf{x}_i} = \sum_{k=1}^K \alpha_{i,k} \sum_{m=1}^M \frac{\partial}{\partial \mathbf{x}_i} \operatorname{sim}_m(\mathbf{x}_i, \mathbf{z}_k).$$

$$-\frac{\partial E}{\partial \mathbf{z}_{k}} = \sum_{i=1}^{N} \alpha_{i,k} \sum_{m=1}^{M} \frac{\partial}{\partial \mathbf{z}_{k}} \operatorname{sim}_{m}(\mathbf{x}_{i}, \mathbf{z}_{k}).$$

This formulation is useful when multiple similarties contribute to the similarity between a child and parent.

Block-slot Attention

Setup: We define a set of child nodes $\{x_i\}_{i=1}^N$, a set of slot parent nodes $\{z_k\}_{k=1}^K$, and a set of memory parent nodes $\{\boldsymbol{m}_{\mu}\}_{\mu=1}^M$. The parameters $\boldsymbol{\theta} = \{\boldsymbol{W}_K, \boldsymbol{W}_Q\}$ consist of projection matrices.

Energy: Each child x_i is compared to slot parents z_k and memory parents m_{μ} :

$$egin{aligned} \sin_{oldsymbol{z}}(oldsymbol{x}_i,oldsymbol{z}_k) &= (oldsymbol{W}_Koldsymbol{x}_i)^ op (oldsymbol{W}_Qoldsymbol{z}_k), \ \sin_{oldsymbol{m}}(oldsymbol{x}_i,oldsymbol{m}_\mu) &= oldsymbol{x}_i^ op oldsymbol{m}_\mu. \end{aligned} \ E^{\mathrm{BlockSlot}} &= -\sum_{i=1}^N \ln\left(\sum_{k=1}^K \exp\left(\sin_{oldsymbol{z}}(oldsymbol{x}_i,oldsymbol{z}_k)\right)
ight) \ -\sum_{i=1}^N \ln\left(\sum_{\mu=1}^M \exp\left(\sin_{oldsymbol{m}}(oldsymbol{x}_i,oldsymbol{m}_\mu)\right)
ight). \end{aligned}$$

Energy Transformer

Setup: We define a set of nodes $\{x_i\}_{i=1}^N$ and a set of memory nodes $\{m_\mu\}_{\mu=1}^M$. The parameters $\boldsymbol{\theta} = \{\boldsymbol{W}^Q, \boldsymbol{W}^K\}$ consist of projection matrices for queries and keys.

Energy: Each node x_i attends to itself (self-attention) and to memory nodes m_{μ} (Hopfield attention):

$$egin{aligned} & \operatorname{sim}_{\mathsf{self}}(\pmb{x}_i,\pmb{x}_j) = (\pmb{W}^Q\pmb{x}_i)^{ op}(\pmb{W}^K\pmb{x}_j), \ & \operatorname{sim}_{\mathsf{memory}}(\pmb{x}_i,\pmb{m}_\mu) = \pmb{x}_i^{ op}\pmb{m}_\mu. \ & E^{\mathrm{ET}} = -\sum_{i=1}^N \ln\left(\sum_{j=1}^N \exp\left(\operatorname{sim}_{\mathsf{self}}(\pmb{x}_i,\pmb{x}_j)\right)
ight) \ & -\sum_{i=1}^N \ln\left(\sum_{\mu=1}^M \exp\left(\operatorname{sim}_{\mathsf{memory}}(\pmb{x}_i,\pmb{m}_\mu)\right)
ight). \end{aligned}$$

Atari Model

Setup: We define a sequence of child nodes $\{\boldsymbol{x}_t\}_{t=1}^T$, a sequence of latent parent nodes $\{\boldsymbol{z}_t\}_{t=1}^T$, and a set of mode parameters $\{\boldsymbol{A}_k, \boldsymbol{b}_k, \boldsymbol{\Sigma}_k\}_{k=1}^K$. The parameters $\boldsymbol{\theta} = \{\boldsymbol{A}_k, \boldsymbol{b}_k, \boldsymbol{\Sigma}_k\}$ define the mappings.

Similarity Functions: The child x_t is assigned to a mixture component z_t using:

$$\operatorname{sim}_{\mathsf{GMM}}(\mathbf{\textit{x}}_t, \mathbf{\textit{z}}_t) = -\frac{1}{2}(\mathbf{\textit{x}}_t - \mathbf{\textit{z}}_t)^{\top} \mathbf{\Sigma}_k^{-1}(\mathbf{\textit{x}}_t - \mathbf{\textit{z}}_t).$$

The latent child z_t is explained by a linear mixture model:

$$\mathrm{sim}_{\mathsf{LM}}(\pmb{z}_t,\pmb{z}_{t-1}) = -rac{1}{2}(\pmb{z}_t-\pmb{A}_k\pmb{z}_{t-1}-\pmb{b}_k)^{ op}\pmb{\Sigma}_k^{-1}(\pmb{z}_t-\pmb{A}_k\pmb{z}_{t-1}-\pmb{b}_k).$$

Atari Model

Energy:

$$egin{aligned} E^{ ext{Atari}} &= -\sum_{t=1}^{T} \ln \left(\sum_{k=1}^{K} \exp \left(ext{sim}_{\mathsf{GMM}}(\pmb{x}_t, \pmb{z}_t)
ight)
ight) \ &- \sum_{t=1}^{T-1} \ln \left(\sum_{k=1}^{K} \exp \left(ext{sim}_{\mathsf{LM}}(\pmb{z}_t, \pmb{z}_{t-1})
ight)
ight). \end{aligned}$$

The gradient for the latent parent z_t combines both responsibilities:

$$-\frac{\partial E}{\partial \mathbf{z}_t} = \sum_{k=1}^K \alpha_{t,k} \, \mathbf{\Sigma}_k^{-1} (\mathbf{x}_t - \mathbf{z}_t) + \sum_{k=1}^K \beta_{t,k} \, \mathbf{\Sigma}_k^{-1} (\mathbf{z}_t - \mathbf{A}_k \mathbf{z}_{t-1} - \mathbf{b}_k).$$

Hierarchy: We define a hierarchy of L layers. Each layer I contains K_I latent variables, where each variable evolves over T time steps. Concretely, let:

$$\mathbf{x}_{k,t}^{(I)} \in \mathbb{R}^{D_I}$$

denote the k-th variable (or "slot") in layer l at time t, with D_l -dimensional representations. The number of variables K_l may differ across layers.

Structure:

- ▶ Inter-layer (vertical): Each variable $\mathbf{x}_{k,t}^{(l)}$ is influenced by variables from the layer below (l-1) at the same time t.
- ▶ Intra-layer (concurrent): Variables within the same layer / interact at each time step t.
- ▶ **Temporal:** Each variable $\mathbf{x}_{k,t}^{(l)}$ is influenced by its own past states $\mathbf{x}_{k,t'}^{(l)}$ for t' < t.



Inter-layer (vertical):

$$\operatorname{sim}_{v}^{(I)}(\boldsymbol{x}, \boldsymbol{x}') = (\boldsymbol{W}_{v}^{K,(I)} \boldsymbol{x})^{\top} (\boldsymbol{W}_{v}^{Q,(I)} \boldsymbol{x}').$$

Intra-layer (concurrent):

$$\operatorname{sim}_c^{(I)}(\boldsymbol{x}, \boldsymbol{x}') = (\boldsymbol{W}_c^{Q,(I)} \, \boldsymbol{x})^\top (\boldsymbol{W}_c^{K,(I)} \, \boldsymbol{x}').$$

Temporal (past states):

$$\operatorname{sim}_{t}^{(I)}(\boldsymbol{x}, \boldsymbol{x}') = (\boldsymbol{W}_{t}^{Q,(I)} \boldsymbol{x})^{\top} (\boldsymbol{W}_{t}^{K,(I)} \boldsymbol{x}').$$

Inter-layer Energy (Slot attentiom):

$$E_{v}^{(l)} = -\sum_{t=1}^{T} \sum_{c=1}^{K_{l-1}} \ln \left(\sum_{k=1}^{K_{l}} \exp \left(\operatorname{sim}_{v}^{(l)}(\boldsymbol{x}_{c,t}^{(l-1)}, \boldsymbol{x}_{k,t}^{(l)}) \right) \right).$$

Intra-layer Energy (Self attention):

$$E_c^{(I)} = -\sum_{t=1}^{T} \sum_{k=1}^{K_I} \ln \left(\sum_{\substack{k'=1\\k' \neq k}}^{K_I} \exp \left(\operatorname{sim}_c^{(I)}(\boldsymbol{x}_{k,t}^{(I)}, \boldsymbol{x}_{k',t}^{(I)}) \right) \right).$$

Temporal Energy (Casual self attention):

$$E_t^{(l)} = -\sum_{k=1}^{K_l} \sum_{t=2}^{T} \ln \left(\sum_{t' < t} \exp \left(\sin_t^{(l)} (\mathbf{x}_{k,t}^{(l)}, \mathbf{x}_{k,t'}^{(l)}) \right) \right).$$

$$-\frac{\partial E}{\partial \mathbf{x}_{k,t}^{(I)}} = \underbrace{-\frac{\partial E_{v}^{(I)}}{\partial \mathbf{x}_{k,t}^{(I)}}}_{\text{bottom-up}} + \underbrace{-\frac{\partial E_{v}^{(I+1)}}{\partial \mathbf{x}_{k,t}^{(I)}}}_{\text{top-down}} + \underbrace{-\frac{\partial E_{c}^{(I)}}{\partial \mathbf{x}_{k,t}^{(I)}}}_{\text{intra-layer}} + \underbrace{-\frac{\partial E_{t}^{(I)}}{\partial \mathbf{x}_{k,t}^{(I)}}}_{\text{temporal}}.$$

Bottom-up gradient

$$-\frac{\partial E_{v}^{(l)}}{\partial \boldsymbol{x}_{k,t}^{(l)}} = \sum_{c=1}^{K_{l-1}} \operatorname{softmax}_{k}(\boldsymbol{A}_{c,k}) \boldsymbol{W}_{v}^{Q,(l)\top} \boldsymbol{W}_{v}^{K,(l)} \boldsymbol{x}_{c,t}^{(l-1)}.$$

Top-down gradient

$$-\frac{\partial E_{v}^{(l+1)}}{\partial \boldsymbol{x}_{k,t}^{(l)}} = \sum_{p=1}^{K_{l+1}} \operatorname{softmax}_{p}(\boldsymbol{A}_{k,p}) \boldsymbol{W}_{v}^{K,(l+1)\top} \boldsymbol{W}_{v}^{Q,(l+1)} \boldsymbol{x}_{p,t}^{(l+1)}.$$

Intra-layer gradient

$$-\frac{\partial E_c^{(I)}}{\partial \boldsymbol{x}_{k,t}^{(I)}} = \sum_{k' \neq k} \operatorname{softmax}_k(\boldsymbol{A}_{k',k}) \boldsymbol{W}_c^{K,(I)\top} \boldsymbol{W}_c^{Q,(I)} \boldsymbol{x}_{k',t}^{(I)} + \sum_{k' \neq k} \operatorname{softmax}_{k'}(\boldsymbol{A}_{k,k'}) \boldsymbol{W}_c^{Q,(I)\top} \boldsymbol{W}_c^{K,(I)} \boldsymbol{x}_{k',t}^{(I)}.$$

Temporal gradient

$$-\frac{\partial E_t^{(l)}}{\partial \boldsymbol{x}_{k,t}^{(l)}} = \sum_{t' < t} \operatorname{softmax}_{t'} (\boldsymbol{A}_{t,t'}) \; \boldsymbol{W}_t^{Q,(l) \top} \; \boldsymbol{W}_t^{K,(l)} \, \boldsymbol{x}_{k,t'}^{(l)}.$$

Remark: By merging inter-layer, intra-layer, and temporal connections into a single large log-sum-exp term, we increase flexibility but at the cost of $\mathcal{O}((N+K)\,T)^2$ complexity.

Renormalised mixture models

We define a hierarchy of L layers, each containing K_l latent variables of dimension D_l , where K_l decreases with l $(K_1 > K_2 > \cdots > K_L)$.

Each variable $\mathbf{x}_{k,t}^{(I)}$ at layer I receives input only from a local subset of variables in layer I-1, forming a receptive field:

$$\mathcal{R}_k^{(l)} \subseteq \{1,\ldots,K_{l-1}\}.$$

In this setting, intra-layer and temporal energy remain the same.

Renormalised Mixture Model

Each variable $\mathbf{x}_{k,t}^{(I)}$ at layer I is explained only by a local receptive field $\mathcal{R}_k^{(I)}$ in layer I-1:

$$E_{v}^{(l)} = -\sum_{t=1}^{T} \sum_{k=1}^{K_{l}} \ln \left(\sum_{c \in \mathcal{R}_{v}^{(l)}} \exp \left(\operatorname{sim}_{v}^{(l)}(\boldsymbol{x}_{c,t}^{(l-1)}, \boldsymbol{x}_{k,t}^{(l)}) \right) \right).$$

Define:

$$\mathbf{A}_{c,k} = \sin_{v}^{(l)}(\mathbf{x}_{c,t}^{(l-1)}, \mathbf{x}_{k,t}^{(l)}), \quad \mathbf{A}_{k,p} = \sin_{v}^{(l+1)}(\mathbf{x}_{k,t}^{(l)}, \mathbf{x}_{p,t}^{(l+1)}).$$

Then the bottom-up and top-down gradients are:

$$-\frac{\partial E_{v}^{(l)}}{\partial \boldsymbol{x}_{k,t}^{(l)}} = \sum_{c \in \mathcal{R}_{v}^{(l)}} \operatorname{softmax}_{c}(\boldsymbol{A}_{c,k}) \frac{\partial}{\partial \boldsymbol{x}_{k,t}^{(l)}} \operatorname{sim}_{v}^{(l)}(\boldsymbol{x}_{c,t}^{(l-1)}, \boldsymbol{x}_{k,t}^{(l)}),$$

$$-\frac{\partial E_{v}^{(l+1)}}{\partial \boldsymbol{x}_{k,t}^{(l)}} = \sum_{\boldsymbol{p} \in \mathcal{R}_{k}^{(l+1)}} \operatorname{softmax}_{\boldsymbol{p}} (\boldsymbol{A}_{k,\boldsymbol{p}}) \frac{\partial}{\partial \boldsymbol{x}_{k,t}^{(l)}} \operatorname{sim}_{v}^{(l+1)} (\boldsymbol{x}_{k,t}^{(l)}, \boldsymbol{x}_{\boldsymbol{p},t}^{(l+1)}).$$



Bayesian model expansion

If a new data point x_{N+1} is not well explained by existing parent components, we introduce a new parent to explain it. We evaluate the energy contribution of the new data point:

$$E_{N+1} = -\ln\left(\sum_{k=1}^{K} \exp\left(\sin(\boldsymbol{x}_{N+1}, \boldsymbol{z}_{k},)\right)\right).$$

If $E_{N+1} > \tau$ (for some threshold τ), then \mathbf{z}_{N+1} is not sufficiently explained, and we add a new parent component \mathbf{z}_{K+1} , where the new parent is initialized based on \mathbf{x}_{N+1} .

Energy Function:

We consider an energy of the form

$$E(\{\mathbf{x}_j\}, \{\boldsymbol{\mu}_i\}; \boldsymbol{\theta}) = -\sum_{j=1}^N \ln \left(\sum_{i=1}^S \exp \left(\sin_{\boldsymbol{\theta}}(\mathbf{x}_j, \boldsymbol{\mu}_i) \right) \right),$$

where θ denotes the parameters of the similarity function.

EM Procedure:

- **E-step:** Update latent variables $\{\mu_i\}$ given fixed θ .
- ▶ **M-step:** Update parameters θ in closed form given current slots.

Slot Attention Example:

$$\theta = \{ \mathbf{W}_K, \mathbf{W}_Q \}, \quad \sin_{\theta}(\mathbf{x}_j, \boldsymbol{\mu}_i) = (\mathbf{W}_K \mathbf{x}_j)^{\top} (\mathbf{W}_Q \boldsymbol{\mu}_i).$$

Define the attention matrix **A** with entries

$$A_{ji} = \operatorname{softmax}_i((\boldsymbol{W}_K \boldsymbol{x}_j)^\top (\boldsymbol{W}_Q \boldsymbol{\mu}_i)).$$

Goal: Perform an **E-step** (update slots μ_i) and **M-step** (update W_K , W_Q).

M-step: Update Parameters

Given fixed slots $\{\mu_i\}$ and attention \mathbf{A} , we update $\mathbf{W}_K, \mathbf{W}_Q$. We consider minimizing

$$\min_{\boldsymbol{W}_{K},\boldsymbol{W}_{Q}} \sum_{j=1}^{N} \sum_{i=1}^{S} A_{ji} \left\| \boldsymbol{W}_{K} \boldsymbol{x}_{j} - \boldsymbol{W}_{Q} \boldsymbol{\mu}_{i} \right\|^{2}.$$

Setting the gradient to zero yields a weighted least-squares problem in W_K and W_Q .

Key idea:

- ▶ **A** is fixed (like responsibilities in EM).
- ▶ Solve for W_K , W_Q in closed form.

Closed-Form Updates

Differentiate and set to zero:

$$\mathbf{W}_{K} = \left(\sum_{j,i} A_{ji} \mathbf{W}_{Q} \boldsymbol{\mu}_{i} \mathbf{x}_{j}^{\top}\right) \left(\sum_{j,i} A_{ji} \mathbf{x}_{j} \mathbf{x}_{j}^{\top}\right)^{-1}.$$

$$\mathbf{W}_{Q} = \left(\sum_{j,i} A_{ji} \mathbf{W}_{K} \mathbf{x}_{j} \boldsymbol{\mu}_{i}^{\top}\right) \left(\sum_{j,i} A_{ji} \boldsymbol{\mu}_{i} \boldsymbol{\mu}_{i}^{\top}\right)^{-1}.$$

Algorithm: Alternate E-step (update $\{\mu_i\}$) and M-step (update W_K , W_Q) until convergence.

Open questions

- Hierarchical POMDPs and hierarchical mixture models differ only in their similairty functions.
- Crucially, hierarchical mixture models induce a discrete state space (in terms of their attention matrices).
- This is seen in SLDS, where we model the dynamics of the induced discrete state space (which mode is active at a given time) as a HMM.
- Is there a way to combine the two models, with continuous mixture models on the bottom and discrete mixture models on the top?