

# Functional analysis

Alejandro Campos

March 20, 2025

## Contents

<b>1</b>	<b>Linear forms</b>	<b>1</b>
<b>2</b>	<b>Some terminology</b>	<b>2</b>
<b>3</b>	<b>Useful equalities and inequalities</b>	<b>2</b>
<b>4</b>	<b>The weak derivative</b>	<b>2</b>
<b>5</b>	<b>Function spaces</b>	<b>3</b>

## 1 Linear forms

- A linear form (or linear functional) is a mapping  $w : V \rightarrow \mathbb{R}$  such that

$$w(\mathbf{v}_1 + \mathbf{v}_2) = w(\mathbf{v}_1) + w(\mathbf{v}_2) \quad \forall \mathbf{v}_1, \mathbf{v}_2 \in V, \quad (1)$$

$$w(\alpha \mathbf{v}) = \alpha w(\mathbf{v}) \quad \forall \alpha \in \mathbb{R}, \mathbf{v} \in V. \quad (2)$$

- A bilinear form (or bilinear functional) is a mapping  $w : V \times U \rightarrow \mathbb{R}$  such that

$$w(\mathbf{v}_1 + \mathbf{v}_2, \mathbf{u}) = w(\mathbf{v}_1, \mathbf{u}) + w(\mathbf{v}_2, \mathbf{u}) \quad \forall \mathbf{v}_1, \mathbf{v}_2 \in V, \mathbf{u} \in U, \quad (3)$$

$$w(\mathbf{v}, \mathbf{u}_1 + \mathbf{u}_2) = w(\mathbf{v}, \mathbf{u}_1) + w(\mathbf{v}, \mathbf{u}_2) \quad \forall \mathbf{v} \in V, \mathbf{u}_1, \mathbf{u}_2 \in U, \quad (4)$$

$$w(\alpha \mathbf{v}, \mathbf{u}) = \alpha w(\mathbf{v}, \mathbf{u}) \quad \forall \alpha \in \mathbb{R}, \mathbf{v} \in V, \mathbf{u} \in U, \quad (5)$$

$$w(\mathbf{v}, \alpha \mathbf{u}) = \alpha w(\mathbf{v}, \mathbf{u}) \quad \forall \alpha \in \mathbb{R}, \mathbf{v} \in V, \mathbf{u} \in U, \quad (6)$$

- A multi-linear form (or multi-linear functional) is a mapping  $w : V^{(1)} \times \dots \times V^{(n)} \rightarrow \mathbb{R}$  such that

$$w(\mathbf{v}^{(1)}, \dots, \mathbf{v}_1^{(i)} + \mathbf{v}_2^{(i)}, \dots, \mathbf{v}^{(n)}) = w(\mathbf{v}^{(1)}, \dots, \mathbf{v}_1^{(i)}, \dots, \mathbf{v}^{(n)}) + w(\mathbf{v}^{(1)}, \dots, \mathbf{v}_2^{(i)}, \dots, \mathbf{v}^{(n)}), \quad (7)$$

$$w(\mathbf{v}^{(1)}, \dots, \alpha \mathbf{v}^{(i)}, \dots, \mathbf{v}^{(n)}) = \alpha w(\mathbf{v}^{(1)}, \dots, \mathbf{v}^{(i)}, \dots, \mathbf{v}^{(n)}), \quad (8)$$

$\forall i, \forall \alpha \in \mathbb{R}, \forall \mathbf{v}^{(1)} \in V^{(1)}, \dots, \forall \mathbf{v}^{(n)} \in V^{(n)}, \text{ and } \forall \mathbf{v}_1^{(i)}, \mathbf{v}_2^{(i)} \in V^{(i)}.$

## 2 Some terminology

- Cauchy sequence: a sequence  $v_1, v_2, v_3, \dots$  is a Cauchy sequence if for every positive real number  $\epsilon$ , there is a positive integer  $N$  such that for all positive integers  $m, n > N$ ,  $\|v_m - v_n\| < \epsilon$ .
- Complete inner product space: an inner product space  $\mathcal{V}$  is complete if every Cauchy sequence  $\{v_i\}_{i=1}^\infty$  in  $\mathcal{V}$  has a limit  $v = \lim v_i \in \mathcal{V}$ .
- Compact set: a set is compact if it is bounded and closed.
- Coercive bilinear form: a bilinear form  $a(\cdot, \cdot)$  is coercive in a Hilbert space  $\mathcal{V}$  if

$$a(v, v) \geq \alpha \|v\|_{\mathcal{V}}^2, \quad \forall v \in \mathcal{V}, \quad \text{with } \alpha > 0. \quad (9)$$

- Bounded linear form: a linear form is bounded in the normed vector space  $\mathcal{V}$  if there exists an  $M > 0$  such that  $|L(v)| \leq M \|v\|$ , for every  $v \in \mathcal{V}$ .
- Bounded bilinear form: a bilinear form is bounded in the normed vector space  $\mathcal{V}$  if there exists an  $M > 0$  such that  $|a(w, v)| \leq M \|w\| \|v\|$ , for every  $w, v \in \mathcal{V}$ .

## 3 Useful equalities and inequalities

$$|ab| = |a||b| \quad \forall a, b \in \mathbb{C} \quad (10)$$

$$|a + b| \leq |a| + |b| \quad \forall a, b \in \mathbb{C} \quad (11)$$

$$|(w, v)| \leq \|w\| \|v\| \quad \forall v, w \in \text{Inner product space (Cauchy-Schwarz inequality)} \quad (12)$$

$$\|w + v\| \leq \|w\| + \|v\| \quad \forall v, w \in \text{Normed space (triangle inequality)} \quad (13)$$

$$\left| \int_a^b v(x) dx \right| \leq \int_a^b |v(x)| dx \quad (14)$$

$$\left\| \int_a^b v(x, y) dx \right\| \leq \int_a^b \|v(x, y)\| dx \quad \text{where the norm is over the y-domain.} \quad (15)$$

## 4 The weak derivative

If  $v \in C^1(\bar{\Omega})$ , then through integration by parts

$$\int_{\Omega} \frac{\partial v}{\partial x_i} \phi dV = - \int_{\Omega} v \frac{\partial \phi}{\partial x_i} dV \quad \forall \phi \in C_0^1(\Omega). \quad (16)$$

However, if  $v \in L_2(\Omega)$  but not necessarily in  $C^1(\bar{\Omega})$ , we cannot write the equation above. Instead, we ask, is there a function  $w$  such that the following holds?

$$\int_{\Omega} w \phi dV = - \int_{\Omega} v \frac{\partial \phi}{\partial x_i} dV \quad \forall \phi \in C_0^1(\Omega). \quad (17)$$

This can be rewritten as  $(w, \phi) = L(\phi)$ , where  $L(\phi) = - \int_{\Omega} v \frac{\partial \phi}{\partial x_i} dV$ . If  $L(\phi)$  is bounded in  $L_2$ , Riesz' representation theorem then states a unique solution  $w \in L_2(\Omega)$  exists. This  $w$  is the weak derivative.

More generally, if  $v \in C^k(\bar{\Omega})$ , then through integration by parts

$$\int_{\Omega} D^{\alpha} v \phi dV = (-1)^{|\alpha|} \int_{\Omega} v D^{\alpha} \phi dV \quad \forall |\alpha| \leq k, \forall \phi \in C_0^{|\alpha|}(\Omega). \quad (18)$$

However, if  $v \in L_2(\Omega)$  but not necessarily in  $C^k(\bar{\Omega})$ , we cannot write the equation above. Instead, we ask, is there a function  $w$  such that the following holds?

$$\int_{\Omega} w \phi dV = (-1)^{|\alpha|} \int_{\Omega} v D^{\alpha} \phi dV \quad \forall \phi \in C_0^{|\alpha|}(\Omega). \quad (19)$$

As before, if the left-hand-side operator is bounded, then we have a unique solution  $w \in L_2(\Omega)$ . This  $w$  is the weak derivative. Often, weak derivatives are referred to as “ $D^{\alpha}v$  in the weak sense.”

## 5 Function spaces

We label function spaces using \mathcal notation, except for the three main function spaces for continuous, square-integrable, and Sobolev functions.

- $C^0$ : the set of all continuous functions
- $C^k$  the set of all functions whose derivatives up to order  $k$  all exist and are continuous. These are called continuously differentiable functions of order  $k$ .
- $L_2$ : the set of all functions that are square integrable.
- $H^k$ : the set of all  $L_2$  functions whose weak partial derivatives up to order  $k$  also belong to  $L_2$ .
- Let  $\Omega$  be a bounded domain in  $\mathbb{R}^d$  with smooth or polygonal boundary. Then part of the Sobolev embedding theorem can be written as

$$H^k(\Omega) \subset C^l(\bar{\Omega}) \text{ if } k > l + d/2. \quad (20)$$

Thus, we have  $H^m(\Omega) \subset C^{m-1}(\bar{\Omega})$  for  $\Omega \in \mathbb{R}$  and  $H^m(\Omega) \subset C^{m-2}(\bar{\Omega})$  for  $\Omega \in \mathbb{R}^2$  or  $\mathbb{R}^3$ .

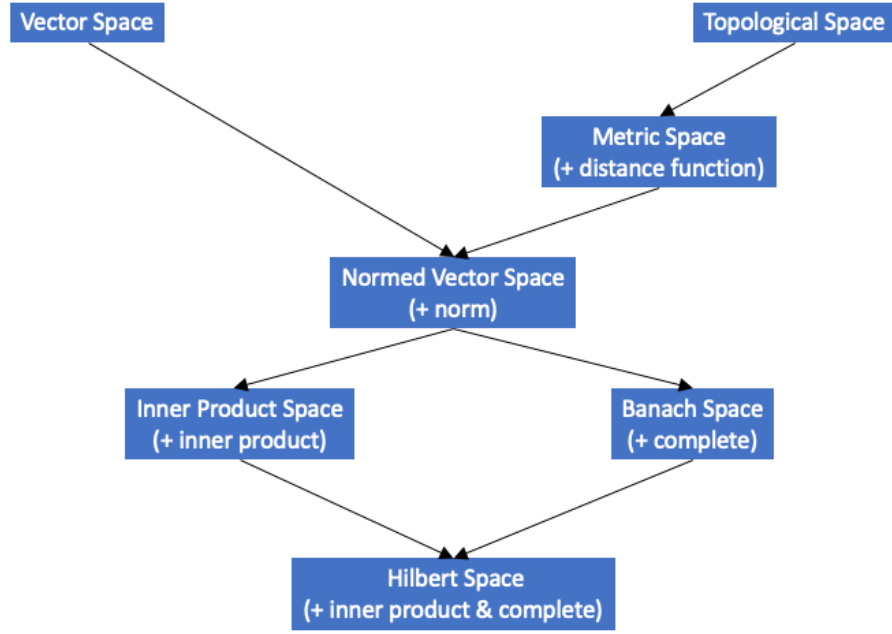


Figure 1: Map of function spaces.

Space	Norm	Inner product
$C(M)$	$\ v\ _C = \sup_{x \in M}  v(x) $	X
$C^k(M)$	$\ v\ _{C^k} = \max_{ \alpha  \leq k} \ D^\alpha v\ _C$ $ v _{C^k} = \max_{ \alpha =k} \ D^\alpha v\ _C$	X
$L_p(\Omega)$	$\ v\ _{L_p} = \left( \int_{\Omega}  v ^p dV \right)^{1/p}$	X
$L_2(\Omega)$	$\ v\ _{L_2} = \left( \int_{\Omega}  v ^2 dV \right)^{1/2}$	$(v, w) = \int_{\Omega} v w^* dV$
$H^k(\Omega)$	$\ v\ _k = \left( \sum_{ \alpha  \leq k} \ D^\alpha v\ ^2 \right)^{1/2}$ $ v _k = \left( \sum_{ \alpha =k} \ D^\alpha v\ ^2 \right)^{1/2}$	$(v, w)_k = \sum_{ \alpha  \leq k} (D^\alpha v, D^\alpha w)$