

Nuclear Physics

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1 Basic definitions

Some basic definitions are provided below:

- Atomic number (Z): # of protons
- Mass number (A): # of protons + # of neutrons
- Atomic mass (m_a): mass of a particular isotope of an element.
- Relative atomic mass (A_r): (defined for an element only)(previously referred to as atomic weight). Average of the atomic masses of all the different isotopes in a *sample*, with each isotope's contribution to the average being its abundance within the sample (as a percentage).
- Standard Atomic Weight (A_r°): (defined for an element only). Average of the atomic masses of all the different isotopes in *planet earth*, with each isotope's contribution to the average being its abundance in earth (as a percentage).
- Atomic mass unit (u): unit of mass, equivalent to $\frac{1}{12}$ the mass of a carbon-12 atom. That is

$$1u = \frac{m_c}{12}. \quad (1)$$

where m_c is the mass of a carbon-12 atom, in grams. Think of u as similar to a microgram.

- Mole: # of elementary entities equal to # of atoms in 12 grams of carbon-12. That is,

$$1mol = \frac{12g}{m_c} \quad (2)$$

Using eq. (1), we get

$$1u = \frac{1}{mol}g. \quad (3)$$

The value of the mole is $6.02214086 \times 10^{23}$.

- Molar mass (M):
 - If it is an atom (e.g. Carbon, C), then it is its atomic weight, but one uses eq. (3) to express the value in g/mol .
 - If it is a compound (e.g. Methane, CH_4), simply add up the atomic weights of each atom in the molecule, and again, express the result in g/mol .
 - If it is a mixture (e.g. air, $N_2, O_2, Ar, CO_2, \dots$), then it is the weighted average of the atomic weights of the constituents, and the result again is expressed in g/mol .
- Avogadro's number (N_a): a conversion factor so that things can be measured in terms of moles.

$$N_a = \frac{6.02214086 \times 10^{23}}{mol} \quad (4)$$

2 The fusion reaction

2.1 Energy of a reaction

The fundamental relation for nuclear reactions is $E = mc^2$. A mass m can be transformed into energy E , and viceversa. Two examples for mass m being transformed into energy are the following:

- Defect mass: the difference in mass between the atom and the sum of its constituents,

$$m = Nm_n + Zm_p - m_a, \quad (5)$$

where m_n is the mass of a neutron, m_p the mass of a proton, and m_a the mass of the atom's nucleus. For example, for carbon we have

$$m = 6 \times 1.008664u + 6 \times 1.007276u - 12u = 0.09564u, \quad (6)$$

and fluorine

$$m = 10 \times 1.008664u + 9 \times 1.007276u - 18.998403u = 0.154u. \quad (7)$$

The binding energy is then the energy corresponding to the mass defect as given by $E_b = mc^2$.

- Mass change of a fusion reaction:

$$m = \text{mass of particles before reaction} - \text{mass of particles after reaction} \quad (8)$$

Consider the DT reaction as an example, then we have

$$m = 2.013553u (D) + 3.015501u (T) - 4.001503u (\alpha) - 1.008665u (n) = 0.018886u. \quad (9)$$

The above mass translates to $E_r = mc^2 = 17.6 MeV$.

Note that E_b and E_r are related.

$$\begin{aligned}
E_r &= \left(\sum_i m_i - \sum_f m_f \right) c^2 \\
&= \left(\sum_i m_i - N_i m_{n,i} - Z_i m_{p,i} - \sum_f m_f - N_f m_{n,f} - Z_f m_{p,f} \right) c^2 \\
&= \sum_f E_{b,f} - \sum_i E_{b,i}.
\end{aligned} \tag{10}$$

2.2 Energy of reactants

As shown in the Material Properties notes, a system of particles colliding with each other can be described by $\mathbf{r}_1, \mathbf{r}_2, \mathbf{v}_1, \mathbf{v}_2$. Similarly, this system can be described using the center-of-mass position \mathbf{R} , the center-of-mass velocity \mathbf{V} , the shifted position $\mathbf{r} = \mathbf{r}_1 - \mathbf{r}_2$ and shifted velocity $\mathbf{v} = \mathbf{v}_1 - \mathbf{v}_2$. Using the shifted velocity, one can define the center-of-mass energy of the initial particles as follows

$$\epsilon = \frac{1}{2} m_r v^2. \tag{11}$$

In the above, $v = |\mathbf{v}|$ and m_r is the reduced mass, which satisfies

$$\frac{1}{m_r} = \frac{1}{m_1} + \frac{1}{m_2}. \tag{12}$$

2.3 Momentum and energy conservation

Lets assume the particles before a fusion reaction move sufficiently slow that their velocities can be neglected, that is, $\epsilon = 0$. Conservation of momentum thus gives

$$0 = m_1 v_1 + m_2 v_2, \tag{13}$$

where m_1, m_2, v_1, v_2 are the mass and velocity of particles after the reaction.

Energy is not conserved since some of the mass is converted to energy. The energy balance can be written as $E_{after} - E_{before} = E_r$. Assuming again that the particles before a fusion reaction move sufficiently slow, then

$$\frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2 = E_r, \tag{14}$$

where E_r is obtained from Einstein's equation. Combining the last two relations above gives

$$\begin{aligned}
\frac{1}{2} m_1 v_1^2 &= \frac{m_2}{m_1 + m_2} E_r \\
\frac{1}{2} m_2 v_2^2 &= \frac{m_1}{m_1 + m_2} E_r.
\end{aligned} \tag{15}$$

That is, the resulting kinetic energy of one of the final particles is proportional to the mass of the other final particle. In other words, the light particle carries most of the energy.

3 Fusion power density

The fusion power density S_f is the fusion energy produced per unit volume per unit time. Label the energy generated by each fusion collision between particles 1 and 2 by E_f , and the number of those fusion collisions per unit volume per unit time (also known as reaction rate) as R_{12} . Then the fusion power density is given by

$$S_f = E_f R_{12}. \quad (16)$$

We note that E_f is an energy released by the reaction (it can either be the total energy, the energy carried out by the alpha particles only, the energy carried out by the neutrons only, etc.).

The reaction rate between two distinct particles is given by

$$R_{12} = n_1 n_2 \langle \sigma v \rangle, \quad (17)$$

where n_1 and n_2 are the number densities of particles 1 and 2, respectively. The expected value $\langle \sigma v \rangle$ is given by

$$\langle \sigma v \rangle = \frac{1}{n_1 n_2} \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} f_1(\mathbf{v}_1) f_2(\mathbf{v}_2) \sigma(v) v d\mathbf{v}_1 d\mathbf{v}_2. \quad (18)$$

Thus, the fusion power density can be expressed as

$$S_f = E_f \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} f_1(\mathbf{v}_1) f_2(\mathbf{v}_2) \sigma(v) v d\mathbf{v}_1 d\mathbf{v}_2. \quad (19)$$

Using the definition of the cross-section, the above can be written as

$$S_f = E_f \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \int_0^{2\pi} \int_0^\infty f_1(\mathbf{v}_1) f_2(\mathbf{v}_2) F(v, b) v b db d\phi d\mathbf{v}_1 d\mathbf{v}_2. \quad (20)$$

For cases in which we are not interested in the energy generated by the collision, but instead on some other physical property associated with the collision (for example change in momentum rather than change in energy) then the above needs to be generalized. Thus, we would use

$$S = \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \int_0^{2\pi} \int_0^\infty f_1(\mathbf{v}_1) f_2(\mathbf{v}_2) E(v, b) F(v, b) v b db d\phi d\mathbf{v}_1 d\mathbf{v}_2, \quad (21)$$

where $E(v, b)$ is the physical property associated with the collision.