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# 1 Basic

## 1.1 vimrc

```

colo ron
syn on
se ai ar nu rnu
se mouse=a bs=2 ts=4 sw=4 ttm=100
se makeprg=g++\ -Wall\ -Wshadow\ -O2\ -std=c++0x\ -o\
    %<\ %
au BufNewFile *.cpp 0r ~/default.cpp | :1,$-7 fo
filetype indent on

map <F7> <ESC>:wa<CR>:make!<CR>
imap <F7> <ESC>:wa<CR>:make!<CR>
map <F8> :cope <CR>
map <S-F8> :ccl <CR>
map <F9> :!./%< <CR>
map <C-F9> :!./%< < %<.in <CR>
map <C-F7> <ESC>:tabe %<.in<CR>

```

## 1.2 Default Code

```

#include<bits/stdc++.h>
#define F first
#define S second
#define PB push_back
#define MP make_pair
#define ALL(x) begin(x),end(x)
#define SZ(x) ((int)(x).size())
#define FZ(n) memset((n),0,sizeof(n))
using namespace std;
typedef long long LL;
typedef double D;
typedef long double LDB;
typedef pair<int, int> PII;
typedef pair<LL, LL> PLL;
#define IOS ios_base::sync_with_stdio(0); cin.tie(0)

int main(){
}

```

# 2 Data Structure

## 2.1 Bigint

```

struct Bigint{
    static const int LEN = 60;
    static const int BIGMOD = 10000;

    int s;
    int v1, v[LEN];
    // vector<int> v;
    Bigint() : s(1) { v1 = 0; }
    Bigint(long long a) {
        s = 1; v1 = 0;
        if (a < 0) { s = -1; a = -a; }
        while (a) {
            push_back(a % BIGMOD);
            a /= BIGMOD;
        }
    }
    Bigint(string str) {
        s = 1; v1 = 0;
        int stPos = 0, num = 0;
        if (!str.empty() && str[0] == '-') {
            stPos = 1;
            s = -1;
        }
        for (int i=SZ(str)-1, q=1; i>=stPos; i--) {
            num += (str[i] - '0') * q;
            if ((q *= 10) >= BIGMOD) {
                push_back(num);
                num = 0; q = 1;
            }
        }
        if (num) push_back(num);
    }
}

```

```

    n();
}

int len() const {
    return vl;
    // return SZ(v);
}

bool empty() const { return len() == 0; }
void push_back(int x) {
    v[vl++] = x;
    // v.PB(x);
}

void pop_back() {
    vl--;
    // v.pop_back();
}

int back() const {
    return v[vl-1];
    // return v.back();
}

void n() {
    while (!empty() && !back()) pop_back();
}

void resize(int nl) {
    vl = nl;
    fill(v, v+vl, 0);
    // v.resize(nl);
    // fill(ALL(v), 0);
}

void print() const {
    if (empty()) { putchar('0'); return; }
    if (s == -1) putchar('-');
    printf("%d", back());
    for (int i=len()-2; i>=0; i--) printf("%.4d", v[i]);
}

friend std::ostream& operator << (std::ostream& out,
    const Bigint &a) {
    if (a.empty()) { out << "0"; return out; }
    if (a.s == -1) out << "-";
    out << a.back();
    for (int i=a.len()-2; i>=0; i--) {
        char str[10];
        snprintf(str, 5, "%.4d", a.v[i]);
        out << str;
    }
    return out;
}

int cp3(const Bigint &b) const {
    if (s != b.s) return s - b.s;
    if (s == -1) return -(*this).cp3(-b);
    if (len() != b.len()) return len() - b.len(); //int
    for (int i=len()-1; i>=0; i--)
        if (v[i] != b.v[i]) return v[i] - b.v[i];
    return 0;
}

bool operator < (const Bigint &b) const { return cp3(b) < 0; }
bool operator <= (const Bigint &b) const { return cp3(b) <= 0; }
bool operator == (const Bigint &b) const { return cp3(b) == 0; }
bool operator != (const Bigint &b) const { return cp3(b) != 0; }
bool operator > (const Bigint &b) const { return cp3(b) > 0; }
bool operator >= (const Bigint &b) const { return cp3(b) >= 0; }

```

```

Bigint operator - () const {
    Bigint r = (*this);
    r.s = -r.s;
    return r;
}

Bigint operator + (const Bigint &b) const {
    if (s == -1) return -(*this) + (-b);
    if (b.s == -1) return (*this) - (-b);
    Bigint r;
    int nl = max(len(), b.len());
    r.resize(nl + 1);
    for (int i=0; i<nl; i++) {
        if (i < len()) r.v[i] += v[i];
        if (i < b.len()) r.v[i] += b.v[i];
        if (r.v[i] >= BIGMOD) {

```

```

            r.v[i+1] += r.v[i] / BIGMOD;
            r.v[i] %= BIGMOD;
        }
    }
    r.n();
    return r;
}

Bigint operator - (const Bigint &b) const {
    if (s == -1) return -(*this) - (-b);
    if (b.s == -1) return (*this) + (-b);
    if ((*this) < b) return -(*this) - b;
    Bigint r;
    r.resize(len());
    for (int i=0; i<len(); i++) {
        r.v[i] += v[i];
        if (i < b.len()) r.v[i] -= b.v[i];
        if (r.v[i] < 0) {
            r.v[i] += BIGMOD;
            r.v[i+1]--;
        }
    }
    r.n();
    return r;
}

Bigint operator * (const Bigint &b) {
    Bigint r;
    r.resize(len() + b.len() + 1);
    r.s = s * b.s;
    for (int i=0; i<len(); i++) {
        for (int j=0; j<b.len(); j++) {
            r.v[i+j] += v[i] * b.v[j];
            if (r.v[i+j] >= BIGMOD) {
                r.v[i+j+1] += r.v[i+j] / BIGMOD;
                r.v[i+j] %= BIGMOD;
            }
        }
    }
    r.n();
    return r;
}

Bigint operator / (const Bigint &b) {
    Bigint r;
    r.resize(max(1, len() - b.len() + 1));
    int oriS = s;
    Bigint b2 = b; // b2 = abs(b)
    s = b2.s = r.s = 1;
    for (int i=r.len()-1; i>=0; i--) {
        int d=0, u=BIGMOD-1;
        while (d<u) {
            int m = (d+u+1)>>1;
            r.v[i] = m;
            if ((r*b2) > (*this)) u = m-1;
            else d = m;
        }
        r.v[i] = d;
    }
    s = oriS;
    r.s = s * b.s;
    r.n();
    return r;
}

Bigint operator % (const Bigint &b) {
    return (*this) - (*this)/b*b;
}
};

```

## 2.2 unordered\_map

```

struct Key {
    int first, second;
    Key () {}
    Key (int _x, int _y) : first(_x), second(_y) {}
    bool operator == (const Key &b) const {
        return tie(F,S) == tie(b.F,b.S);
    }
};

struct KeyHasher {
    size_t operator()(const Key& k) const {
        return k.first + k.second*100000;
    }
};

typedef unordered_map<Key,int,KeyHasher> map_t;

```

```
int main(int argc, char** argv){
    map_t mp;
    for (int i=0; i<10; i++)
        mp[Key(i,0)] = i+1;
    for (int i=0; i<10; i++)
        printf("%d\n", mp[Key(i,0)]);

    return 0;
}
```

## 2.3 extc\_heap

```
#include <bits/extc++.h>
typedef __gnu_pbds::priority_queue<int> heap_t;
heap_t a,b;

int main() {
    a.clear();
    b.clear();
    a.push(1);
    a.push(3);
    b.push(2);
    b.push(4);
    assert(a.top() == 3);
    assert(b.top() == 4);
    // merge two heap
    a.join(b);
    assert(a.top() == 4);
    assert(b.empty());

    return 0;
}
```

## 2.4 extc\_balance\_tree

```
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
using namespace std;
using namespace __gnu_pbds;
typedef tree<int, null_type, less<int>, rb_tree_tag,
    tree_order_statistics_node_update> set_t;
typedef cc_hash_table<int,int> umap_t;

int main()
{
    // Insert some entries into s.
    set_t s;
    s.insert(12);
    s.insert(505);

    // The order of the keys should be: 12, 505.
    assert(*s.find_by_order(0) == 12);
    assert(s.find_by_order(2) == end(s));

    // The order of the keys should be: 12, 505.
    assert(s.order_of_key(12) == 0);
    assert(s.order_of_key(505) == 1);

    // Erase an entry.
    s.erase(12);

    // The order of the keys should be: 505.
    assert(*s.find_by_order(0) == 505);

    // The order of the keys should be: 505.
    assert(s.order_of_key(505) == 0);
}
```

## 2.5 Disjoint Set

```
struct DisjointSet {
    // save() is like recursive
    // undo() is like return
    int n, fa[MXN], sz[MXN];
    vector<pair<int*,int>> h;
    vector<int> sp;
    void init(int tn) {
        n=tn;
        for (int i=0; i<n; i++) {
```

```
        fa[i]=i;
        sz[i]=1;
    }
    sp.clear(); h.clear();
}
void assign(int *k, int v) {
    h.PB({k, *k});
    *k=v;
}
void save() { sp.PB(SZ(h)); }
void undo() {
    assert(!sp.empty());
    int last=sp.back(); sp.pop_back();
    while (SZ(h)!=last) {
        auto x=h.back(); h.pop_back();
        *x.F=x.S;
    }
}
int f(int x) {
    while (fa[x]!=x) x=fa[x];
    return x;
}
void uni(int x, int y) {
    x=f(x); y=f(y);
    if (x==y) return;
    if (sz[x]<sz[y]) swap(x, y);
    assign(&sz[x], sz[x]+sz[y]);
    assign(&fa[y], x);
}
}djs;
```

## 2.6 Treap

```
const int MEM = 16000004;
struct Treap {
    static Treap nil, mem[MEM], *pmem;
    Treap *l, *r;
    char val;
    int size;
    Treap () : l(&nil), r(&nil), size(0) {}
    Treap (char _val) :
        l(&nil), r(&nil), val(_val), size(1) {}
} Treap::nil, Treap::mem[MEM], *Treap::pmem = Treap::
    mem;

int size(const Treap *t) { return t->size; }
void pull(Treap *t) {
    if (!size(t)) return;
    t->size = size(t->l) + size(t->r) + 1;
}
Treap* merge(Treap *a, Treap *b) {
    if (!size(a)) return b;
    if (!size(b)) return a;
    Treap *t;
    if (rand() % (size(a) + size(b)) < size(a)) {
        t = new (Treap::pmem++) Treap(*a);
        t->r = merge(a->r, b);
    } else {
        t = new (Treap::pmem++) Treap(*b);
        t->l = merge(a, b->l);
    }
    pull(t);
    return t;
}
void split(Treap *t, int k, Treap *&a, Treap *&b) {
    if (!size(t)) a = b = &Treap::nil;
    else if (size(t->l) + 1 <= k) {
        a = new (Treap::pmem++) Treap(*t);
        split(t->r, k - size(t->l) - 1, a->r, b);
        pull(a);
    } else {
        b = new (Treap::pmem++) Treap(*t);
        split(t->l, k, a, b->l);
        pull(b);
    }
}

int nv;
Treap *rt[50005];

void print(const Treap *t) {
    if (!size(t)) return;
    print(t->l);
    cout << t->val;
```

```

    print(t->r);
}

int main(int argc, char** argv) {
    IOS;
    rt[nv=0] = &Treap::nil;
    Treap::pmem = Treap::mem;
    int Q, cmd, p, c, v;
    string s;
    cin >> Q;
    while (Q--) {
        cin >> cmd;
        if (cmd == 1) {
            // insert string s after position p
            cin >> p >> s;
            Treap *tl, *tr;
            split(rt[nv], p, tl, tr);
            for (int i=0; i<SZ(s); i++)
                tl = merge(tl, new (Treap::pmem++) Treap(s[i]))
                    ;
            rt[++nv] = merge(tl, tr);
        } else if (cmd == 2) {
            // remove c characters starting at position
            Treap *tl, *tm, *tr;
            cin >> p >> c;
            split(rt[nv], p-1, tl, tm);
            split(tm, c, tm, tr);
            rt[++nv] = merge(tl, tr);
        } else if (cmd == 3) {
            // print c characters starting at position p, in
            // version v
            Treap *tl, *tm, *tr;
            cin >> v >> p >> c;
            split(rt[v], p-1, tl, tm);
            split(tm, c, tm, tr);
            print(tm);
            cout << "\n";
        }
    }
    return 0;
}

```

## 3 Graph

### 3.1 BCC Edge

```

struct BccEdge {
    static const int MXN = 100005;
    struct Edge { int v, eid; };
    int n, m, step, par[MXN], dfn[MXN], low[MXN];
    vector<Edge> E[MXN];
    DisjointSet djs;
    void init(int _n) {
        n = _n; m = 0;
        for (int i=0; i<n; i++) E[i].clear();
        djs.init(n);
    }
    void add_edge(int u, int v) {
        E[u].PB({v, m});
        E[v].PB({u, m});
        m++;
    }
    void DFS(int u, int f, int f_eid) {
        par[u] = f;
        dfn[u] = low[u] = step++;
        for (auto it:E[u]) {
            if (it.eid == f_eid) continue;
            int v = it.v;
            if (dfn[v] == -1) {
                DFS(v, u, it.eid);
                low[u] = min(low[u], low[v]);
            } else {
                low[u] = min(low[u], dfn[v]);
            }
        }
    }
    void solve() {
        step = 0;
        memset(dfn, -1, sizeof(int)*n);
        for (int i=0; i<n; i++) {
            if (dfn[i] == -1) DFS(i, i, -1);
        }
    }
}

```

```

    djs.init(n);
    for (int i=0; i<n; i++) {
        if (low[i] < dfn[i]) djs.uni(i, par[i]);
    }
}
}graph;

```

### 3.2 BCC Vertex

```

struct BccVertex {
    int n, nBcc, step, root, dfn[MXN], low[MXN];
    vector<int> E[MXN], ap;
    vector<pii> bcc[MXN];
    int top;
    pii stk[MXN];
    void init(int _n) {
        n = _n;
        nBcc = step = 0;
        for (int i=0; i<n; i++) E[i].clear();
    }
    void add_edge(int u, int v) {
        E[u].PB(v);
        E[v].PB(u);
    }
    void DFS(int u, int f) {
        dfn[u] = low[u] = step++;
        int son = 0;
        for (auto v:E[u]) {
            if (v == f) continue;
            if (dfn[v] == -1) {
                son++;
                stk[top++] = {u, v};
                DFS(v, u);
                if (low[v] >= dfn[u]) {
                    if (v != root) ap.PB(v);
                    do {
                        assert(top > 0);
                        bcc[nBcc].PB(stk[--top]);
                    } while (stk[top] != pii(u, v));
                    nBcc++;
                }
                low[u] = min(low[u], low[v]);
            } else {
                if (dfn[v] < dfn[u]) stk[top++] = pii(u, v);
                low[u] = min(low[u], dfn[v]);
            }
        }
        if (u == root && son > 1) ap.PB(u);
    }
    // return the edges of each bcc;
    vector<vector<pii>> solve() {
        vector<vector<pii>> res;
        for (int i=0; i<n; i++) {
            dfn[i] = low[i] = -1;
        }
        ap.clear();
        for (int i=0; i<n; i++) {
            if (dfn[i] == -1) {
                top = 0;
                root = i;
                DFS(i, i);
            }
        }
        REP(i, nBcc) res.PB(bcc[i]);
        return res;
    }
}
}graph;

```

### 3.3 Strongly Connected Components

```

struct Scc{
    int n, nScc, vst[MXN], bln[MXN];
    vector<int> E[MXN], rE[MXN], vec;
    void init(int _n){
        n = _n;
        for (int i=0; i<n; i++){
            E[i].clear();
            rE[i].clear();
        }
    }
    void add_edge(int u, int v){
        E[u].PB(v);
    }
}

```

```

    rE[v].PB(u);
}
void DFS(int u){
    vst[u]=1;
    for (auto v : E[u])
        if (!vst[v]) DFS(v);
    vec.PB(u);
}
void rDFS(int u){
    vst[u] = 1;
    bln[u] = nScc;
    for (auto v : rE[u])
        if (!vst[v]) rDFS(v);
}
void solve(){
    nScc = 0;
    vec.clear();
    for (int i=0; i<n; i++) vst[i] = 0;
    for (int i=0; i<n; i++)
        if (!vst[i]) DFS(i);
    reverse(vec.begin(),vec.end());
    for (int i=0; i<n; i++) vst[i] = 0;
    for (auto v : vec){
        if (!vst[v]){
            rDFS(v);
            nScc++;
        }
    }
}
};

```

### 3.4 Maximum Clique

```

class MaxClique {
public:
    static const int MV = 210;

    int V;
    int el[MV][MV/30+1];
    int dp[MV];
    int ans;
    int s[MV][MV/30+1];
    vector<int> sol;

    void init(int v) {
        V = v; ans = 0;
        FZ(el); FZ(dp);
    }

    /* Zero Base */
    void addEdge(int u, int v) {
        if(u > v) swap(u, v);
        if(u == v) return;
        el[u][v/32] |= (1<<(v%32));
    }

    bool dfs(int v, int k) {
        int c = 0, d = 0;
        for(int i=0; i<(V+31)/32; i++) {
            s[k][i] = el[v][i];
            if(k != 1) s[k][i] &= s[k-1][i];
            c += __builtin_popcount(s[k][i]);
        }
        if(c == 0) {
            if(k > ans) {
                ans = k;
                sol.clear();
                sol.push_back(v);
                return 1;
            }
            return 0;
        }
        for(int i=0; i<(V+31)/32; i++) {
            for(int a = s[k][i]; a ; d++) {
                if(k + (c-d) <= ans) return 0;
                int lb = a&(-a), lg = 0;
                a ^= lb;
                while(lb!=1) {
                    lb = (unsigned int)(lb) >> 1;
                    lg ++;
                }
                int u = i*32 + lg;
                if(k + dp[u] <= ans) return 0;
                if(dfs(u, k+1)) {

```

```

                    sol.push_back(v);
                    return 1;
                }
            }
        }
        return 0;
    }

    int solve() {
        for(int i=V-1; i>=0; i--) {
            dfs(i, 1);
            dp[i] = ans;
        }
        return ans;
    }
};

```

### 3.5 MinimumMeanCycle

```

/* minimum mean cycle */
const int MAXE = 1805;
const int MAXN = 35;
const double inf = 1029384756;
const double eps = 1e-6;
struct Edge {
    int v,u;
    double c;
};
int n,m,prv[MAXN][MAXN], prve[MAXN][MAXN], vst[MAXN];
Edge e[MAXE];
vector<int> edgeID, cycle, rho;
double d[MAXN][MAXN];
inline void bellman_ford() {
    for(int i=0; i<n; i++) d[0][i]=0;
    for(int i=0; i<n; i++) {
        fill(d[i+1], d[i+1]+n, inf);
        for(int j=0; j<m; j++) {
            int v = e[j].v, u = e[j].u;
            if(d[i][v]<inf && d[i+1][u]>d[i][v]+e[j].c) {
                d[i+1][u] = d[i][v]+e[j].c;
                prv[i+1][u] = v;
                prve[i+1][u] = j;
            }
        }
    }
}
double karp_mmc() {
    // returns inf if no cycle, mmc otherwise
    double mmc=inf;
    int st = -1;
    bellman_ford();
    for(int i=0; i<n; i++) {
        double avg=-inf;
        for(int k=0; k<n; k++) {
            if(d[n][i]<inf-eps) avg=max(avg,(d[n][i]-d[k][i])/(n-k));
            else avg=max(avg,inf);
        }
        if (avg < mmc) tie(mmc, st) = tie(avg, i);
    }
    for(int i=0; i<n; i++) vst[i] = 0;
    edgeID.clear(); cycle.clear(); rho.clear();
    for (int i=n; !vst[st]; st=prv[i--][st]) {
        vst[st]++;
        edgeID.PB(prve[i][st]);
        rho.PB(st);
    }
    while (vst[st] != 2) {
        int v = rho.back(); rho.pop_back();
        cycle.PB(v);
        vst[v]++;
    }
    reverse(ALL(edgeID));
    edgeID.resize(SZ(cycle));
    return mmc;
}

```

## 4 Flow

### 4.1 Dinic

```

struct Dinic{
    static const int MXN = 10000;
    struct Edge{ int v,f,re; };
    int n,s,t,level[MXN];
    vector<Edge> E[MXN];
    void init(int _n, int _s, int _t){
        n = _n; s = _s; t = _t;
        for (int i=0; i<n; i++) E[i].clear();
    }
    void add_edge(int u, int v, int f){
        E[u].PB({v,f,SZ(E[v])});
        E[v].PB({u,0,SZ(E[u])-1});
    }
    bool BFS(){
        for (int i=0; i<n; i++) level[i] = -1;
        queue<int> que;
        que.push(s);
        level[s] = 0;
        while (!que.empty()){
            int u = que.front(); que.pop();
            for (auto it : E[u]){
                if (it.f > 0 && level[it.v] == -1){
                    level[it.v] = level[u]+1;
                    que.push(it.v);
                }
            }
        }
        return level[t] != -1;
    }
    int DFS(int u, int nf){
        if (u == t) return nf;
        int res = 0;
        for (auto &it : E[u]){
            if (it.f > 0 && level[it.v] == level[u]+1){
                int tf = DFS(it.v, min(nf,it.f));
                res += tf; nf -= tf; it.f -= tf;
                E[it.v][it.re].f += tf;
                if (nf == 0) return res;
            }
        }
        if (!res) level[u] = -1;
        return res;
    }
    int flow(int res=0){
        while ( BFS() )
            res += DFS(s,2147483647);
        return res;
    }
}flow;

```

## 4.2 Cost Flow

```

typedef pair<long long, long long> pll;
struct CostFlow {
    static const int MXN = 205;
    static const long long INF = 102938475610293847LL;
    struct Edge {
        int v, r;
        long long f, c;
    };
    int n, s, t, prv[MXN], prvl[MXN], inq[MXN];
    long long dis[MXN], fl, cost;
    vector<Edge> E[MXN];
    void init(int _n, int _s, int _t) {
        n = _n; s = _s; t = _t;
        for (int i=0; i<n; i++) E[i].clear();
        fl = cost = 0;
    }
    void add_edge(int u, int v, long long f, long long c)
    {
        E[u].PB({v, SZ(E[v]), f, c});
        E[v].PB({u, SZ(E[u])-1, 0, -c});
    }
    pll flow() {
        while (true) {
            for (int i=0; i<n; i++) {
                dis[i] = INF;
                inq[i] = 0;
            }
            dis[s] = 0;
            queue<int> que;
            que.push(s);
            while (!que.empty()) {
                int u = que.front(); que.pop();

```

```

                inq[u] = 0;
                for (int i=0; i<SZ(E[u]); i++) {
                    int v = E[u][i].v;
                    long long w = E[u][i].c;
                    if (E[u][i].f > 0 && dis[v] > dis[u] + w) {
                        prv[v] = u; prvl[v] = i;
                        dis[v] = dis[u] + w;
                        if (!inq[v]) {
                            inq[v] = 1;
                            que.push(v);
                        }
                    }
                }
            }
            if (dis[t] == INF) break;
            long long tf = INF;
            for (int v=t, u, l; v!=s; v=u) {
                u=prv[v]; l=prvl[v];
                tf = min(tf, E[u][l].f);
            }
            for (int v=t, u, l; v!=s; v=u) {
                u=prv[v]; l=prvl[v];
                E[u][l].f -= tf;
                E[v][E[u][l].r].f += tf;
            }
            cost += tf * dis[t];
            fl += tf;
        }
        return {fl, cost};
    }
}flow;

```

## 4.3 Maximum Simple Graph Matching

```

struct GenMatch { // 1-base
    static const int MAXN = 514;
    int V;
    bool el[MAXN][MAXN];
    int pr[MAXN];
    bool inq[MAXN],inp[MAXN],inb[MAXN];
    queue<int> qe;
    int st,ed;
    int nb;
    int bk[MAXN],djs[MAXN];
    int ans;
    void init(int _V) {
        V = _V;
        for(int i = 0; i <= V; i++) {
            for(int j = 0; j <= V; j++) el[i][j] = 0;
            pr[i] = bk[i] = djs[i] = 0;
            inq[i] = inp[i] = inb[i] = 0;
        }
        ans = 0;
    }
    void add_edge(int u, int v) {
        el[u][v] = el[v][u] = 1;
    }
    int lca(int u,int v) {
        for(int i = 0; i <= V; i++) inp[i] = 0;
        while(1) {
            u = djs[u];
            inp[u] = true;
            if(u == st) break;
            u = bk[pr[u]];
        }
        while(1) {
            v = djs[v];
            if(inp[v]) return v;
            v = bk[pr[v]];
        }
        return v;
    }
    void upd(int u) {
        int v;
        while(djs[u] != nb) {
            v = pr[u];
            inb[djs[u]] = inb[djs[v]] = true;
            u = bk[v];
            if(djs[u] != nb) bk[u] = v;
        }
    }
    void blo(int u,int v) {
        nb = lca(u,v);
        for (int i=0; i<=V; i++) inb[i] = 0;
    }

```

```

    upd(u); upd(v);
    if(djs[u] != nb) bk[u] = v;
    if(djs[v] != nb) bk[v] = u;
    for(int tu = 1; tu <= V; tu++)
        if(inb[djs[tu]]) {
            djs[tu] = nb;
            if(!inq[tu]){
                qe.push(tu);
                inq[tu] = 1;
            }
        }
}
void flow() {
    for(int i = 1; i <= V; i++) {
        inq[i] = 0;
        bk[i] = 0;
        djs[i] = i;
    }

    while(qe.size()) qe.pop();
    qe.push(st);
    inq[st] = 1;
    ed = 0;
    while(qe.size()) {
        int u = qe.front(); qe.pop();
        for(int v = 1; v <= V; v++)
            if(el[u][v] && (djs[u] != djs[v]) && (pr[u] != v)) {
                if((v == st) || ((pr[v] > 0) && bk[pr[v]] > 0))
                    blo(u,v);
                else if(bk[v] == 0) {
                    bk[v] = u;
                    if(pr[v] > 0) {
                        if(!inq[pr[v]]) qe.push(pr[v]);
                    } else {
                        ed = v;
                        return;
                    }
                }
            }
    }
}
void aug() {
    int u,v,w;
    u = ed;
    while(u > 0) {
        v = bk[u];
        w = pr[v];
        pr[v] = u;
        pr[u] = v;
        u = w;
    }
}
int solve() {
    for(int i = 0; i <= V; i++) pr[i] = 0;
    for(int u = 1; u <= V; u++)
        if(pr[u] == 0) {
            st = u;
            flow();
            if(ed > 0) {
                aug();
                ans ++;
            }
        }
    return ans;
}
}G;

int main() {
    G.init(V);
    for(int i=0; i<E; i++) {
        int u, v;
        cin >> u >> v;
        G.add_edge(u, v);
    }
    cout << G.solve() << endl;
}

```

#### 4.4 Minimum Weight Matching (Clique version)

```
struct Graph {
```

```

// Minimum General Weighted Matching (Perfect Match)
// 0-base
static const int MXN = 105;

int n, edge[MXN][MXN];
int match[MXN],dis[MXN],onstk[MXN];
vector<int> stk;

void init(int _n) {
    n = _n;
    for (int i=0; i<n; i++)
        for (int j=0; j<n; j++)
            edge[i][j] = 0;
}

void add_edge(int u, int v, int w) {
    edge[u][v] = edge[v][u] = w;
}

bool SPFA(int u){
    if (onstk[u]) return true;
    stk.PB(u);
    onstk[u] = 1;
    for (int v=0; v<n; v++){
        if (u != v && match[u] != v && !onstk[v]){
            int m = match[v];
            if (dis[m] > dis[u] - edge[v][m] + edge[u][v]){
                dis[m] = dis[u] - edge[v][m] + edge[u][v];
                onstk[v] = 1;
                stk.PB(v);
                if (SPFA(m)) return true;
            }
            stk.pop_back();
            onstk[v] = 0;
        }
    }
    onstk[u] = 0;
    stk.pop_back();
    return false;
}

int solve() {
    // find a match
    for (int i=0; i<n; i+=2){
        match[i] = i+1;
        match[i+1] = i;
    }
    while (true){
        int found = 0;
        for (int i=0; i<n; i++)
            dis[i] = onstk[i] = 0;
        for (int i=0; i<n; i++){
            stk.clear();
            if (!onstk[i] && SPFA(i)){
                found = 1;
                while (SZ(stk)>=2){
                    int u = stk.back(); stk.pop_back();
                    int v = stk.back(); stk.pop_back();
                    match[u] = v;
                    match[v] = u;
                }
            }
        }
        if (!found) break;
    }
    int ret = 0;
    for (int i=0; i<n; i++)
        ret += edge[i][match[i]];
    ret /= 2;
    return ret;
}
}graph;

```

## 5 Math

### 5.1 $ax+by=gcd$

```

typedef pair<int, int> pii;

pii gcd(int a, int b){
    if(b == 0) return make_pair(1, 0);
    else{
        int p = a / b;
        pii q = gcd(b, a % b);
    }
}

```



```

    return make_pair(q.second, q.first - q.second * p);
}
}

```

## 5.2 Fast Fourier Transform

```

struct cp{
    double _a,_b;
    cp operator +(const cp &o) const {return (cp){_a+_o._a,
        _b+_o._b};}
    cp operator -(const cp &o) const {return (cp){_a-_o._a,
        _b-_o._b};}
    cp operator *(const cp &o) const {return (cp){_a*_o._a-
        _b*_o._b, _b*_o._a+_a*_o._b};}
    cp operator *(const double &o) const {return (cp){_a*
        _o, _b*_o};}
    cp operator !() const{return (cp){_a,-_b};}
}w[MAX];
int pos[MAX];
void fft_init(int len){
    int j = 0;
    while((1<<j) < len) j++;
    j--;
    for(int i=0;i<len;i++)
        pos[i] = pos[i>>1]>>1 | ((i&1)<<j);
}
void fft(cp *x, int len, int sta){
    for(int i = 0; i < len; i++)
        if(i < pos[i]) swap(_x[i], _x[pos[i]]);
    w[0] = (cp){1,0};
    for(unsigned i = 2; i <= len; i <= 1){
        cp g=(cp){cos(2*PI/i),sin(2*PI/i)*sta};
        for(int j = i>>1; j >= 0; j -= 2) w[j] = w[j]
            >>1;
        for(int j = 1; j < (i>>1); j += 2)w[j] = w[j]
            -1*g;
        for(int j = 0; j < len; j += i){
            cp *_a = _x+j, *_b = _a+(i>>1);
            for(int l = 0; l < (i>>1); l++){
                cp o = _b[l]*w[l];
                _b[l] = _a[l]-o;
                _a[l] = _a[l]+o;
            }
        }
    }
    if(sta == -1) for(int i = 0; i < len; i++) _x[i]._a
        /= len, _x[i]._b /= len;
}
cp _x[MAX],_y[MAX],_z[MAX];
void FFT(int _a, int _b, int l1, int l2, int _c){
    int len = 1;
    while(len <= (l1+l2)>>1)len <= 1;
    fft_init(len);
    for(int i = l1>>1; i<len; i++) _x[i]._a = _x[i]._b
        = 0;
    for(int i = l2>>1; i<len; i++) _y[i]._a = _y[i]._b
        = 0;
    for(int i = 0; i < l1; i++) (i&1 ? _x[i>>1]._b : _x
        [i>>1]._a) = st[_a][i];
    for(int i = 0; i < l2; i++) (i&1 ? _y[i>>1]._b : _y
        [i>>1]._a) = st[_b][i];
    fft(_x, len, 1), fft(_y, len, 1);
    for(int i = 0; i < len>>1; i++){
        int j = len - 1&len - i;
        _z[i] = _x[i]*_y[i] - (_x[i]-!_x[j])*( _y[i]-!_y
            [j])*(w[i]+(cp){1,0})*0.25;
    }
    for(int i = len>>1; i < len; i++){
        int j = len - 1&len - i;
        _z[i] = _x[i]*_y[i] - (_x[i]-!_x[j])*( _y[i]-!_y
            [j])*((cp){1,0}-w[i^len>>1])*0.25;
    }
    fft(_z, len, -1);
    for(int i = 0; i < l1 + l2 - 1;i++)
        if(i&1) st[_c][i] = (LL)(_z[i>>1]._b+0.5);
        else st[_c][i] = (LL)(_z[i>>1]._a+0.5);
}
}

```

## 5.3 Theorem

### 5.3.1 Lucas' Theorem

For non-negative integer  $n, m$  and prime  $p$ ,  $\binom{m}{n} \equiv \prod_{i=0}^k \binom{m_i}{n_i} \pmod{p}$  where  $m_i$  is the  $i$ -th digit of  $m$  in base  $p$ .

### 5.3.2 Sum of Two Squares Thm (Legendre)

For a given positive integer  $n$ , let  
 $D_1 = (\# \text{ of positive integers } d \text{ dividing } N \text{ that } 1 \equiv d \pmod{4})$   
 $D_3 = (\# \text{ of positive integers } d \text{ dividing } N \text{ that } 3 \equiv d \pmod{4})$   
then  $n$  can be written as a sum of two squares in exactly  
 $R(n) = 4(D_1 - D_3)$  ways.

### 5.3.3 Difference of D1-D3 Thm

let  $n = 2^t \cdot (p_1^{e_1} \cdot \dots \cdot p_r^{e_r}) \cdot \dots \cdot (q_1^{f_1} \cdot \dots \cdot q_s^{f_s})$   
where  $p_i, q_i$  are primes and  $1 \equiv p_i \pmod{4}, 3 \equiv q_i \pmod{4}$   
then  $D_1 - D_3 = \begin{cases} (e_1 + 1)(e_2 + 1) \dots (e_r + 1), & \text{if } f_i \text{ all even} \\ 0, & \text{if any } f_i \text{ is odd} \end{cases}$

### 5.3.4 Krush–Kuhn–Tucker Conditions

#### Stationarity

For maximizing  $f(x)$ :  $\nabla f(x^*) = \sum_{i=1}^m \mu_i \nabla g_i(x^*) + \sum_{j=1}^l \lambda_j \nabla h_j(x^*)$   
For minimizing  $f(x)$ :  $-\nabla f(x^*) = \sum_{i=1}^m \mu_i \nabla g_i(x^*) + \sum_{j=1}^l \lambda_j \nabla h_j(x^*)$

#### Primal feasibility

$g_i(x^*) \leq 0$ , for all  $i = 1, \dots, m$   
 $h_j(x^*) = 0$ , for all  $j = 1, \dots, l$

#### Dual feasibility

$\mu_i \geq 0$ , for all  $i = 1, \dots, m$

#### Complementary slackness

$\mu_i g_i(x^*) = 0$ , for all  $i = 1, \dots, m$

### 5.3.5 Chinese remainder theorem

$x \equiv r_i \pmod{p_i}$   
 $N = \prod p_i$   
 $N_i = N/p_i$   
 $x \equiv \sum r_i N_i (N_i)_{p_i}^{-1} \pmod{N}$

## 6 Geometry

### 6.1 Point operators

```

#define x first
#define y second

#define cpdd const pdd
struct pdd : pair<double, double> {
    using pair<double, double>::pair;

    pdd operator + (cpdd &p) const {
        return {x+p.x, y+p.y};
    }

    pdd operator - () const {
        return {-x, -y};
    }

    pdd operator - (cpdd &p) const {
        return (*this) + (-p);
    }

    pdd operator * (double f) const {
        return {f*x, f*y};
    }

    double operator * (cpdd &p) const {
        return x*p.x + y*p.y;
    }
};

double abs(cpdd &p) { return hypot(p.x, p.y); }
double arg(cpdd &p) { return atan2(p.y, p.x); }
double cross(cpdd &p, cpdd &q) { return p.x*q.y - p.y*q
    .x; }

```



```
double cross(cpdd &p, cpdd &q, cpdd &o) { return cross(
    p-o, q-o); }
pdd operator * (double f, cpdd &p) { return p*f; } //
    !! Not f*p !!
```

## 6.2 Intersection of two circles

```
using ld = double;
vector<pdd> interCircle(pdd o1, double r1, pdd o2,
    double r2) {
    ld d2 = (o1 - o2) * (o1 - o2);
    ld d = sqrt(d2);
    if (d < abs(r1-r2)) return {};
    if (d > r1+r2) return {};
    pdd u = 0.5*(o1+o2) + ((r2*r2-r1*r1)/(2*d2))*(o1-o2);
    double A = sqrt((r1+r2+d) * (r1-r2+d) * (r1+r2-d) *
        (-r1+r2+d));
    pdd v = A / (2*d2) * pdd(o1.S-o2.S, -o1.F+o2.F);
    return {u+v, u-v};
}
```

## 6.3 Intersection of two lines

```
const double EPS = 1e-9;
pdd interPnt(pdd p1, pdd p2, pdd q1, pdd q2, bool &res)
{
    double f1 = cross(p2, q1, p1);
    double f2 = -cross(p2, q2, p1);
    double f = (f1 + f2);

    if(fabs(f) < EPS) {
        res = false;
        return {};
    }

    res = true;
    return (f2 / f) * q1 + (f1 / f) * q2;
}
```

## 6.4 Circle cover

```
typedef double type;
typedef pair<type,type> Pt;
typedef pair<Pt,Pt> Line;
typedef pair<Pt,type> Circle;
#define X first
#define Y second
#define O first
#define R second
Pt operator+( const Pt& p1 , const Pt& p2 ){
    return { p1.X + p2.X , p1.Y + p2.Y };
}
Pt operator-( const Pt& p1 , const Pt& p2 ){
    return { p1.X - p2.X , p1.Y - p2.Y };
}
Pt operator*( const Pt& tp , const type& tk ){
    return { tp.X * tk , tp.Y * tk };
}
Pt operator/( const Pt& tp , const type& tk ){
    return { tp.X / tk , tp.Y / tk };
}
type operator*( const Pt& p1 , const Pt& p2 ){
    return p1.X * p2.X + p1.Y * p2.Y;
}
type operator^( const Pt& p1 , const Pt& p2 ){
    return p1.X * p2.Y - p1.Y * p2.X;
}
type norm2( const Pt& tp ){
    return tp * tp;
}
double norm( const Pt& tp ){
    return sqrt( norm2( tp ) );
}
Pt perp( const Pt& tp ){
    return { tp.Y , -tp.X };
}
#define N 1021
```

```
struct CircleCover{
    int C; Circ c[ N ];
    bool g[ N ][ N ], overlap[ N ][ N ];
    // Area[i] : area covered by at least i circles
    D Area[ N ];
    void init( int _C ){ C = _C; }
    bool CCinter( Circ& a , Circ& b , Pt& p1 , Pt& p2 ){
        Pt o1 = a.O , o2 = b.O;
        D r1 = a.R , r2 = b.R;
        if( norm( o1 - o2 ) > r1 + r2 ) return {};
        if( norm( o1 - o2 ) < max(r1, r2) - min(r1, r2) )
            return {};
        D d2 = ( o1 - o2 ) * ( o1 - o2 );
        D d = sqrt(d2);
        if( d > r1 + r2 ) return false;
        Pt u=(o1+o2)*0.5 + (o1-o2)*((r2*r2-r1*r1)/(2*d2));
        D A=sqrt((r1+r2+d)*(r1-r2+d)*(r1+r2-d)*(-r1+r2+d));
        Pt v=Pt( o1.Y-o2.Y , -o1.X + o2.X ) * A / (2*d2);
        p1 = u + v; p2 = u - v;
        return true;
    }
    struct Teve {
        Pt p; D ang; int add;
        Teve() {}
        Teve(Pt _a, D _b, int _c):p(_a), ang(_b), add(_c){}
        bool operator<(const Teve &a)const
            {return ang < a.ang;}
    }eve[ N * 2 ];
    // strict: x = 0, otherwise x = -1
    bool disjuct( Circ& a, Circ &b, int x )
    {return sign( norm( a.O - b.O ) - a.R - b.R ) > x;}
    bool contain( Circ& a, Circ &b, int x )
    {return sign( a.R - b.R - norm( a.O - b.O ) ) > x;}
    bool contain(int i, int j){
        /* c[j] is non-strictly in c[i]. */
        return (sign(c[i].R - c[j].R) > 0 ||
            (sign(c[i].R - c[j].R) == 0 && i < j) ) &&
            contain(c[i], c[j], -1);
    }
    void solve(){
        for( int i = 0 ; i <= C + 1 ; i ++ )
            Area[ i ] = 0;
        for( int i = 0 ; i < C ; i ++ )
            for( int j = 0 ; j < C ; j ++ )
                overlap[i][j] = contain(i, j);
        for( int i = 0 ; i < C ; i ++ )
            for( int j = 0 ; j < C ; j ++ )
                g[i][j] = !(overlap[i][j] || overlap[j][i] ||
                    disjuct(c[i], c[j], -1));
        for( int i = 0 ; i < C ; i ++ ){
            int E = 0, cnt = 1;
            for( int j = 0 ; j < C ; j ++ )
                if( j != i && overlap[j][i] )
                    cnt ++;
            for( int j = 0 ; j < C ; j ++ )
                if( i != j && g[i][j] ){
                    Pt aa, bb;
                    CCinter(c[i], c[j], aa, bb);
                    D A=atan2(aa.Y - c[i].O.Y, aa.X - c[i].O.X);
                    D B=atan2(bb.Y - c[i].O.Y, bb.X - c[i].O.X);
                    eve[E ++] = Teve(bb, B, 1);
                    eve[E ++] = Teve(aa, A, -1);
                    if(B > A) cnt ++;
                }
            if( E == 0 ) Area[ cnt ] += pi * c[i].R * c[i].R;
            else{
                sort( eve , eve + E );
                eve[E] = eve[0];
                for( int j = 0 ; j < E ; j ++ ){
                    cnt += eve[j].add;
                    Area[cnt] += (eve[j].p ^ eve[j + 1].p) * .5;
                    D theta = eve[j + 1].ang - eve[j].ang;
                    if( theta < 0 ) theta += 2. * pi;
                    Area[cnt] +=
                        (theta - sin(theta)) * c[i].R*c[i].R * .5;
                }
            }
        }
    }
};
```

## 6.5 Half Plane Intersection

```
const double EPS = 1e-9;
```

```

pdd interPnt(Line l1, Line l2, bool &res){
    pdd p1, p2, q1, q2;
    tie(p1, p2) = l1;
    tie(q1, q2) = l2;
    double f1 = cross(p2, q1, p1);
    double f2 = -cross(p2, q2, p1);
    double f = (f1 + f2);

    if(fabs(f) < EPS) {
        res = false;
        return {0, 0};
    }

    res = true;
    return (f2 / f) * q1 + (f1 / f) * q2;
}

bool isin(Line l0, Line l1, Line l2) {
    // Check inter(l1, l2) in l0
    bool res;
    pdd p = interPnt(l1, l2, res);
    return cross(l0.S, p, l0.F) > EPS;
}

/* If no solution, check: 1. ret.size() < 3
 * Or more precisely, 2. interPnt(ret[0], ret[1])
 * in all the lines. (use (l.S - l.F).cross(p - l.F) >
 * 0
 */
vector<Line> halfPlaneInter(vector<Line> lines) {
    int sz = lines.size();
    vector<double> ata(sz), ord(sz);
    for (int i=0; i<sz; i++) {
        ord[i] = i;
        pdd d = lines[i].S - lines[i].F;
        ata[i] = atan2(d.y, d.x);
    }
    sort(ALL(ord), [&](int i, int j) {
        if (abs(ata[i] - ata[j]) < EPS) {
            return cross(lines[i].S, lines[j].S, lines[
                i].F) < 0;
        }
        return ata[i] < ata[j];
    });
    vector<Line> fin;
    for (int i=0; i<sz; i++) {
        if (!i or fabs(ata[ord[i]] - ata[ord[i-1]]) >
            EPS) {
            fin.PB(lines[ord[i]]);
        }
    }

    deque<Line> dq;
    for (int i=0; i<SZ(fin); i++) {
        while(SZ(dq) >= 2 and
            not isin(fin[i], dq[SZ(dq)-2], dq[SZ(dq)
                -1])) {
            dq.pop_back();
        }
        while(SZ(dq) >= 2 and
            not isin(fin[i], dq[0], dq[1])) {
            dq.pop_front();
        }
        dq.push_back(fin[i]);
    }

    while (SZ(dq) >= 3 and
        not isin(dq[0], dq[SZ(dq)-2], dq[SZ(dq)-1]))
    {
        dq.pop_back();
    }

    while (SZ(dq) >= 3 and
        not isin(dq[SZ(dq)-1], dq[0], dq[1])) {
        dq.pop_front();
    }
    vector<Line> res(ALL(dq));
    return res;
}

```

## 6.6 dao point

`typedef double Type;`

```

struct Point{
    Type x, y;
    Point(){};
    Point(Type _x, Type _y){
        x = _x, y = _y;
    }
    void read(){
        scanf("%lf %lf", &x, &y);
    }
    Point operator +(const Point & P2){
        return Point(x + P2.x, y + P2.y);
    }
    Point operator -(const Point & P2){
        return Point(x - P2.x, y - P2.y);
    }
    Point operator *(const Type & Len){
        return Point(x*Len, y*Len);
    }
    Type operator *(const Point & P2){
        return x*P2.x + y*P2.y;
    }
    Type operator ^(const Point & P2){
        return x*P2.y - y*P2.x;
    }
    Type dis(){
        return x*x+y*y;
    }
};

struct Line{
    Point s, e;
    Line(){};
    Line(Point _s, Point _e){
        s = _s, e = _e;
    }
    void read(){
        s.read(); e.read();
    }
};

```

## 6.7 dao inter

```

Point(Line l1, Line l2){
    Type v1 = (l1.s - l1.e) ^ (l2.s - l1.e);
    Type v2 = (l1.s - l1.e) ^ (l1.e - l2.e);
    Type v3 = (v1 + v2);
    return l2.s*(v2/v3) + l2.e*(v1/v3);
}

```

## 6.8 dao 2D convex hull

```

int ori(Point s, Point e, Point P){
    Type val = (s - e)^(P - e);
    if(fabs(val) < eps) return 0;
    else if(val > 0) return 1;
    else return -1;
}

vector<Point> convex_hull(vector<Point> pt){
    sort(pt.begin(), pt.end());
    int top=0;
    vector<Point> stk(2*pt.size());
    for (int i=0; i<(int)pt.size(); i++){
        while (top >= 2 && ori(stk[top-2], stk[top-1], pt[i])
            >= 0)
            top--;
        stk[top++] = pt[i];
    }
    for (int i=pt.size()-2, t=top+1; i>=0; i--){
        while (top >= t && ori(stk[top-2], stk[top-1], pt[i])
            >= 0)
            top--;
        stk[top++] = pt[i];
    }
    stk.resize(top-1);
    return stk;
}

```

## 6.9 Minimum Covering Circle

```

struct Mcc{
    // return pair of center and r^2
    static const int MAXN = 1000100;
    int n;
    pdd p[MAXN], cen;
    double r2;

    void init(int _n, pdd _p[]){
        n = _n;
        memcpy(p, _p, sizeof(pdd)*n);
    }
    double sqr(double a){ return a*a; }
    double abs2(pdd a){ return a*a; }
    pdd center(pdd p0, pdd p1, pdd p2) {
        pdd a = p1-p0;
        pdd b = p2-p0;
        double c1=abs2(a)*0.5;
        double c2=abs2(b)*0.5;
        double d = a % b;
        double x = p0.x + (c1 * b.y - c2 * a.y) / d;
        double y = p0.y + (a.x * c2 - b.x * c1) / d;
        return pdd(x,y);
    }

    pair<pdd, double> solve(){
        random_shuffle(p, p+n);
        r2=0;
        for (int i=0; i<n; i++){
            if (abs2(cen-p[i]) <= r2) continue;
            cen = p[i];
            r2 = 0;
            for (int j=0; j<i; j++){
                if (abs2(cen-p[j]) <= r2) continue;
                cen = 0.5 * (p[i]+p[j]);
                r2 = abs2(cen-p[j]);
                for (int k=0; k<j; k++){
                    if (abs2(cen-p[k]) <= r2) continue;
                    cen = center(p[i], p[j], p[k]);
                    r2 = abs2(cen-p[k]);
                }
            }
        }
        return {cen, r2};
    }
}mcc;

```

## 7 Stringology

### 7.1 Suffix Array

```

const int MAX = 1020304;
int ct[MAX], he[MAX], rk[MAX], sa[MAX], tsa[MAX], tp[
    MAX][2];

void suffix_array(char *ip){
    int len = strlen(ip);
    int alp = 256;

    memset(ct, 0, sizeof(ct));
    for(int i=0; i<len; i++) ct[ip[i]+1]++;
    for(int i=1; i<alp; i++) ct[i]+=ct[i-1];
    for(int i=0; i<len; i++) rk[i]=ct[ip[i]];

    for(int i=1; i<len; i*=2){
        for(int j=0; j<len; j++){
            if(j+i>len) tp[j][1]=0;
            else tp[j][1]=rk[j+i]+1;

            tp[j][0]=rk[j];
        }
        memset(ct, 0, sizeof(ct));
        for(int j=0; j<len; j++) ct[tp[j][1]+1]++;
        for(int j=1; j<len+2; j++) ct[j]+=ct[j-1];
        for(int j=0; j<len; j++) tsa[ct[tp[j][1]]]=j;

        memset(ct, 0, sizeof(ct));
        for(int j=0; j<len; j++) ct[tp[j][0]+1]++;
        for(int j=1; j<len+1; j++) ct[j]+=ct[j-1];
        for(int j=0; j<len; j++) sa[ct[tp[j][0]]]=tsa[
            j];
    }
}

```

```

rk[sa[0]]=0;
for(int j=1; j<len; j++){
    if( tp[sa[j]][0] == tp[sa[j-1]][0] &&
        tp[sa[j]][1] == tp[sa[j-1]][1] )
        rk[sa[j]] = rk[sa[j-1]];
    else
        rk[sa[j]] = j;
}

for(int i=0, h=0; i<len; i++){
    if(rk[i]==0) h=0;
    else{
        int j=sa[rk[i]-1];
        h=max(0, h-1);
        for(; ip[i+h]==ip[j+h]; h++);
    }
    he[rk[i]]=h;
}
}

```

### 7.2 KMP

```

#include<bits/stdc++.h>
using namespace std;

void build_fail_function(string B, int *fail) {
    int len = B.length(), pos;
    pos = fail[0] = -1;
    for (int i = 1; i < len; i++) {
        while (pos != -1 and B[pos + 1] != B[i])
            pos = fail[pos];
        if (B[pos + 1] == B[i]) pos++;
        fail[i] = pos;
    }
}

void match(string A, string B, int *fail) {
    int lenA = A.length(), lenB = B.length();
    int pos = -1;
    for (int i = 0; i < lenA; i++) {
        while (pos != -1 and B[pos + 1] != A[i])
            pos = fail[pos];

        if (B[pos + 1] == A[i]) pos++;

        if (pos == lenB - 1) {
            // Match ! A[i - lenB + 1, i] = B
            pos = fail[pos];
        }
    }
}

```

### 7.3 Z value

```

void Zval(const char *s, int len, int *z) {
    z[0] = 0;
    for (int b=0, i=1; i<len; i++) {
        z[i] = max(min(z[i-b], z[b] + b - i), 0);
        while (s[i + z[i]] == s[z[i]]) z[i]++;
        if (i+z[i] > b+z[b]) b=i;
    }
}

```

### 7.4 Lexicographically Smallest Rotation

```

string mcp(string s){
    int n = s.length();
    s += s;
    int i=0, j=1;
    while (i<n && j<n){
        int k = 0;
        while (k < n && s[i+k] == s[j+k]) k++;
        if (s[i+k] <= s[j+k]) j += k+1;
        else i += k+1;
        if (i == j) j++;
    }
    int ans = i < n ? i : j;
    return s.substr(ans, n);
}

```