from linearalgebra import vec

$$\begin{split} &icf_{i} = vec\left(c_{i}^{-1}\right) \\ &qq1_{i} = \left(icf_{i,1}, icf_{i,2}, icf_{i,3}\right) \\ &qq2_{i} = \left(icf_{i,5}, icf_{i,6}, icf_{i,9}\right) \\ &qlin_{i} = c_{i}^{-1}v_{i,*} \\ &v_out_{i} = \begin{bmatrix} qq1_{i}^{T} \\ \left(qq1_{i,2}, qq2_{i,1}, qq2_{i,2}\right)^{T} \\ \left(qq1_{i,3}, qq2_{i,2}, qq2_{i,3}\right)^{T} \end{bmatrix}^{-1} qlin_{i} \end{split}$$

where

$$v \in \mathbb{R}^{m \times 3}$$
 $f \in \mathbb{R}^{t \times 3}$
 $c_i \in \mathbb{R}^{3 \times 3}$
 $n \in \mathbb{Z}$