PIER PORTAL

A Thesis

presented to

the Faculty of California Polytechnic State University,

San Luis Obispo

In Partial Fulfillment

of the Requirements for the Degree

Master of Science in Mechanical Engineering

by

Alec W. Hardy

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ABSTRACT

Pier Portal

Alec W. Hardy

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ACKNOWLEDGMENTS

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Chapter 1

BACKGROUND

1.1 Provided Components

1.1.1 Winch System

Yaskawa Servo Motor

Table 1.1: TODO: Caption

Yaskawa AC Servo Motor					
Type	SGMGV-05A3A6E				
Voltage	200 V				
Power	$0.45~\mathrm{kW}$				
Torque (Continuous)	2.86 N*m				
Torque (Peak)	8.92 N*m				

BIBLIOGRAPHY

[1] Cal Poly Github. http://www.github.com/CalPoly.