

PIER PORTAL

A Thesis

presented to

the Faculty of California Polytechnic State University,

San Luis Obispo

In Partial Fulfillment

of the Requirements for the Degree

Master of Science in Mechanical Engineering

by

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## ABSTRACT

Pier Portal

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Your abstract goes in here

## ACKNOWLEDGMENTS

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## Chapter 1

### BACKGROUND

#### 1.1 Provided Components

##### 1.1.1 Winch System

Yaskawa Servo Motor

**Table 1.1: TODO: Caption**

Yaskawa AC Servo Motor	
Type	SGMGV-05A3A6E
Voltage	200 V
Power	0.45 kW
Torque (Continuous)	2.86 N*m
Torque (Peak)	8.92 N*m

## BIBLIOGRAPHY

- [1] Cal Poly Github. <http://www.github.com/CalPoly>.