

```

1  for all edges in E:
2      if connected to a dangerous node make weight 1
3      else make weight 0
4
5  pred[] // predecessor list per node
6  dist[] // min dist from s
7
8  for each vertex V:
9      dist[V] = inf
10     pred[V] = -1
11
12  Q = empty deque
13  enqueue(Q,s)
14  while Q is not empty:
15     v = dequeue(Q)
16     for each u adjacent to v:
17         if dist[u] > dist[v] + w(u,v):
18             dist[u] = dist[v] + w(u,v)
19             pred[u] = v
20             if w(u,v) == 0:
21                 push_front(Q, u)
22             else:
23                 push_back(Q, u)
24
25  return pred backwards from t to s

```