

## Water Level Monitoring Subsystem

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# Chapter 1

## Hierarchical Index

### 1.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

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## Chapter 2

# Class Index

### 2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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## Chapter 3

# File Index

### 3.1 File List

Here is a list of all documented files with brief descriptions:

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## Chapter 4

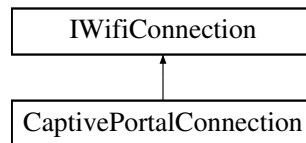
# Class Documentation

### 4.1 CaptivePortalConnection Class Reference

[CaptivePortalConnection](#) class. Connect to a free wifi with Captive Portal authentication.

```
#include <CaptivePortalConnection.h>
```

Inheritance diagram for CaptivePortalConnection:



#### Public Member Functions

- [CaptivePortalConnection](#) ()  
*Construct a new [CaptivePortalConnection](#) object.*
- [CaptivePortalConnection](#) (const char \*ssid, const char \*captivePortalDomain, const char \*query)  
*Construct a new [CaptivePortalConnection](#) object.*
- void [setup\\_wifi](#) () override  
*Initialize WiFi connection.*
- void [setSSID](#) (const char \*ssid) override  
*Set the SSID of the WiFi network.*
- const char \* [getSSID](#) () override  
*Get the SSID of the WiFi network.*
- void [setCaptive](#) (const char \*captivePortalDomain)  
*Set the captive portal domain.*
- const char \* [getCaptive](#) ()  
*Get the captive portal domain.*
- void [setQuery](#) (const char \*query)  
*Set the query for the radius server.*
- const char \* [getQuery](#) ()  
*Get the query for the radius server.*
- int [status](#) () override  
*Check connection status (a `WiFi.status()` wrapper).*

## Private Attributes

- const char \* **captivePortalDomain**
- const char \* **query**

## Additional Inherited Members

## Protected Attributes inherited from [IWifiConnection](#)

- const char \* **ssid**

### 4.1.1 Detailed Description

[CaptivePortalConnection](#) class. Connect to a free wifi with Captive Portal authentication.

### 4.1.2 Constructor & Destructor Documentation

#### 4.1.2.1 CaptivePortalConnection() [1/2]

```
CaptivePortalConnection::CaptivePortalConnection ( )
```

Construct a new [CaptivePortalConnection](#) object.

Default values for ssid, captivePortalDomain and query are used (see ../config.h).

#### 4.1.2.2 CaptivePortalConnection() [2/2]

```
CaptivePortalConnection::CaptivePortalConnection (
    const char * ssid,
    const char * captivePortalDomain,
    const char * query )
```

Construct a new [CaptivePortalConnection](#) object.

#### Parameters

<i>ssid</i>	WiFi network SSID.
<i>captivePortalDomain</i>	URL or IP of the radius server.
<i>query</i>	Usually a POST request.

### 4.1.3 Member Function Documentation

#### 4.1.3.1 getCaptive()

```
const char * CaptivePortalConnection::getCaptive ( )
```

Get the captive portal domain.

**Returns**

char\* captivePortalDomain: URL or IP of the radius server.

**4.1.3.2 getQuery()**

```
const char * CaptivePortalConnection::getQuery ( )
```

Get the query for the radius server.

**Returns**

char\* query: Usually a POST request.

**4.1.3.3 getSSID()**

```
const char * CaptivePortalConnection::getSSID ( ) [override], [virtual]
```

Get the SSID of the WiFi network.

**Returns**

char\* ssid: WiFi network SSID.

Implements [IWifiConnection](#).

**4.1.3.4 setCaptive()**

```
void CaptivePortalConnection::setCaptive (
    const char * captivePortalDomain )
```

Set the captive portal domain.

**Parameters**

<i>captivePortalDomain</i>	URL or IP of the radius server.
----------------------------	---------------------------------

**4.1.3.5 setQuery()**

```
void CaptivePortalConnection::setQuery (
    const char * query )
```

Set the query for the radius server.

**Parameters**

<i>query</i>	Usually a POST request.
--------------	-------------------------

#### 4.1.3.6 setSSID()

```
void CaptivePortalConnection::setSSID (
    const char * ssid ) [override], [virtual]
```

Set the SSID of the WiFi network.

##### Parameters

<i>ssid</i>	WiFi network SSID.
-------------	--------------------

Implements [IWifiConnection](#).

#### 4.1.3.7 setup\_wifi()

```
void CaptivePortalConnection::setup_wifi ( ) [override], [virtual]
```

Initialize WiFi connection.

Implements [IWifiConnection](#).

#### 4.1.3.8 status()

```
int CaptivePortalConnection::status ( ) [override], [virtual]
```

Check connection status (a WiFi.status() wrapper).

##### Returns

int status: WiFi network status.

Implements [IWifiConnection](#).

The documentation for this class was generated from the following files:

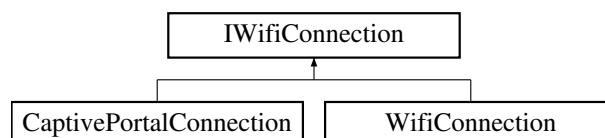
- src/utils/CaptivePortalConnection.h
- src/utils/CaptivePortalConnection.cpp

## 4.2 IWifiConnection Class Reference

Interface for WiFi connection.

```
#include <IWifiConnection.h>
```

Inheritance diagram for IWifiConnection:



### Public Member Functions

- virtual void [setup\\_wifi](#) ()=0
- virtual void [setSSID](#) (const char \*ssid)=0
- virtual const char \* [getSSID](#) ()=0
- virtual int [status](#) ()=0

### Protected Attributes

- const char \* **ssid**

## 4.2.1 Detailed Description

Interface for WiFi connection.

## 4.2.2 Member Function Documentation

### 4.2.2.1 getSSID()

```
virtual const char * IWiFiConnection::getSSID ( ) [pure virtual]
```

Implemented in [CaptivePortalConnection](#), and [WifiConnection](#).

### 4.2.2.2 setSSID()

```
virtual void IWiFiConnection::setSSID (
    const char * ssid ) [pure virtual]
```

Implemented in [CaptivePortalConnection](#), and [WifiConnection](#).

### 4.2.2.3 setup\_wifi()

```
virtual void IWiFiConnection::setup_wifi ( ) [pure virtual]
```

Implemented in [CaptivePortalConnection](#), and [WifiConnection](#).

### 4.2.2.4 status()

```
virtual int IWiFiConnection::status ( ) [pure virtual]
```

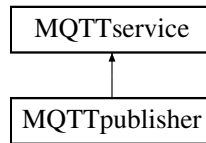
Implemented in [CaptivePortalConnection](#), and [WifiConnection](#).

The documentation for this class was generated from the following file:

- [src/utls/IWiFiConnection.h](#)

## 4.3 MQTTpublisher Class Reference

Inheritance diagram for MQTTpublisher:



### Public Member Functions

- [MQTTPublisher](#) (const char \*server, const char \*client\_id, const char \*topic)  
*Construct a new [MQTTPublisher](#) object.*
- [MQTTPublisher](#) (const char \*server, const char \*client\_id)  
*Construct a new [MQTTPublisher](#) object.*
- void [publish](#) (const char \*topic, const char \*payload)  
*Publish a message to a topic (a PubSubClient::publish wrapper).*
- void [publish](#) (const char \*payload)  
*Publish a message to the default topic (a PubSubClient::publish wrapper).*
- void [publishJSON](#) (const char \*topic, const char \*JSONfield, const char \*JSONvalue)  
*Publish a JSON message to a topic.*

### Public Member Functions inherited from [MQTTservice](#)

- [MQTTservice](#) (const char \*server, const char \*client\_id, const char \*topic)  
*Construct a new [MQTTservice](#) object.*
- [MQTTservice](#) (const char \*server, const char \*client\_id)  
*Construct a new [MQTTservice](#) object.*
- void **connect** ()  
*Connect to MQTT broker.*
- void **loop** ()  
*Loop function (a PubSubClient::loop wrapper).*
- bool [connected](#) ()  
*Check if the client is connected to the MQTT broker (a PubSubClient::connected wrapper).*

### Additional Inherited Members

### Protected Attributes inherited from [MQTTservice](#)

- const char \* **mqtt\_server**
- const char \* **mqtt\_client\_id**
- const char \* **mqtt\_topic**
- WiFiClient **espClient**
- PubSubClient **mqttClient**



## 4.3.1 Constructor & Destructor Documentation

### 4.3.1.1 MQTTpublisher() [1/2]

```
MQTTPublisher::MQTTPublisher (  
    const char * server,  
    const char * client_id,  
    const char * topic ) [inline]
```

Construct a new [MQTTPublisher](#) object.

## Parameters

<i>server</i>	The MQTT broker server.
<i>client↔ _id</i>	The MQTT client ID.
<i>topic</i>	The MQTT topic.

**4.3.1.2 MQTTpublisher() [2/2]**

```
MQTTPublisher::MQTTPublisher (
    const char * server,
    const char * client_id ) [inline]
```

Construct a new [MQTTPublisher](#) object.

## Parameters

<i>server</i>	The MQTT broker server.
<i>client↔ _id</i>	The MQTT client ID.

**4.3.2 Member Function Documentation****4.3.2.1 publish() [1/2]**

```
void MQTTPublisher::publish (
    const char * payload )
```

Publish a message to the default topic (a PubSubClient::publish wrapper).

## Parameters

<i>payload</i>	The payload to publish.
----------------	-------------------------

**4.3.2.2 publish() [2/2]**

```
void MQTTPublisher::publish (
    const char * topic,
    const char * payload )
```

Publish a message to a topic (a PubSubClient::publish wrapper).

## Parameters

<i>topic</i>	The topic to publish to.
<i>payload</i>	The payload to publish.

## 4.3.2.3 publishJSON()

```
void MQTTpublisher::publishJSON (
    const char * topic,
    const char * JSONfield,
    const char * JSONvalue )
```

Publish a JSON message to a topic.

## Parameters

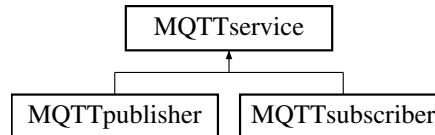
<i>topic</i>	The topic to publish to.
<i>JSONfield</i>	The field of the JSON message.
<i>JSONvalue</i>	The value of the JSON message.

The documentation for this class was generated from the following files:

- src/api/MQTTpublisher.h
- src/impl/MQTTpublisher.cpp

## 4.4 MQTTservice Class Reference

Inheritance diagram for MQTTservice:



## Public Member Functions

- [MQTTservice](#) (const char \*server, const char \*client\_id, const char \*topic)  
*Construct a new [MQTTservice](#) object.*
- [MQTTservice](#) (const char \*server, const char \*client\_id)  
*Construct a new [MQTTservice](#) object.*
- void **connect** ()  
*Connect to MQTT broker.*
- void **loop** ()  
*Loop function (a PubSubClient::loop wrapper).*
- bool [connected](#) ()  
*Check if the client is connected to the MQTT broker (a PubSubClient::connected wrapper).*

## Protected Attributes

- const char \* **mqtt\_server**
- const char \* **mqtt\_client\_id**
- const char \* **mqtt\_topic**
- WiFiClient **espClient**
- PubSubClient **mqttClient**

## 4.4.1 Constructor & Destructor Documentation

### 4.4.1.1 MQTTservice() [1/2]

```
MQTTservice::MQTTservice (
    const char * server,
    const char * client_id,
    const char * topic ) [inline]
```

Construct a new [MQTTservice](#) object.

#### Parameters

<i>server</i>	The MQTT broker server.
<i>client_id</i>	The MQTT client ID.
<i>topic</i>	The MQTT topic.

### 4.4.1.2 MQTTservice() [2/2]

```
MQTTservice::MQTTservice (
    const char * server,
    const char * client_id ) [inline]
```

Construct a new [MQTTservice](#) object.

#### Parameters

<i>server</i>	The MQTT broker server.
<i>client_id</i>	The MQTT client ID.

## 4.4.2 Member Function Documentation

### 4.4.2.1 connected()

```
bool MQTTservice::connected ( )
```

Check if the client is connected to the MQTT broker (a PubSubClient::connected wrapper).

#### Returns

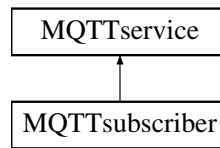
true if connected, false otherwise.

The documentation for this class was generated from the following files:

- src/api/MQTTservice.h
- src/impl/MQTTservice.cpp

## 4.5 MQTTsubscriber Class Reference

Inheritance diagram for MQTTsubscriber:



### Public Member Functions

- [MQTTsubscriber](#) (const char \*server, const char \*client\_id)  
*Construct a new [MQTTsubscriber](#) object.*
- void [subscribe](#) (const char \*topic)  
*Subscribe to a topic.*
- void [callback](#) (char \*topic, byte \*payload, unsigned int length)  
*Callback function for MQTT messages (see [PubSubClient::callback](#)).*
- void [subscribeJSON](#) (const char \*topic)  
*Subscribe to a topic and parse the payload as JSON (a [PubSubClient::subscribe](#) wrapper).*
- void [callbackJSON](#) (char \*topic, byte \*payload, unsigned int length)  
*Callback function for MQTT messages (see [PubSubClient::callback](#)).*
- void [setSavedPayload](#) (byte \*payload)  
*Set the local payload.*
- byte \* [getSavedPayload](#) ()  
*Get the local payload.*
- void [setSavedPayload](#) (int payload)  
*Set the local int payload.*
- int [getSavedPayloadInt](#) ()  
*Get the local int payload.*

### Public Member Functions inherited from [MQTTservice](#)

- [MQTTservice](#) (const char \*server, const char \*client\_id, const char \*topic)  
*Construct a new [MQTTservice](#) object.*
- [MQTTservice](#) (const char \*server, const char \*client\_id)  
*Construct a new [MQTTservice](#) object.*
- void [connect](#) ()  
*Connect to MQTT broker.*
- void [loop](#) ()  
*Loop function (a [PubSubClient::loop](#) wrapper).*
- bool [connected](#) ()  
*Check if the client is connected to the MQTT broker (a [PubSubClient::connected](#) wrapper).*

### Private Attributes

- byte \* [saved\\_payload](#)
- int [saved\\_payload\\_int](#)

## Additional Inherited Members

### Protected Attributes inherited from [MQTTservice](#)

- const char \* **mqtt\_server**
- const char \* **mqtt\_client\_id**
- const char \* **mqtt\_topic**
- WiFiClient **espClient**
- PubSubClient **mqttClient**

## 4.5.1 Constructor & Destructor Documentation

### 4.5.1.1 MQTTsubscriber()

```
MQTTsubscriber::MQTTsubscriber (
    const char * server,
    const char * client_id ) [inline]
```

Construct a new [MQTTsubscriber](#) object.

#### Parameters

<i>server</i>	The MQTT broker server.
<i>client_id</i>	The MQTT client ID.

## 4.5.2 Member Function Documentation

### 4.5.2.1 callback()

```
void MQTTsubscriber::callback (
    char * topic,
    byte * payload,
    unsigned int length )
```

Callback function for MQTT messages (see PubSubClient::callback).

#### Parameters

<i>topic</i>	The topic of the message.
<i>payload</i>	The payload of the message.
<i>length</i>	The length of the payload.

### 4.5.2.2 callbackJSON()

```
void MQTTsubscriber::callbackJSON (
    char * topic,
```

```
byte * payload,  
unsigned int length )
```

Callback function for MQTT messages (see PubSubClient::callback).

#### Parameters

<i>topic</i>	The topic of the message.
<i>payload</i>	The payload of the message.
<i>length</i>	The length of the payload.

#### 4.5.2.3 getSavedPayload()

```
byte * MQTTsubscriber::getSavedPayload ( )
```

Get the local payload.

#### Returns

byte\* : The local payload.

#### 4.5.2.4 getSavedPayloadInt()

```
int MQTTsubscriber::getSavedPayloadInt ( )
```

Get the local int payload.

#### Returns

int : The local int payload.

#### 4.5.2.5 setSavedPayload() [1/2]

```
void MQTTsubscriber::setSavedPayload (   
    byte * payload )
```

Set the local payload.

#### Parameters

<i>payload</i>	The payload to save.
----------------	----------------------

#### 4.5.2.6 setSavedPayload() [2/2]

```
void MQTTsubscriber::setSavedPayload (   
    int payload )
```

Set the local int payload.

#### Parameters

<i>payload</i>	The payload to save.
----------------	----------------------

#### 4.5.2.7 subscribe()

```
void MQTTsubscriber::subscribe (
    const char * topic )
```

Subscribe to a topic.

#### Parameters

<i>topic</i>	The topic to subscribe to.
--------------	----------------------------

#### 4.5.2.8 subscribeJSON()

```
void MQTTsubscriber::subscribeJSON (
    const char * topic )
```

Subscribe to a topic and parse the payload as JSON (a PubSubClient::subscribe wrapper).

#### Parameters

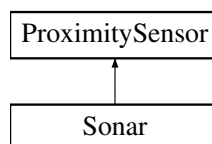
<i>topic</i>	The topic to subscribe to.
--------------	----------------------------

The documentation for this class was generated from the following files:

- src/api/MQTTsubscriber.h
- src/impl/MQTTsubscriber.cpp

## 4.6 ProximitySensor Class Reference

Inheritance diagram for ProximitySensor:





### Public Member Functions

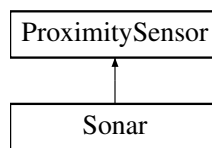
- virtual float **getDistance** ()=0

The documentation for this class was generated from the following file:

- src/api/ProximitySensor.h

## 4.7 Sonar Class Reference

Inheritance diagram for Sonar:



### Public Member Functions

- **Sonar** (int echoPin, int trigPin, long maxTime)
- float **getDistance** ()
- void **setTemperature** (float temp)

### Private Member Functions

- float **getSoundSpeed** ()

### Private Attributes

- const float **vs** = 331.5 + 0.6\*20
- float **temperature**
- int **echoPin**
- int **trigPin**
- long **timeOut**

### 4.7.1 Member Function Documentation

#### 4.7.1.1 getDistance()

```
float Sonar::getDistance ( ) [virtual]
```

Implements [ProximitySensor](#).

The documentation for this class was generated from the following files:

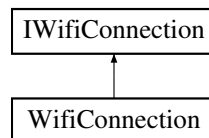
- src/api/Sonar.h
- src/impl/Sonar.cpp

## 4.8 WifiConnection Class Reference

[WifiConnection](#) class Connect to a wifi network, with or without password.

```
#include <WifiConnection.h>
```

Inheritance diagram for WifiConnection:



### Public Member Functions

- [WifiConnection](#) ()  
*Construct a new [WifiConnection](#) object.*
- [WifiConnection](#) (const char \*ssid)  
*Construct a new [WifiConnection](#) object.*
- [WifiConnection](#) (const char \*ssid, const char \*password)  
*Construct a new [WifiConnection](#) object.*
- void [setup\\_wifi](#) () override  
*Initialize WiFi connection.*
- void [setSSID](#) (const char \*ssid) override  
*Set the SSID object.*
- const char \* [getSSID](#) () override  
*Get the SSID object.*
- void [setPassword](#) (const char \*password)  
*Set the Password object.*
- int [status](#) () override  
*Check connection status (a `WiFi.status()` wrapper).*

### Private Attributes

- const char \* **password**

### Additional Inherited Members

### Protected Attributes inherited from [IWifiConnection](#)

- const char \* **ssid**

## 4.8.1 Detailed Description

[WifiConnection](#) class Connect to a wifi network, with or without password.

## 4.8.2 Constructor & Destructor Documentation

### 4.8.2.1 WifiConnection() [1/3]

```
WifiConnection::WifiConnection ( )
```

Construct a new [WifiConnection](#) object.

Default values for ssid are used (see ../config.h)

### 4.8.2.2 WifiConnection() [2/3]

```
WifiConnection::WifiConnection (
    const char * ssid )
```

Construct a new [WifiConnection](#) object.

#### Parameters

<i>ssid</i>	WiFi network SSID
-------------	-------------------

### 4.8.2.3 WifiConnection() [3/3]

```
WifiConnection::WifiConnection (
    const char * ssid,
    const char * password )
```

Construct a new [WifiConnection](#) object.

#### Parameters

<i>ssid</i>	WiFi network SSID
<i>password</i>	WiFi network password

## 4.8.3 Member Function Documentation

### 4.8.3.1 getSSID()

```
const char * WifiConnection::getSSID ( ) [override], [virtual]
```

Get the SSID object.

#### Returns

char\* ssid: WiFi network SSID.

Implements [IWifiConnection](#).

#### 4.8.3.2 setPassword()

```
void WifiConnection::setPassword (
    const char * password )
```

Set the Password object.

##### Parameters

<i>password</i>	WiFi network password.
-----------------	------------------------

#### 4.8.3.3 setSSID()

```
void WifiConnection::setSSID (
    const char * ssid ) [override], [virtual]
```

Set the SSID object.

##### Parameters

<i>ssid</i>	WiFi network SSID.
-------------	--------------------

Implements [IWifiConnection](#).

#### 4.8.3.4 setup\_wifi()

```
void WifiConnection::setup_wifi ( ) [override], [virtual]
```

Initialize WiFi connection.

Implements [IWifiConnection](#).

#### 4.8.3.5 status()

```
int WifiConnection::status ( ) [override], [virtual]
```

Check connection status (a WiFi.status() wrapper).

##### Returns

int status: WiFi network status.

Implements [IWifiConnection](#).

The documentation for this class was generated from the following files:

- src/Utils/WifiConnection.h
- src/Utils/WifiConnection.cpp

# Chapter 5

## File Documentation

### 5.1 MQTTpublisher.h

```
00001 #include "MQTTservice.h"
00002
00003 class MQTTpublisher : public MQTTservice
00004 {
00005 public:
00006
00013     MQTTpublisher(const char *server, const char *client_id, const char *topic)
00014         : MQTTservice(server, client_id, topic) {}
00015
00021     MQTTpublisher(const char *server, const char *client_id)
00022         : MQTTservice(server, client_id) {}
00023
00029     void publish(const char *topic, const char *payload);
00030
00035     void publish(const char *payload);
00036
00043     void publishJSON(const char *topic, const char *JSONfield, const char *JSONvalue);
00044 };
```

### 5.2 MQTTservice.h

```
00001 #ifndef MQTT_SERVICE_H
00002 #define MQTT_SERVICE_H
00003
00004 #include <PubSubClient.h>
00005 #include <WiFiClient.h>
00006
00007 class MQTTservice
00008 {
00009 protected:
00010     const char *mqtt_server;
00011     const char *mqtt_client_id;
00012     const char *mqtt_topic;
00013
00014     WiFiClient espClient;
00015     PubSubClient mqttClient;
00016
00017 public:
00018
00025     MQTTservice(const char *server, const char *client_id, const char *topic)
00026         : mqtt_server(server), mqtt_client_id(client_id), mqtt_topic(topic), mqttClient(espClient) {}
00027
00033     MQTTservice(const char *server, const char *client_id)
00034         : mqtt_server(server), mqtt_client_id(client_id), mqttClient(espClient) {}
00035
00039     void connect();
00040
00044     void loop();
00045
00050     bool connected();
00051 };
00052
00053 #endif // MQTT_SERVICE_H
```

## 5.3 MQTTsubscriber.h

```

00001 #include "MQTTservice.h"
00002
00003 class MQTTsubscriber : public MQTTservice
00004 {
00005 public:
00006
00012     MQTTsubscriber(const char *server, const char *client_id)
00013         : MQTTservice(server, client_id) {}
00014
00019     void subscribe(const char *topic);
00020
00027     void callback(char *topic, byte *payload, unsigned int length);
00028
00033     void subscribeJSON(const char *topic);
00034
00041     void callbackJSON(char *topic, byte *payload, unsigned int length);
00042
00047     void setSavedPayload(byte *payload);
00048
00053     byte *getSavedPayload();
00054
00059     void setSavedPayload(int payload);
00060
00065     int getSavedPayloadInt();
00066
00067 private:
00068     byte *saved_payload;
00069     int saved_payload_int;
00070 };

```

## 5.4 ProximitySensor.h

```

00001 #ifndef __PROXIMITYSENSOR__
00002 #define __PROXIMITYSENSOR__
00003
00004 class ProximitySensor {
00005
00006 public:
00007     virtual float getDistance() = 0;
00008
00009 };
00010
00011 #endif

```

## 5.5 Sonar.h

```

00001 #ifndef __SONAR__
00002 #define __SONAR__
00003
00004 #include "ProximitySensor.h"
00005
00006 #define NO_OBJ_DETECTED -1
00007
00008 class Sonar: public ProximitySensor {
00009
00010 public:
00011     Sonar(int echoPin, int trigPin, long maxTime);
00012     float getDistance();
00013     void setTemperature(float temp);
00014
00015 private:
00016     const float vs = 331.5 + 0.6*20;
00017     float getSoundSpeed();
00018
00019     float temperature;
00020     int echoPin, trigPin;
00021     long timeOut;
00022 };
00023
00024 #endif

```

## 5.6 config.h

```

00001 #ifndef CONFIG_H

```

```

00002 #define CONFIG_H
00003
00004 /* LEDs PINs */
00005 #define GREEN_LED 19
00006 #define RED_LED 21
00007
00008 /* sonar sensor info */
00009 #define ECHO_PIN 5
00010 #define TRIG_PIN 18
00011 #define SONAR_TIMER 10000
00012
00013 /* mqtt buffers dimensions*/
00014 #define FREQ_MSG_SIZE 16
00015 #define SONAR_MSG_SIZE 16
00016 // #define __CAPTIVE_PORTAL /* Comment this line to use a regular WiFi network */
00017
00018 extern const char *captive_ssid;
00019 extern const char *captive_PortalDomain;
00020 extern const char *captive_query;
00021
00022
00023 extern const char *ssid;
00024 extern const char *password;
00025
00026 /* MQTT server address */
00027 extern const char *default_mqtt_server; /* MQTT server IP address/hostname */
00028
00029 /* MQTT topics */
00030 extern const char *freq_topic;
00031 extern const char *wl_topic;
00032
00033 /* JSON fields */
00034 extern const char *frequency_field;
00035 extern const char *water_level_field;
00036
00037 #endif /* CONFIG_H */

```

## 5.7 CaptivePortalConnection.h

```

00001 // CaptivePortalConnection.h
00002 #ifndef CAPTIVE_PORTAL_CONNECTION_H
00003 #define CAPTIVE_PORTAL_CONNECTION_H
00004
00005 #include "IWifiConnection.h"
00006
00011 class CaptivePortalConnection : public IWifiConnection
00012 {
00013 public:
00021     CaptivePortalConnection();
00022
00023     ~CaptivePortalConnection() = default;
00024
00033     CaptivePortalConnection(const char *ssid, const char *captivePortalDomain, const char *query);
00034
00039     void setup_wifi() override;
00040
00046     void setSSID(const char *ssid) override;
00047
00052     const char *getSSID() override;
00053
00060     void setCaptive(const char *captivePortalDomain);
00061
00066     const char *getCaptive();
00067
00073     void setQuery(const char *query);
00074
00079     const char *getQuery();
00080
00085     int status() override;
00086
00087 private:
00088     const char *captivePortalDomain;
00089     const char *query;
00090 };
00091
00092 #endif // CAPTIVE_PORTAL_CONNECTION_H

```

## 5.8 IWifiConnection.h

```

00001 // IWifiConnection.h

```

```
00002 #ifndef IWIFI_CONNECTION_H
00003 #define IWIFI_CONNECTION_H
00004
00009 class IWifiConnection
00010 {
00011 public:
00012     virtual ~IWifiConnection() = default;
00013     virtual void setup_wifi() = 0;
00014     virtual void setSSID(const char *ssid) = 0;
00015     virtual const char *getSSID() = 0;
00016     virtual int status() = 0;
00017
00018 protected:
00019     const char *ssid;
00020 };
00021
00022 #endif // IWIFI_CONNECTION_H
```

## 5.9 WifiConnection.h

```
00001 // WifiConnection.h
00002 #ifndef WIFI_CONNECTION_H
00003 #define WIFI_CONNECTION_H
00004
00005 #include "IWifiConnection.h"
00006
00011 class WifiConnection : public IWifiConnection
00012 {
00013 public:
00014
00022     WifiConnection();
00023
00028     WifiConnection(const char *ssid);
00029
00035     WifiConnection(const char *ssid, const char *password);
00036     ~WifiConnection() = default;
00037
00042     void setup_wifi() override;
00043
00048     void setSSID(const char *ssid) override;
00049
00054     const char *getSSID() override;
00055
00060     void setPassword(const char *password);
00061
00066     int status() override;
00067
00068 private:
00069     const char *password;
00070 };
00071
00072 #endif // WIFI_CONNECTION_H
```



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