

# Preparation for the Workshop

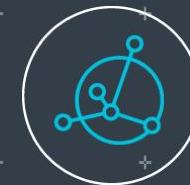
<https://github.com/alegeno92/docker-workshop/>

- Go to “Requirements”
- Follow instructions in prep for the workshop:
  - Important: Need Xcode for Mac

arm

AIoT Dev Summit

Innovate. Learn. Experience.



# Containers in an IoT World

How Docker Can Make It Easier to Deploy Your  
Application on an Edge Device / Maurizio Caporali, Alessandro  
Genovese and Jenny Fong

arm #ArmDevSummit

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# Speakers



Alessandro Genovese  
IoT and UDOO  
Software Engineer  
SECO



Maurizio Caporali  
IoT and UDOO Product  
Manager  
SECO



Jenny Fong  
Sr. Director Product  
Marketing  
DOCKER



# Introduction to Docker for Embedded Developers

Jenny Fong

# Developers Love Docker!



1st

Most Wanted  
Platform



2nd

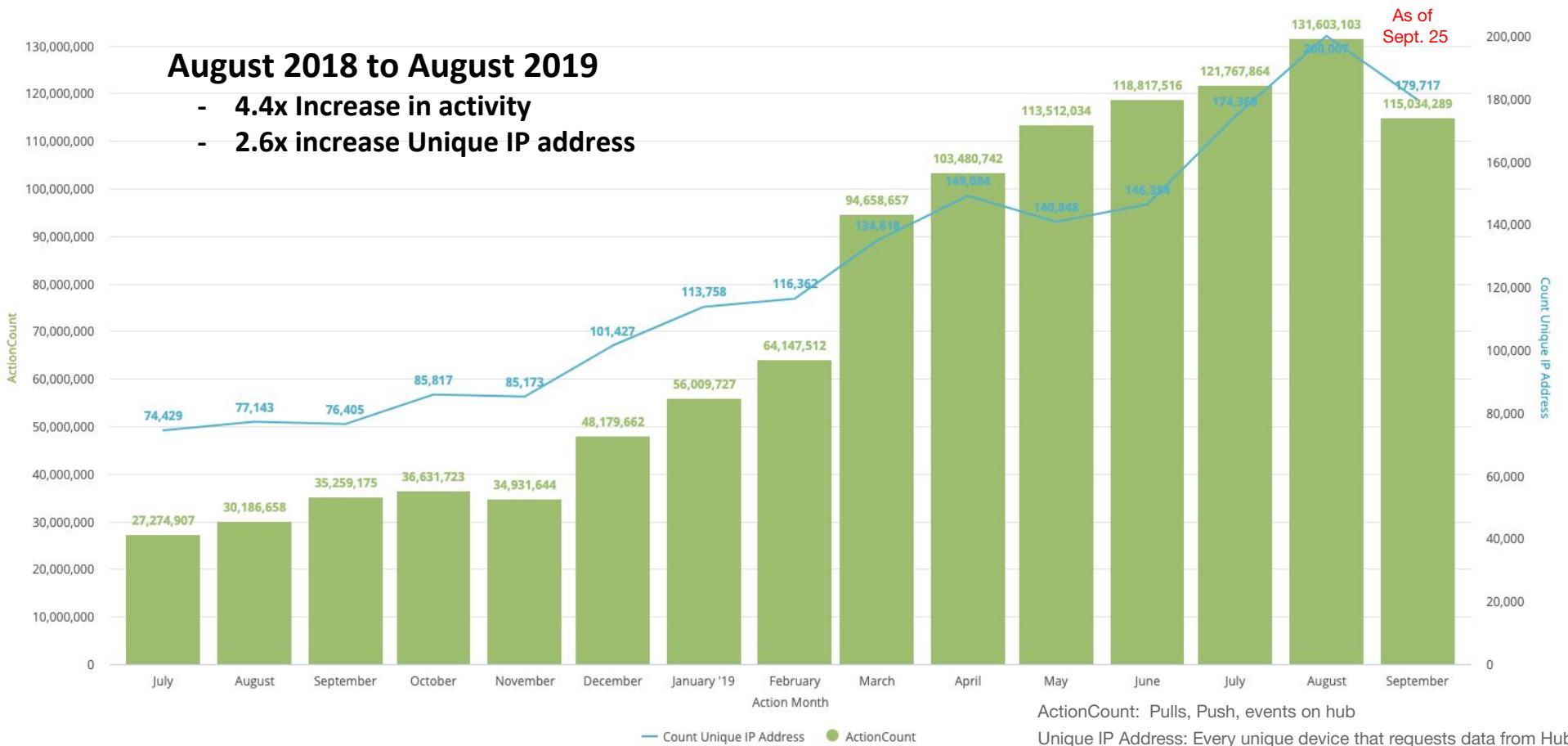
Most Loved  
Platform



3rd

Most Used  
Platform

# Docker Hub Activity and IP address Count - last 15 months



# Alternatives for embedded software development

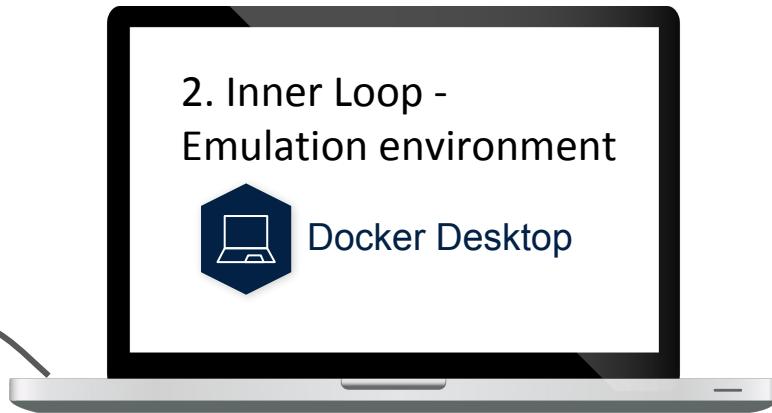
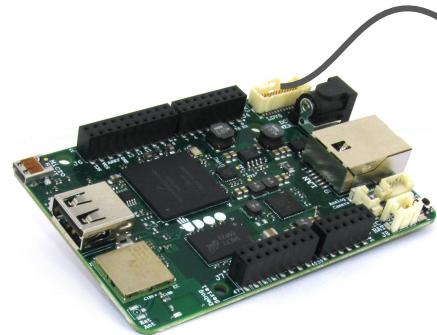
Docker improves on cross-compilation and target compilation

	Cross-compile	Target Build	Docker
Complexity	 Different environment leads to more porting errors	 Same environment	 Consistent environment
At scale deployment	 Medium, must reconfigure each target environment	 Slow	 Simple, must setup docker on each target
Build time	 Quickest, host PC speeds	 Very slow, must reconfigure environment and app on each device	 OK: Host PC with QEMU Good: Using remote Arm build farm

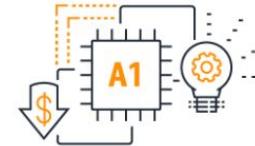
# Docker's Edge/IoT Developer Platform

Embedded developers become cloud-native in minutes!

1. Embedded developer loop



3. Native build on remote server



4. CI/CD pipeline



Docker  
Trusted Registry

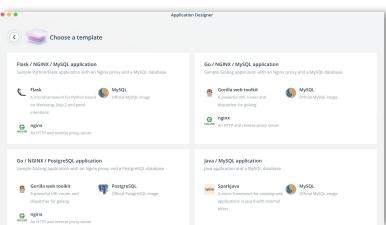
# Docker Enterprise Platform for Secure Edge Development

## Key Features

### Application Templates

Start new projects quickly, with all the required Docker configuration files

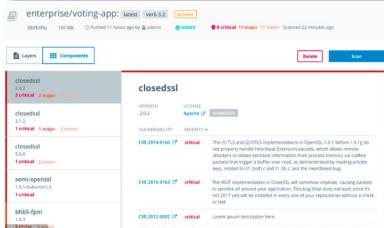
- SecOps builds templates for your Dev teams
- GUI and CLI



### Image Scanning & Signing

Know what's inside your containers, track provenance

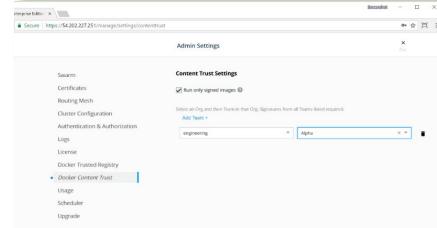
- Binary-level scans against NIST CVEs
- Add digital signatures to approve content



### Secure Engine Runtime

Run only trusted content at the edge

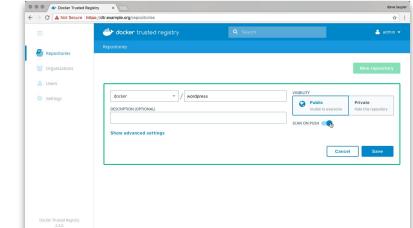
- Prevent unsigned images from being deployed
- Leverage hardware-based security



### Automated Pipelines

Rapidly deliver new applications to devices

- Secure collaboration through Docker Trusted Registry and Docker Hub
- Webhooks integrate with your chosen IDE and CI tools



# Introducing PARSEC

## Platform Abstraction for SECurity

Microservice abstracts hardware security

Surfaces a modern, simple,  
multi-language friendly, Open Source API  
that is common to IoT endpoints

Multiple back-ends: use the best  
capabilities of a given platform

Developing collaboratively and in the  
open



Secure  
element

TEE



# Problem statement and workshop flow – Docker/SECO

Maurizio Caporali & Jenny Fong

# Problem Statement

Developing complex embedded applications for a PoC  
or a project in a few days.

# Project

Our project is:

- Application: People Counter device to control the passage of people in a shopping center, with the possibility of accessing the real time counter and sending the data to the cloud.
- Hardware: Arm SBC based on NXP 1GHz ARM® Cortex-A9 with 1GB of RAM with Yocto OS.

# What do we need?

## **Base Applications:**

Python + Libraries

OpenCV

C++ Compilers

CMake

Paho MQTT Client Libraries

Redis (maybe)

Mosquitto MQTT Broker

## **Specific Applications:**

People Counter

Cloud Connector

Telemetry Agent

Restful Server + Dashboard

# Standard Approach

Activities and Timing estimation for the project using a standard approach:

- Compiling the Base Applications on the Arm SBC with Yocto OS - **TIME: 5 Days**
- Developing or porting the Specific Applications - **TIME: 2 Days**
- Write Yocto recipes - **TIME: 4 Days**
- Tests - **TIME: 1 Days**

# The Workshop Flow

## What we're going to do:

- Take a hands on approach with the UDOO hardware Kit
- Define the Docker Container structure for the project (Docker Approach)
- Startup the Arm board and test the Docker Engine runs
- Build Containers from scratch
- Connect many Docker containers together using Docker Compose tool
- Deploy on UDOO NEO (Linux Ubuntu)
- Deploy on an Industrial IoT Gateway with EDGEHOG OS (Yocto based): Seco SBC-C23, Seco SBC-C61



# Intro to UDOO – SECO boards

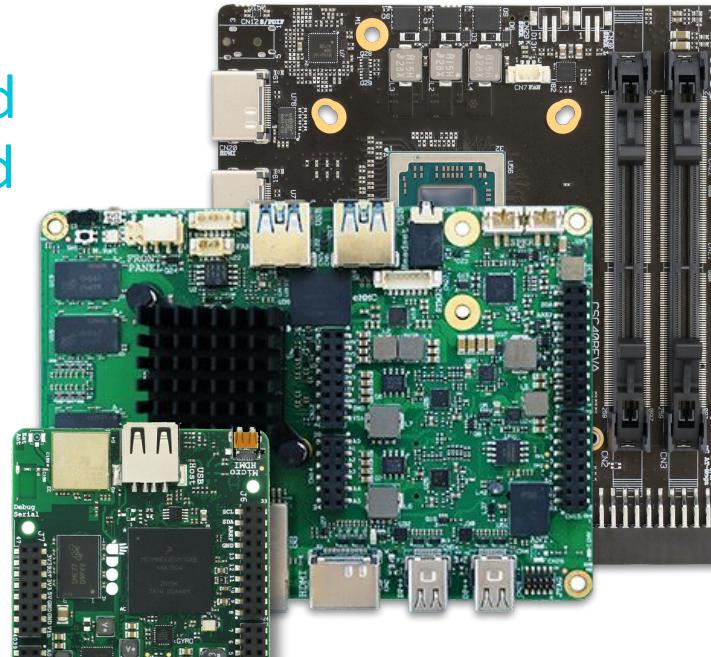
Maurizio Caporali

# UDOO

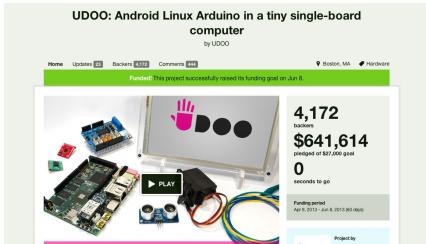
## What is UDOO?

UDOO is a family of open source embedded boards that merges physical computing and programming.

- UDOO is a co-founded project by SECO, embedded manufacturer, and AIDILAB, interaction design firm.
- Four Kickstarter Campaigns raising 2.3M+ with 13k+ backers, and 150k+ boards sold from 2014



1st Board Launched on  
Kickstarter:  
**UDOO QUAD/DUAL**



The start of the hottest  
events in tech



2013/2014

Raised \$1 Million on Kickstarter



2nd Board Launched on  
Kickstarter:  
**UDOO NEO**



2015

Further product range  
expansion: **BRICKS**



3rd Board launched on Kickstarter:  
**UDOO X86**



4,245 backers pledged \$800,211 to help  
bring this project to life.

2016

4th Board launched on  
Kickstarter:  
**UDOO BOLT**



1,447 backers pledged \$635,769 to  
help bring this project to life.

2018

# UDOO

## The UDOO Community

150k+ UDOO Boards sold all around the world.

- UDOO Boards are considered one of the best professional hacking SBC.
- Google, Amazon, IBM, engineers use the UDOO boards.



Updated daily  
37k+ likes



Updated daily  
1800+ followers



Updated daily  
4.7k+ followers



Updated daily  
500+ members



1.6M+ visualizations  
7.3k+ registered users

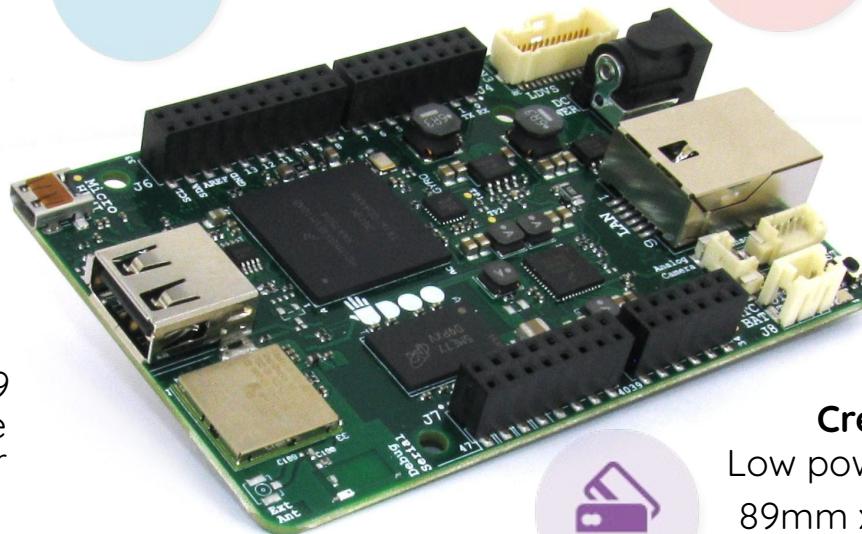


28k+ total posts  
12.2k+ members

# UDOO

## The UDOO NEO

**Powerful** 1GHz Cortex-A9  
+M4 I/O realtime  
co-processor



**Born to be wireless**

Wi-Fi 802.11 b/g/n

Bluetooth 4.0 BLE



4.0



**9 Axis sensors**

Accelerometer

Gyroscope

Magnetometer



**Credit-card sized**

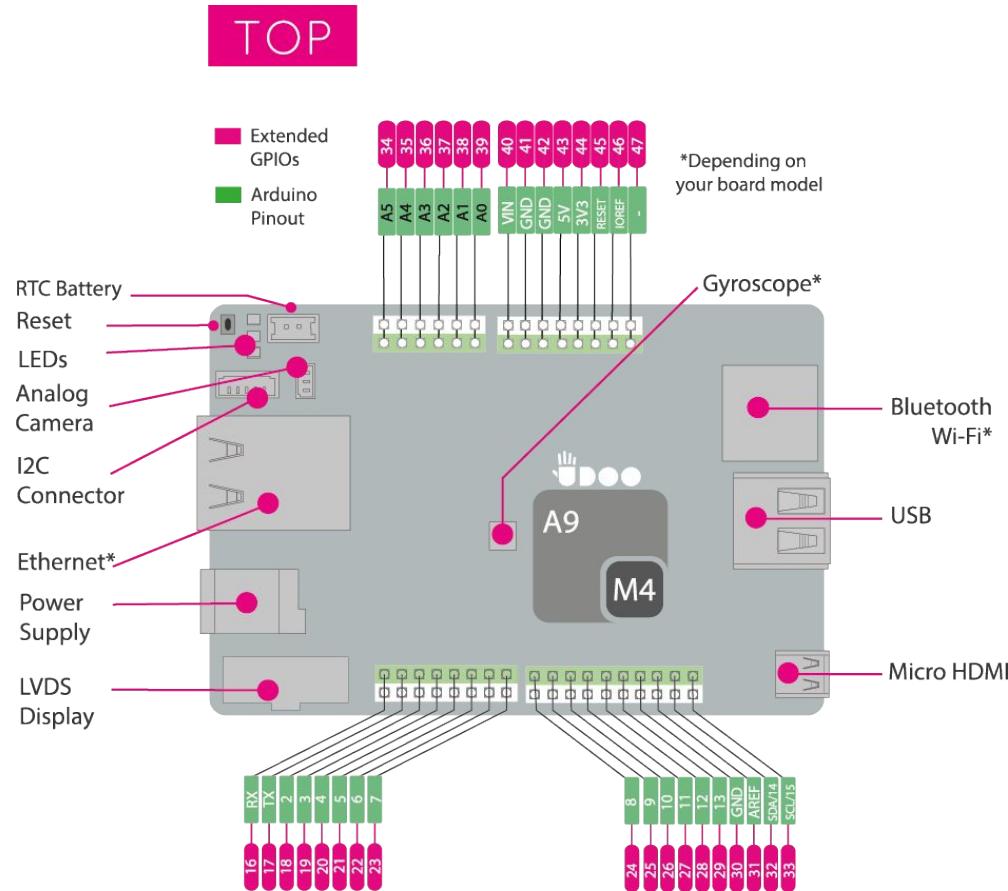
Low power consumption board

89mm x 59mm (3.50" x 2.32")



# UDOO

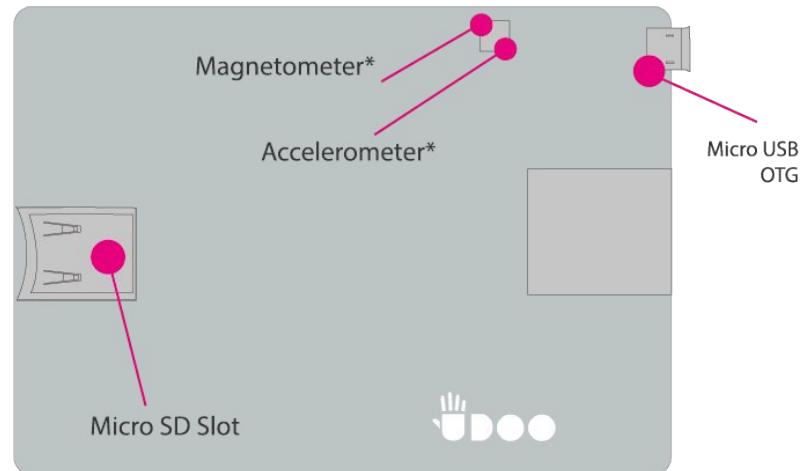
## The UDOO NEO



# UDOO

## The UDOO NEO

BOTTOM





# Hands-on – SECO

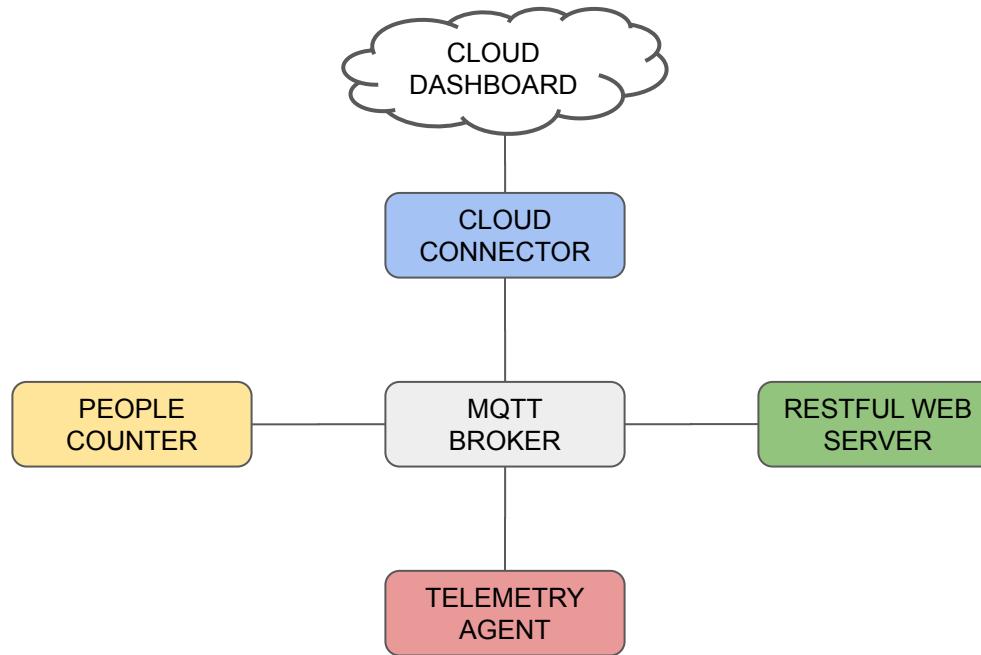
Alessandro Genovese

# Workshop Flow

What are we going to do:

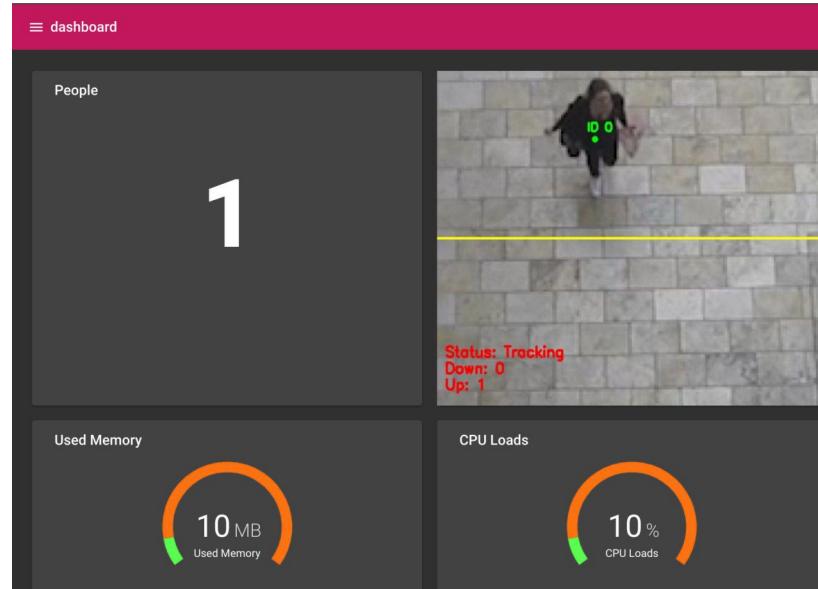
- **Define the Docker Container structure for the project (Docker Approach)**
- Test Docker Engine runs on the Laptop
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# The Docker Container Approach



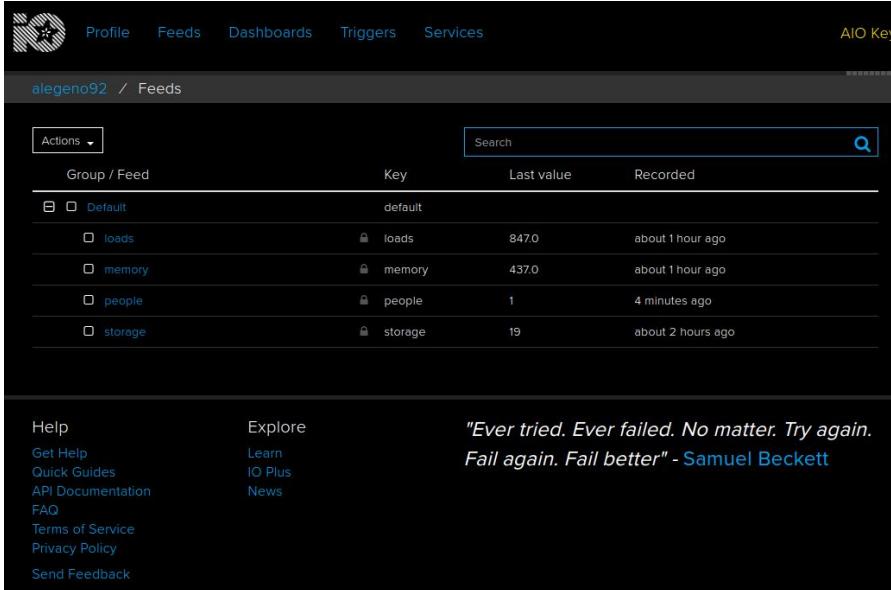
# What we are going to implement

## Restful Server - Dashboard



# What we are going to implement

## Adafruit IO - Cloud Dashboard



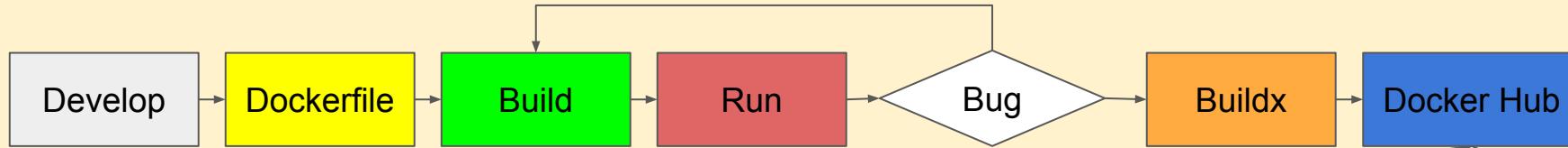
The screenshot shows the Adafruit IO Cloud Dashboard interface. At the top, there's a navigation bar with links for Profile, Feeds, Dashboards, Triggers, Services, and AIO Key. Below the navigation is a header bar with the user name 'alegeno92' and a 'Feeds' button. Underneath is a search bar with a magnifying glass icon. The main content area displays a table of feeds. The columns are 'Group / Feed', 'Key', 'Last value', and 'Recorded'. The data in the table is as follows:

Group / Feed	Key	Last value	Recorded
Default	default		
loads	loads	847.0	about 1 hour ago
memory	memory	437.0	about 1 hour ago
people	people	1	4 minutes ago
storage	storage	19	about 2 hours ago

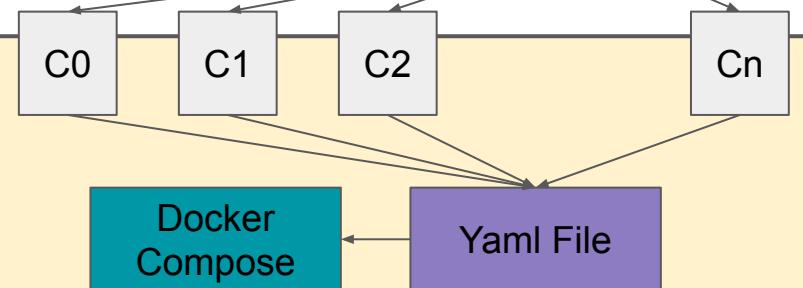
At the bottom of the dashboard, there are links for Help (Get Help, Quick Guides, API Documentation, FAQ), Explore (Learn, IO Plus, News), and a quote by Samuel Beckett: "Ever tried. Ever failed. No matter. Try again. Fail again. Fail better" - Samuel Beckett.

# Development Workflow

LAPTOP



EMBEDDED DEVICE  
(UDOO NEO)



# Workshop Flow

## What are we going to do:

- ~~Define the Docker Container structure for the project (Docker Approach)~~
- Test Docker Engine runs on the Laptop
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# Docker

## Installation

Check that **docker engine** and **docker-compose** are installed locally

```
docker --version  
docker-compose --version
```

# Workshop Flow

What are we going to do:

- ~~Define the Docker Container structure for the project (Docker Approach)~~
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# Docker

## Develop

Clone the cloud connector app from Github.

```
git clone https://github.com/alegeno92/cloud-connector.git  
cd cloud-connector
```

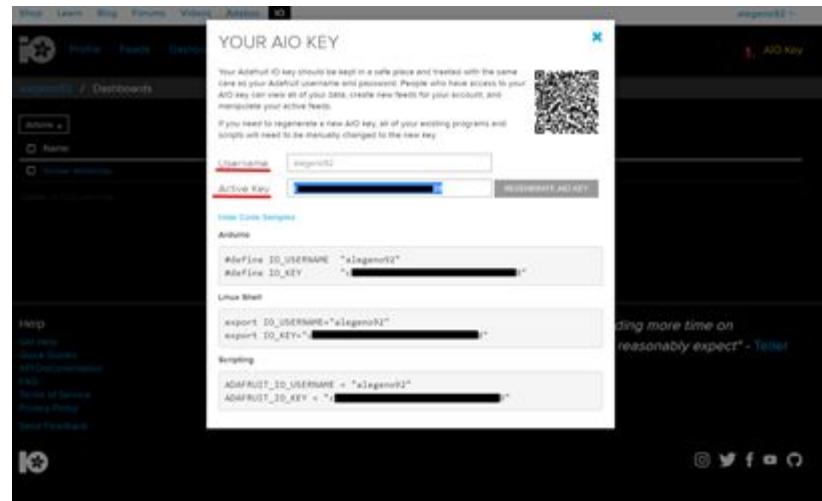
# Docker



## Develop - Send data to Adafruit IO cloud

Register to Adafruit IO: [https://accounts.adafruit.com/users/sign\\_up](https://accounts.adafruit.com/users/sign_up)

Generate a new Auth Token:





# Docker

## Develop - Send data to Adafruit IO cloud

Edit the file config.json in order to see the data online:

```
{  
  "AIO": {  
    "username": "",  
    "key": ""  
  },  
  "mock_client": true  
}  
...
```



# Docker

## Dockerfile

Create the Dockerfile in the root of the project

```
FROM python:3-alpine
RUN pip install --no-cache-dir paho-mqtt adafruit-io
RUN mkdir /app
WORKDIR /app
COPY *.py /app/
CMD ["python", "-u", "/app/main.py" , "/config/config.json"]
```



# Docker

## Build

First of all, build the container:

```
docker build . -t cloud-connector
```

Check if everything works fine:

```
docker image ls
```



# Docker

## Run

```
docker run -v <directory_path_of_config.json>:/config --network=host cloud-connector
```

# Workshop Flow

What are we going to do:

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# Docker

## Develop - A more complex application: the Telemetry Agent

Clone the cloud connector app from Github.

```
cd ~  
git clone https://github.com/alegeno92/agent.git  
cd agent
```



# Docker

## Dockerfile - A more complex application: the Telemetry Agent

Dockerizing the telemetry agent: a C++ application that depends on many libraries (e.g. Paho MQTT C and C++ libraries). We use a smart approach.

Split the Dockerfile in two (or more):

- Build:
  - Build tools: cmake, gcc, dev libraries, ...
  - Build dependencies
  - Build the application
- Runtime:
  - Binary app
  - Shared libraries



# Docker

## Dockerfile

First of all, start building the Paho MQTT C library:

```
FROM alpine:latest AS paho-c
RUN apk add --no-cache cmake g++ make
RUN apk add --no-cache git libressl-dev
RUN git clone https://github.com/eclipse/paho.mqtt.c.git
WORKDIR paho.mqtt.c
RUN git checkout v1.3.1
RUN cmake -Bbuild -H. -DPAHO_WITH_SSL=ON -DPAHO_ENABLE_TESTING=OFF
RUN cmake --build build/ --target install
```



# Docker

## Dockerfile

Next, starting from the previous container build the Paho MQTT C++ library:

```
FROM paho-c AS paho-cpp
WORKDIR /
RUN apk add --no-cache git libressl-dev
RUN apk add --no-cache --upgrade bash
RUN git clone https://github.com/eclipse/paho.mqtt.cpp.git
WORKDIR paho.mqtt.cpp
RUN cmake -Bbuild -H. -DPAHO_BUILD_DOCUMENTATION=FALSE -DPAHO_BUILD_SAMPLES=FALSE
RUN cmake --build build/ --target install
```



# Docker

## Dockerfile

Next, let's build our project:

```
FROM paho-cpp AS build-container
RUN apk add --no-cache zlib-dev
COPY . /home/agent
WORKDIR /home/agent
RUN if [ \-d "./build" ] ; then rm -rvf build && mkdir build ; else mkdir build ; fi
WORKDIR build
RUN cmake ..
RUN cmake --build . --target agent --
```



# Docker

## Dockerfile

At the end, the cunning idea: starting from a vanilla alpine container, copy on it only the built libraries and the necessary files:

```
FROM alpine:latest  
  
RUN apk add --no-cache zlib libressl libstdc++  
  
COPY --from=build-container /paho.mqtt.c/build/src/* /usr/lib/  
COPY --from=build-container /paho.mqtt.cpp/build/src/* /usr/lib/  
COPY --from=build-container /home/agent/build/bin/agent /  
  
CMD ["/agent", "/config/config.json"]
```



# Docker

## Build

Build the container:

```
docker build -t agent .
```

Check if everything works fine:

```
docker image ls
```



# Docker

## Run

Run the container:

```
docker run -v /home/alessandro/Projects/agent/config:/config/ --network=host agent
```

# Workshop Flow

What are we going to do:

- ~~Define the Docker Container structure for the project (Docker Approach)~~
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# Docker Buildx

\*New\* CLI plugin that extends the docker command with the full support of the features provided by [Moby BuildKit](#) builder toolkit.

Supports multi-architecture builds for both x86 and Arm (one build, multiple images)

Using the Buildx feature to create images for different kind of architectures at the same time. (refs. <https://docs.docker.com/buildx/working-with-buildx/>)



# Docker Buildx

## Create a new Buildx builder

Create our builder

```
docker buildx create --name arm_builder
```

List the builders

```
docker buildx ls
```

Starts the builder

```
docker buildx inspect --bootstrap
```

Use the builder

```
docker buildx use arm_builder
```



# Docker Buildx

## Build the Telemetry Agent using buildx

Build the containers for the needed platforms:

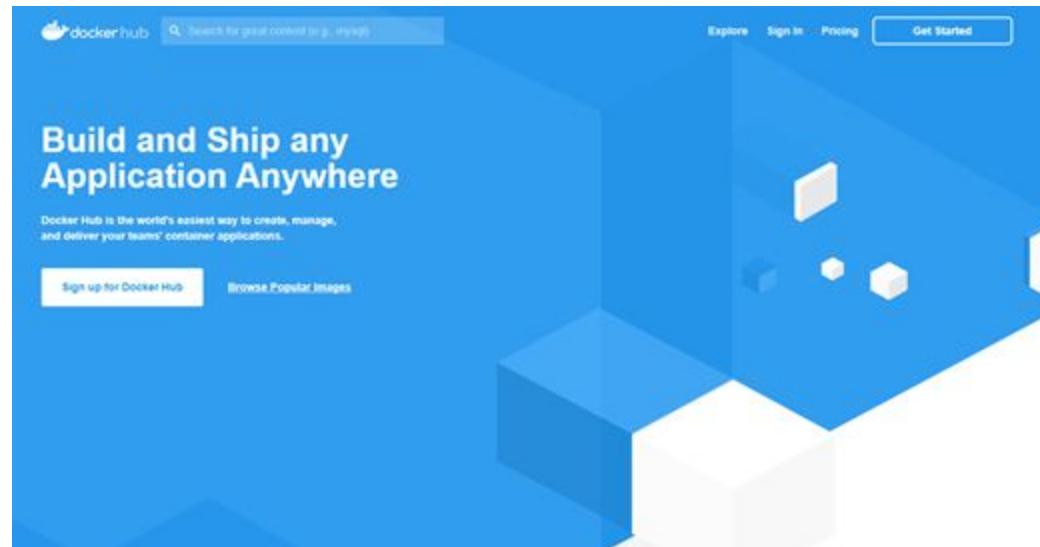
```
docker buildx build -t alegeno92/agent --platform linux/arm64,linux/arm/v7 --load .
```



# DockerHub

## Uploading an image to DockerHub

Create an account to DockerHub: [\[hub.docker.com\]](https://hub.docker.com)





# DockerHub

## Login to DockerHub

- Login to DockerHub via cli:

```
docker login
```



# Docker Buildx

Build the REST Server using Buildx and push on DockerHub

Build the agent for different platforms and push them on DockerHub:

```
docker buildx build -t alegeno92/agent --platform linux/amd64,linux/arm/v7 --push .
```

# Workshop Flow

What are we going to do:

- ~~Define the Docker Container structure for the project (Docker Approach)~~
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# UDOO NEO SSH connection

A first condition to establish a SSH connection with your UDOO Neo is to have previously completed the tutorial about the USB Direct Connection.

[https://github.com/alegeno92/docker-workshop/blob/master/SSH\\_connection.md](https://github.com/alegeno92/docker-workshop/blob/master/SSH_connection.md)

A second condition is to download and install an SSH Client for your system (if not):

- Windows: Putty
- Linux: Shell
- Mac: Shell

# UDOO NEO SSH connection

Open an SSH connection to the board

In your laptop run:

```
ssh udooyer@192.168.7.2 (password: udooyer)
```

```
cd ~
```

# Workshop Flow

What are we going to do:

- ~~Define the Docker Container structure for the project (Docker Approach)~~
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# Docker Compose

A tool to run many docker containers together

- Compose is a tool for defining and running multi-container Docker applications.
- It uses a YAML file to configure your application's services.
- With a single command, you create and start all the services from your configuration.

# Docker Compose

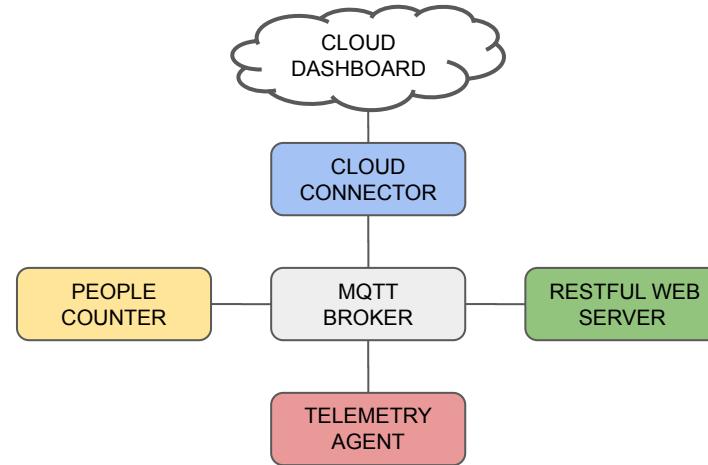
Download the Docker compose repo

```
ssh udooer@192.168.7.2 (password: udooer)
cd ~
git clone https://github.com/alegeno92/compose.git (if there isn't)
cd compose
```

# Docker Compose

## The YAML file

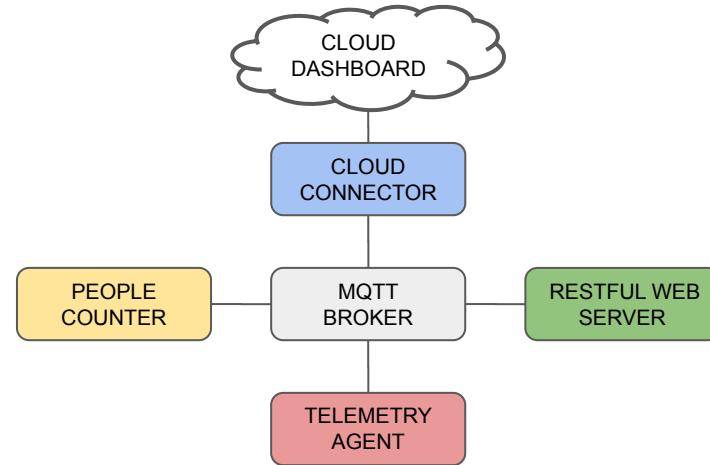
```
version: '3'  
  
services:  
  
server:  
    image: alegeno92/server:latest  
    ports:  
        - "8000:8000"  
        - "8086:8086"  
    depends_on:  
        - "mosquitto"  
        - "people-counter"  
    volumes:  
        - ./configurations/server:/config
```



# Docker

## The YAML file

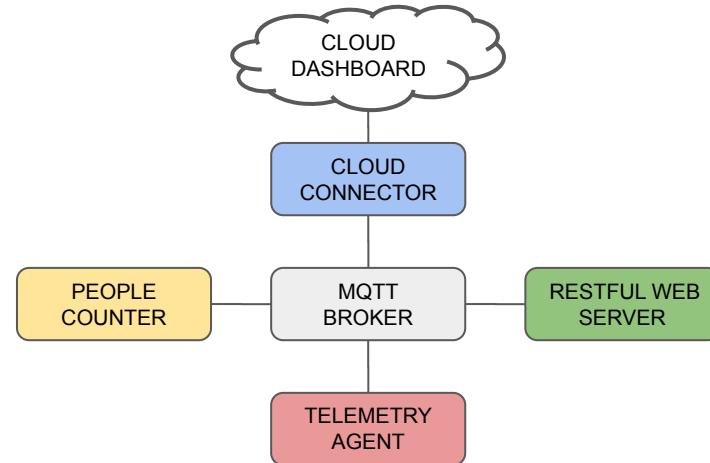
```
...  
agent:  
    image: alegeno92/agent:latest  
    hostname: agent  
    depends_on:  
        - "mosquitto"  
    volumes:  
        - ./configurations/agent:/config/  
...  
TELEMETRY AGENT
```



# Docker

## The YAML file

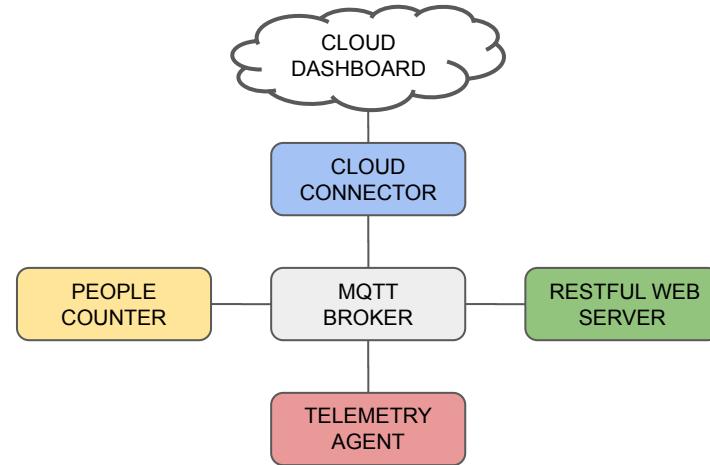
```
...  
cloud-connector: CLOUD CONNECTOR  
image: alegeno92/cloud-connector:latest  
hostname: cloudconnector  
depends_on:  
  - "mosquitto"  
volumes:  
  - ./configurations/cloud-connector/:/config  
environment:  
  - PYTHONUNBUFFERED=1  
...  
...
```



# Docker

## The YAML file

```
...  
people-counter:  
    image: alegeno92/people-counter:latest  
    depends_on:  
        - "mosquitto"  
    expose:  
        - "8084"  
    ports:  
        - "8084:8084"  
    volumes:  
        - ./configurations/people-counter/:/config  
    environment:  
        - PYTHONUNBUFFERED=1  
...  
PEOPLE COUNTER
```



# Workshop Flow

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Compose

Y

# Docker Compose

## Testing the App on the UDOO NEO

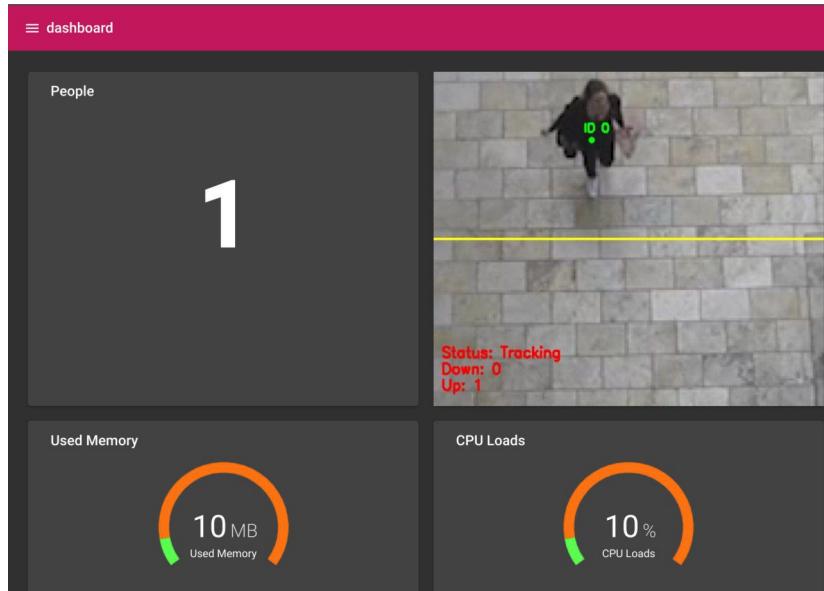
Launch the Docker Compose command:

```
docker-compose -f "docker-compose.yml" up
```

And the magic happens!! :D

# The final outcome

192.168.7.2:8000



Adafruit IO

Group / Feed	Key	Last value	Recorded
Default	default	847.0	about 1 hour ago
loads	loads	437.0	about 1 hour ago
memory	memory	437.0	about 1 hour ago
people	people	1	4 minutes ago
storage	storage	19	about 2 hours ago

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"Ever tried. Ever failed. No matter. Try again.  
Fail again. Fail better" - Samuel Beckett

# Workshop Flow

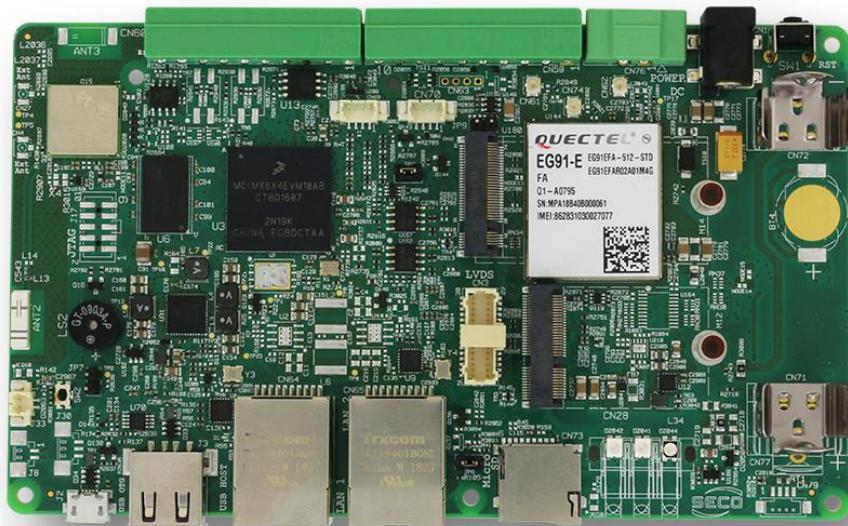
What are we going to do:

- Define the Docker Container structure for the project (Docker Approach)
- Test Docker Engine runs on the Laptop
- Build Python Container from scratch
- Build C++ Container from scratch
- Use Buildx to create containers for different platform and Push them on DockerHub
- Startup the Arm board and test the Docker Engine runs
- Connect many Docker containers together using Docker Compose
- Deploy on UDOO NEO (Linux Ubuntu)
- Deploy on an Industrial IoT Gateway with EDGEHOG OS (Yocto based): Seco SBC-C23, Seco SBC-C61

# The final outcome

## Moving on the industrial case

SECO SBC C23 Industrial Board based on the same processor of the UDOO NEO and running EDGEHOG OS (Yocto).



Compose

Y

# Docker

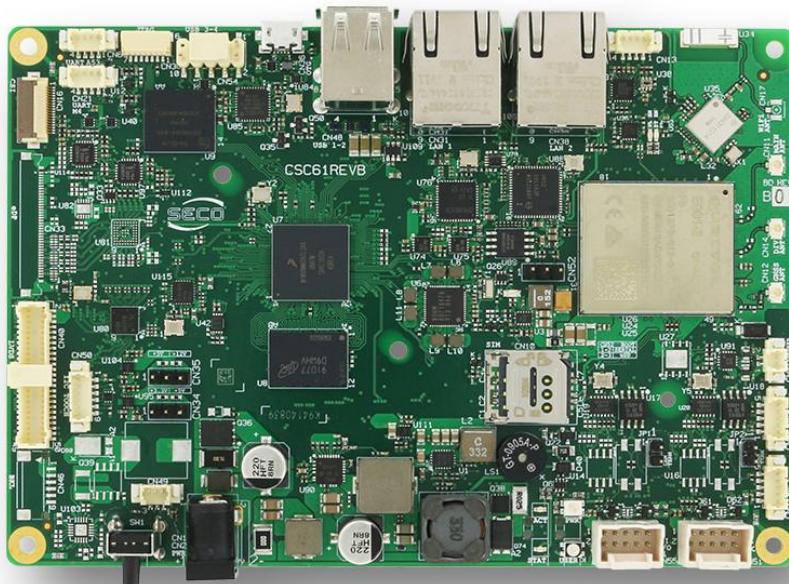
## Testing on industrial board

Copy Docker Compose and launch the same command on the SECO SBC C23

# The final outcome

I need to scale performance

SECO SBC C61 Industrial Board based on i.MX 8M Mini Quad – Full featured, 4x Cortex®- A53 cores up to 1.8GHz and running EDGEHOG OS (Yocto).



Compose

Y

# Docker

## Testing on industrial board

As before, copy Docker Compose and launch the same command on the SECO SBC C61

# Conclusions

## PROs

Docker is a smart solution for the development of complex applications on an ARM embedded device

Buildx is a very powerful tool (easy cross compilation)

Application Configurations is the same for different platforms

Useful for CI and CD: update made by download the updated container

Good Performance wise: Docker is not a Virtual Machine, the application runs natively (thanks to cgroup feature of Linux Kernel)

High security wise: each container runs inside a sandbox. Who runs it decides the accessible resources

## CONS

Heavy disk utilization: each containers contains a replica of an entire file system



# Questions?



# Thank you

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# Useful Links

## Something to think about

Workshop Resources:

<https://github.com/alegeno92/docker-workshop.git>

[www.docker.com](http://www.docker.com)

[www.udoo.org](http://www.udoo.org)

[www.seco.com](http://www.seco.com)