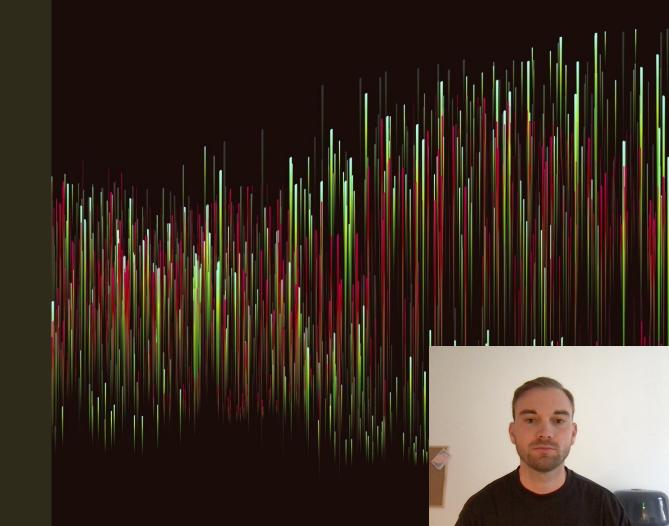
Applications of Datascience



Preprocessing

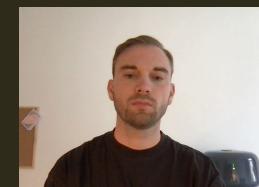
< > Messung 180323 Fahrrad	2023-03-18	· · ·	○ ~ Q					
Synchronisierung mit iCloud angehalten								
Name	^ Änderungsdatum	Größe	Art					
Accelerometer.csv	18.03.23, 16:41	33 KB	Commet (.csv)					
Barometer.csv	18.03.23, 16:41	16 KB	Commet (.csv)					
Gyroscope.csv	18.03.23, 16:41	24 KB	Commet (.csv)					
Linear Accelerometer.csv	18.03.23, 16:41	24 KB	Commet (.csv)					
Location.csv	18.03.23, 16:41	127 KB	Commet (.csv)					
Magnetometer.csv	18.03.23, 16:41	23 KB	Commet (.csv)					
> 🚞 meta	18.03.23, 16:42		Ordner					
Proximity.csv	18.03.23, 16:41	16 KB	Commet (.csv)					
25								
25								
25								



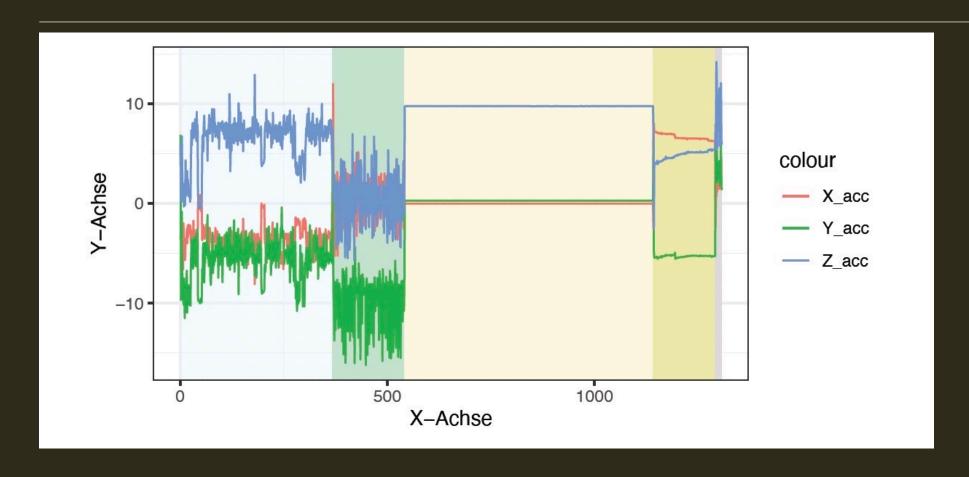
Dataframe I worked with

Head of the Dataframe with 1 column for every sensor

X_acc	X_hPa	X_{rad}	X_{linacc}	Х_μТ	Activity
-3.656746	993.4352	5.40708780	-3.9807026	-28.163292	fahrrad
-1.297652	993.4512	0.19785871	0.4741257	6.101456	fahrrad
-2.451302	993.4512	-0.09114313	-0.1024862	4.411934	fahrrad
-6.856941	993.4512	-0.69596463	2.1904757	3.494606	fahrrad
-2.876269	993.4512	0.22384980	-0.7286204	-4.406799	fahrrad

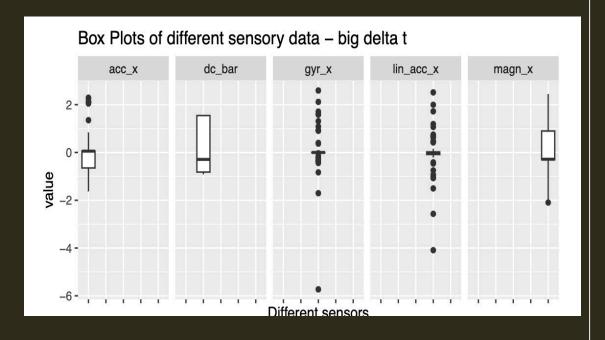


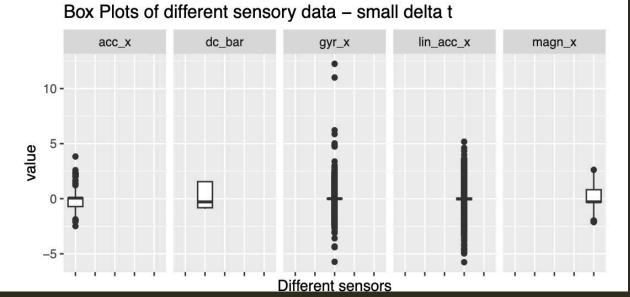
Plot of acceleration data

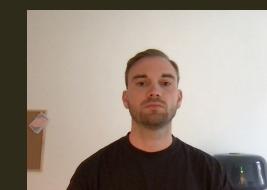




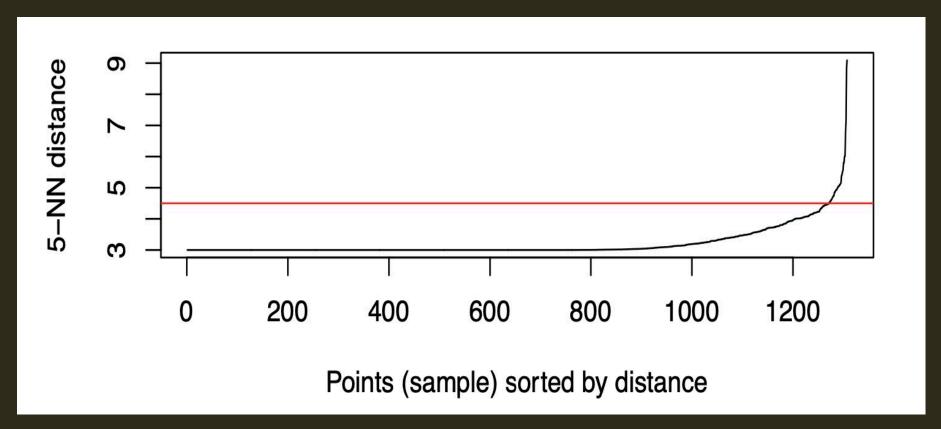
Difference in delta t





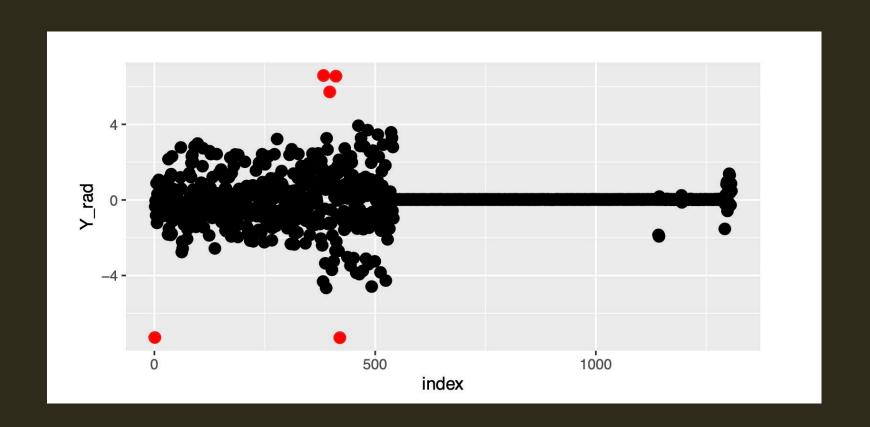


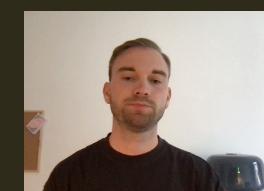
Outlier detection with dbscan - 1



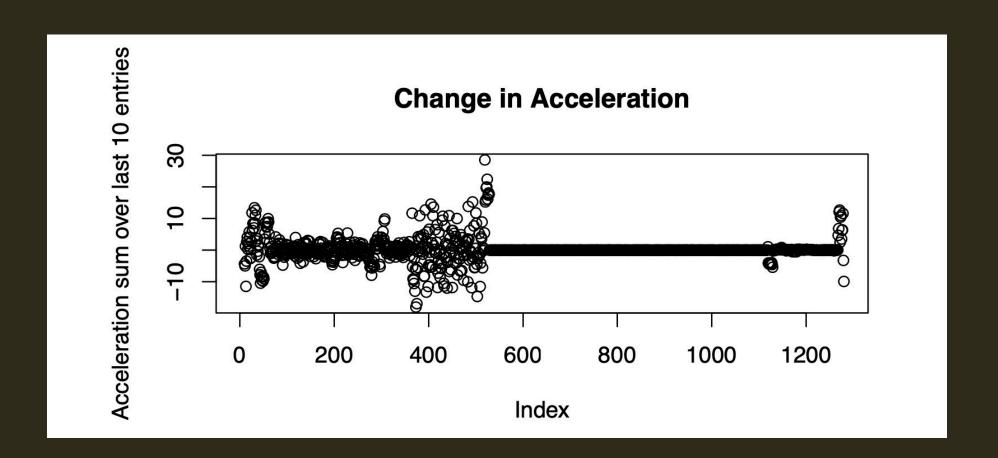


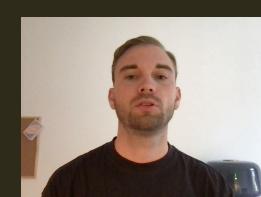
Outlier detection with dbscan - 2



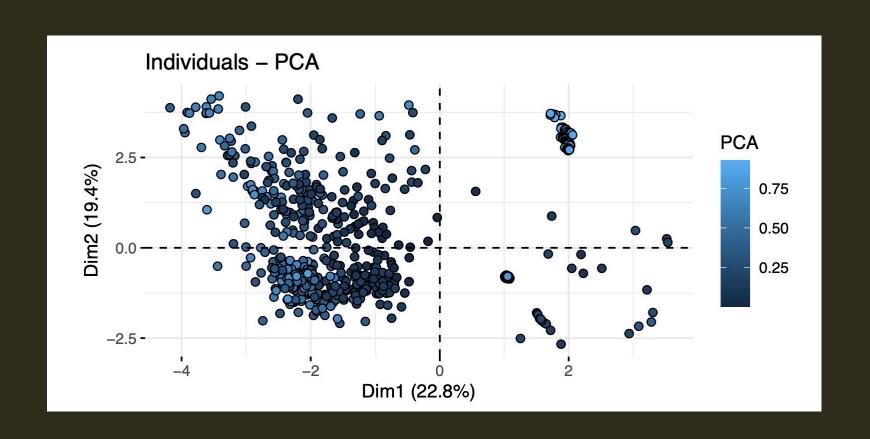


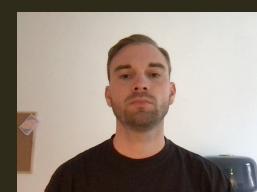
Feature engineering - Temporal Aggregation of acceleration data



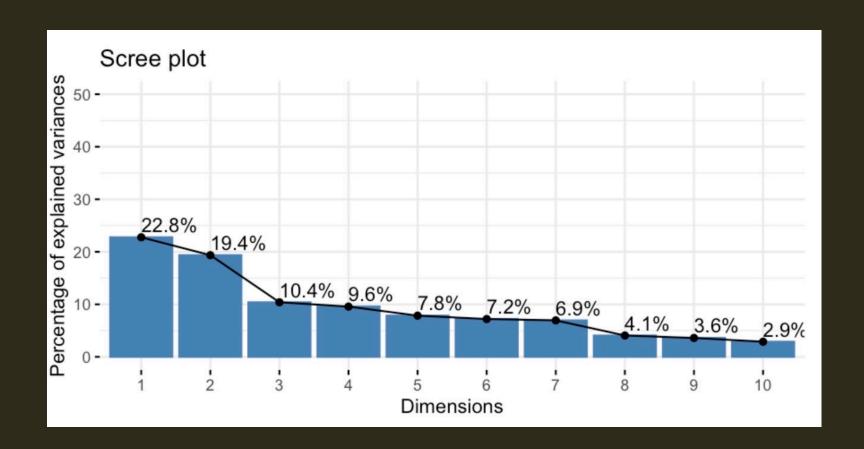


PCA to get a better understanding of the data



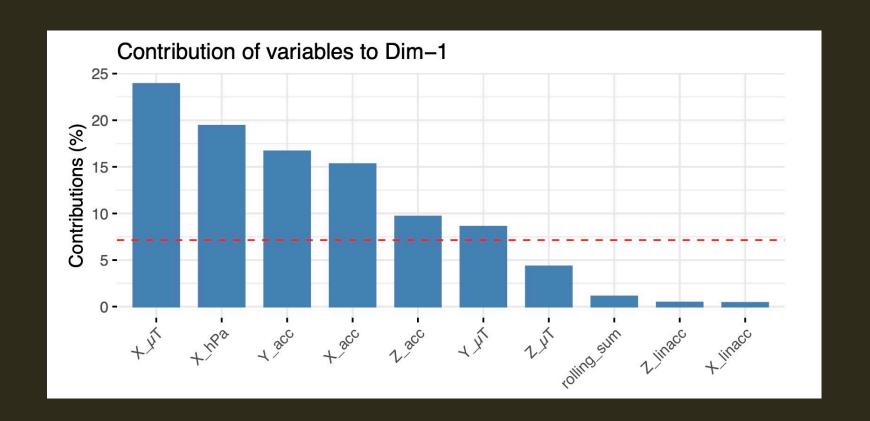


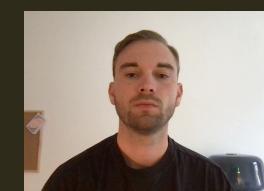
Scree plot



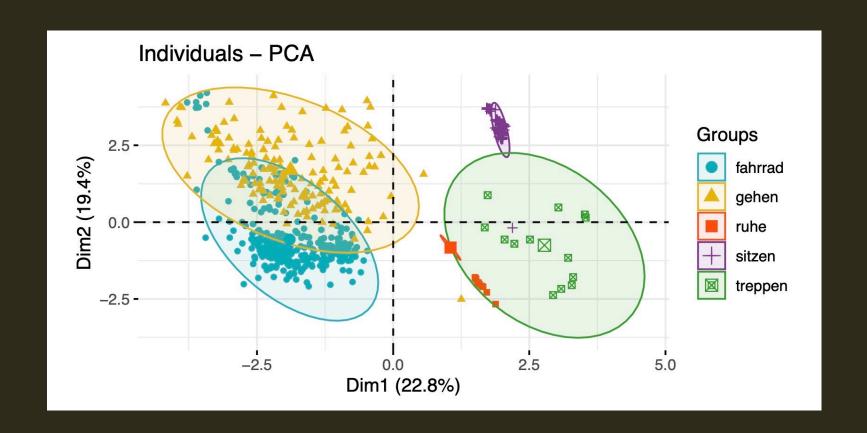


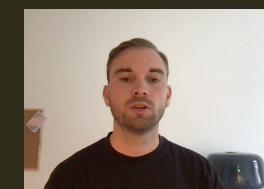
Contribution to principal component



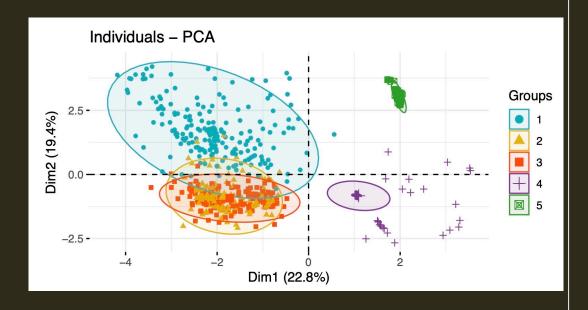


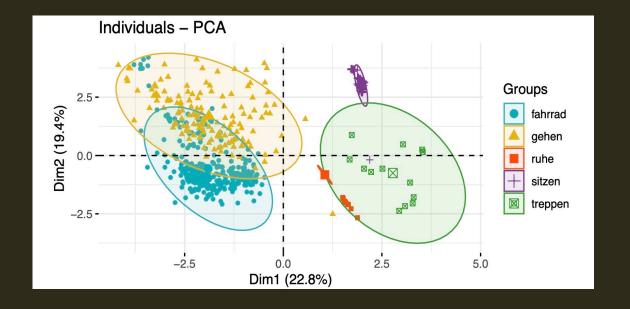
Real Cluster





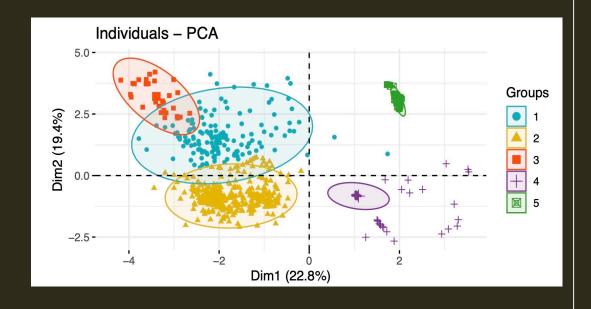
Hierarchial clustering - 1

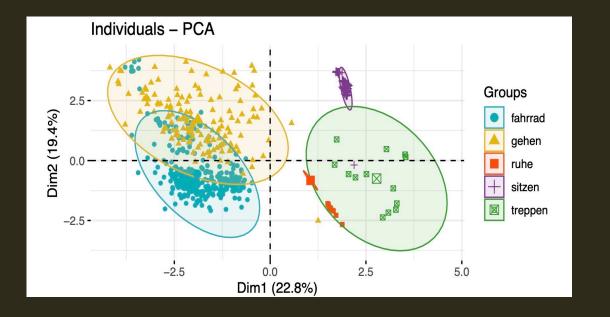






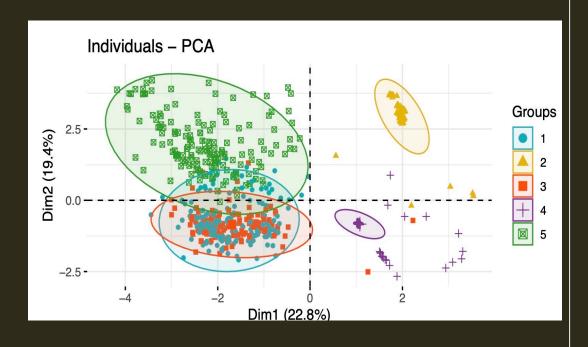
Hierarchial clustering - 2

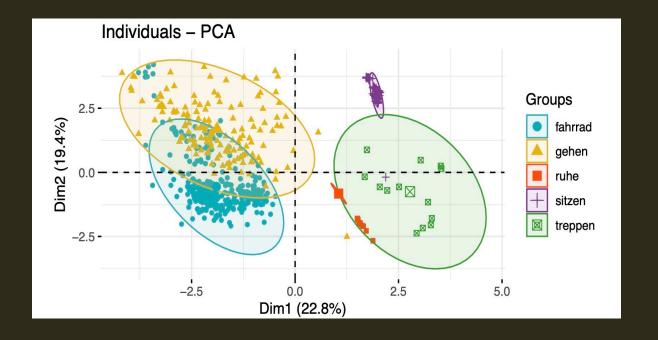






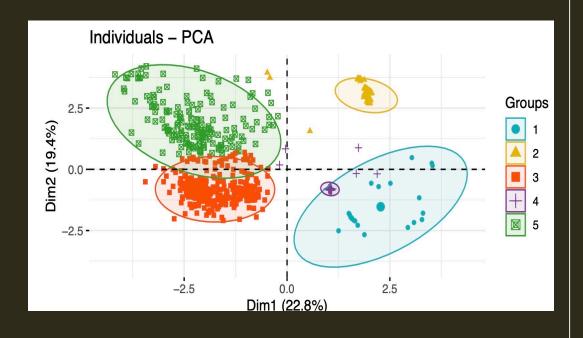
K-means clustering - 1

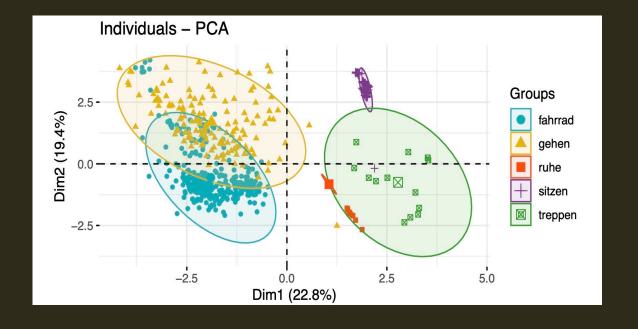






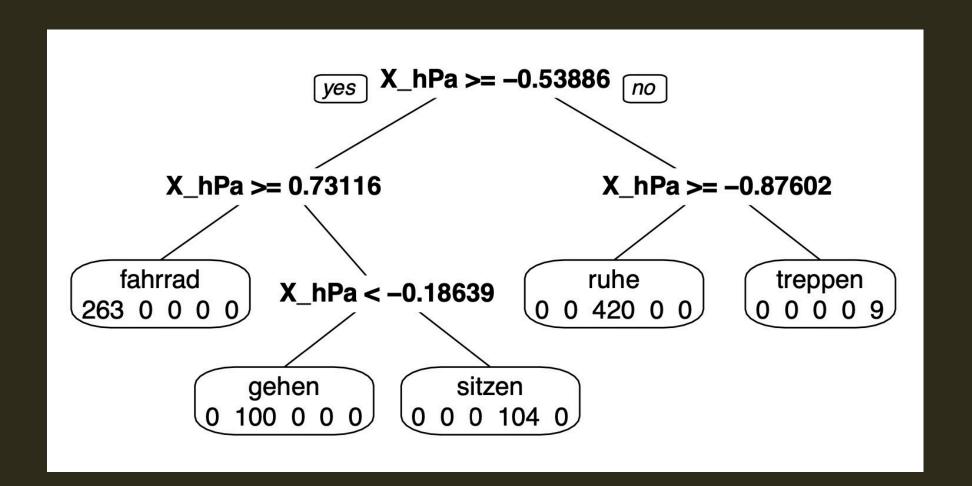
K-means clustering - 2





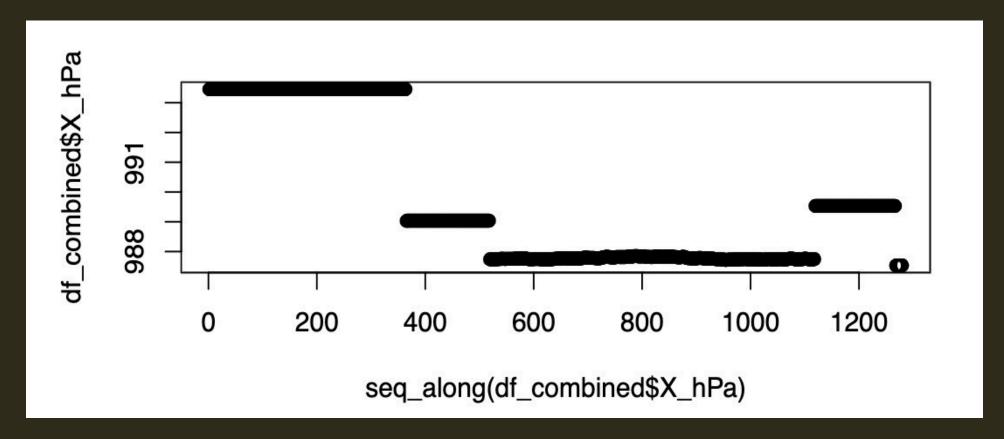


Classification tree — original data





Exploring reasons





Classification tree – confusion matrix

	fahrrad	gehen	ruhe	sitzen	treppen
fahrrad	101	0	0	0	0
gehen	0	54	0	0	0
ruhe	0	0	180	0	0
sitzen	0	0	0	45	0
treppen	0	0	0	0	4

