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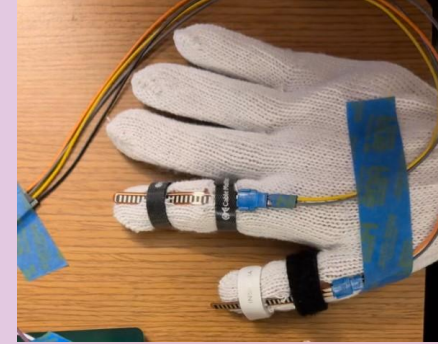
# Dits & Dahs

## ECE 167

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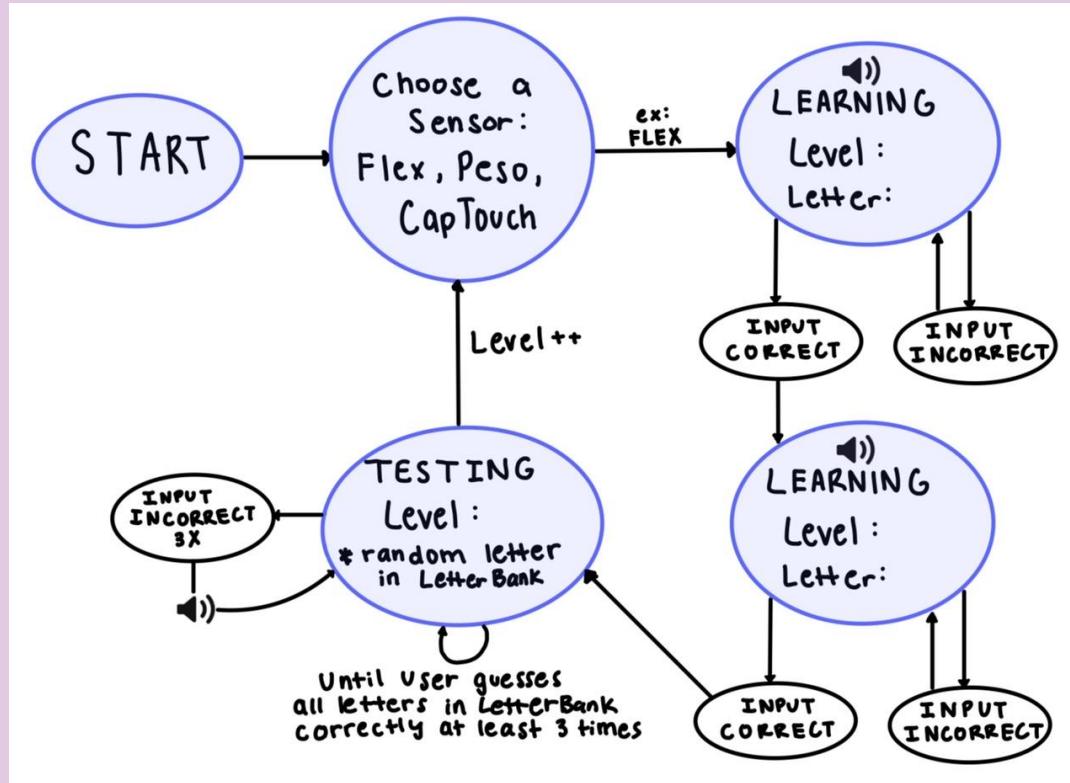
# Overview

- ❖ Game:
  - Morse Code training game is modeled after MorseMania® where the user is prompted a letter and enters a Morse Code translation
  - Two Modes: Learning where Morse Code is played/tested. Testing where user is tested on new and previous letters
- ❖ Sensors:
  - Modeled after different Morse Code Keyers
    - Flex Sensor: User bends thumb or index finger to type a dit or dah
    - Peso CapTouch Sensor: User's duration of touch determines dit or dah
    - Custom 167 CapTouch: User's duration of touch determines dit or dah

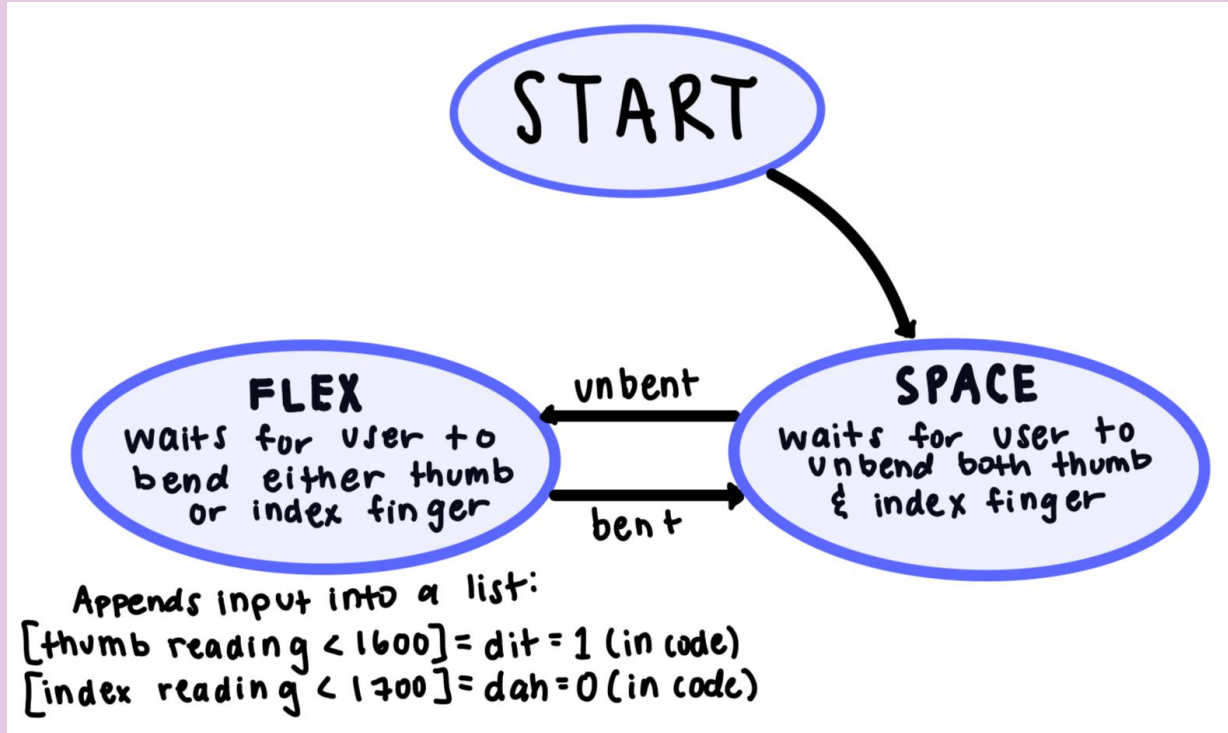




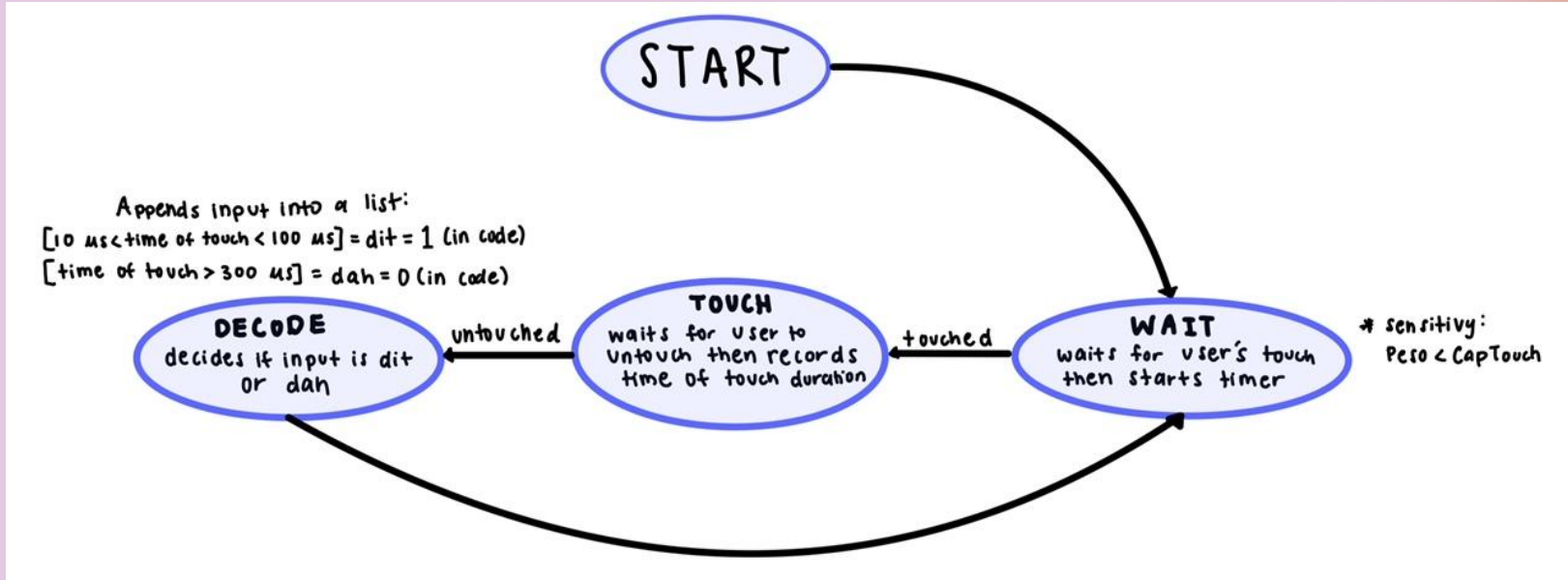
# Game



# Morse Code Decoder for Flex



# Morse Code Decoder for CapTouch



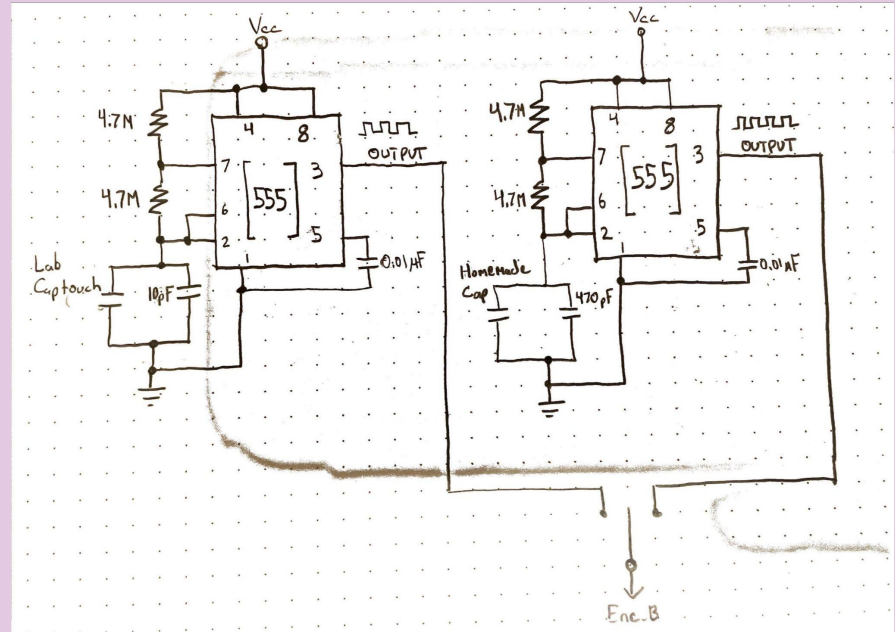
# CapTouch -> Morse Code

## How?

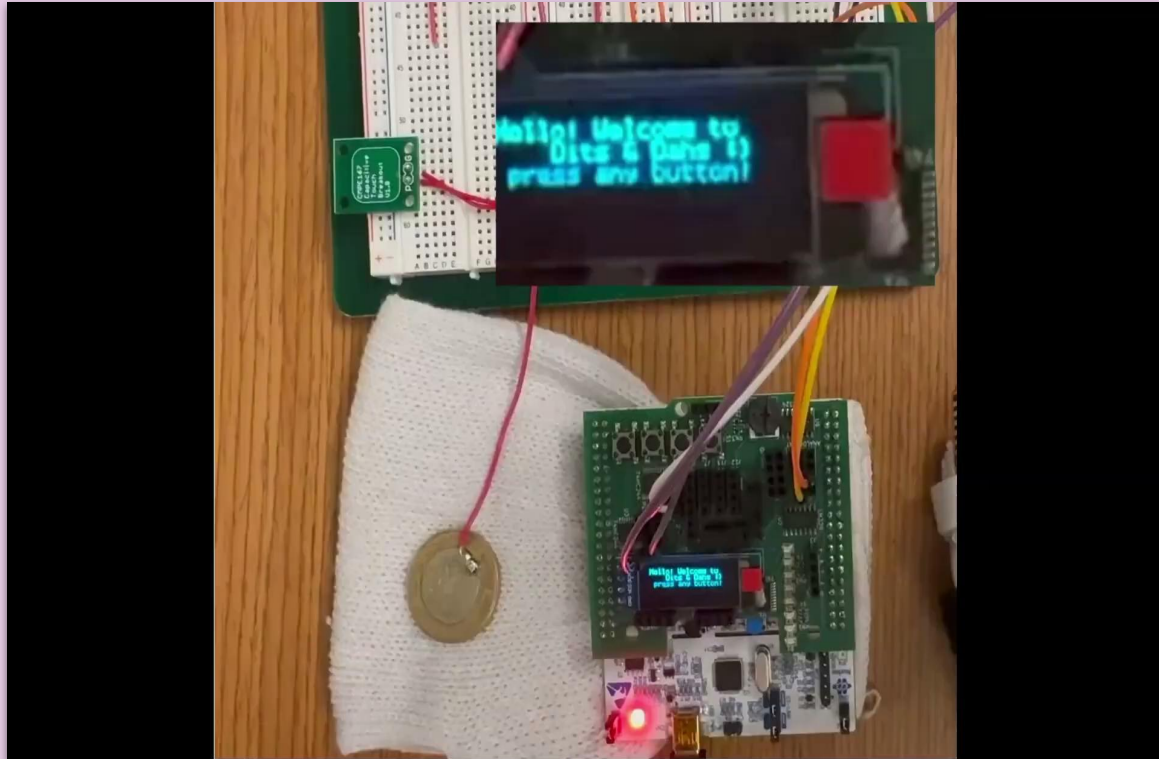
- ❖ Taking advantage of the LM555 astable mode configuration, the frequency was adjusted to work with both sensors.
- ❖ Utilized CAPISTOUCHE() function to measure the duration a user is touching the sensor.
- ❖ Used duration of touch to translate the touch to Dit or Dah.

$$f = \frac{1.44}{(R_1 + 2R_2) * (C + C_{Sensor})}$$

## Schematic

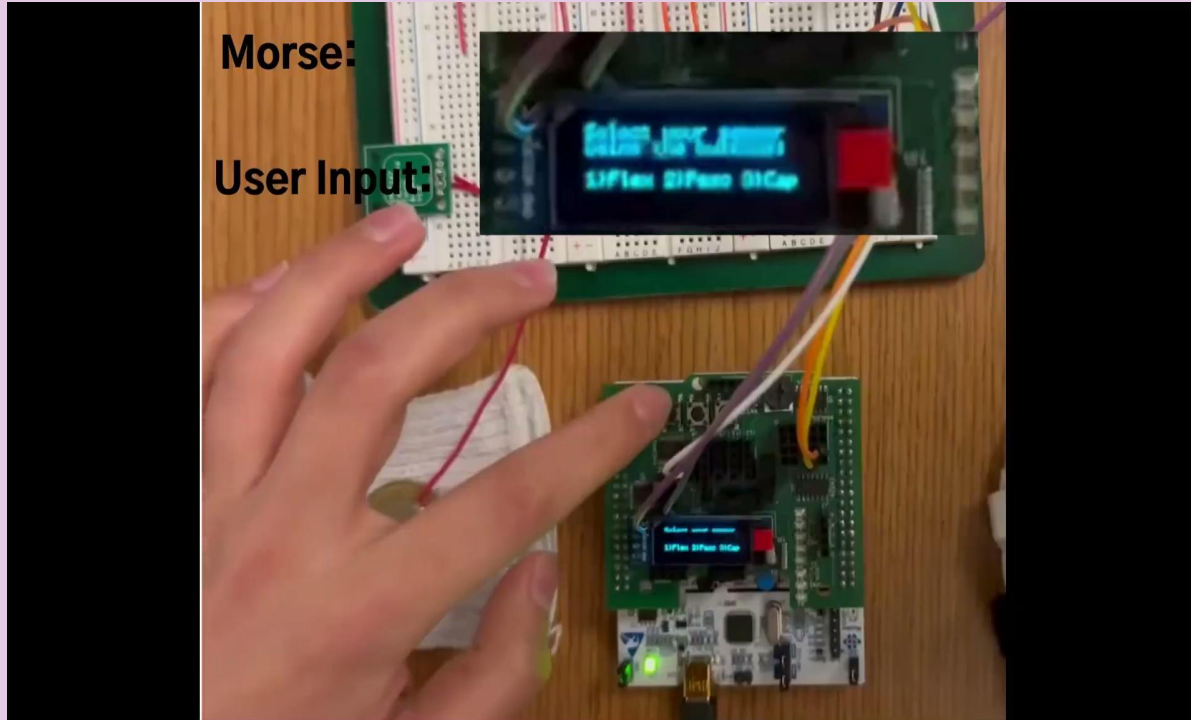


# Demo for CapTouch





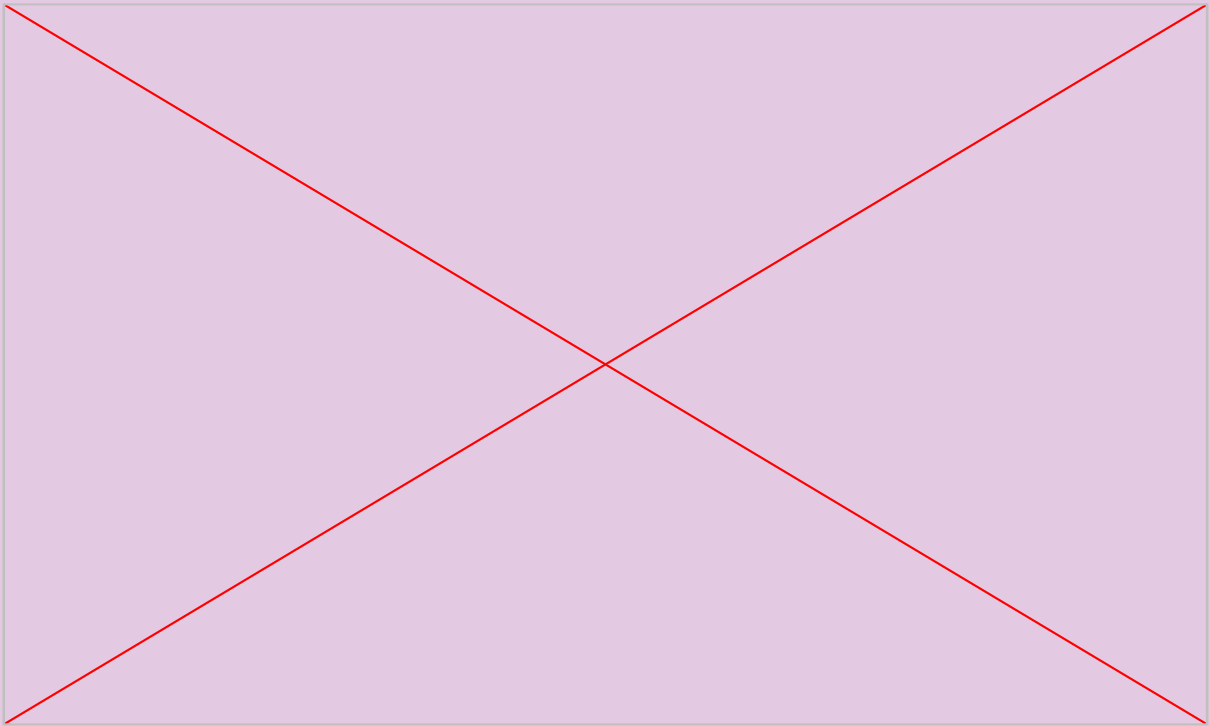
# Demo for Peso







# Demo for Flex





# Thank You Or

T - H ● ● ● ● A ● - N - ● K - ● - Y - ● - - O - - - U ● ● -

# CapTouch Interface

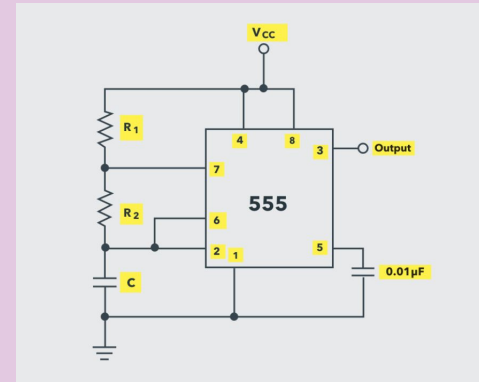
## Capacitive Touch Sensors

- ❖ Detect changes in capacitance when a conductive object (e.g. human finger) comes close or touches.
- ❖ This occurs when distance,  $d$ , between plates changes, thereby altering  $C$ .

$$C = \frac{\epsilon_r \epsilon_0 A}{d}$$

## LM555 - Astable Mode

- ❖ Popular IC used as a timer or pulse generator.
- ❖ Astable mode generates a free running square wave oscillator.
- ❖ Frequency is controlled by external resistors and capacitors.



$$f = \frac{1.44}{(R_1 + 2R_2) * C}$$

# Homemade CapTouch using Peso

## Idea

- ❖ A coin, like a peso, can act as one plate in a capacitor, with the human finger as the other.
- ❖ Potentially convenient for transmitting morse Code messages.

## Implementation Challenges

- ❖ The changes in capacitance were much larger than that of the lab CapTouch (*More* sensitive).
- ❖ As a result, it caused greater changes to the oscillators frequency.
- ❖ Touch detection became unreliable.

## Solution

- ❖ Since changes in capacitance were greater, the way around was to simply increase magnitude of C.
- ❖ C was raised by a magnitude of  $10^3$  times the original configuration.
- ❖ Results were reliable and sensitivity of Peso became manageable.