

# Package ‘causalimage’

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**Title** causalimage: Smart Description Here

**Version** 2.0

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**Description** Description here.

**Depends** R (>= 3.3.3)

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**Encoding** UTF-8

**LazyData** true

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**Imports** Rsolnp

**RoxygenNote** 7.1.2

## R topics documented:

causalimage . . . . .	1
estimate . . . . .	3
simulate . . . . .	4
<b>Index</b>	<b>5</b>

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causalimage

*causalimage*

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## Description

This function (1) generates simulated causal structures using images and also (2) performs estimation using the methods described in CITES.

## Usage

```
causalimage(
  dag,
  treatment = NULL,
  image_pool = NULL,
  analysis_level = "scene",
  control = list(),
  ...
)
```

## Arguments

<code>dag</code>	( <i>character string</i> ) An input DAG specifying causal structure. This input should be of the form ‘ <code>i-&gt;t, i-&gt;y, t-&gt;y, ...</code> ’. Currently, only one node in a DAG can be an image (this should be labeled “ <code>i</code> ”). The non-image nodes can have arbitrary string labels. The image can be a confounder, effect moderator, effect mediator. If the image is to be used as a moderator, use the notation, <code>t-i&gt;y</code> .
<code>treatment</code>	( <i>character string, optional</i> ) In estimation mode, users specify the treatment variable here. If <code>treatment</code> is specified, users must provide other data inputs to the DAG (see <code>...</code> ).
<code>image_pool</code>	( <i>character string, optional</i> ) The path to where analysis specific images are located. This can be specified both in simulation and estimation mode. If not specified, the simulation uses a pool of Landsat images from Nigeria.
<code>analysis_level</code>	( <i>character string, default is ‘scene’</i> ) Defines the unit of analysis used in the simulation framework. This is ignored in estimation mode, where the unit of analysis is inferred from the data dimensions.
<code>control</code>	( <i>list</i> ) A list containing control parameters in the data generating process.
<code>...</code>	( <i>optional</i> ) In estimation mode, users input the data matrices associated with the non-image nodes of DAG and image node <code>i</code> . For example, if <code>x</code> is a DAG node, users must, in estimation mode, supply data to <code>x</code> in a form that can be coerced to a tensor.

## Value

A list:

- In *simulation mode*, the function returns a list with as many elements as unique nodes in DAG. Each element represents the simulated data.
- In *estimation mode*, the function returns an estimated treatment effect with 95% confidence intervals.

## References

- CITES

## Examples

```
#set seed
set.seed(1)

# Simulation mode
#simulatedData <- causalimage('r->i, i->t, t->y, r->y')
```

```
#print(names(simulatedData))

# Estimation mode
#estimatedResults <- causalimage('r->i, i->t, t->y, r->y', y=y, r=r, y=y', treatment='t')
#print( estimatedResults )
```

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estimate	<i>estimate</i>
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**Description**

Implements ...

**Usage**

```
estimate(dag = NULL, ...)
```

**Arguments**

DAG                    'DAG'.

**Value**

A list consiting of

- Items.

**References**

- References here

**Examples**

```
#set seed
set.seed(1)

#Geneate data
x <- rnorm(100)
```

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simulate	<i>simulate</i>
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**Description**

Implements ...

**Usage**

```
simulate(dag = NULL, ...)
```

**Arguments**

DAG                    'DAG'. An input DAG specifying causal structure. Only one node in a DAG can be an image. The image can be a confounder, effect moderator, effect mediator,

**Value**

A list consiting of

- Items.

**References**

- References here

**Examples**

```
#set seed
set.seed(1)

#Geneate data
x <- rnorm(100)
```

# Index

causalimage, [1](#)

estimate, [3](#)

simulate, [4](#)