Decond Order Diff Equations. Decond order lift equations depend on the second derivative, Ex:  $\frac{\lambda x}{dt} + \frac{\lambda}{m} x = 0$   $\leftarrow$  depring-mass system, To treat 2<sup>nd</sup> order diff equations, we convert them into a system of 1<sup>st</sup> order diff equations,  $\frac{d^2x}{dt^2} + \frac{x}{m}x = 0 \quad \rightarrow \quad \begin{bmatrix} \frac{dx}{dt} = v = 9(v, x, t) \\ \frac{dx}{dt} = v = 9(v, x, t) \end{bmatrix}$  $\frac{dv}{dt} = -\frac{xx}{m} = f(v, x, t)$ In general any 2 order diff. eg. cm be written as Two first order diff equations,  $\frac{dy}{dt} = v$ ,  $\frac{dv}{dt} = f(v, y, t)$ Then the Euler method applied to this system takes the form  $\begin{bmatrix} v_{n+1} \\ y_{n+1} \end{bmatrix} = \begin{bmatrix} v_n + f(v_n, y_n, t_n) h \\ y_n + g(v_n, y_n, t_n) h \end{bmatrix}$ biven the initial conditions No, Yo, to, and h=tn+1-tn. And the 4th order Runge-Kutta takes the form,

[Vn+x] [Vn+ \frac{h}{6} [Kn+2 Knu+2 Xsu+ K40]] [ Yn+ ] [ Yn+ = [ Ky + 2kzy+ 2kzy+ kyy]]

With, 
$$K_{1}y = g(v_{1}, Y_{1}, t_{1})$$
,  $K_{1}v = f(v_{1}, Y_{1}, t_{1})$   
 $K_{2}y = g(v_{1} + K_{1}v) \frac{1}{2}, t_{1}v + \frac{1}{2}, t_{2}v = f(v_{1} + K_{1}v) \frac{1}{2}, t_{1}v + \frac{1}{2}, t_{2}v + \frac{1}{2}, t_{2}v$