

## Wigner Seitz Cell for simple cubic lattice

Define origin. Define a length scale a for graphical representation.

```
In[*]:= a = 2;  
o = {0, 0, 0};  
c =  $\frac{2 \pi}{a}$ ;
```

Define primitive vectors of the reciprocal lattice

```
In[*]:= b1 = c {1, 0, 0};  
b2 = c {0, 1, 0};  
b3 = c {0, 0, 1};
```

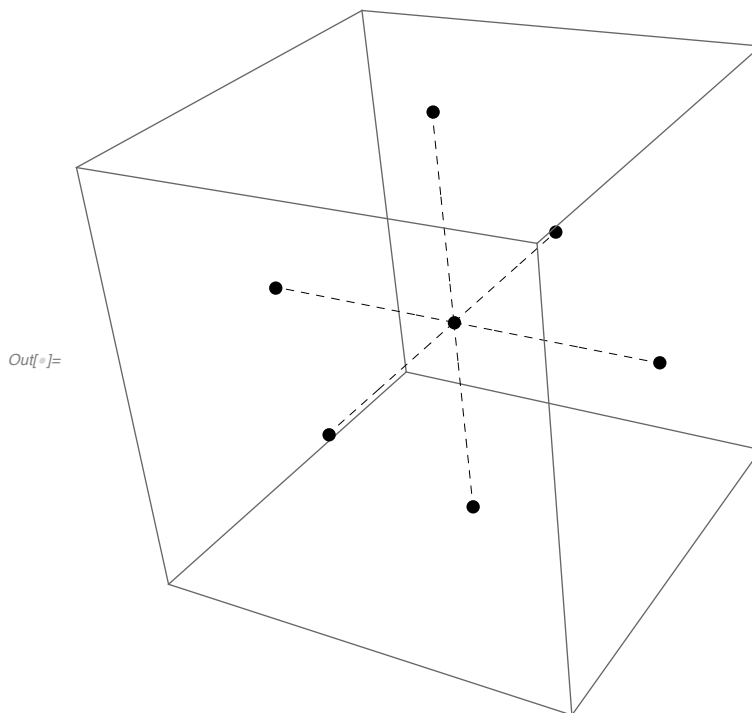
Plot origin and first neighbours

```
In[*]:= nodes = ListPointPlot3D[  
    {o, o + b1, o - b1, o + b2, o - b2, o + b3, o - b3}, Filling -> None, PlotStyle -> Black];
```

Plotting connecting lines

```
In[*]:= g1 = Graphics3D[{Arrowheads[.0], Dashed, Arrow[{o, b1}]}];  
g2 = Graphics3D[{Arrowheads[.0], Dashed, Arrow[{o, -b1}]}];  
g3 = Graphics3D[{Arrowheads[.0], Dashed, Arrow[{o, b2}]}];  
g4 = Graphics3D[{Arrowheads[.0], Dashed, Arrow[{o, -b2}]}];  
g5 = Graphics3D[{Arrowheads[.0], Dashed, Arrow[{o, b3}]}];  
g6 = Graphics3D[{Arrowheads[.0], Dashed, Arrow[{o, -b3}]}];
```

```
In[*]:= first = Show[g1, g2, g3, g4, g5, g6, nodes]
```



Adding second nearest neighbours for visualization

```

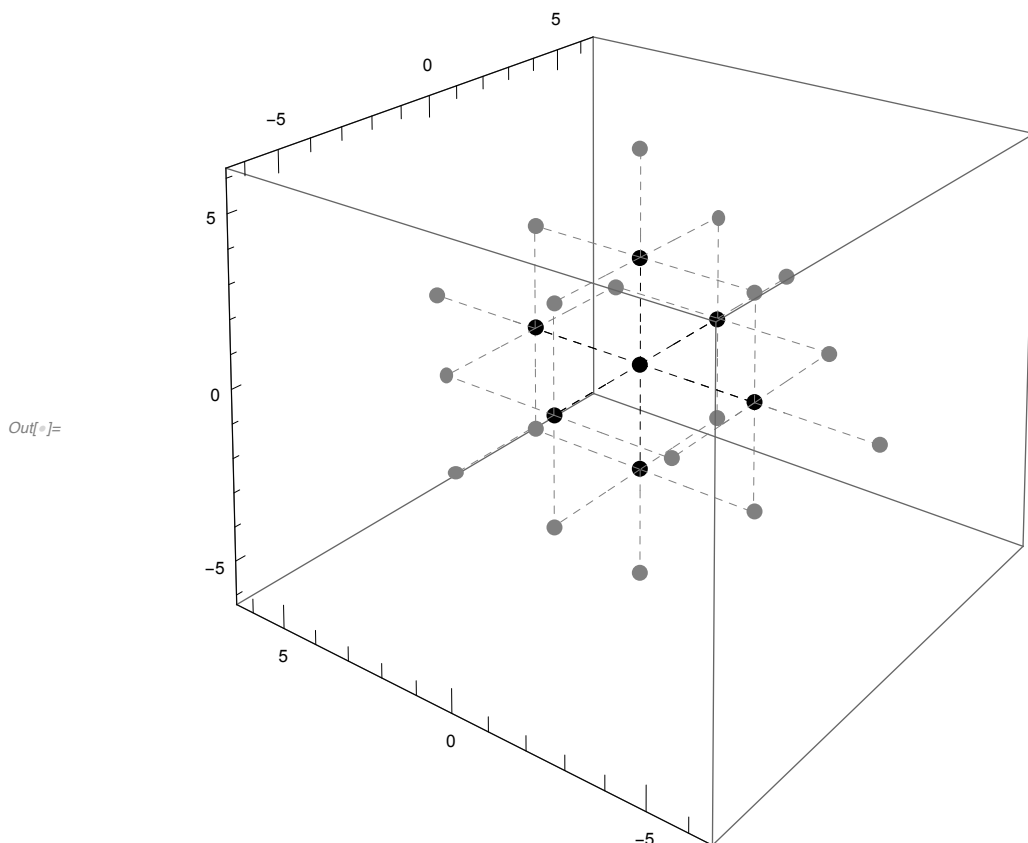
In[ ]:= nodes2 = ListPointPlot3D[
  {b1 + b1, b1 + b2, b1 - b2, b1 + b3, b1 - b3, b2 - b1, b2 + b3, b2 - b3, b2 + b2, b3 + b3,
  b3 - b1, b3 - b2, -b2 - b2, -b1 - b1, -b3 - b3, -b1 - b2, -b1 - b3, -b2 - b3},
  Filling → None, PlotStyle → Gray, PlotRange → Full];

In[ ]:= m1 = Graphics3D[{Arrowheads[.0], Dashed, Gray,
  Arrow[{b1, b1 + b1}], Arrow[{b1, b1 + b2}], Arrow[{b1, b1 - b2}],
  Arrow[{b1, b1 + b3}], Arrow[{b1, b1 - b3}], Arrow[{b2, b2 + b3}],
  Arrow[{b2, b2 + b1}], Arrow[{b2, b2 - b1}], Arrow[{b2, b2 - b3}],
  Arrow[{b2, b2 + b2}], Arrow[{b3, b3 + b3}], Arrow[{b3, b3 + b1}],
  Arrow[{b3, b3 - b1}], Arrow[{b3, b3 + b2}], Arrow[{b3, b3 - b2}]}}];

m2 = Graphics3D[{Arrowheads[.0], Dashed, Gray, Arrow[{-b1, -b1 - b1}],
  Arrow[{-b1, -b1 + b2}], Arrow[{-b1, -b1 - b2}], Arrow[{-b1, -b1 + b3}],
  Arrow[{-b1, -b1 - b3}], Arrow[{-b2, -b2 + b1}], Arrow[{-b2, -b2 + b3}],
  Arrow[{-b2, -b2 - b1}], Arrow[{-b2, -b2 - b3}], Arrow[{-b2, -b2 - b2}],
  Arrow[{-b3, -b3 - b3}], Arrow[{-b3, -b3 + b1}], Arrow[{-b3, -b3 - b1}],
  Arrow[{-b3, -b3 + b2}], Arrow[{-b3, -b3 - b2}]}}];

In[ ]:= seconds = Show[nodes2, nodes, m1, m2, g1, g2, g3, g4, g5, g6, AspectRatio → 1]

```



Define a plane normal to a vector.

$$\mathbf{n} \cdot (\mathbf{x} - \mathbf{x}_0) = 0$$

$\mathbf{n}$  is a primitive vector of the reciprocal lattice:  $b_1, b_2, b_3$

$\mathbf{x}_0$  is a point laying on the plane.

$\mathbf{x}=(x,y,z)$  is a generic vector on the plane to be defined.

The equation becomes:

$$n_x x + n_y y + n_z z = n_x x_0 + n_y y_0 + n_z z_0$$

3-dimensional plane: 2 degrees of freedom:  $z=z(f)$ . The plane equation is

$$z = \frac{n_x x_0 + n_y y_0 + n_z z_0 - (n_x x + n_y y)}{n_z} \text{ if } n_z \neq 0$$

If  $n_z=0$  the plane equation is

$$n_x x + n_y y = n_x x_0 + n_y y_0$$

then no constraints on  $z$ , and

$$y = \frac{n_x x_0 + n_y y_0 - (n_x x)}{n_y} \text{ if } n_y \neq 0 \text{ (holds true if } n_x=0 \text{ too)}$$

OR

$$x = \frac{n_x x_0 + n_y y_0 - (n_y y)}{n_x} \text{ if } n_x \neq 0 \text{ (holds true if } n_y=0 \text{ too)}$$

Thus, we can define three functions based on these considerations:

- if normal vector has  $n_z \neq 0$

```
In[ ]:= plane0[normal_, point_] :=
  Plot3D[ $\frac{\text{normal.point} - \text{normal}[[1]] x - \text{normal}[[2]] y}{\text{normal}[[3]]}$ , {x, -c/2, c/2},
    {y, -c/2, c/2}, Mesh -> None, PlotStyle -> {Yellow, Opacity[0.25]}]
```

- if normal vector has  $y$  coordinate  $\neq 0$

```
In[ ]:= plane1[normal_, point_] := ParametricPlot3D[{x,  $\frac{\text{normal.point} - \text{normal}[[1]] x}{\text{normal}[[2]]}$ , z},
  {x, -c/2, c/2}, {z, -c/2, c/2}, Mesh -> None, PlotStyle -> {Red, Opacity[0.25]}]
```

- if normal vector has  $x$  coordinate  $\neq 0$

```
In[ ]:= plane2[normal_, point_] := ParametricPlot3D[{ $\frac{\text{normal.point} - \text{normal}[[2]] y}{\text{normal}[[1]]}$ , y, z},
  {y, -c/2, c/2}, {z, -c/2, c/2}, Mesh -> None, PlotStyle -> {Blue, Opacity[0.25]}]
```

We put everything together to define a general function with three cases

```
In[ ]:= plane[normal_, point_] := If[normal[[3]] != 0, plane0[normal, point],
  If[normal[[2]] != 0, plane1[normal, point], plane2[normal, point]]];
```

Plot planes: perpendicular to primitive vectors  $\pm \mathbf{b}_1, \pm \mathbf{b}_2, \pm \mathbf{b}_3$ . The Wigner-Seitz is defined by the vectors having modulus smaller than the half distance to the center of the next cell

```

In[ ]:= p01 = plane[b1, b1 / 2];
p10 = plane[-b1, -b1 / 2];
p02 = plane[b2, b2 / 2];
p20 = plane[-b2, -b2 / 2];
p03 = plane[b3, b3 / 2];
p30 = plane[-b3, -b3 / 2];

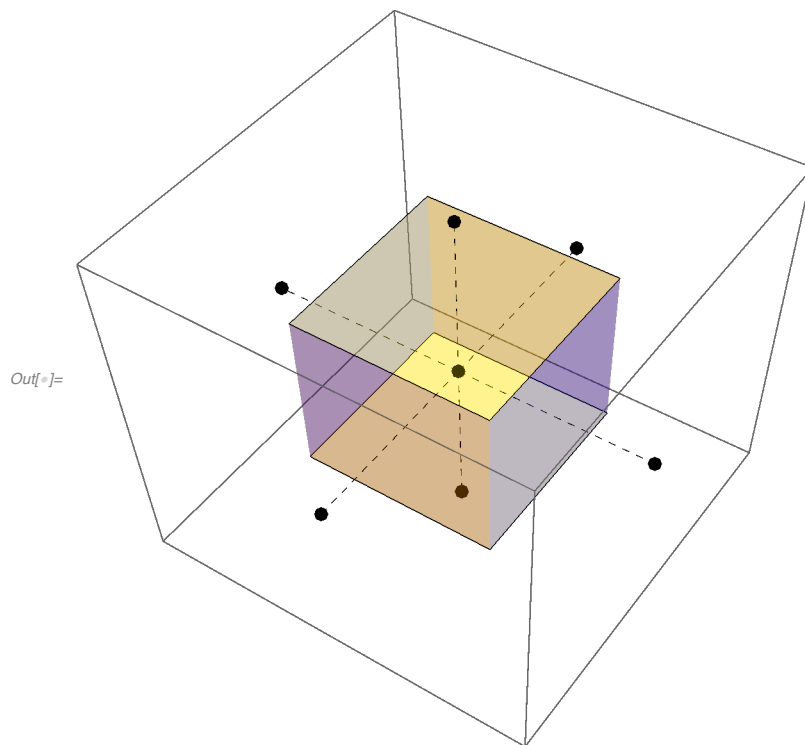
```

Plot planes on 1st neighbours

```

In[ ]:= WScell = Show[first, p01, p02, p03, p10, p20, p30, AspectRatio → 1]

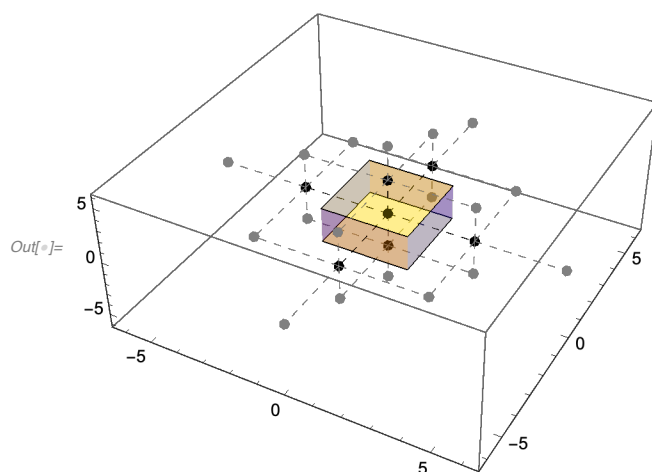
```



```

In[ ]:= Show[seconds, p01, p02, p03, p10, p20, p30, AspectRatio → Automatic]

```



Points of interest:

Gamma: **0**

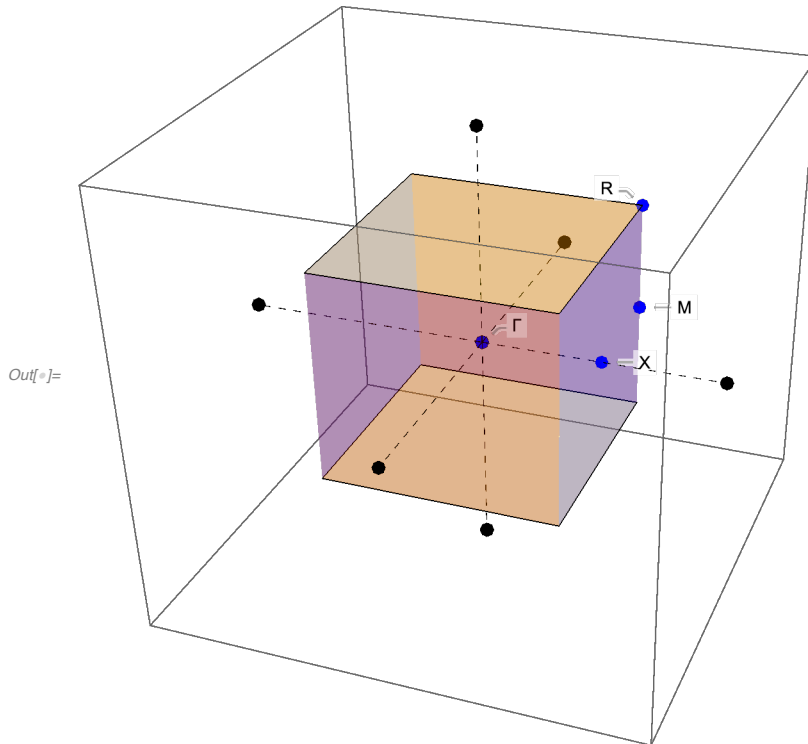
M: center of an edge

R: vertex

X: center of a face

```
In[ ]:= points = ListPointPlot3D[{Callout[o, "Γ"], Callout[b1 / 2 + b2 / 2, "M", Right],
  Callout[b1 / 2 + b2 / 2 + b3 / 2, "R"], Callout[b1 / 2, "X", Right]},
  PlotStyle → {Blue, PointSize[Large]}];
```

```
In[ ]:= Show[WScell, points]
```



## Fcc lattice

Now, same story with a fcc lattice.

Primitive vectors in the Bravais lattice

```
In[ ]:= a1 = a / 2 {1, 1, 0};
a2 = a / 2 {1, 0, 1};
a3 = a / 2 {0, 1, 1};
```

Calculate the primitive vectors of the reciprocal lattice

$$\mathbf{b}_1 = 2\pi \frac{\mathbf{a}_2 \times \mathbf{a}_3}{\mathbf{a}_1 \cdot (\mathbf{a}_2 \times \mathbf{a}_3)}$$

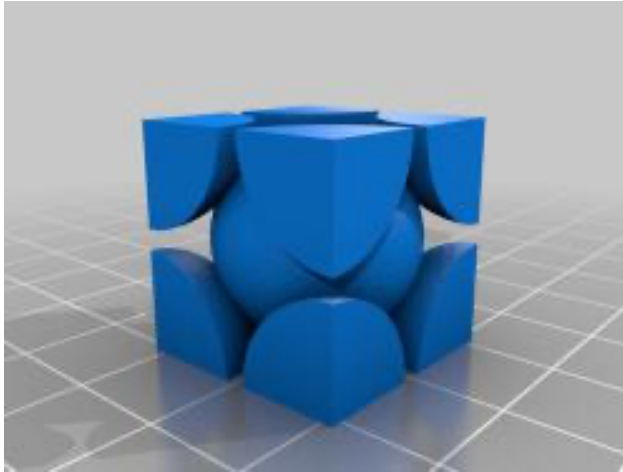
$$\mathbf{b}_2 = 2\pi \frac{\mathbf{a}_3 \times \mathbf{a}_1}{\mathbf{a}_2 \cdot (\mathbf{a}_3 \times \mathbf{a}_1)}$$

$$\mathbf{b}_3 = 2\pi \frac{\mathbf{a}_1 \times \mathbf{a}_2}{\mathbf{a}_3 \cdot (\mathbf{a}_1 \times \mathbf{a}_2)}$$

```
In[ ]:= c = \frac{2 \pi}{a};
```

```
In[ ]:= b1 = c {1, 1, -1};
b2 = c {1, -1, 1};
b3 = c {-1, 1, 1};
```

then the operations will be exactly the same as for the simple cubic lattice, but... the reciprocal lattice of a fcc cell is a bcc cell!



In rigid spheres approximation, there are **14** nearest neighbours:

- 8 atoms at the vertices of the cube
- 6 atoms at the center of the adjacent cubic cells.

Plot origin and first neighbours

```
In[ ]:= nodes = ListPointPlot3D[{o, o + b1, o - b1, o + b2, o - b2, o + b3, o - b3,
    o + b1 + b2 + b3, o - b1 - b2 - b3}, Filling -> None, PlotStyle -> Black];
halfnodes = ListPointPlot3D[{o +  $\frac{b_1 + b_2}{1}$ , -  $\frac{b_1 + b_2}{1}$ ,  $\frac{b_1 + b_3}{1}$ ,  $\frac{b_1 + b_3}{1}$ ,
    -  $\frac{b_1 + b_3}{1}$ ,  $\frac{b_3 + b_2}{1}$ , -  $\frac{b_3 + b_2}{1}$ }, Filling -> None, PlotStyle -> LightGray];
```

Plotting connecting lines between origin and first neighbours

Vertices

```
In[ ]:= g1 = Graphics3D[{Arrowheads[.0], Dashed, Arrow[{o, b1}]}}];
g2 = Graphics3D[{Arrowheads[.0], Dashed, Arrow[{o, -b1}]}}];
g3 = Graphics3D[{Arrowheads[.0], Dashed, Arrow[{o, b2}]}}];
g4 = Graphics3D[{Arrowheads[.0], Dashed, Arrow[{o, -b2}]}}];
g5 = Graphics3D[{Arrowheads[.0], Dashed, Arrow[{o, b3}]}}];
g6 = Graphics3D[{Arrowheads[.0], Dashed, Arrow[{o, -b3}]}}];
g7 = Graphics3D[{Arrowheads[.0], Dashed, Arrow[{o, b3 + b2 + b1}]}}];
g8 = Graphics3D[{Arrowheads[.0], Dashed, Arrow[{o, -b3 - b2 - b1}]}}];
```

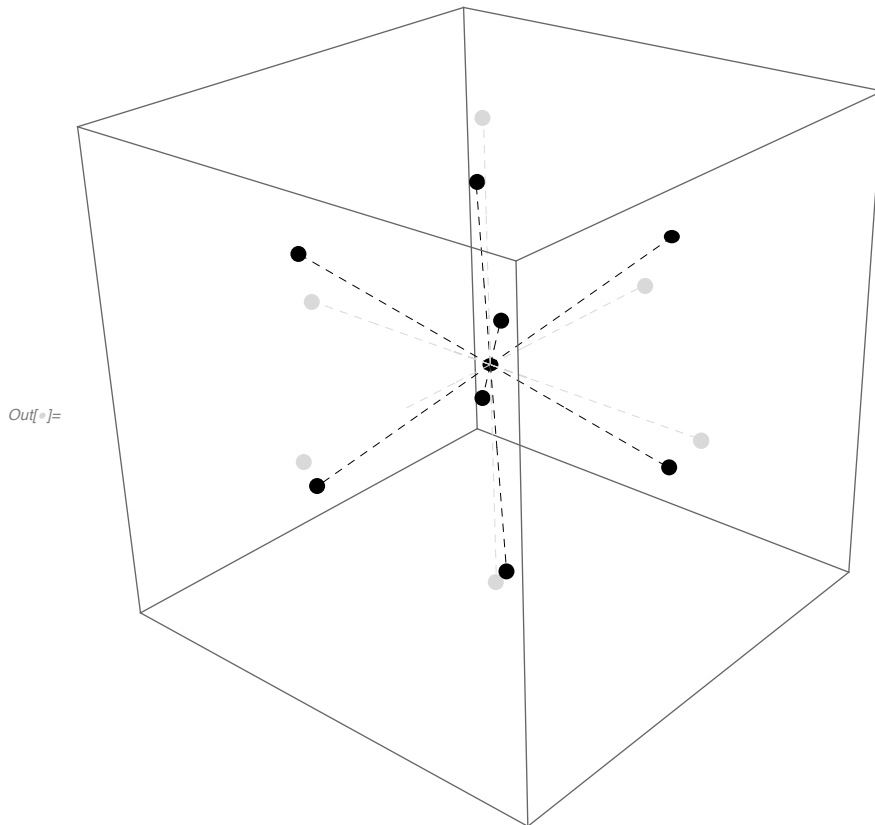
Center

```

In[ ]:= h1 = Graphics3D[{Arrowheads[.0], LightGray, Dashed, Arrow[{0,  $\frac{b_1 + b_2}{1}$ ]}]}];
h2 = Graphics3D[{Arrowheads[.0], LightGray, Dashed, Arrow[{0,  $-\frac{b_1 + b_2}{1}$ ]}]}];
h3 = Graphics3D[{Arrowheads[.0], LightGray, Dashed, Arrow[{0,  $\frac{b_1 + b_3}{1}$ ]}]}];
h4 = Graphics3D[{Arrowheads[.0], LightGray, Dashed, Arrow[{0,  $-\frac{b_1 + b_3}{1}$ ]}]}];
h5 = Graphics3D[{Arrowheads[.0], LightGray, Dashed, Arrow[{0,  $\frac{b_3 + b_2}{2}$ ]}]}];
h6 = Graphics3D[{Arrowheads[.0], LightGray, Dashed, Arrow[{0,  $-\frac{b_3 + b_2}{1}$ ]}]}];

In[ ]:= first = Show[g1, g2, g3, g4, g5, g6, g7, g8, h1, h2, h3, h4,
h5, h6, nodes, halfnodes, PlotRange -> Full, BoxRatios -> {1, 1, 1}]

```



Here, I modify the functions to plot planes. I need to select the range of each parameter to plot only the portion of plane in the region of interest. 2 DOF, each with min and max value for the plot. The mathematical equation is left unchanged

```

In[ ]:= plane0[normal_, point_, range1_, range2_, range3_, range4_] :=
Plot3D[ $\frac{\text{normal}.\text{point} - \text{normal}[[1]] x - \text{normal}[[2]] y}{\text{normal}[[3]]}$ , {x, range1, range2},
{y, range3, range4}, Mesh -> None, PlotStyle -> {Gray, Opacity[0.1]}]

```

if normal vector has y coordinate  $\neq 0$

```

In[ ]:= plane1[normal_, point_, range1_, range2_, range3_, range4_] :=
  ParametricPlot3D[{x,  $\frac{\text{normal.point} - \text{normal}[[1]] x}{\text{normal}[[2]]}$ , z}, {x, range1, range2},
    {z, range3, range4}, Mesh → None, PlotStyle → {Gray, Opacity[0.1]}]

```

if normal vector has x coordinate  $\neq 0$

```

In[ ]:= plane2[normal_, point_, range1_, range2_, range3_, range4_] :=
  ParametricPlot3D[{ $\frac{\text{normal.point} - \text{normal}[[2]] y}{\text{normal}[[1]]}$ , y, z}, {y, range1, range2},
    {z, range3, range4}, Mesh → None, PlotStyle → {Gray, Opacity[0.1]}]

```

Put together the cases to define the function

```

In[ ]:= plane[normal_, point_, range1_, range2_, range3_, range4_] :=
  If[normal[[3]]  $\neq$  0, plane0[normal, point, range1, range2, range3, range4],
    If[normal[[2]]  $\neq$  0, plane1[normal, point, range1, range2, range3, range4],
      plane2[normal, point, range1, range2, range3, range4]]];

```

Plot planes: perpendicular to primitive vectors  $\pm \mathbf{b}_1, \pm \mathbf{b}_2, \pm \mathbf{b}_3$ . The Wigner-Seitz is defined by the vectors having modulus smaller than the half distance to the center of the next cell

```

In[ ]:= p01 = plane[b1, b1 / 2, 0, c, 0, c];
p10 = plane[-b1, -b1 / 2, 0, -c, 0, -c];
p02 = plane[b2, b2 / 2, 0, c, -c, 0];
p20 = plane[-b2, -b2 / 2, -c, 0, 0, c];
p03 = plane[b3, b3 / 2, -c, 0, 0, c];
p30 = plane[-b3, -b3 / 2, 0, c, -c, 0];
p04 = plane[b1 + b2 + b3, (b1 + b2 + b3) / 2, 0, c, 0, c];
p40 = plane[-(b1 + b2 + b3), -(b1 + b2 + b3) / 2, 0, -c, 0, -c];

```

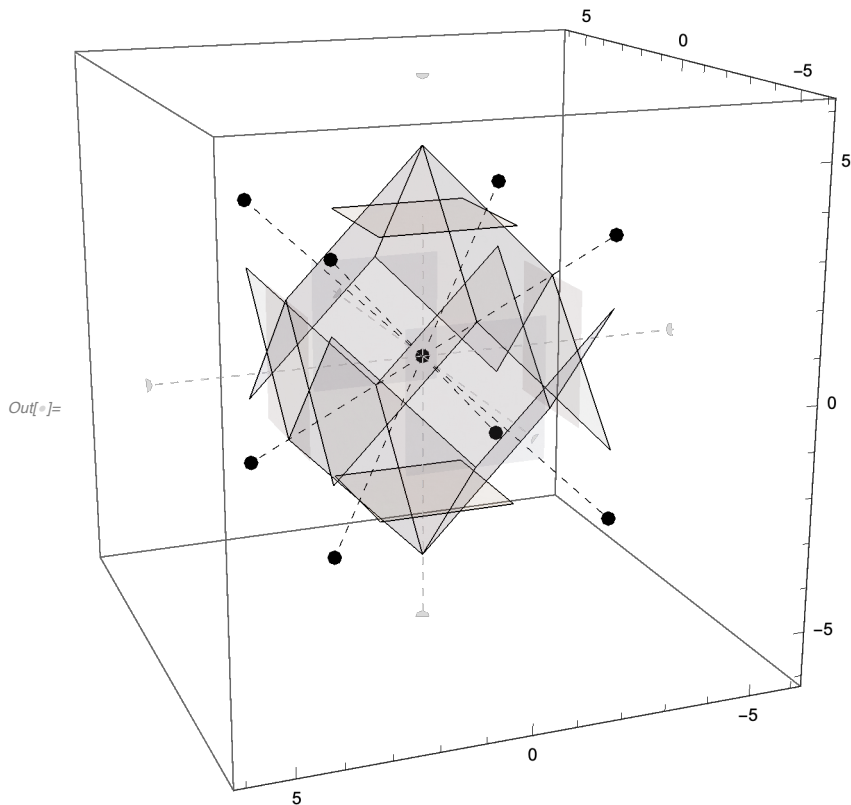
Plot planes: perpendicular to the vectors connecting the center of the adjacent cells:



```

In[ ]:= p50 = plane[(b1 + b2), (b1 + b2) / 2, -c / 2, c / 2, -c / 2, c / 2];
p05 = plane[-(b1 + b2), -(b1 + b2) / 2, -c / 2, c / 2, -c / 2, c / 2];
p60 = plane[(b2 + b3), (b2 + b3) / 2, -c / 2, c / 2, -c / 2, c / 2];
p06 = plane[-(b2 + b3), -(b2 + b3) / 2, -c / 2, c / 2, -c / 2, c / 2];
p70 = plane[(b1 + b3), (b1 + b3) / 2, -c / 2, c / 2, -c / 2, c / 2];
p07 = plane[-(b1 + b3), -(b1 + b3) / 2, -c / 2, c / 2, -c / 2, c / 2];
WScell = Show[p01, p10, p02, p20, p03, p30, p04,
  p40, p50, p05, p60, p06, p70, p07, first, AspectRatio -> 1,
  PlotRange -> {{-3 a, 3 a}, {-3 a, 3 a}, {-3 a, 3 a}}, BoxRatios -> {1, 1, 1}]

```



Gamma: **0**

M: center of an edge

R: vertex

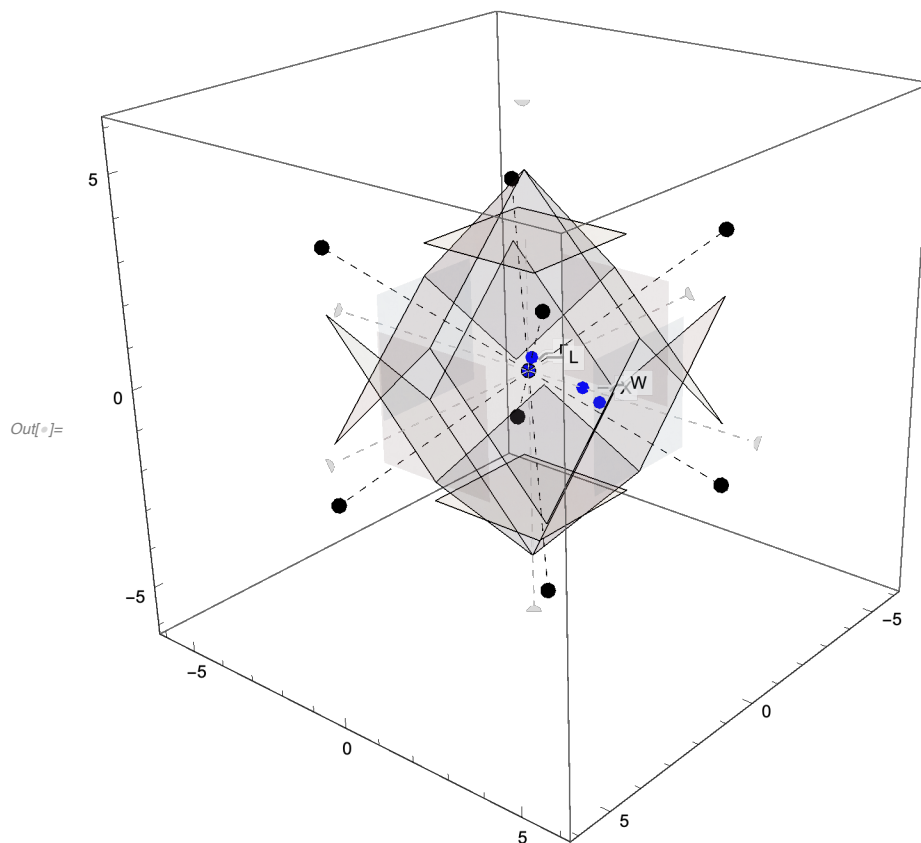
X: center of a face

```

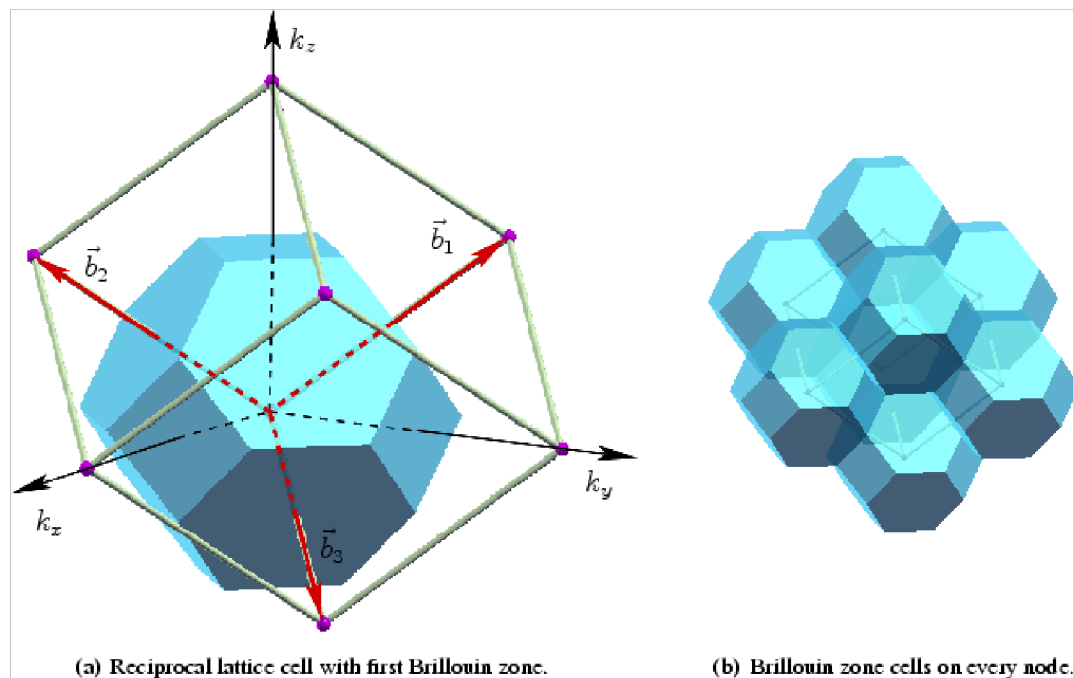
In[ ]:= points =
  ListPointPlot3D[{Callout[0, "Γ"], Callout[π / a {1 / 2, 1 / 2, 1 / 2}, "L", Right],
    Callout[π / a {1 / 4, 3 / 2, 0}, "W"], Callout[{0, π / a, 0}, "X", Right]},
  PlotStyle -> {Blue, PointSize[Large]}, BoxRatios -> {1, 1, 1}];

```

```
In[ ]:= Show[WScell, points]
```



An artist impression is still better: truncated octahedron



Points of interest:

Gamma: center of the cell:  $\Gamma = \frac{\pi}{a}(0,0,0)$

X: center of the square face  $X = \frac{\pi}{a}(1,0,0)$

X: center of the hexagonal face  $L = \frac{\pi}{a}(\frac{1}{2}, \frac{1}{2}, \frac{1}{2})$

W: vertex

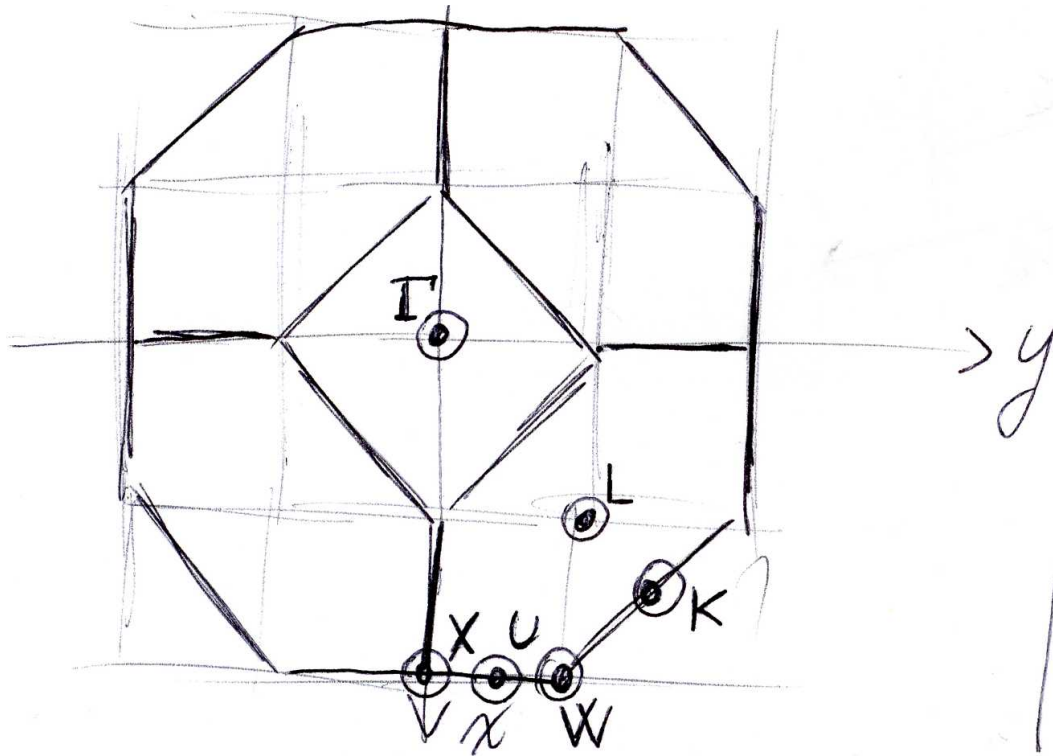
$$\mathbf{W} = \frac{\pi}{a} \left( 1, \frac{1}{2}, 0 \right)$$

U: center of a square edge

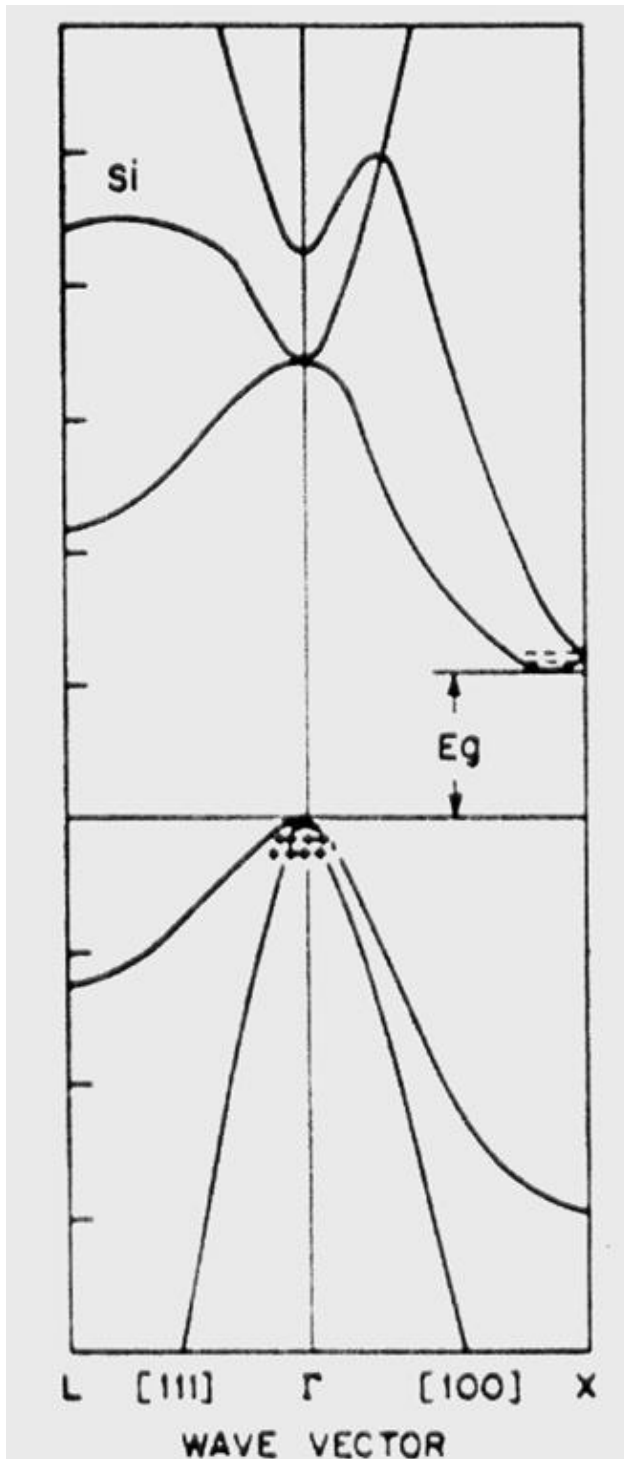
$$\mathbf{U} = \frac{\pi}{a} \left( 1, \frac{1}{4}, \frac{1}{4} \right)$$

K: center of a hexagon edge

$$\mathbf{K} = \frac{\pi}{a} \left( \frac{3}{4}, \frac{3}{4}, 0 \right)$$



Lecture notes here



Lecture notes here

