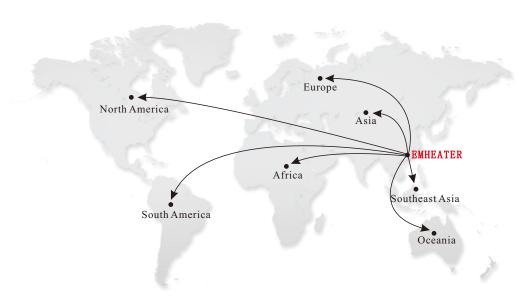
EMHEATER

User's Manual

EM-GW Series Soft Starter





China EM Technology Limited

Address: No.80, Baomin 2 road, Xixiang, Bao'an District, Shenzhen, China

Phone: 86-0755-29985851
Fax: 86-0755-29970305

Zip code: 518101

Website: www.emheater.com

Safety Clauses

Thanks for your using EMHEATER intelligent motor soft starter, this product is used for three-phase squirrel cage induction motor soft starting and soft stopping control. Before using, please carefully read and understand the contents of this manual.

In the process of using the soft starter, please note the following Safety Clauses:



Please check this user manual carefully before using the product.



Only the technical person is allowed to install the product.



To be sure that the motor is correctly matched with the soft starter.



It is forbid to connect capacitors to the output terminals (U V W).



Please seal the terminal switch insulation glue after finishing connect them.



The soft starter and its enclosures must be fixedly earthed.



During the maintenance and repair, the input must be off-power.

This user manual content may be changed due to technical reasons or modified. We reserve the updating right.

Table of Contents

1. EM-GW Series Soft Starter	
1.1 Motor soft starter profile 1.2 The main function 1.3 The main feature of soft starter 1.4 Technical specification	1 1
2. Nameplate Explanation and Inspection	3
3. Usage Condition and Installation	4
3.1 The usage condition 3.2 The installation requirement 3.3 The installation dimensions 3.4 Installation diagram	
4. Connection and External Terminal	7
4.1 The diagram connection 4.2 The external terminal 4.3 The communication interfaces	7
5. Control Panel and Operation	10
5.1 The operation of control panel 5.2 Parameters set and explanation 5.3 Parameters code function explanation 5.4 Helping message and explanation	
6. Protection Functions and Directions	15
6.1 Protection classes and explanation	
7. Test Run and Application	17
7.1 Power on to test running 7.2 The starting mode and application 7.2.1 Current-limit to start 7.2.2 Voltage ramp to start 7.2.3 Torque control + current limit or + voltage ramp to start 7.2.4 Current ramp to start	
7.2.5 Voltage current-limiting double closed-loop start	20
7.3 The stopping mode and application	
7.3.1 Soft-stopping Mode	
7.4 Special application	21
7.5 Application examples	21
Ouality Warranty	22

1. EM-GW Series Soft Starter

1.1 Motor soft starter profile

Intelligent motor soft starter, the use of intelligent digital control; With the single chip processor as the intelligence center, thyristor module for actuators for full automatic control motor. It applies various squirrel-cage asynchronous motor control of load, the motor can smooth starting under any working conditions, protect the drag system, reduce the starting current impact on power grid, ensure reliable motor starting. Smoothly soft stopping function can effectively solve the inertial system surge problem, eliminate the drag system of inertial impact, that is traditional equipment cannot be achieved. Intelligent digital motor soft start equipment system with the complete protection function, extend the service life of the system, reduce the cost of system cost, improve the reliability of system and compatible with all the functions of starting equipment; It is a new ideal alternative for traditional star triangle starter and self-coupling decompression starter.

1.2 The main function

- Effectively reduce the starting current of the motor; Can reduce the distribution capacity, avoid grid expansion investment.
- Reduce the starting stress of motor and load equipment; Prolong the service life of the motor and related equipments.
- Soft stopping function can effectively solve the parking surge problem of inertial systems; That is a traditional starting equipment cannot be achieved.
- With six unique starting mode; To adapt to the complex motor and load, achieve perfect priming effect.
- With complete and reliable protection function; effectively protect the safety of motor and related production equipment.
- Intelligent motor soft starter, the application of network technology used motor control technology to adapt to the rapid development of electric power automation technology in the higher requirements.

1.3 The main feature of soft starter

Reliable quality

- The computer simulation design.
- SMT production process.
- Good EMC performance.
- The machine before delivery on the high temperature aging, vibration test.

Perfect and reliable system protection function

- Protection of no voltage, less voltage and over voltage.
- Protection of overheating and starting time too long.
- Protection of Input phase lost, output phase lost and 3 phase unbalance.
- Protection of starting over current, running overload, and load short circuit protection.

Maintenance function

- Fault self-diagnosis(short circuit, over voltage, less voltage, one phase grounded, motor overload, one phase lost, motor blocked, and intelligent software can inspect drag system working state).
- Combination of modular design, according to the fault display content, quick troubleshooting.

Independent intellectual property products

- Independently software copyright.
- Motor starting and protection proprietary technology.
- Unique way to detect debug equipment and process.

Quick and thoughtful after-sales service

- Reliable performances lay the foundation of qualified service and quality.
- Provide perfect system solution.
- The timely and thoughtful Consulting Services.
- Constantly improve the product performance according to user's opinion.

1.4 Technical specification

Item		Description					
Input Powe		Three-phase 380V/480V/660 AC					
Supply	Frequency	50/60Hz					
Adap	otive Motor	Squirrel-cage three-phase asynchronous motor					
Star	ting Times	It is recommended not to exceed 20 times per hour.					
		(1) Operation panel control.					
		2) Operation panel + external control.					
		(3) External control.					
Con	trol Mode	(4) External control + COM control.					
Con	itioi wiode	(5) Operation panel + external + COM control.					
		(6) Operation panel + COM control.					
		(7) COM control.					
		(8) No start or stop operation.					
		(1) Current-limiting to start.					
		(2) Voltage ramp to start.					
Ste	art Mode	(3) Torque control + current-limiting to start.					
56	art Wiode	(4) Torque control + voltage ramp to start.					
		(5) Current ramp to start.					
		(6) Voltage current-limiting double closed-loop start.					
St	op Mode	(1) Soft stop.					
50	op wode	(2) Free stop.					
		(1) Open loop protection for external instantaneous stop terminals.					
		(2) Over-heat protection for soft starter.					
		(3) Protection for too long starting time.					
		(4) Input open phase protection.					
		(5) Output open phase protection.					
		(6) Unbalanced three-phase protection.					
Protect	tive Function	(7) starting over current protection.					
11000	iive i unetion	(8) Running overload protection.					
		(9) Under voltage protection for power voltage.					
		(10) Overvoltage protection for power voltage.					
		(11) Protection for fault parameter setting.					
		(12) Load short circuit protection.					
		(13) Auto restart or incorrect wiring protection.					
		(14)Incorrect wiring protection of external control stop terminals.					
	Place to be used	Indoor location with good ventilation free from corrosive gas and conductive dust.					
	Altitude	Below 1000M. It have to rise the rate power when the altitude is more than					
Ambient		1000M.					
7 1111010111	Temperature	-20 +45 °C					
	Humidity	90%RH without dew condensation.					
	Vibration <0.5G						
Structure	Protection Class	IP20					
Structure	Cooling Pattern	Fans cooling.					

2. Nameplate Explanation and Inspection

Please check up the products before using, if in some problems; please do not hesitate to contact us with any request for additional information. Check-up the type of product whether it is the right one you order.

Nameplate explanation:

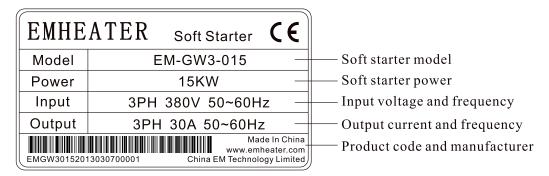


Diagram 2.1

Model explanation:

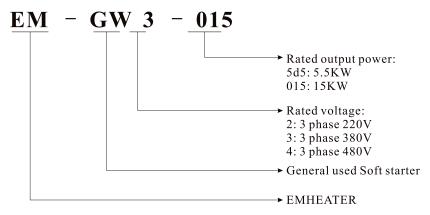


Diagram 2.2

- Check any damage to the product because of the transport, such as the spare parts are apart from the main body or the shell be damage etc.
- Check others, including the user's manual.

3. Usage Condition and Installation

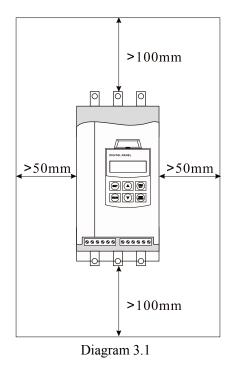
It is strict rule for the users to use or install the soft starter according to the requirement; otherwise, it will be in bad result.

3.1 The usage condition

- Power Supply: City grid power, self-provided power, diesel oil dynamotor, 3-phase alternating current 380V/480V/660V±15%, 50Hz or 60Hz. The power capacity of the soft start must meet the motor starting requirement.
- Matched Motor: Motor should be three phase squirrel asynchronous motor, and its power capacity must be matched with soft starters.
- Starting Frequency: The starting time is according to the loading equipments.
- Cooling Mode: Naturally wind cooling.
- Protective Grade: IP20
- Environment Conditions: when altitude is less than 1000m, the temperature of the environment should be between -20°C ~ 45 °C, relative humidity should be less than 90% RH, no vapor, no flammable, volatile, corrosive gas. No electric dirt, indoor installation, ventilated, vibration is less 0.5G.

3.2 The installation requirement

- The direction and distance of installation: In order to make sure that the soft starter be in good ventilation and heat dissipation, please install the product in vertical direction, and be sure the space around the product is enough. (See the following diagram 3.1)
- If the soft starter is installed in a box, please note that the ventilation is very good, as well as the above notes. (See the following diagram 3.1)



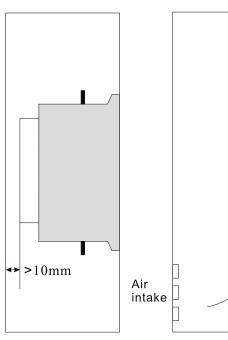
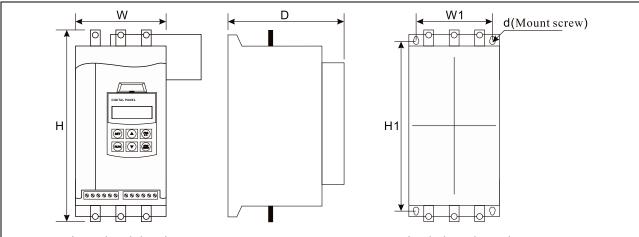


Diagram 3.2

Air out

3.3 The installation dimensions

The external shape and installation dimensions of $11 \text{KW} \sim 55 \text{KW}$.

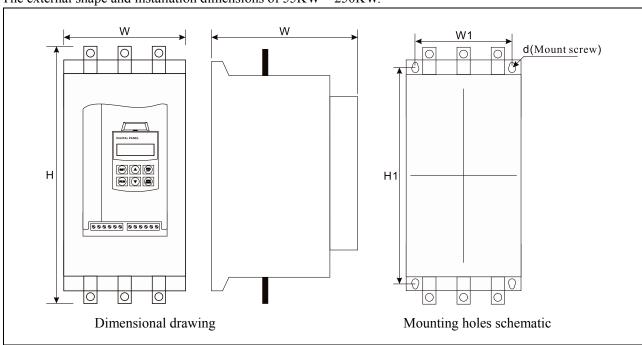


Dimensional drawing

Mounting holes schematic

Model	Power	Current	External Dimensions (mm)			Installation Dimensions (mm)			N.W
Model	(KW)	(A)	Н	W	D	H1	W1	d	(Kg)
EM-GW3-011	11	23	315	145	215	298	85	M6	<6
EM-GW3-015	15	30	315	145	215	298	85	M6	<6
EM-GW3-018	18.5	37	315	145	215	298	85	M6	<6
EM-GW3-022	22	45	315	145	215	298	85	M6	<6
EM-GW3-030	30	60	315	145	215	298	85	M6	<6
EM-GW3-037	37	75	315	145	215	298	85	M6	<6
EM-GW3-045	45	90	315	145	215	298	85	M6	<6

The external shape and installation dimensions of $55 \text{KW} \sim 250 \text{KW}$.



Model	Power	Current	External Dimensions (mm)			Installation Dimensions (mm)			N.W
Model	(KW)	(A)	Н	W	D	H1	W1	d	Н
EM-GW3-055	55	110	360	210	255	343	150	M8	<14
EM-GW3-075	75	150	360	210	255	343	150	M8	<14
EM-GW3-090	90	180	360	210	255	343	150	M8	<14
EM-GW3-115	115	230	465	330	255	440	260	M8	<30
EM-GW3-132	132	260	465	330	255	440	260	M8	<30
EM-GW3-160	160	320	465	330	255	440	260	M8	<30
EM-GW3-185	185	370	562	490	295	535	335	M8	<60
EM-GW3-200	200	400	562	490	295	535	335	M8	<60
EM-GW3-250	250	500	562	490	295	535	335	M8	<60

: The rated power of motor in the above form is the maximum rated value. Generally, the values of matched motor power capacity should not be more than this value.

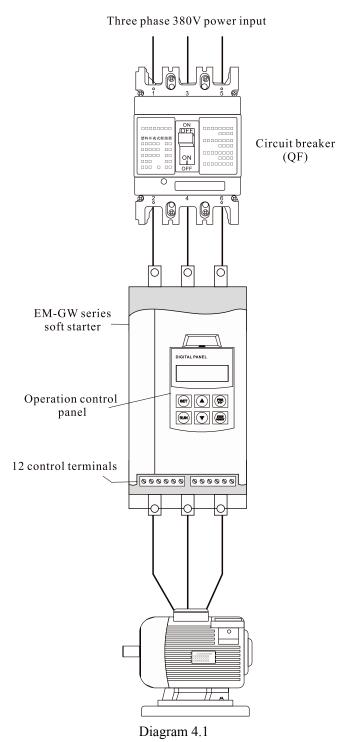
3.4 Installation diagram

The EM-GW series soft starter has three types of connection as following:

- Main circuit connection: It contains the wiring of 3-phase source input, the output to motor.
- External terminal connection: That is the wire comes from twelve external terminals which including control signal and analogue output signal.
- Communication connection: One standard RJ-45 network cable socket and one DB9 socket can be used to connect computer or network.

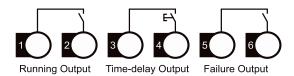
4. Connection and External Terminal

4.1 The diagram connection



4.2 The external terminal

Please see the diagram diagram 4.2:



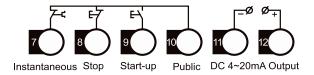


Diagram 4.2

No.	Name	Description					
12	Running (by-pass)	They are normal open contacts and are closed when finishing starting.					
1)2	output	The terminal contact capacity is AC 250V/5A.					
		The delay time is set by FE code. The output command type is set by FE code.					
(3)(4)	Programmable	They are normal open no-power terminals, being close when output valid. Please					
	relay output	see the detailed information in item 5.3.					
		This terminal contact capacity is AC250V/5A.					
		They will be closed when there are any fault matters happened to the soft starter or					
56	Fault output	ectricity lost, while at normal case they are open.					
		This terminal contact Capacity is AC250V/0.5A.					
		This terminal must be connected with terminal 10 when the starter works					
	Instantaneous stop	normally. But if these two terminals are open, the soft starter will stop, and at this					
7	input	time the starter is at the state of fault protection. This terminal 7 can be controlled					
	mpat	by the normally closed output terminals of external protection device, and it is					
		useless when the FA code is set to 0(Primary protection).					
		There are two ways of connections for your selection; those are 3-wire connection					
		and 2-wire connection, as below:					
8910	External start up or Stop input	Start-up Start-up Start-up Start-up Instantaneous					
		3-Wire connection 2-wire connection: Close K will start up Open K will stop					
		They indicate the current value of motor at real-time working. The 20mA is					
(1) (12)	DC 4 \sim 20mA	full-scale value and that is four times than rated current of nominal power of soft					
11) 12)	analog output	starter, while, we can connect a $4 \sim 20 \text{mA}$ DC current meter to check. The max					
		value of output load resistance is 300Ω .					

Note: Please make sure that external terminals are in right connection; otherwise, the product may be damaged.

4.3 The communication interfaces

RJ-45 is the standard web line socket.

DB9 socket has RS485 and RS232 interfaces inside.

Please see the diagram 4.4

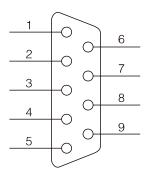


Diagram 4.4

- 1) is RS485+
- (6) is RS485-
- ② is RS232 output.
- ③ is RS232 input.
- (4) is +5V output (limit-current is 50mA)
- (5) is earthed GND.
- 789 are empty.

The user can choose the following software:

- Computer collector distribution control communication software.
- Device Net interface card and communication.
- Device Net/Mod-bus/Profi-bus gateways.
- Others.

5. Control Panel and Operation

The motor soft starter has five kinds of working state; Ready ,Run ,Error, Starting and Stopping, the showing parameter is easy to understand and modify.

5.1 The operation of control panel

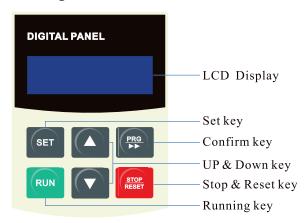


Diagram 5.1

- Open state: Please do not press the key until the ready-lamp lights and show rEAdy.
- Time-delay state: When the ready-lamp or fault-lamp is shining, it means it is interval time delay; and when the display screen shows "dEXXX" and count down, that means staring time-delay.
- The RUN or key: In the process of staring, the panel shows "XXXX" that is the value of start-up current. At this time only key is valid. And the lamps of ready, Run and Error are all dark, and you can't come into the "Set Menu" and "Help Menu" state. While, in the process of stopping, the panel shows "XXXX" that is the value of motor current. At this time, only key is valid, and the lamps of Ready, Run and Error are all dark, and you can't come into the "Set Menu" and "Help Menu" state. The key also has reset function.
- The set key: Press set key to enter the "Set Menu" and panel shows FX:XXX. Please press key again and Colon is shining, then you can change the parameters after the colon you need. If you want to save the parameter change, please press key. If you do not want to save, please press the set key until the colon stops shining, then the parameters recover. Having finished the above operation, please press the key to exit or press key to exit directly.
- The key: Under non-Set State, press the key to enter "Help Menu" and the panel shows HX: XXX. When you finish reading the "Help Menu", you can press key again or key to exit. Under Set State, This key can save parameters, and press again can exit set state.
- The "UP" A and "DOWN" key: In "Set Menu", when the colon is not shining, you can press these two keys to select the Function Code; When colon is shining, you can press these two keys to change parameters. It is the same as the operation in "Help Menu". When the Pass-by -lamp is lighting and the display Screen shows AXXX which means the operation current value of motor, now you can press "UP" or "DOWN" key and the screen will display PXXXX or HXXXX. (PXXXX means the apparent power of motor; HXXXX means the over-load heat balance coefficient, if this value is more than 100%, the screen shows Errob, that means soft starter is at state of over-load protection.)

5.2 Parameters set and explanation

The explanation for "Parameter-set" codes.

		I	T	1				
770	Setting range	30-70%	Default	30%				
F0	This code can be used when the starting mode is set as "Voltage ramp to start", and if the							
Initial voltage	motor load is heavy, please set F0=40%, or higher a little. Under "Limit-current" mode ,the F0 value will be fixed as 40%.							
	Setting range	as 40%. 2-60s	Default	16s				
F1		t soft starting process t						
Soft starting time		alid under "Limit-Curre		inie maybe shorter for				
F2	Setting range	0-60s	Default	0s				
Soft stopping time	If the code set as "0", t set "0".	the code set as "0", the motor will free stop. One soft starter for 2 motor, this code sho a "0".						
F3	Setting range	Setting range 0-999s Default						
Start-up time delay	Delay is with countdox	vn mode; If set as "0", t	he starter will start up t	he motor immediately.				
F4 *	Setting range	0-999s	Default	0s				
Programming time-delay		t delay time of 3&4 ose. (Please refer to FE						
F5	Setting range	50~500%	Default	400%				
Start-up current limited value		aring mode is "current e is "Voltage ramp to s		will be fixed as 400%				
F6 *	Setting range	50~200%	Default	100%				
Maximum current		sic on the nominal curr						
of soft starter		vill reverse to overheat		value of this code over				
F7	Setting range	40~90%	Default	80%				
Lower voltage		oltage is under the vol	tage range(80%),the s	oft starter will be low				
protection	voltage protection	· 		T				
F8	Setting range	100~130%	Default	120%				
Over voltage		ltage is over the volta	ge range(120%),the so	oft starter will be over				
protection	voltage protection	T	T	T				
	Setting range	0~5	Default	1				
	0: Limit-current to star	rt						
F9	1: Voltage ramp start 2: Torque control + lin	nit current						
Modes of starting	3: Torque control + vo							
	4: Current ramp start							
	5: Double closed loop	,						
	Setting range	0~4	Default	4				
FA	0. Primary protection							
	1. Light-load protection							
Protection Level	2. Standard protection	on.						
	3. Heavy-load protecti4. The superior level p							
	Setting range	0~7	Default	1				
	0: Run by keypad	V /	Demuit	1				
	1: Run by keypad and terminal							
FB	2: Run by terminal							
Operation control	3: Run by terminal and							
mode	4: Run by keypad, terr							
	5: Run by keypad and	KS485						
	6: Run by RS485							
	7: Inhibit start up or st	op						

FC	Setting range	0~2	Default	1				
	0: Parameter revise prohibit;							
Parameter revise	1: Partial parameter re							
	2: All parameter allow	revising. 0~63	T	T				
FD *	Setting range	0						
Communication	M 0 1							
address	Many soft starters com	nect with upper compu	ter.					
FE*	Setting range	0~19	Default	6				
Programming		T. 5.0						
output	Setting the detailed in	Item 5.3						
FF*	Setting range 20~100% Default 80%							
Soft-stopping								
limited current	Setting the detailed in	Setting the detailed in Item 7.3						
	Setting range		Default	Rated value				
FP		l						
Motor rated current	"The rated current of motor" is the same as the motor nominal current. If your motor rated power is much lower than soft starter, please revise the FP same as motor rated current. And							
	then soft starter can pro-							
FU *	Setting range	0~99s	Default	5s				
Running or By pass	This parameter can del	av soft starter switching	to bypass contactor ti	me. If soft starter starts				
suck time	very heavy fan or pum	p, please set the param	eter to 10 or 15 second	ls.				
FL *	Setting range	0~1	Default	1				
3 phase balance	0: Invalid							
valid	1: Valid							
FM *	Setting range	50~150%	Default	100%				
Current coefficient	Showing current slants high, to set coefficient down; Lower conversely							
FN *	Setting range	50~150%	Default	100%				
voltage coefficient	Showing voltage slants	s high, to set coefficien	t down; lower convers	ely				
_								

Note:

- F6 the "Max working current", is basic on the value of FP (nominal current of motor).
- If you have no any operation for 2 minutes after you come into the "set" state, soft starter will exit from "set" state.
- You can not set any parameters in the process of starting or stopping.
- If you press the key to power on soft starter, all parameters will recover to default setting except FE code. When FC=1, these parameters with "*" is prohibited to revise. When FC=2, all parameters can be revised.

5.3 Parameters code function explanation

The parameter Fb is used to set the control ways of soft starter; as the following form:

Numerical value	0	1	2	3	4	5	6
Keypad	1	1	0	0	1	1	0
External terminal control	0	1	1	1	1	0	0
RS485 Communication	0	0	0	1	1	1	1

Note: In the above form,"1" is allowing,"0" is forbidding. For example, If you press keypad "RUN", and meet Err 14, please set Fb=0. And then soft starter can be run by keypad.

If the "External Control" is allowing, you must contact a normally closed switch button between the terminal (7)(8) and terminal (10), otherwise the soft starter can't start-up the motor and show "Erro 1/Err 16".

The number setting by FE	The moment of programmable relay output	
0(10)	When sending the order of starting, the program output	
1(11) When beginning to start, the program output		
2(12) When at the start of bypass operation, the program output		
3(13)	When sending the order of stopping, the program output	

The parameter **FE** is use to setting the way of 3&4 programmable relay output, As the following form:

If users need programmable relay output time delay, the time can be setting by parameter F4.

• When the FE is setting as 5~9(15~19), the terminal ③&4 will display the state of programmable relay output. As the following form:

When finishing the operation of stopping, the program output

The number setting by FE	The state of programmable relay output
5(15)	Error state
6(16)	Working state
7(17)	Ready state
8(18)	Starting state
9(19)	By-pass operation state

- The state of programmable relay output is used to show the working state of soft starter, and under this way, the **F4** setting delay time is invalid;
- The default setting of **FE** code is "7" showing the ready state of soft starter and at this state the motor can be started up;
- When the **FE** code is "5" outputting error state of motor, Terminal ③ ④ can output fault such as: (ErrO5, ErrO6, ErrO7, ErrO8, Err 12, and Err 15). This will not affect the function of ⑤⑥ error output terminals.
- When FE >9, the programmable output will be "reverse phase output", (Normal open will reverse to normal close).
- When **FE** =0, all parameters cannot be revised. And when **FC**=1, (F4,F5,Fd,FE,FF,FU) cannot be revised. When **FC**=2, all parameters can be revised.

5.4 Helping message and explanation

4(14)

When the product is not starting or stopping ,or not at the "set" state, you can press key and come into helping menu ,then press the "UP" or "DOWN" key to choose the help message. Please press or key to return. Helping message Form

Message displayed	Explanation			
U0380	That is the 3-phase power voltage is AC 380V.			
030-3	That is the specification is AC 380V, 50Hz, 30A.			
H (EO I	The fault message Err01 that happened at the last time.			
:				
H9E00	It says no fault happened.			
UA-3.0	It says the software of the products is Ver3.0.			
L0000	□□□□ is times of successful soft starting			
RUNDO	□□ is last soft starting time			
Note: The message H1 ~ H	Note: The message H1 ~ H9 displayed means 9 faults records that happened lately.			

• Not in state of soft starting and stopping, and not in setting state, to press key to enter helping menu, and

press "UP" or "DOWN" key to choose helping information.

• Under state of helping, to pres key of key to quit helping menu.

6. Protection Functions and Directions

We make our soft starters have all kinds of protection functions to protect the safety of soft starter and the motor. Please choose the correct protection Class and parameters according to your application conditions!

Over-heat protection: When soft starter inside temperature is up to $80^{\circ}\text{C} \pm 5^{\circ}\text{C}$, the starter will turn to over-heat protection, when be down to 55 °C, this protection removes.

- Input less-phase protection: The delayed time < 3s
- Output less-phase protection: The delayed time < 3s
- Three-phase unbalance protection: The delayed time < 3s, when the difference of current among three phrases is more than $50\% \pm 10\%$, the protection be valid.
- Starting over-current protection time: The diagram of over current 5 times of **F6** set rated working current is just as diagram 6.1.
- Working over-load protection time: The starter will be in inverse time thermal protection on. Base of the Max working current of motor (Set by **F6**), (The diagram 6.1 show)
- Low voltage protection delay time: When power voltage is less than 40%, the protection delayed time < 0.5s; When power voltage is less than 80%, the protection delayed time < 3S.
- Over-voltage protection delay time: When power voltage is more than 140%, the protection delayed time < 0.5S; When power voltage is more than 120%, the protection delayed time < 3S.
- Loads short-circuit protection delay time: The protection delayed time < 0.1S.

6.1 Protection classes and explanation

According different usage conditions, EM-GW series Soft Starter has five protection classes, as following:

- 0. Primary protection
- 1. Light-load protection
- 2. Standard protection
- 3. Heavy-load protection
- 4. The superior protection
- Primary protection includes the protection functions of overheat, short circuit, and input default phase protection
 and prohibit external instantaneous stop terminal. Which is proper urgently startup conditions, such as fire pump.
- The protections of light load, standard and heavy-load have the overall protection function of soft starter. The difference among them is protection level of overload and over current. See the diagram of 6.1.
- Under the superior protection, the soft starter has a higher protection level.
- The protection classes and the time of heat protection as (diagram 6.1)

FA code	0:Basic protection	1:Light-load protection	2:Standard protection	3:Heavy-load protection	4:Superior protection	Note
The grade of overload protection	No	2 grade	10 grade	20 grade	10 grade	Standard of IEC60947-4-2
The grade of over-current protection	No	3 Second	15 Second	30 Second	15 Second	The 5 times of F6 current

FA code	0:Basic protection		ight-l otecti			tand otect			eavy- otect	load ion		Super otect		Note
Overload drop-away time	The multiple to the rated current	3	4	5	3	4	5	3	4	5	3	4	5	They are the typical values
	Drop-away time (S)	4.5	2.2	1.5	23	12	7.5	46	23	15	23	12	7.5	

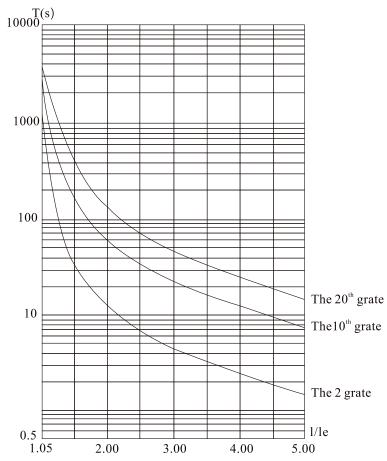


Diagram 6.1 (IEC60947-4-2 standard) Motor heat protection curve (overload drop-away time)

Remark:

• **FP** set value should be same as motor nameplate rated current.

The **FP** set value should not be less than 20% of soft starter rated current, otherwise the overheat protection will be useless because of big tolerance.

7. Test Run and Application

Please do some examinations before test running as following:

- Whether the rated power of soft starter is matched with the Motor.
- Whether the insulation of motor meets requirement.
- Whether the main circuit connection of input and output is correct.
- Whether all the screws of terminals are twisted tightly.

7.1 Power on to test running

- After Power on, please do not disassemble the soft starter cover that is dangerous!
- Power on, soft starter displays rEAdY, and the Ready is light, then you can press key to start.
- Set **FP** be same as motor nameplate rated current.
- After started the motor, you should examine whether the motor running direction is correct, or whether runs normally. If not, you can press key or cut off the power to stop running.
- If the soft starter starting state is not satisfied. Please see the detailed explanation at 7.2: the starting mode and application
- If the start torque is not enough, you can change the starting voltage (when the starting mode is voltage control) or the certain current value (when the mode is current control) to improve start torque.
- Do not open the face cover in case of electric shock.
- If there is any abnormal voice, smoke or taste, please cut off power as soon as fast, and check the reason.
- When the starter power on or be in starting, the error lamp is lighting and screen displays "Err??", at this time, you can check diagram 7.1 to find out reason.
- Press key or external stop button can reset the error state.

Note: When ambient temperature is less than -10°C, the starter should be power on to preheat for 30 minute, and then to start.

Error Code	Error 00	Fault Type	The fault is removed			
Reason and	Any faults are removed, such as low-voltage, over-voltage, over-heat. Now the Ready-lamp is					
solution	lighting and you can start the motor.					
Error Code	Error 01	Fault Type	The external instantaneous stop terminal is open			
Reason and	Please connect the external instantaneous stop terminal (terminal 7) and stop terminal 8 with					
solution	the public terminal (terminal 10) together.					
Error Code	Error 02	Fault Type	The soft starter is over heat			
Reason and	The soft starter is started too frequently, or the soft starter rated current is smaller than motor, or					
solution	motor is heavy over load.					
Error Code	Error 03	Fror 03 Fault Type The starting time is over long, which is longer than 60s.				
Reason and	The starter parameter is set wrong; or the motor load is heavy, or voltage transformer capacity is					
solution	not enough: or power supply cable is too long. If soft starter capacity is enough and load is hea					
Solution	fan or pump, please set FU to 10 or 15 second.					
Error Code	Error 04	Fault Type	Input phase failure			
Reason and	Please check whether the input circuit connections, bypass contactor and the controlled silicon is					
solution	open or whether the thyristor wire is not connected.					
Error Code	Error 05	Fault Type	Output phase-failure			

	Please check whether the output circuit connection, bypass contactor and the controlled silicon								
Reason and	are short circuit, or whether the thyristor wire is connected well; The power supply should								
solution			ontactor should connect with L1,L2,L3; If motor KW is much						
Б С 1	smaller than soft starter, please set parameter FA=2.								
Error Code	Error 06		Three-phase unbalance						
Reason and	Please check the input three-phase power voltage is balance or not, and check the motor 3phase								
solution	is abnormal. Or se	t parameter F	C=2 and E1=0.						
Error Code	Error 07	Fault Type	Starting over current						
Reason and solution	Overload, or the motor is not matched with the soft starter.								
Error Code	Error 08	Fault Type	Running over load						
Reason and solution	Overload or the F5 code is set wrong.								
Error Code	Error 09	Fault Type	Low voltage						
Reason and solution	Please check the voltage of input power or the F7 item is set wrong.								
Error Code	Error 10	Fault Type	Over voltage						
Reason and solution	Please check the voltage of input power or the FB item is set wrong.								
Error Code	Error 11	Fault Type	The parameters are set wrong						
Reason and	Please change the parameter correctly, or you can press the key to power on the starter								
solution	again to recovery the default setting.								
Error Code	Error 12	Fault Type	Load short circuit						
Reason and solution	Check load and the controlled silicon is short circuit or overload.								
Error Code	Error 13	Fault Type	The wiring of automatic Re-start is wrong						
Reason and solution	The external terminals is not connected according the 2-wire way.								
Error Code	Error 14	Fault Type	The wiring of external terminal is wrong						
Reason and	Change Fb=0,When external control mode is allowing, the external stop terminal is open, and								
solution	soft starter cannot start.								
Error Code	Error 15	Fault Type	Motor less load						
Reason and solution	Please match the appropriate motor.								
Error Code	Error 16	Fault Type	(8),(10) terminal open circuit						
Reason and solution	Please check and connect(8) (10)								
Note: When the motor starts successfully, 1 and 2 will close to suck by pass contactor running. At this time,									

Note: When the motor starts successfully, ① and ② will close to suck by pass contactor running. At this time, if the contactor is not closed, the motor will stop running, so you can check whether the wiring of the bypass contactor is right.

7.2 The starting mode and application

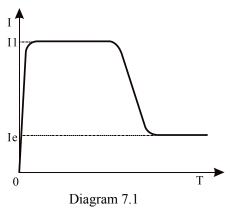
The EM-GW series soft starter has six starting modes for the user to select according the motor and load equipments.

7.2.1 Current-limit to start

(The F9 code is set as"0") Diagram 7.1 shows the waveform of motor current . I1 is the starting limit-current preset

value. When starting, the output voltage rises quickly till the motor current up to I1 value and not beyond this value. The motor runs steadily in pace with the rising of output voltage, and when the motor runs to be the rated speed, the output current will have a quick-drop and down to the motor rated current (Ie value), then the bypass contactor is working, the stating process finished.

Note: When motor load is too light or I1 preset value is too high, the max current of starting may can not reach I1 value. This starting mode fits for the conditions which requires strict current limit of starting.



7.2.2 Voltage ramp to start

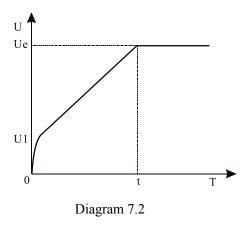
(The F9 code is set as"1") Diagram 7.2 shows the output voltage waveform. In the diagram, the U1 is the initial voltage value of starting. When starting, if the motor current is not more 400% than the rated current, the output voltage of soft starter will rapidly rise to U1, and the output voltage rises gradually to the rated voltage (Ue), and the motor gradually increase and until running at rated voltage and speed, and then the bypass contactor closed, the starting process finished.

Starting time "T" is obtained in the standard experiment under the condition of soft starter with standard load. And soft starter takes this control parameters as a benchmark, smooth acceleration by controlling the output voltage to motor starting process to complete, not mechanically controlled time "T"

and regardless smooth of whether the motor speed. In view of this, when the load is lighter, starting time are often less than the set starting time, as long as can smooth starter is normal

In general, the voltage ramp is generally used mode; it is suitable for requiring higher starting stability without strictly current limitation case.

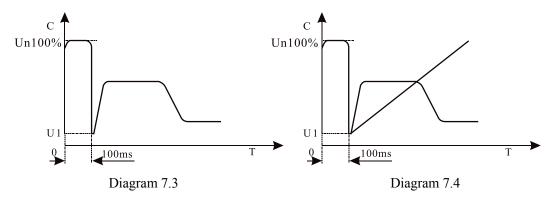
Note:"T" is the automatic detecting starting time according to load. It will be less than set time when the load equipments are light; this starting mode fits for the common occasions where the motor need to be started smoothly.



7.2.3 Torque control + current limit or + voltage ramp to start

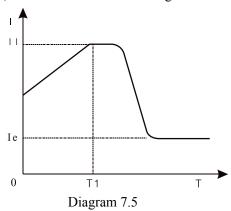
(The F9 code is set as "2" or "3") Diagram 7.3 and 7.4 shows the output changing waveform of torque control starting mode. When the static friction force of heavy load is too stronger to start the motor, user can use this starting mode. At first state of starting, the motor needs a higher voltage to conquer the static friction force of heavy load, and then starts with current-limit or voltage ramp mode to start the heavy motor.

Note: This mode will cause big-current shock to the motor, so if the voltage ramp or current limit starting mode can startup the motor, it is better not to use this torque control mode to start.



7.2.4 Current ramp to start

(The F9 code is set as"4") Diagram 7.5 shows the output current waveform. The I1 in the diagram is current value preset by F5 code, and T1 is time value present by F1 code. This starting mode has very stronger speed-up ability and is suit for the bipolar motors, and it can reduce the starting time.



7.2.5 Voltage current-limiting double closed-loop start

(Both voltage ramp and current limit) to start (The F9 items set as"5"). This starting mode uses voltage ramp and current limit double closed loop circuit; it is a composite starting mode. The output voltage waveform is changed as different motor and the load equipments. This mode fits for smooth starting and strictly current limit occasions.

7.3 The stopping mode and application

The soft starter has two stopping modes; those are Soft-stopping mode and Free-stopping mode.

7.3.1 Soft-stopping Mode

(The F2 item is not set as"0") When using this mode to stop the motor, the power supply of motor will be transferred from the bypass contactor to the controlled silicon of soft starter, and the output voltage of starter will be reduced gradually so that the running speed of motor can be cut down smoothly avoid mechanical shock. The output ending voltage is the same as the starting initial voltage. Soft-stopping mode can reduce or remove the surge of the loading equipments such as the water pump.

You can set the soft-stopping current limit value through the FF code to reduce the high current shock to the motor when stopping. This current limit value is percentage of F5.

7.3.2 Free-stopping Mode

(The FZ code is set as"0") When using this mode to stop the motor, the soft starter will cut off the connection to the bypass contactor and forbid the controlled silicon output voltage after receiving stopping command. The motor

stops gradually with its inertia. One soft start connecting with two motors must use this free stopping mode. Generally, if the soft stopping mode is not necessary, please choose the free stopping mode to prolong the service life of soft starter. This mode completely forbids the instantaneous output; avoid instantaneous high current shock to the motor of specially applying.

7.4 Special application

- In parallel the starting of the motors: If the motors total power is less than 80% of soft starter, the motors can be parallel connection. But at this time should be also provides for each motor thermal protection device.
- **Double speed motor:** Motor soft starter can cooperate with double speed motor starting, must go through demagnetization delay period before change from low speed to high speed, to avoid anti-phase current generated between the lines and motor.
- Too long cable: f the cable is too long, the cable voltage drop will be high, and that will increase current loss and reduce starting torque, so please use big KW soft starter and motor.
- Soft starter parallel connected with one power-line: If several soft starter parallel installed in the one power line, the input line reactor should be installed in the middle of the transformer and the soft starter circuit. Reactor should be installed at each line input side between circuit breaker and soft starter.
- The application of surge protection device (SPD): The surge protection device should be considered to installed in the application case, where is easily caused trouble by lightning or other reasons, such as over voltage, over-current, surge interference. Please refer to SPD related documents for details.

7.5 Application examples

The parameters of the different loads are different, please refer to diagram 7.2.

The loading	Voltage ramp starting time(s)	Voltage ramp stopping time(s)	Initial voltage	Voltage ramp (current limit)	Current limit to start
Ball mill machine	20	6	60%	400%	350%
Fan	26	4	30%	400%	350%
Centrifugal	16	20	40%	400%	250%
Piston compressor	16	4	40%	400%	300%
hoister	16	10	60%	400%	350%
Stirring machine	16	2	50%	400%	300%
Breaker	16	10	50%	400%	350%
Screw compressor	16	2	40%	400%	300%
Rotating conveyor	20	10	40%	400%	200%
Light load	16	2	30%	400%	300%
Convey belt	20	10	40%	400%	250%
Heat pump	16	20	40%	400%	300%

Quality Warranty

The warranty of soft starter is as follows:

(1) Warranty period under normal conditions.

We provide guarantees for repair and replacement in 1 month from the date of use.

We provide guarantee for repair in 12 months from the date of use or 18 month from the date of ex-factory.

- (2) The purchaser enjoys life-long paid service whenever and wherever he uses a motor soft starter made in our company.
- (3) Service in the following cases, even within the warranty period, shall be charged to the purchaser:

Problems caused by mal-operation in violation of this manual, or caused by unauthorized repair or renovation.

Problems caused by improper use of soft starter that is off standard and requirement;

Malfunction or damage caused by improper transit or storage after purchase;

Induced failure or aging of the device due to poor ambient;

Malfunction or damage caused by fire, flood, thunder, earthquake, abnormal voltage or other natural disasters;

Unidentifiable nameplate, mark and ORD number due to intentional spoilage;

Delayed or unsatisfied payment in violation of purchase appointment;

Fail to give an objective description on the use of installation, wiring, operation, maintenance or else;

- (4) Defective products should be sent to us for repair, replacement and return, which can be proceeded only after verifying the burden of liability.
- (5) In case there is any quality problem or accident, we merely promise to bear the above-mentioned responsibilities. If a user needs more guarantees for liabilities, please assure on the insurance company voluntarily.

Product Warranty Card									
	Company address:								
Customer Information	Company Name:	Contact Person:							
	Post Code:	Tel:							
	Product model:								
Product information	Body barcode (Attach here):								
	Name of agent:								
Failure information	(Maintenance time and conte	nt):							
	Maintenance personnel:								