ФЕДЕРАЛЬНОЕ ГОСУДАРСТВЕННОЕ АВТОНОМНОЕ ОБРАЗОВАТЕЛЬНОЕ УЧЕРЕЖДЕНИЕ ВЫСШЕГО ОБРАЗОВАНИЯ

«Санкт-Петербургский политехнический университет Петра Великого»

ИНСТИТУТ КОМПЬЮТЕРНЫХ НАУК И ТЕХНОЛОГИЙ Высшая школа программной инженерии

Отчет по лабораторной работе по дисциплине «Вычислительная математика»

Выполнила студентка гр. 3530904/80001

Прохорова А. И.

Руководитель

Устинов С. М.

 $ext{Caнкт-}\Pi$ етербург 2020

1 Задание

Для таблично заданной функции f(x)

X	-1.0	-0.9	-0.8	-0.7	-0.6	-0.5
f(x)	0.5440	-0.4121	-0.9894	-0.6570	0.2794	0.9589

построить сплайн-функцию и использовать её для нахождения корня уравнения $f(x) = 1.8 \cdot x^2$ на промежутке [-1, -0.5] методом бисекции.

2 Результаты работы программы

```
Original function f(x):
-1; 0.544
-0.9; -0.4121
-0.8 ; -0.9894
-0.7; -0.657
-0.6; 0.2794
-0.5; 0.9589
Spline coefficients:
spline 0: -9.4901; -9.55729; 88.4833
spline 1: -8.74706; 16.9877; 127.529
spline 2: -1.52365; 55.2465; -67.7
spline 3: 7.49465; 34.9365; -162.429
spline 4: 9.60906; -13.7923; -143.483
spline 5: 2.5461; -56.8373; -143.483
Function given by equation f(x) = rightPart(x)
-1; -1.256
-0.9 ; -1.8701
-0.8; -2.1414
-0.7; -1.539
-0.6; -0.3686
-0.5; 0.5089
Number of roots: 1
-0.55
```

3 Приложение

3.1 Код lab1.hpp

```
#ifndef COMPUTATIONAL_MATH_LAB1
#define COMPUTATIONAL_MATH_LAB1

#include <iosfwd>
#include <vector>

#define CUSTOM_EPSILON 1e-7

struct point_t
{
    double x;
```

```
double y;
12
13 };
14
  struct function_t
15
16 {
17
    std::vector<double> x;
18
    std::vector<double> y;
19
    function_t();
20
    function_t(size_t n);
21
22
    size_t size() const;
23
    double* X();
24
    double* Y();
^{25}
26 };
27 std::istream& operator>>(std::istream& in, function_t& function);
28 std::ostream& operator<<(std::ostream& out, const function_t& function);
^{29}
30 struct spline_t
31 {
32
    std::vector<double> b;
    std::vector<double> c;
33
    std::vector<double> d;
34
35
    spline_t(size_t n);
36
37
    double* B();
    double* C();
38
    double* D();
39
40
    size_t size() const;
41 };
42 std::ostream& operator << (std::ostream& out, const spline_t& factors);
43
44
45
46 #endif // COMPUTATIONAL_MATH_LAB1
```

3.2 Код lab1.cpp

```
1 #include <iostream>
2 #include <iomanip>
3 #include <algorithm>
4 #include <iterator>
6 #include "../cmath.h"
  #include "lab1.hpp"
9 double RightPart(double x)
11
    return 1.8 * x * x;
12 }
13
  double bisection(function_t& function, spline_t& factors,
14
      double leftX, double rightX, double (*rightPart)(double))
15
16
    double middleX = -1;
17
    double middleY = -4;
18
    int last = 5;
19
^{20}
    while (abs(middleY) > CUSTOM_EPSILON)
21
^{22}
      middleX = (leftX + rightX) / 2;
^{23}
      middleY = seval(function.size(), middleX,
24
```

```
function.X(), function.Y(),
25
           factors.B(), factors.C(), factors.D(), &last) -
26
           rightPart(middleX);
27
28
      double rightY = seval(function.size(), rightX,
29
           function.X(), function.Y(),
30
           factors.B(), factors.C(), factors.D(), &last) -
31
^{32}
           rightPart(rightX);
      double leftY = seval(function.size(), leftX,
33
           function.X(), function.Y(),
34
           factors.B(), factors.C(), factors.D(), &last) -
35
           rightPart(leftX);
36
37
       if (leftY * rightY > 0)
38
39
40
         std::cout << leftY << " " << rightY << "\n";
         throw std::runtime_error("LeftY and RightY must be of different signs.");
41
42
43
      if (leftY * middleY < 0)</pre>
44
      {
45
        rightX = middleX;
46
47
      else if (middleY * rightY < 0)</pre>
48
        leftX = middleX;
49
50
      }
51
      else
52
         throw std::runtime_error("middleY must have different sign with one of the
53
      border.");
      }
54
    }
55
56
    return middleX;
  }
57
58
59
  int main()
61
62
  {
63
    function_t function;
    std::cin >> function;
64
    std::cout << "Original function f(x):\n" << function << "\n";
65
66
67
    spline_t factors(function.size());
68
69
    int flag = 0;
    spline(function.size(), 0, 0, 0, function.X(), function.Y(), factors.B(),
70
      factors.C(), factors.D(), &flag);
    if (flag != 0)
71
72
      std::cout << "Error occured in spline function.\n";</pre>
73
74
      return 1;
    }
75
    std::cout << "Spline coefficients:\n" << factors << "\n";</pre>
76
77
78
    function_t newFunction(function.size());
79
    std::copy(function.x.begin(), function.x.end(), newFunction.x.begin());
80
    int last = 0;
81
    std::transform(newFunction.x.begin(), newFunction.x.end(), newFunction.y.begin(),
82
         [&](double x){
             return seval(function.size(), x,
83
               function.X(), function.Y(),
84
               factors.B(), factors.C(), factors.D(), &last) -
85
```

```
RightPart(x);
86
            });
87
88
     std::cout << "Function given by equation <math>f(x) = rightPart(x) \setminus n" << newFunction << "
89
       \n";
90
91
     std::vector<double> ans;
92
     for (int i = 1; i < newFunction.size(); ++i)</pre>
93
       if (newFunction.y[i] * newFunction.y[i - 1] < 0)</pre>
94
95
          ans.push_back(bisection(function, factors,
96
              newFunction.x[i - 1], newFunction.x[i], RightPart));
97
98
     }
99
100
     std::cout << "Number of roots: " << ans.size() << "\n";</pre>
     std::copy(ans.begin(), ans.end(), std::ostream_iterator<double>(std::cout, " "));
102 \\
103
     std::cout << "\n";
104
105
     return 0;
106 }
```

3.3 Код lab1 impl.cpp

```
1 #include "lab1.hpp"
3 #include <iostream>
4 #include <iterator>
5 #include <algorithm>
6 #include <functional>
  std::istream& operator>>(std::istream& in, point_t& point)
8
9 {
10
    in >> point.x >> point.y;
11
    return in;
12 }
13
  std::ostream& operator << (std::ostream& out, const point_t& point)
14 {
    out << point.x << " ; " << point.y << "\n";
15
    return out;
16
17 }
18 function_t::function_t()
19 {}
20 function_t::function_t(size_t n):
    x(n),
21
^{22}
    y(n)
23 {}
24 size_t function_t::size() const
25 {
26
    return x.size();
27 }
28 double* function_t::X()
29 {
30
    return x.data();
31
  double* function_t::Y()
32
33
34
    return y.data();
35 }
37 std::istream& operator>>(std::istream& in, function_t& function)
```

```
38 {
    std::vector<point_t> points(std::istream_iterator<point_t>(std::ref(in)),
39
        std::istream_iterator<point_t>());
40
    std::transform(points.begin(), points.end(), std::back_inserter(function.x), [](
41
     const point_t& point){return point.x;});
42
    std::transform(points.begin(), points.end(), std::back_inserter(function.y), [](
      const point_t& point){return point.y;});
43
    return in;
44 }
45 std::ostream& operator<<(std::ostream& out, const function_t& function)
46
    std::transform(function.x.begin(), function.x.end(), function.y.begin(),
47
        std::ostream_iterator<point_t>(out), [](double x, double y){return point_t{x, y}
48
      };});
    return out;
49
50 }
51 spline_t::spline_t(size_t n):
    b(n),
52
53
    c(n),
54
    d(n)
55
  {
  }
56
57 double * spline_t::B()
58 {
    return b.data();
59
  }
60
61 double * spline_t::C()
62 {
63
    return c.data();
64 }
65 double * spline_t::D()
66 {
67
    return d.data();
68 }
69 size_t spline_t::size() const
70 {
71
    return b.size();
72 }
73 std::ostream& operator <<(std::ostream& out, const spline_t& factors)
74 {
    for (int i = 0; i < factors.size(); ++i)</pre>
75
76
      out << "spline " << i << ": " << factors.b[i] << "; " << factors.c[i] << "; " <<
77
      factors.d[i] << "\n";</pre>
78
79
    return out;
80 }
```