

Task 2

Convolutional Neural Network

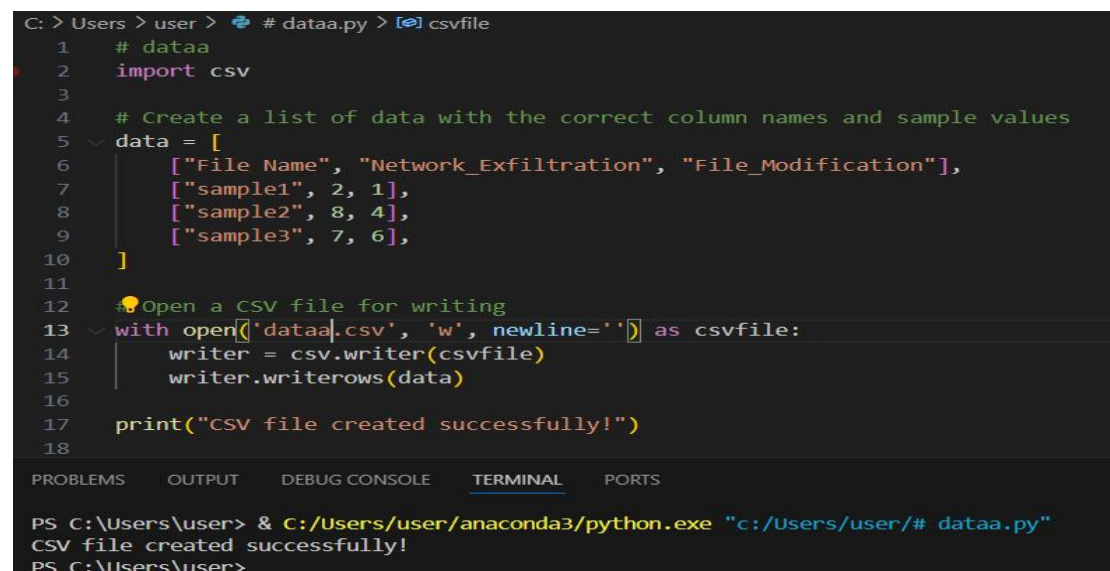
(CNN) is a specialized type of artificial neural network designed primarily for analyzing structured grid data, such as images. Unlike traditional neural networks, CNNs are particularly adept at recognizing patterns and spatial hierarchies within data through their unique architecture. The core building blocks of a CNN are convolutional layers, pooling layers, and fully connected layers.

Convolutional layers apply a series of filters to the input data, performing a convolution operation that slides the filter across the input to produce feature maps. These filters help detect local features such as edges, textures, and shapes in the early layers, and more complex patterns in deeper layers. Pooling layers, often following convolutional layers, reduce the spatial dimensions of the feature maps through operations like max pooling or average pooling. This down-sampling helps to decrease the computational load and mitigate overfitting by making the detection of features invariant to small translations in the input.

In the final stages, the fully connected layers take the high-level, abstracted features extracted by the convolutional and pooling layers and use them for classification or regression tasks. These layers operate like traditional neural networks, where each neuron is connected to every neuron in the previous layer, allowing the network to make decisions based on the global patterns identified in the earlier layers.

CNNs are renowned for their ability to handle large amounts of data and have become the backbone of many modern computer vision applications, including image and video recognition, object detection, and segmentation. Their hierarchical structure, inspired by the visual cortex of animals, allows them to learn and recognize complex patterns in a way that is both computationally efficient and highly effective. Advances in CNN architectures, such as AlexNet, VGG, ResNet, and more recently, EfficientNet, have significantly pushed the boundaries of performance, making CNNs a cornerstone of deep learning in various domains.

For practical job, I created an example csv file.



```

C: > Users > user > # dataaa.py > [e] csvfile
1  # dataaa
2  import csv
3
4  # Create a list of data with the correct column names and sample values
5  data = [
6      ["File Name", "Network_Exfiltration", "File_Modification"],
7      ["sample1", 2, 1],
8      ["sample2", 8, 4],
9      ["sample3", 7, 6],
10 ]
11
12 # Open a CSV file for writing
13 with open('dataaa.csv', 'w', newline='') as csvfile:
14     writer = csv.writer(csvfile)
15     writer.writerows(data)
16
17 print("CSV file created successfully!")
18
PROBLEMS  OUTPUT  DEBUG CONSOLE  TERMINAL  PORTS

PS C:\Users\user> & C:/Users/user/anaconda3/python.exe "c:/Users/user/# dataaa.py"
CSV file created successfully!
PS C:\Users\user>

```

Processing:

C:\> Users > user > # task 2.py > ...

```
1  import numpy as np
2  import pandas as pd
3  import cv2
4  from sklearn.model_selection import train_test_split
5  from sklearn.preprocessing import LabelEncoder # Optional, for future label encoding
6  from keras.utils import to_categorical # Optional, for multi-class encoding
7  from keras.models import Sequential
8  from keras.layers import Conv2D, MaxPooling2D, Flatten, Dense
9
10 # Import the os module
11 import os
12
13 # Function to convert executable to grayscale image
14 def convert_executable_to_image(file_path, image_size=64):
15     with open(file_path, 'rb') as f:
16         # Read the first N bytes of the executable (adjust N as needed)
17         byte_data = f.read(image_size * image_size)
18         # Convert byte data to a list of integers
19         int_data = [int(x) for x in byte_data]
20         # Reshape the data into a 2D array for image representation
21         img = np.reshape(int_data, (image_size, image_size))
22         # Normalize pixel values (optional)
23         img = img / 255.0
24     return img
25
26 # Path to the dataset
27 data_dir = './data'
28 label_file = 'dataaa.csv'
29
30 # Load labels
31 labels = pd.read_csv(label_file)
32
33 # Initialize lists to hold image data and labels
34 images = []
35 y = []
36
37 # Process each file in the dataset
38 for index, row in labels.iterrows():
39     file_name = row['File Name']
40     label = row['Network_Exfiltration']
41     file_path = os.path.join(data_dir, f'{file_name}.exe')
42     if not os.path.exists(os.path.join(data_dir, f'{file_name}.exe')):
43         print(f"Warning: File {file_path} not found, skipping")
44         continue
45     img = convert_executable_to_image(file_path)
46     images.append(img)
47     y.append(label)
48
49 # Convert lists to numpy arrays
50 X = np.array(images)
51 y = np.array(y)
52
53 # Normalize pixel values (already done in convert_executable_to_image)
54 X = X / 255.0
```

