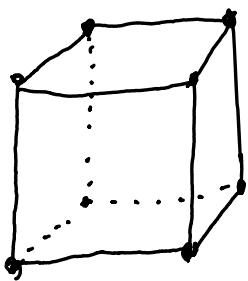


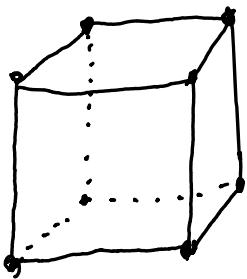
$$V =$$

$$- E =$$

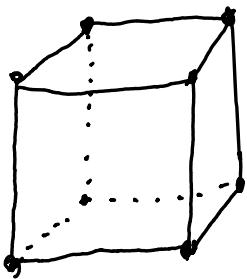
$$+ F =$$



$$\begin{aligned}V &= 8 \\ - E &= 12 \\ + F &= 6\end{aligned}$$

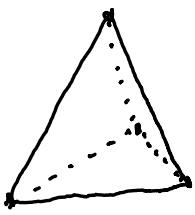


$$\begin{aligned} V &= 8 \\ - E &= 12 \\ + F &= 6 \\ \hline 8 - 12 + 6 &= 14 - 12 = 2 \end{aligned}$$

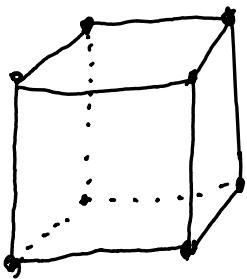


$$\begin{array}{r} V = 8 \\ - E = 12 \\ + F = 6 \\ \hline \end{array}$$

$$8 - 12 + 6 = 14 - 12 = 2$$



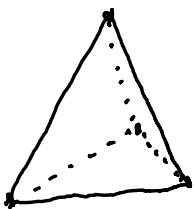
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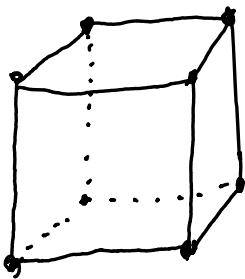
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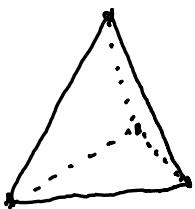
$$\begin{aligned}V &= 4 \\ - E &= 6 \\ + F &= 4\end{aligned}$$

---



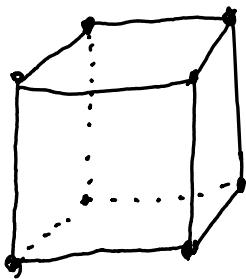
$$\begin{array}{r} V = 8 \\ - E = 12 \\ + F = 6 \\ \hline \end{array}$$

$$8 - 12 + 6 = 14 - 12 = 2$$



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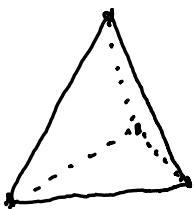
$$4 - 6 + 4 = 8 - 6 = 2$$



$$\begin{aligned}V &= 8 \\ -E &= 12 \\ +F &= 6\end{aligned}$$

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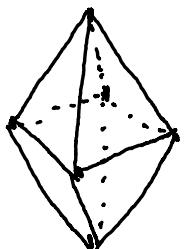
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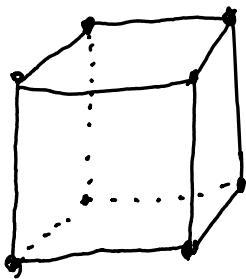
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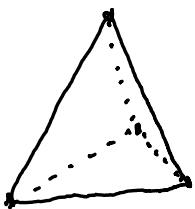
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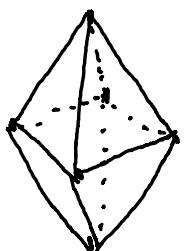
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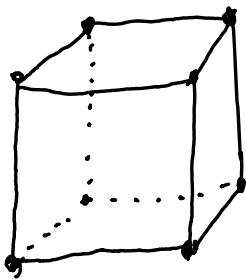
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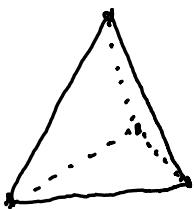
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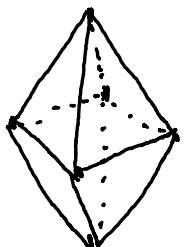
$$8 - 12 + 6 = 14 - 12 = 2$$



$$\begin{aligned}V &= 4 \\ -E &= 6 \\ +F &= 4\end{aligned}$$

---

$$4 - 6 + 4 = 8 - 6 = 2$$



$$\begin{aligned}V &= 6 \\ -E &= 12 \\ +F &= 8\end{aligned}$$

---

$$6 - 12 + 8 = 2$$

I can't draw it, but  
trust me, it works for  
the icosahedron and dodecahedron  
as well ( $12 - 30 + 20$ ) and ( $20 - 30 + 12$ ).

---

These are the regular (Platonic) solids, but  
there are more "semi regular"  
(Archimedean) solids!

Loosely, a regular 3D arrangement of  
regular n-gons, but allowing different types.

Eg: truncated regular polyhedra,  
snub polyhedra, etc. (Try EC here)

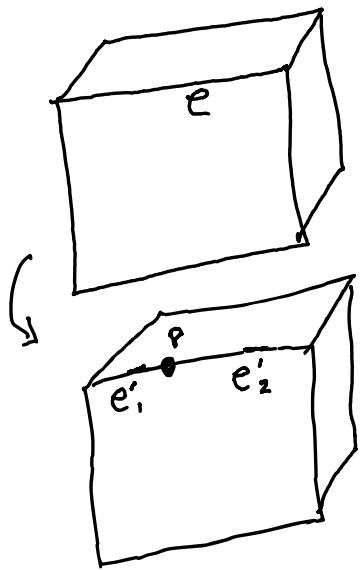
Even works for non regular faces!  
(Look up rhombus one)

May not be surprising that  
the "exact shape of things" doesn't  
seem to change  $V - E + F$ .



We've changed the curvature, and  
thus, the shape of our edges and  
faces, but we haven't changed  
what's connected to what, and  
so we haven't changed the  
number of vertices edges or faces.  
So  $V - E + F = 2$  still.

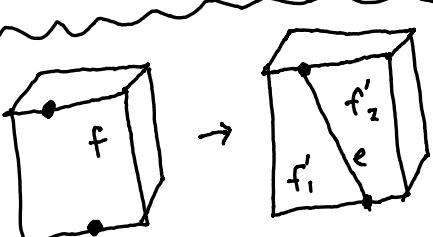
By now, you're probably dying to know why! Here's some intuition:



If I add a vertex on an existing edge, I've increased  $V$  by one, but I also split one edge into 2! So  $E$  increases by one as well.

$$\text{So } (V+1) - (E+1) + F$$

$$= V - E + F \text{ still.} \quad \begin{matrix} \text{It} \\ \text{doesn't} \\ \text{change.} \end{matrix}$$



Likewise, if I add an edge, I end up splitting one face into 2. Both  $E$  and

$$F \text{ go up by one. } V - (E+1) + (F+1) = V - E + F$$

To turn this idea into a proof that any polyhedron has  $V-E+F=2$ , you need to argue why you can get from any polyhedron to any other using these moves. Since these moves don't change  $V-E+F$ , we would then know this quantity would be the same for all polyhedra.

Then just calculate it for any one of them, like we did, and we see it is 2.

More technical than you'd think! But I believe the intuition is good enough.

Ok, so it works. Who cares?

Ok, so it works. Who cares?

- algebraic topologists

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- algebraic topologists
- differential topologists

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Ok, but who cares about topology?

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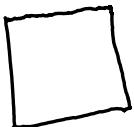
- Grant Sanderson
- Anna Marie Bohmann

But really, theres something going on here. The quantity  $V - E + F$  doesn't seem to depend on the exact shape of things, like distances, angles, or volume. The number  $V - E + F$  doesn't "see" these geometric properties...

This brings us to topology.

It's "looser" than geometry because it "ignores" more. In topology:

a square

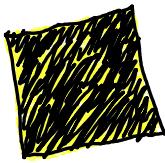


into a circle!



can be  
continuously  
deformed

a solid square



into a  
disk!



can be  
continuously  
deformed

---

But topology doesn't ignore everything!

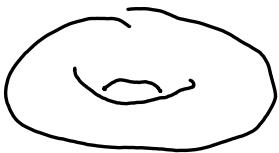


So, If we take some shape, put vertices edges and faces on it, and compute  $V - E + F$ , it ends up only depending on the topology of the shape !

Every example of a polyhedron so far has basically been an (angular and pointy) sphere!

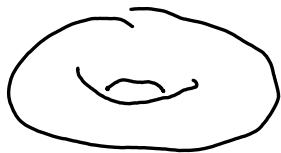
What if we do this with something that isn't topologically a sphere? Like ...

A donut!



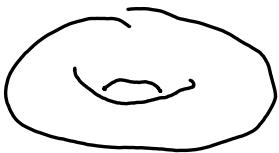
Lets put some vertices and edges on this shape.

A donut!



Lets put some vertices and edges on this (holesome) shape.

A donut!

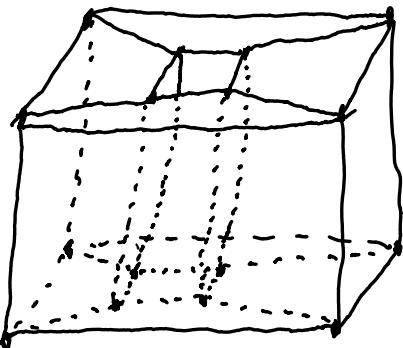


Lets put some vertices and edges on this shape.

A donut!



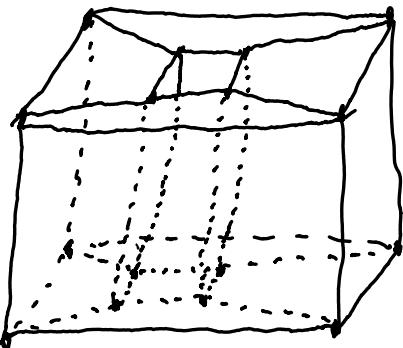
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A donut!



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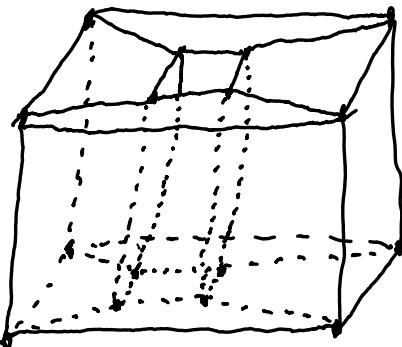


$$V = 16$$

A donut!



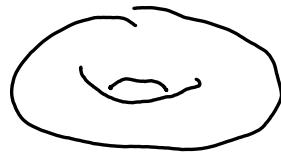
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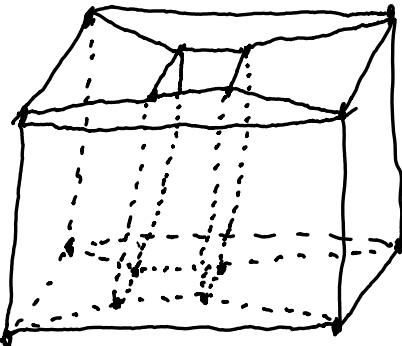
$$V = 16$$

$$E = 32$$

A donut!



Lets put some vertices and edges on this shape.

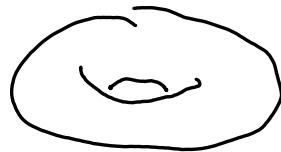


$$V = 16$$

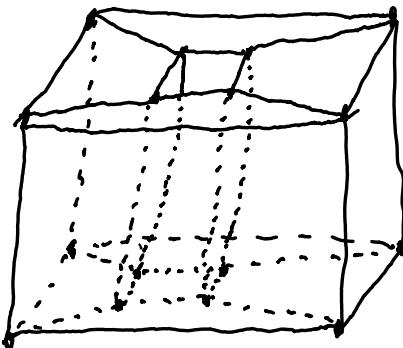
$$E = 32$$

$$F = 16$$

A donut!



Lets put some vertices and edges on this shape.



$$V = 16$$

$$E = 32$$

$$F = 16$$

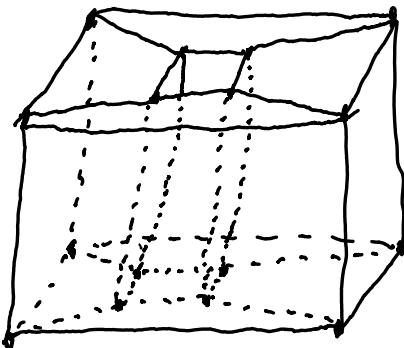
$$V - E + F = 16 - 32 + 16 = 0$$

Big Wow, it isn't 2!

A donut!



Lets put some vertices and edges on this shape.



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$$E = 32$$

$$F = 16$$

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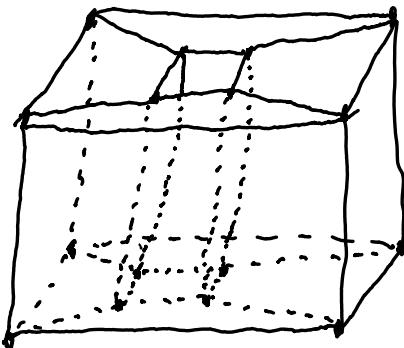
Big Wow, it isn't  $2^*$ !

\* technically, this is contingent on theorem 3.4.18.

A donut!



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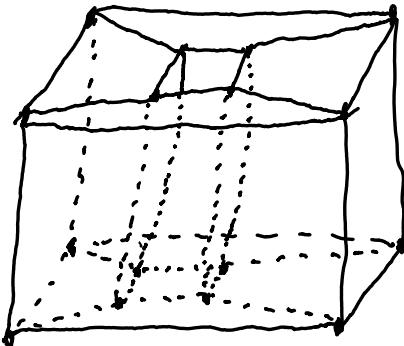
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[Theorem 3.4.18:  $0 \neq 2$ ]

A donut!



Let's put some vertices and edges on this shape.



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Big Wow, it isn't  $2^*$ !

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Theorem 3.4.18:  $0 \neq 2$

Theorem 3.4.18,  
(that's a joke, but it)  
(doesn't always feel  
that way)

So if we slap vs, es, fs on a donut (torus),  $V - E + F$  is different than with the sphere!

In general,  $V - E + F$  of some shape is called that shape's Euler characteristic, and its denoted  $\chi$ .

$$\text{So } \chi(\text{sphere}) = 2,$$

$$\chi(\text{torus}) = 0.$$

It's a fact that if actually doesn't depend on how you place the vertices edges and faces

$\chi$  only depends on the topology of the shape.

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for any "triangulation", since they will all give the same number

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Deep connections to other areas of math:

The Euler characteristic, in its modern form, is one of the most powerful invariants used across geometry and topology. It connects to many different concepts, even though it's fundamentally a topological property. 2 big connections:

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- to geometry (Gauss-Bonnet)

- to physics (Poincaré-Hopf)

Euler characteristic for something seemingly unrelated!      Big Theorems relating

Deep connections to other areas of math:

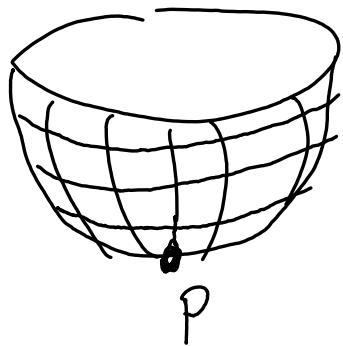
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— to geometry  
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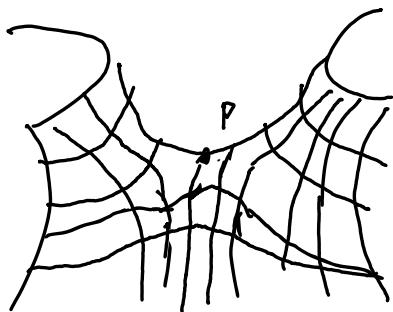
— to physics  
(specifically, vector fields) (Poincaré-Hopf)

Euler characteristic for something unrelated! Big Theorems relating seemingly unrelated!

# Gauss - Bonnet

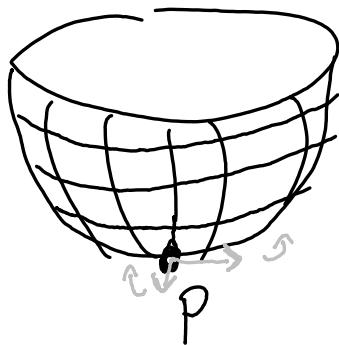


positive curvature  
at P



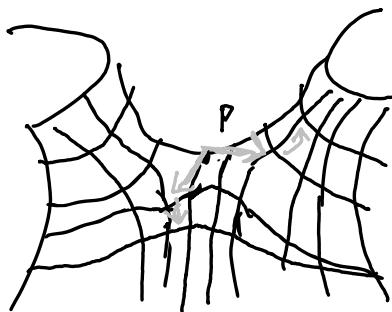
negatively curved  
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# Gauss - Bonnet



positive curvature  
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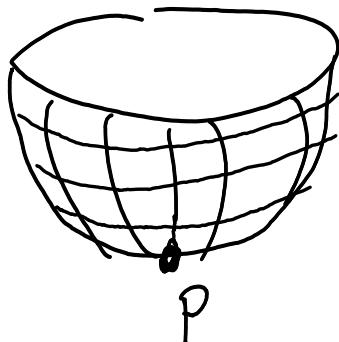
Tangent vectors in direction  
of greatest and least curvature  
curve in the same direction



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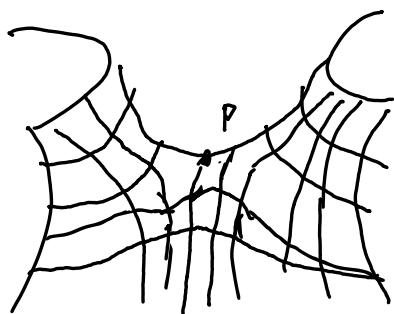
Tangent vectors in direction  
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# Gauss - Bonnet



positive curvature  
at P

Tangent vectors in direction of greatest and least curvature curve in the same direction



negatively curved  
at P.

Tangent vectors in direction of greatest and least curvature curve in different directions

analogy:  $(+) \cdot (+) = +$

$$0 \cdot (+) = 0 \quad (-) \cdot (-) = +$$

$$0 \cdot (-) = 0 \quad (-) \cdot (+) = -$$

$$(+) \cdot (-) = -$$

The theorem:

"Add up" the measure of curvature at each point  
(the technical way to do this  
is to take an integral).

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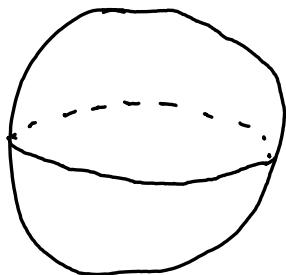
In symbols,  $\int_S k dA = 2\pi \chi(S)$

(In principle, could depend)  
on the geometry)

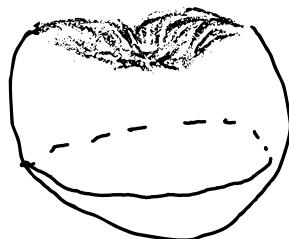
(only depends)  
on the topology!)

# Illustration :

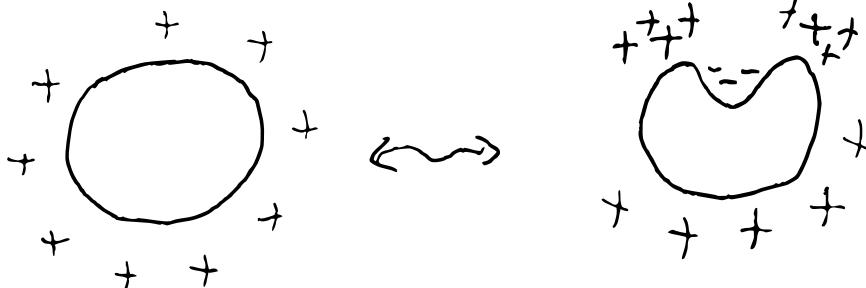
"geometric" sphere



Still a topological sphere.



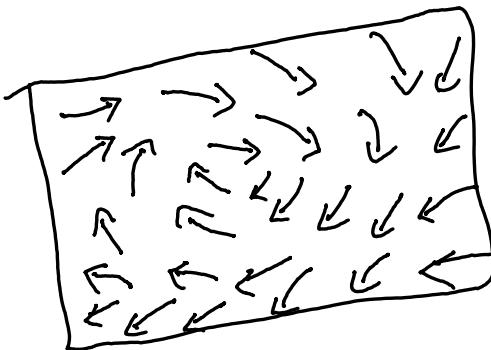
in 2 dimensions:



You can make a geometric distortion, but all you do is shift around where the curvature is. Total curvature is conserved, because (miraculously) it's topological!

Poincare - Hopf :

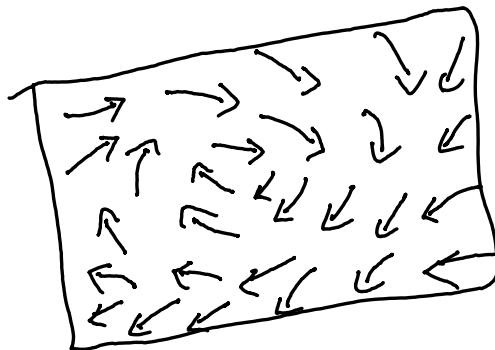
put a <sup>(smooth)</sup> vector field on  
your surface :



(Better pictures  
exist.)

# Poincare - Hopf :

put a <sup>(smooth)</sup> vector field on your surface :

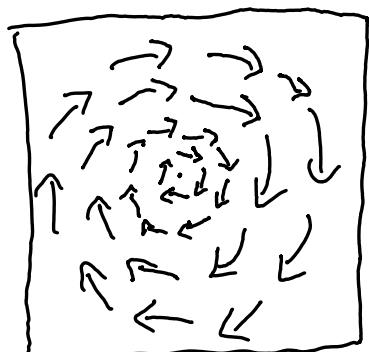


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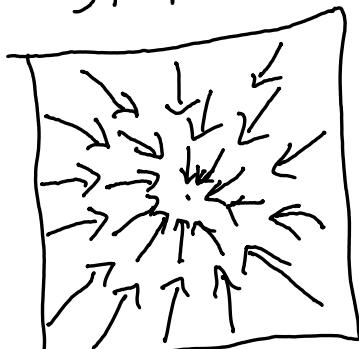
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There could be "stationary points", aka, zero's of the vector field

spirals

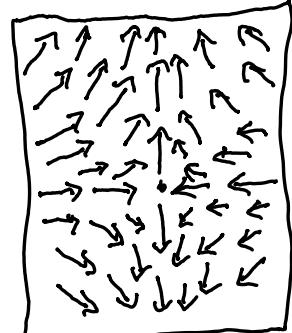


sinks



(and sources)

saddles

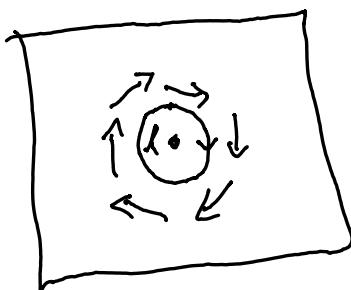


etc.

Let's define the Index of a stationary point:

(clockwise)  
As you take a small loop around the zero, how many times does the arrow turn clockwise?

spiral :

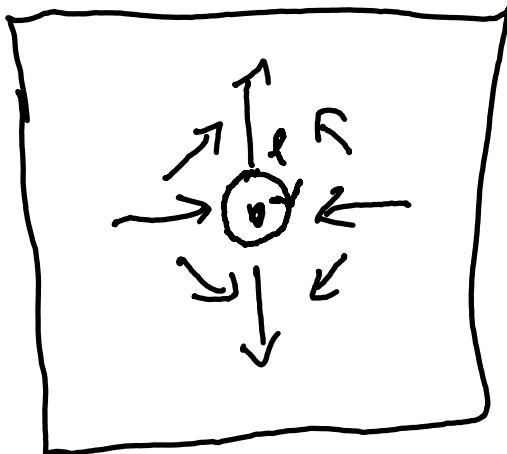


as we walk around it,

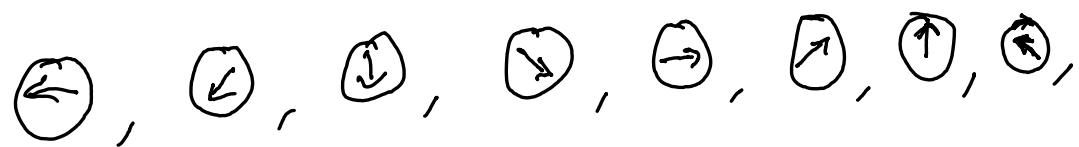
the arrows look like  $\textcirclearrowleft$ ,  $\textcirclearrowright$ ,  $\textcirclearrowleft$ ,  $\textcirclearrowright$ ,  $\textcirclearrowleft$ ,  $\textcirclearrowright$ ,  $\textcirclearrowleft$ ,  $\textcirclearrowright$ , back to  $\textcirclearrowleft$ .

Arrows net turn is one time clockwise. Index of this zero is 1!

what about a saddle?



as we traverse  
clockwise, the  
arrows do this:



then back to  $\leftarrow$ . Arrows go  
around counter clockwise!

We say this zero has  
index -1 !

Big theorem (PH) :

Put any smooth vector field on a surface  $S$  having finitely many stationary points. Then :

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The sum of all of the indexes of the zeros is exactly the Euler characteristic.

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Worth Stressing: this works for any vector field!

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Easy by - product :

If  $S$  is any surface  
that has  $\chi(S) \neq 0$   
(like how a sphere has  $\chi=2$ ),  
then any vector field  
you put on  $S$  must have  
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Real life "application" :-

- There is always some spot on  
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Real life "application" :-

- There is always some spot on earth with zero wind !
- You can't comb the hair on a hairy ball  
(welcome to higher math!)

Big theorems over how

Heres some fun stuff  
you can do with the Euler  
Characteristic :

Show that if  $P$  is a polyhedron with only pentagon and hexagon faces, and every vertex in  $P$  meets 3 edges, then  $P$  has exactly 12 pentagons!

(A "soccer ball" (truncated icosahedron) is an example of this)

2) give an alternative proof using  $\chi$  (any polyhedron with no holes) = 2 that there are only 5 platonic solids!

3) The game Brussel Sprouts!  
(like our last game Sprouts, but where the rules are actually right, and every vertex has 4 edges coming out!)

Show that its actually a joke game.  
No matter who does what, player 1 (resp 2) wins if we start with an odd (resp even) number of crosses

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+ +

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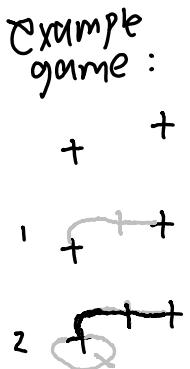
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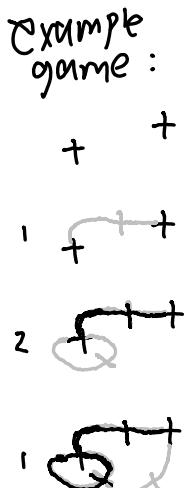
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Example game:

+ +

, + ++

2 + ++

, 5 +

2 5 +

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+ +

, + ++

2, ~~+ +~~

, ~~+ +~~

2, ~~+ +~~

, ~~+ +~~

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, + + +

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, + + +

Player 2 wins,  
since I can't move.

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Thanks For Coming!

Have a great Thursday!

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