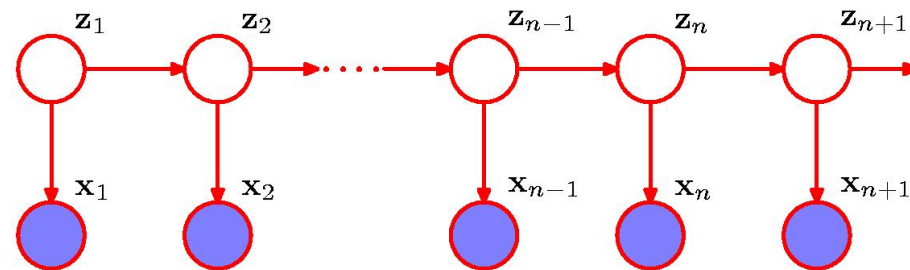


Hidden Markov Models

Terminology, Representation and Basic Problems



Data – Observations

A sequence of observations from a finite and discrete set, e.g. measurements of weather patterns, daily values of stocks, the composition of DNA or proteins, or ...

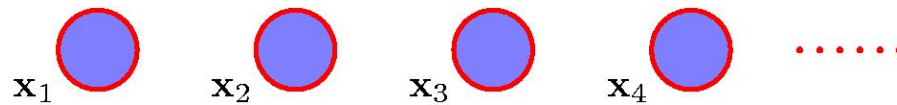
$$\mathbf{X} = \mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N$$

Typical question/problem: How likely is a given \mathbf{X} , i.e. $p(\mathbf{X})$?

We need a model that describes how to compute $p(\mathbf{X})$

Simple Models (1)

Observations are independent and identically distributed



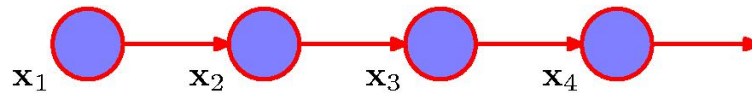
$$p(\mathbf{x}_1, \dots, \mathbf{x}_N) = \prod_{n=1}^N p(\mathbf{x}_n)$$

Too simplistic for realistic modelling of many phenomena

Simple Models (2)

The n 'th observation in a chain of observations is influenced only by the $n-1$ 'th observation, i.e.

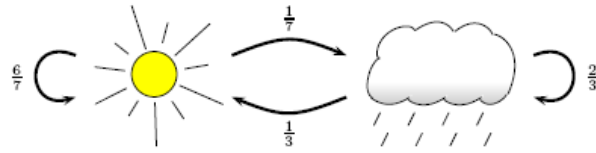
$$p(\mathbf{x}_n | \mathbf{x}_1, \dots, \mathbf{x}_{n-1}) = p(\mathbf{x}_n | \mathbf{x}_{n-1})$$



The chain of observations is a **1st-order Markov chain**, and the probability of a sequence of N observations is

$$p(\mathbf{x}_1, \dots, \mathbf{x}_N) = \prod_{n=1}^N p(\mathbf{x}_n | \mathbf{x}_1, \dots, \mathbf{x}_{n-1}) = p(\mathbf{x}_1) \prod_{n=2}^N p(\mathbf{x}_n | \mathbf{x}_{n-1})$$

The model, i.e. $p(\mathbf{x}_n | \mathbf{x}_{n-1})$:



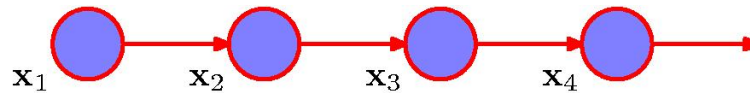
A sequence of observations:



The
the $n-1$ 'th observation, i.e.

by

$$p(\mathbf{x}_n | \mathbf{x}_1, \dots, \mathbf{x}_{n-1}) = p(\mathbf{x}_n | \mathbf{x}_{n-1})$$

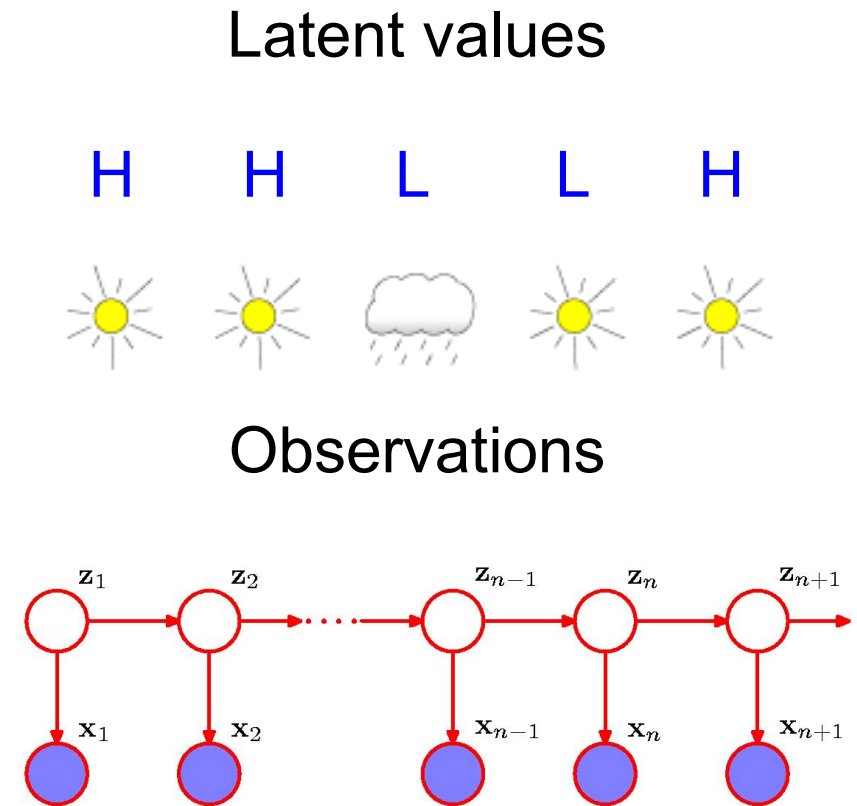


The chain of observations is a **1st-order Markov chain**, and the probability of a sequence of N observations is

$$p(\mathbf{x}_1, \dots, \mathbf{x}_N) = \prod_{n=1}^N p(\mathbf{x}_n | \mathbf{x}_1, \dots, \mathbf{x}_{n-1}) = p(\mathbf{x}_1) \prod_{n=2}^N p(\mathbf{x}_n | \mathbf{x}_{n-1})$$

Hidden Markov Models

What if the n 'th observation in a chain of observations is influenced by a corresponding hidden variable?

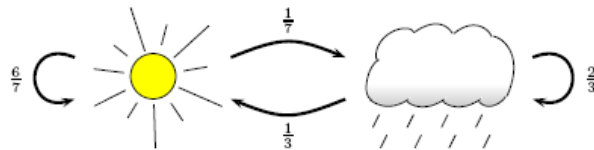


If the hidden variables are discrete and form a Markov chain, then it is a **hidden Markov model (HMM)**

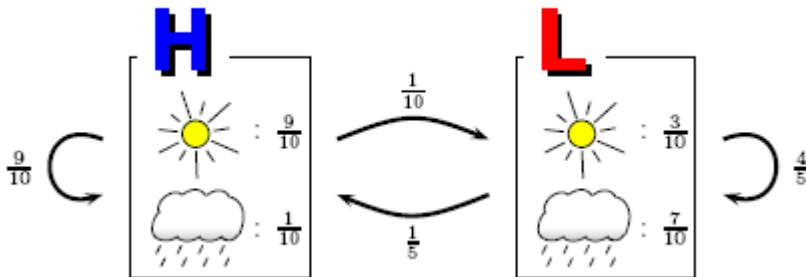
Hidden Markov Models

What if the n 'th observation in a chain of observations is influenced by a corresponding hidden variable?

Markov Model



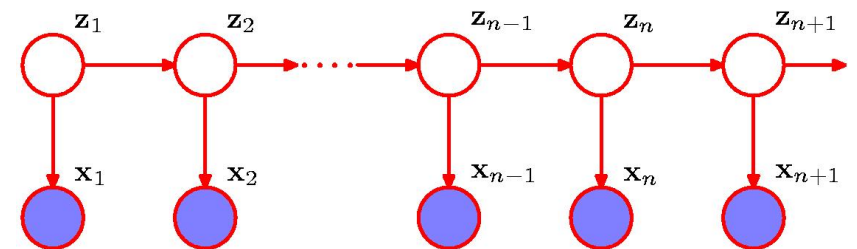
Hidden Markov Model



Latent values



Observations



If the hidden variables are discrete and form a Markov chain, then it is a **hidden Markov model (HMM)**

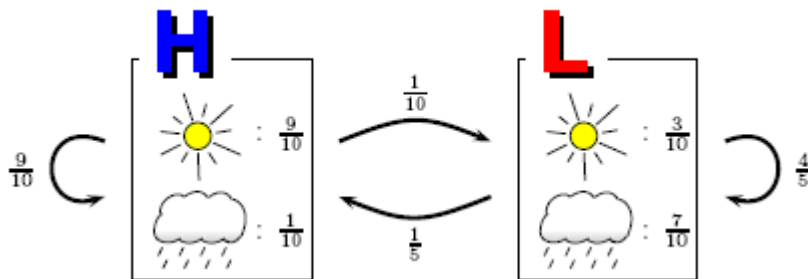
Hidden Markov Models

What if the n 'th observation in a chain of observations is influenced

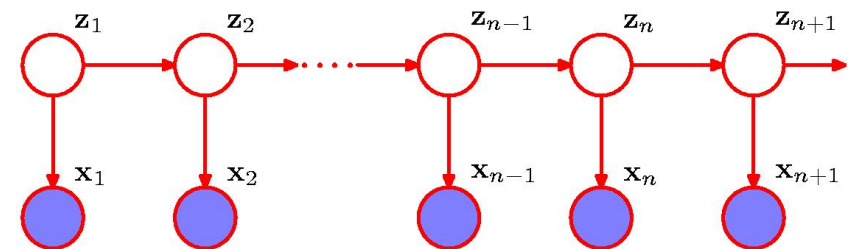
The joint distribution

$$p(\mathbf{x}_1, \dots, \mathbf{x}_N, \mathbf{z}_1, \dots, \mathbf{z}_N) = p(\mathbf{z}_1) \left[\prod_{n=2}^N p(\mathbf{z}_n | \mathbf{z}_{n-1}) \right] \prod_{n=1}^N p(\mathbf{x}_n | \mathbf{z}_n)$$

Hidden Markov Model



Observations



If the hidden variables are discrete and form a Markov chain, then it is a **hidden Markov model (HMM)**

Hidden Markov Models

What if

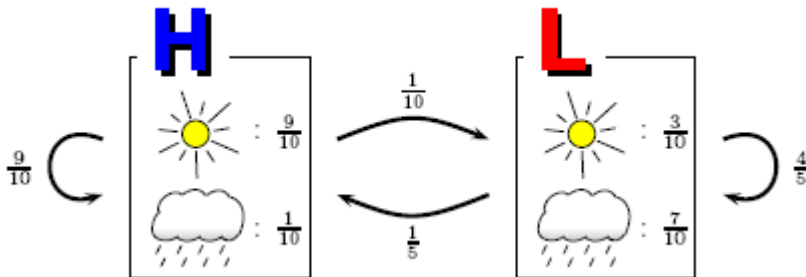
Transition probabilities

chain of observations

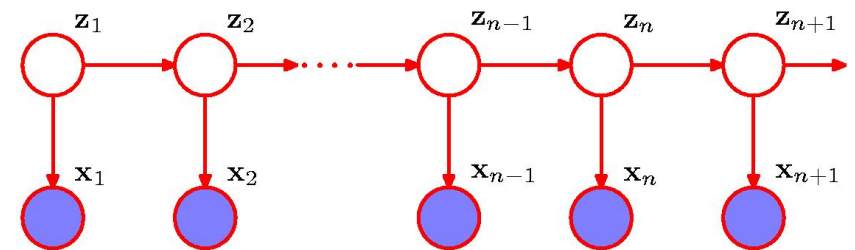
Emission probabilities

$$p(\mathbf{x}_1, \dots, \mathbf{x}_N, \mathbf{z}_1, \dots, \mathbf{z}_N) = p(\mathbf{z}_1) \left[\prod_{n=2}^N p(\mathbf{z}_n | \mathbf{z}_{n-1}) \right] \prod_{n=1}^N p(\mathbf{x}_n | \mathbf{z}_n)$$

Hidden Markov Model



Observations



If the hidden variables are discrete and form a Markov chain, then it is a **hidden Markov model (HMM)**

Transition probabilities

Notation: In Bishop, the hidden variables \mathbf{z}_n are positional vectors, e.g. if $\mathbf{z}_n = (0,0,1)$ then the model in step n is in state $k=3$

Transition probabilities: If the hidden variables are discrete with K states, the conditional distribution $p(\mathbf{z}_n | \mathbf{z}_{n-1})$ is a $K \times K$ table \mathbf{A} , and the marginal distribution $p(\mathbf{z}_1)$ describing the initial state is a K vector $\boldsymbol{\pi}$

The probability of going from state j to state k is:

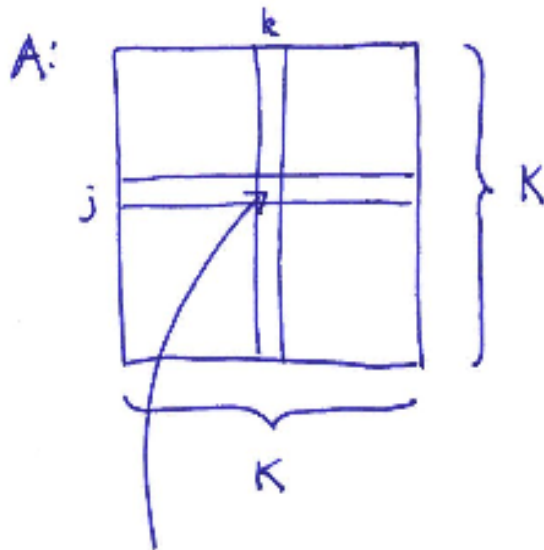
The probability of state k being the initial state is:

$$A_{jk} \equiv p(z_{nk} = 1 | z_{n-1,j} = 1)$$

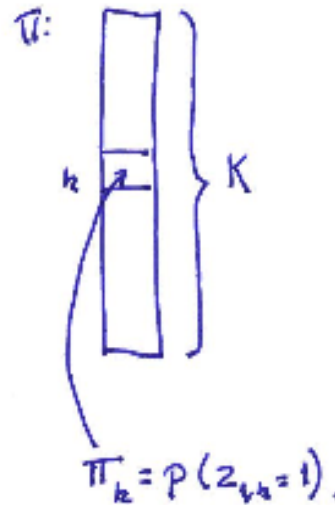
$$\pi_k \equiv p(z_{1k} = 1)$$

$$\sum_k A_{jk} = 1$$

$$\sum_k \pi_k = 1$$



$$A_{jk} = p(z_{n,k} = 1 | z_{n-1,j} = 1) = "p(j \rightarrow k)."$$



$$\pi_k = p(z_{1k} = 1).$$

ities

the positional vectors,
state $k=3 \dots$

s are discrete with K
a $K \times K$ table \mathbf{A} , and
initial state is a K

vector $\boldsymbol{\pi} \dots$

The probability of going from
state j to state k is:

The probability of state k
being the initial state is:

$$A_{jk} \equiv p(z_{nk} = 1 | z_{n-1,j} = 1)$$

$$\pi_k \equiv p(z_{1k} = 1)$$

$$\sum_k A_{jk} = 1$$

$$\sum_k \pi_k = 1$$

The transition probabilities:

$$p(\mathbf{z}_n | \mathbf{z}_{n-1}, \mathbf{A}) = \prod_{k=1}^K \prod_{j=1}^K A_{jk}^{z_{n-1,j} z_{nk}}$$

$$p(\mathbf{z}_1 | \pi) = \prod_{k=1}^K \pi_k^{z_{1k}}$$

tors,

with K
and

The probability of going from state j to state k is:

The probability of state k being the initial state is:

$$A_{jk} \equiv p(z_{nk} = 1 | z_{n-1,j} = 1)$$

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$$\sum_k A_{jk} = 1$$

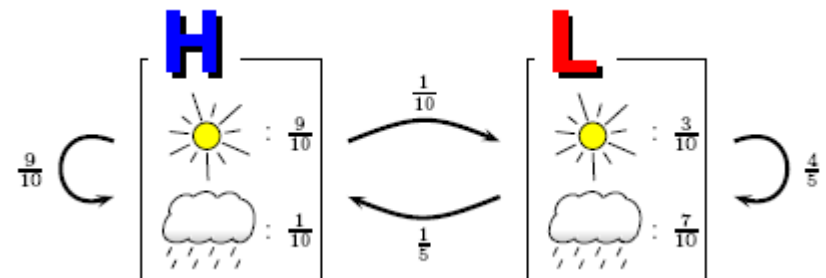
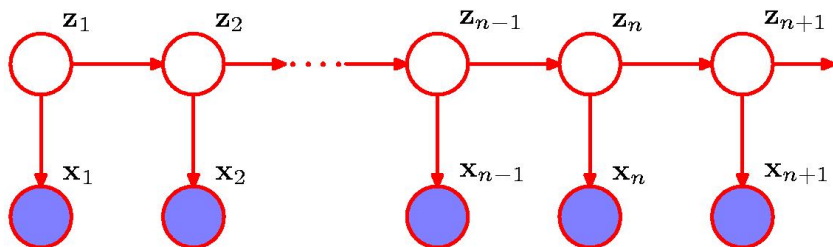
$$\sum_k \pi_k = 1$$

Emission probabilities

Emission probabilities: The conditional distributions of the observed variables $p(\mathbf{x}_n | \mathbf{z}_n)$ from a specific state

If the observed values \mathbf{x}_n are discrete (e.g. D symbols), the emission probabilities ϕ is a $K \times D$ table of probabilities which for each of the K states specifies the probability of emitting each observable ...

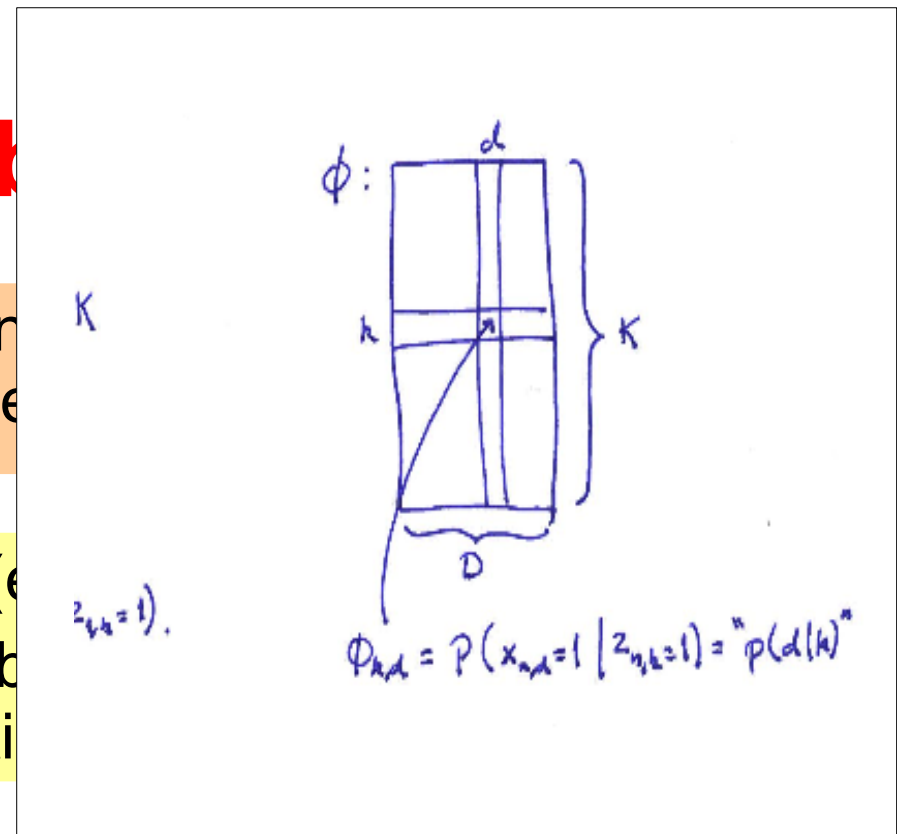
$$p(\mathbf{x}_n | \mathbf{z}_n, \phi) = \prod_{k=1}^K p(\mathbf{x}_n | \phi_k)^{z_{nk}}$$



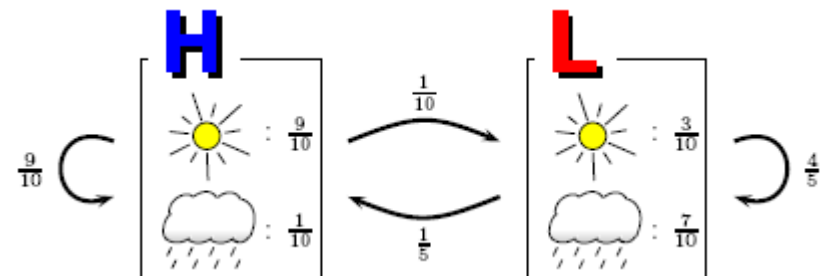
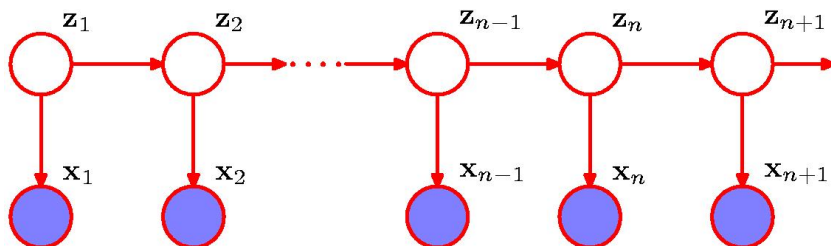
Emission prob

Emission probabilities: The conditional probabilities of observed variables $p(\mathbf{x}_n | \mathbf{z}_n)$ from a specific state \mathbf{z}_n .

If the observed values \mathbf{x}_n are discrete (e.g., weather conditions), the emission probabilities ϕ is a $K \times D$ table of probabilities. Each row in the table specifies the probability of emitting a particular observed value from a given hidden state.



$$p(\mathbf{x}_n | \mathbf{z}_n, \phi) = \prod_{k=1}^K p(\mathbf{x}_n | \phi_k)^{z_{nk}}$$



HMM joint probability distribution

$$p(\mathbf{X}, \mathbf{Z} | \Theta) = p(\mathbf{z}_1 | \pi) \left[\prod_{n=2}^N p(\mathbf{z}_n | \mathbf{z}_{n-1}, \mathbf{A}) \right] \prod_{n=1}^N p(\mathbf{x}_n | \mathbf{z}_n, \phi)$$

Observables:

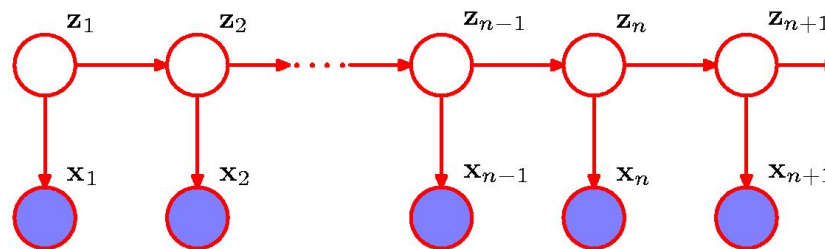
Latent states:

Model parameters:

$$\mathbf{X} = \{\mathbf{x}_1, \dots, \mathbf{x}_N\}$$

$$\mathbf{Z} = \{\mathbf{z}_1, \dots, \mathbf{z}_N\}$$

$$\Theta = \{\pi, \mathbf{A}, \phi\}$$

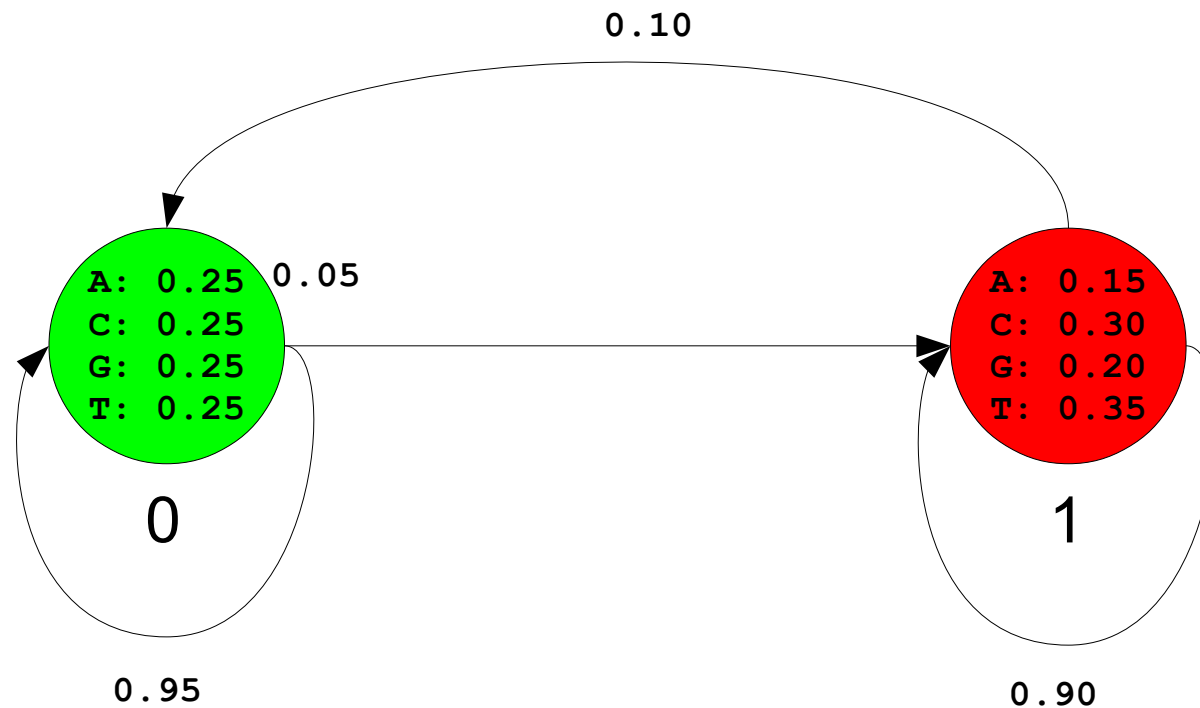


If \mathbf{A} and ϕ are the same for all n then the HMM is *homogeneous*

Example – 2-state HMM

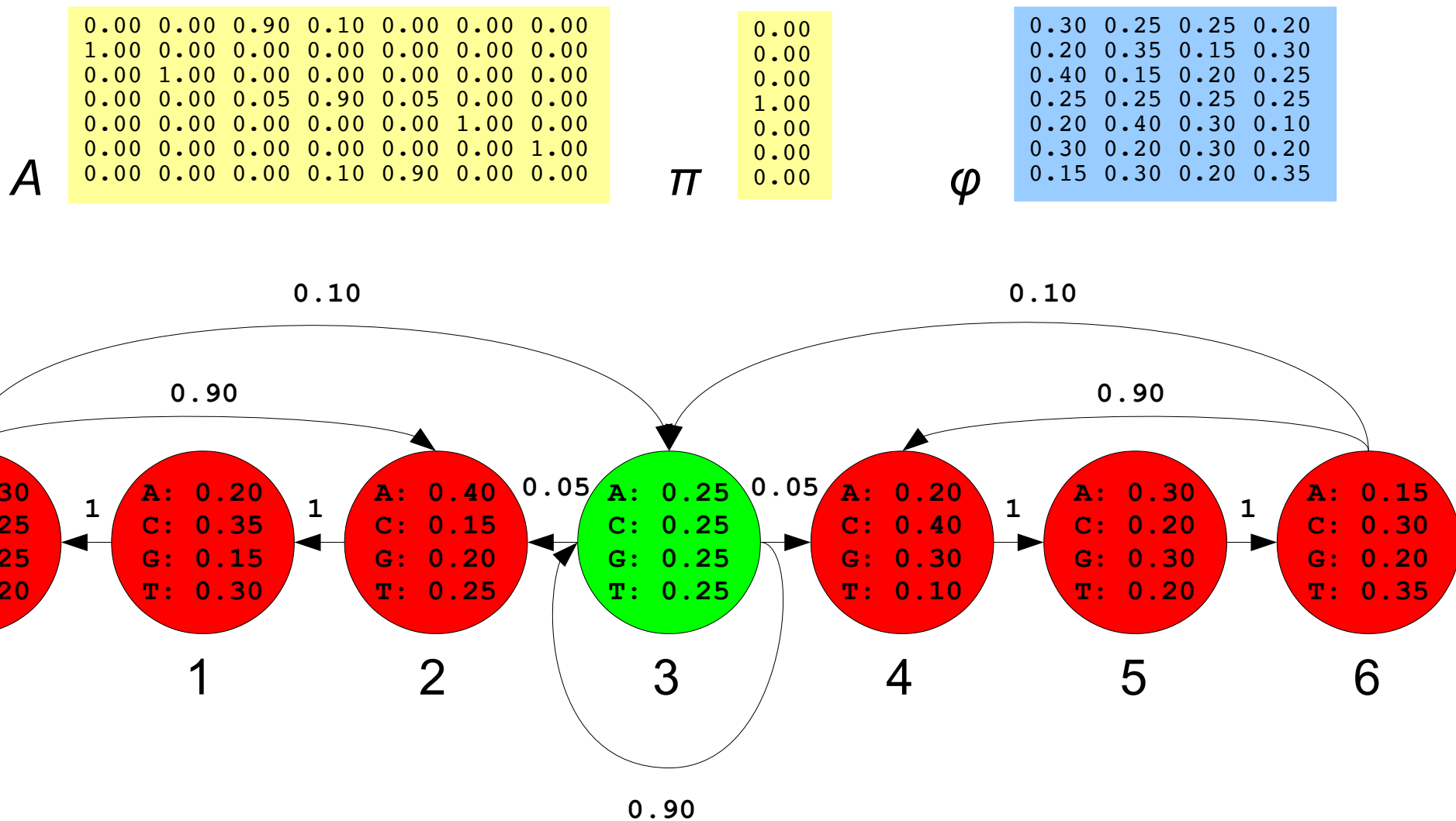
Observable: {A, C, G, T}, States: {0,1}

A	<table><tr><td>0.95</td><td>0.05</td></tr><tr><td>0.10</td><td>0.90</td></tr></table>	0.95	0.05	0.10	0.90	π	<table><tr><td>1.00</td></tr><tr><td>0.00</td></tr></table>	1.00	0.00	φ	<table><tr><td>0.25</td><td>0.25</td><td>0.25</td><td>0.25</td></tr><tr><td>0.20</td><td>0.30</td><td>0.30</td><td>0.20</td></tr></table>	0.25	0.25	0.25	0.25	0.20	0.30	0.30	0.20
0.95	0.05																		
0.10	0.90																		
1.00																			
0.00																			
0.25	0.25	0.25	0.25																
0.20	0.30	0.30	0.20																



Example – 7-state HMM

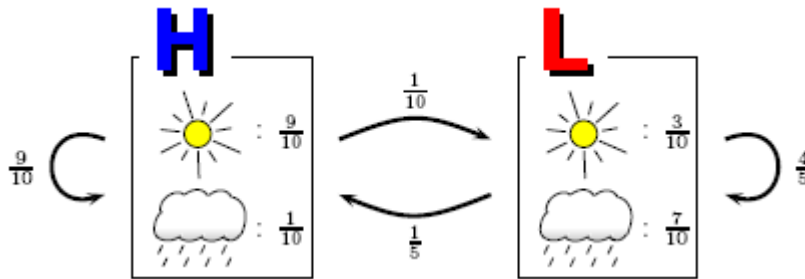
Observable: {A, C, G, T}, States: {0, 1, 2, 3, 4, 5, 6}



HMMs as a generative model

A HMM *generates a sequence of observables* by moving from latent state to latent state according to the transition probabilities and *emitting an observable* (from a discrete set of observables, i.e. a finite alphabet) from each latent state visited *according to the emission probabilities* of the state ...

Model M :



A *run* follows a sequence of states:

H H L L H

And *emits* a sequence of symbols:



Computing $P(\mathbf{X}, \mathbf{Z})$

$$p(\mathbf{X}, \mathbf{Z} | \Theta) = p(\mathbf{z}_1 | \pi) \left[\prod_{n=2}^N p(\mathbf{z}_n | \mathbf{z}_{n-1}, \mathbf{A}) \right] \prod_{n=1}^N p(\mathbf{x}_n | \mathbf{z}_n, \phi)$$

```
def joint_prob(x, z):  
    """  
    Returns the joint probability of x and z  
    """  
    p = init_prob[z[0]] * emit_prob[z[0]][x[0]]  
    for i in range(1, len(x)):  
        p = p * trans_prob[z[i-1]][z[i]] * emit_prob[z[i]][x[i]]  
    return p
```

Computing P(X,Z)

$$p(\mathbf{X}, \mathbf{Z} | \Theta) = p(\mathbf{z}_1 | \pi) \left[\prod_{n=2}^N p(\mathbf{z}_n | \mathbf{z}_{n-1}, \mathbf{A}) \right] \prod_{n=1}^N p(\mathbf{x}_n | \mathbf{z}_n, \phi)$$

```
def jo
$ python hmm_jointprob.py hmm-7-state.txt test_seq100.txt
> seq100
p(x,z) = 1.8619524290102162e-65

$ python hmm_jointprob.py hmm-7-state.txt test_seq200.txt
> seq200
p(x,z) = 1.6175774997005771e-122

$ python hmm_jointprob.py hmm-7-state.txt test_seq300.txt
> seq300
p(x,z) = 3.0675430597843052e-183

$ python hmm_jointprob.py hmm-7-state.txt test_seq400.txt
> seq400
p(x,z) = 4.860704144302979e-247

$ python hmm_jointprob.py hmm-7-state.txt test_seq500.txt
> seq500
p(x,z) = 5.258724342206735e-306

$ python hmm_jointprob.py hmm-7-state.txt test_seq600.txt
> seq600
p(x,z) = 0.0
```

[x[i]]

Computing $P(\mathbf{X}, \mathbf{Z})$

$$p(\mathbf{X}, \mathbf{Z} | \Theta) = p(\mathbf{z}_1 | \pi) \left[\prod_{n=2}^N p(\mathbf{z}_n | \mathbf{z}_{n-1}, \mathbf{A}) \right] \prod_{n=1}^N p(\mathbf{x}_n | \mathbf{z}_n, \phi)$$

```
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> seq300
p(x,z) = 3.0675430597843052e-183

$ python hmm_jointprob.py hmm-7-state.txt test_seq400.txt
> seq400
p(x,z) = 4.860704144302979e-247

$ python hmm_jointprob.py hmm-7-state.txt test_seq500.txt
> seq500
p(x,z) = 5.258724342206735e-306

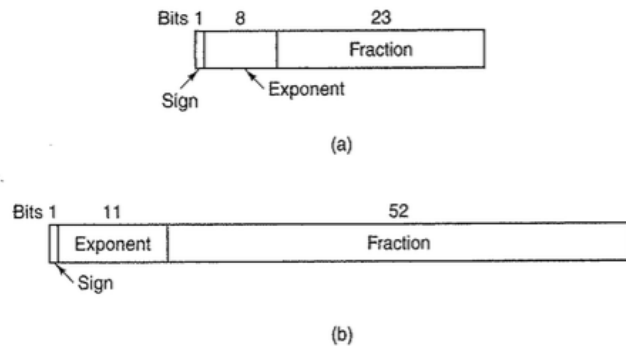
$ python hmm_jointprob.py hmm-7-state.txt test_seq600.txt
> seq600
p(x,z) = 0.0
```

[x[i]]

Should be >0 by construction of \mathbf{X} and \mathbf{Z}

Representing numbers

A floating point number n is represented as $n = f * 2^e$ cf. the IEEE-754 standard which specify the range of f and e



Item	Single precision	Double precision
Bits in sign	1	1
Bits in exponent	8	11
Bits in fraction	23	52
Bits, total	32	64
Exponent system	Excess 127	Excess 1023
Exponent range	-126 to +127	-1022 to +1023
Smallest normalized number	2^{-126}	2^{-1022}
Largest normalized number	approx. 2^{128}	approx. 2^{1024}
Decimal range	approx. 10^{-38} to 10^{38}	approx. 10^{-308} to 10^{308}
Smallest denormalized number	approx. 10^{-45}	approx. 10^{-324}

Figure B-5. Characteristics of IEEE floating-point numbers.

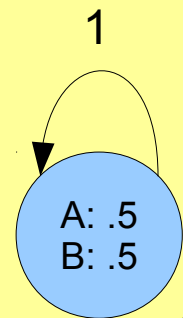
See e.g. Appendix B in Tanenbaum's Structured Computer Organization for further details.

The problem – Too small numbers

For the simple HMM, the joint-probability $p(\mathbf{X}, \mathbf{Z})$ is

$$p(\mathbf{X}, \mathbf{Z}) = 1 \cdot \prod_{n=2}^N 1 \cdot \prod_{n=1}^N \frac{1}{2} = \left(\frac{1}{2}\right)^n = 2^{-n}$$

If $n > 467$ then 2^{-n} is smaller than 10^{-324} , i.e. cannot be represented



A simple HMM

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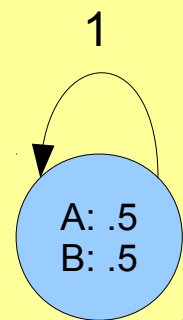
$$p(\mathbf{X}, \mathbf{Z}) = 1 \cdot \prod_{n=2}^N 1 \cdot \prod_{n=1}^N \frac{1}{2} = \left(\frac{1}{2}\right)^n = 2^{-n}$$

If $n > 467$ then 2^{-n} is smaller than 10^{-324} , i.e. cannot be represented

No problem representing

$$\log p(\mathbf{X}, \mathbf{Z}) = -n$$

as the decimal range is approx -10^{308} to 10^{308}



A simple HMM

Solution: Compute $\log P(\mathbf{X}, \mathbf{Z})$

$$p(\mathbf{X}, \mathbf{Z} | \Theta) = p(\mathbf{z}_1 | \pi) \left[\prod_{n=2}^N p(\mathbf{z}_n | \mathbf{z}_{n-1}, \mathbf{A}) \right] \prod_{n=1}^N p(\mathbf{x}_n | \mathbf{z}_n, \phi)$$

Use $\log (XY) = \log X + \log Y$, and define $\log 0$ to be $-\infty$

$$\log p(\mathbf{X}, \mathbf{Z} | \Theta) = \log p(\mathbf{z}_1 | \pi) + \sum_{n=2}^N \log p(\mathbf{z}_n | \mathbf{z}_{n-1}, \mathbf{A}) + \sum_{n=1}^N \log p(\mathbf{x}_n | \mathbf{z}_n, \phi)$$

Solution: Compute $\log P(\mathbf{X}, \mathbf{Z})$

$$\log p(\mathbf{X}, \mathbf{Z} | \Theta) = \log p(\mathbf{z}_1 | \pi) + \sum_{n=2}^N \log p(\mathbf{z}_n | \mathbf{z}_{n-1}, \mathbf{A}) + \sum_{n=1}^N \log p(\mathbf{x}_n | \mathbf{z}_n, \phi)$$

```
def log_joint_prob(self, x, z):  
    """  
    Returns the log transformed joint probability of x and z  
    """  
    logp = log(init_prob[z[0]]) + log(emit_prob[z[0]][x[0]])  
    for i in range(1, len(x)):  
        logp = logp + log(trans_prob[z[i-1]][z[i]]) + log(emit_prob[z[i]][x[i]])  
    return logp
```

Solution: Compute log P(X,Z)

$$\log p(\mathbf{X}, \mathbf{Z} | \Theta) = \log p(\mathbf{z}_1 | \pi) + \sum_{n=2}^N \log p(\mathbf{z}_n | \mathbf{z}_{n-1}, \mathbf{A}) + \sum_{n=1}^N \log p(\mathbf{x}_n | \mathbf{z}_n, \phi)$$

```
def log_joint
    """
    Returns the log joint probability
    log p = log p(z|x)
    for i in range(len(x)):
        logp = logp + log p(z[i]|x[i])
    return logp
```

```
$ python hmm_log_jointprob.py hmm-7-state.txt test_seq100.txt
> seq100
log p(x,z) = -149.04640541441395

$ python hmm_log_jointprob.py hmm-7-state.txt test_seq200.txt
> seq200
log p(x,z) = -280.43445168576596

$ python hmm_log_jointprob.py hmm-7-state.txt test_seq300.txt
> seq300
log p(x,z) = -420.25219508298494

$ python hmm_log_jointprob.py hmm-7-state.txt test_seq400.txt
> seq400
log p(x,z) = -567.1573346564519

$ python hmm_log_jointprob.py hmm-7-state.txt test_seq500.txt
> seq500
log p(x,z) = -702.9311499793356

$ python hmm_log_jointprob.py hmm-7-state.txt test_seq600.txt
> seq600
log p(x,z) = -842.0056730984585
```

[z[i]][x[i]]

Using HMMs

- Determine the likelihood of a sequence of observations.
- Find a plausible underlying explanation (or decoding) of a sequence of observations.

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- Determine the likelihood of a sequence of observations.
- Find a plausible underlying explanation (or decoding) of a sequence of observations.

$$p(\mathbf{X}|\Theta) = \sum_{\mathbf{Z}} p(\mathbf{X}, \mathbf{Z}|\Theta)$$

Using HMMs

- Determine the likelihood of a sequence of observations.
- Find a plausible underlying explanation (or decoding) of a sequence of observations.

$$p(\mathbf{X}|\Theta) = \sum_{\mathbf{Z}} p(\mathbf{X}, \mathbf{Z}|\Theta)$$

The sum has K^N terms, but it turns out that it can be computed in $O(K^2N)$ time, but first we will consider **decoding**

Decoding using HMMs

Given a HMM Θ and a sequence of observations $\mathbf{X} = \mathbf{x}_1, \dots, \mathbf{x}_N$, find a plausible explanation, i.e. a sequence $\mathbf{Z}^* = \mathbf{z}_1^*, \dots, \mathbf{z}_N^*$ of values of the hidden variable.

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Viterbi decoding

\mathbf{Z}^* is the overall most likely explanation of \mathbf{X} :

$$\mathbf{Z}^* = \arg \max_{\mathbf{Z}} p(\mathbf{X}, \mathbf{Z} | \Theta)$$

Decoding using HMMs

Given a HMM Θ and a sequence of observations $\mathbf{X} = \mathbf{x}_1, \dots, \mathbf{x}_N$, find a plausible explanation, i.e. a sequence $\mathbf{Z}^* = \mathbf{z}_1^*, \dots, \mathbf{z}_N^*$ of values of the hidden variable.

Viterbi decoding

\mathbf{Z}^* is the overall most likely explanation of \mathbf{X} :

$$\mathbf{Z}^* = \arg \max_{\mathbf{Z}} p(\mathbf{X}, \mathbf{Z} | \Theta)$$

Posterior decoding

\mathbf{z}_n^* is the most likely state to be in the n 'th step:

$$\mathbf{z}_n^* = \arg \max_{\mathbf{z}_n} p(\mathbf{z}_n | \mathbf{x}_1, \dots, \mathbf{x}_N)$$

Summary

- Terminology of hidden Markov models (**HMMs**)
- **Viterbi-** and **Posterior decoding** for finding a plausible underlying explanation (sequence of hidden states) of a sequence of observation
- **Next:** Algorithms for computing the Viterbi and Posterior decodings efficiently