This document is used to assist with the Algebra in Appendix A.2

Note that ∇ has been replaced with to ensure the code works okay.

> restart;

We normalise the velocity coefficents by u_0 and the field components by $(B_0 * u_0 / v_{A+})$. We start by solving the Matrix equation given by Equation (57).

>
$$eqn1 := a_{11} \cdot x_1 + a_{12} \cdot x_2 + a_{13} \cdot x_3 + a_{14} \cdot x_4 = y_1$$

 $eqn1 := a_{11} x_1 + a_{12} x_2 + a_{13} x_3 + a_{14} x_4 = y_1$ (1)

>
$$eqn2 := a_{21} \cdot x_1 + a_{22} \cdot x_2 + a_{23} \cdot x_3 + a_{24} \cdot x_4 = y_2$$

 $eqn2 := a_{21} x_1 + a_{22} x_2 + a_{23} x_3 + a_{24} x_4 = y_2$
(2)

>
$$eqn3 := a_{31} \cdot x_1 + a_{32} \cdot x_2 + a_{33} \cdot x_3 + a_{34} \cdot x_4 = y_3$$

 $eqn3 := a_{31} x_1 + a_{32} x_2 + a_{33} x_3 + a_{34} x_4 = y_3$
(3)

>
$$eqn4 := a_{41} \cdot x_1 + a_{42} \cdot x_2 + a_{43} \cdot x_3 + a_{44} \cdot x_4 = y_4$$

 $eqn4 := a_{41} x_1 + a_{42} x_2 + a_{43} x_3 + a_{44} x_4 = y_4$ (4)

(5)

(6)

> $solns := solve(\{eqn1, eqn2, eqn3, eqn4\}, \{x_1, x_2, x_3, x_4\})$:

$$> sol1 := rhs(solns[1])$$

$$sol1 := -\left(a_{12}a_{23}a_{34}y_4 - a_{12}a_{23}a_{44}y_3 - a_{12}a_{24}a_{33}y_4 + a_{12}a_{24}a_{43}y_3 + a_{12}a_{33}a_{44}y_2 - a_{12}a_{34}a_{43}y_2 - a_{13}a_{22}a_{34}y_4 + a_{13}a_{22}a_{44}y_3 + a_{13}a_{24}a_{32}y_4 - a_{13}a_{24}a_{42}y_3 - a_{13}a_{22}a_{44}y_2 + a_{13}a_{34}a_{42}y_2 + a_{14}a_{22}a_{33}y_4 - a_{14}a_{22}a_{43}y_3 - a_{14}a_{23}a_{32}y_4 + a_{14}a_{23}a_{42}y_3 + a_{14}a_{32}a_{43}y_2 - a_{14}a_{33}a_{42}y_2 - a_{22}a_{33}a_{44}y_1 + a_{22}a_{34}a_{43}y_1 + a_{23}a_{32}a_{44}y_1 - a_{23}a_{34}a_{42}y_1 - a_{24}a_{32}a_{43}y_1 + a_{24}a_{33}a_{42}y_1\right) / \left(a_{11}a_{22}a_{33}a_{44} - a_{11}a_{23}a_{32}a_{44} + a_{11}a_{23}a_{34}a_{42} + a_{11}a_{24}a_{32}a_{43} - a_{11}a_{24}a_{33}a_{42} - a_{11}a_{24}a_{33}a_{42} + a_{11}a_{24}a_{32}a_{34}a_{41} - a_{12}a_{24}a_{31}a_{43} + a_{12}a_{21}a_{34}a_{43} + a_{12}a_{23}a_{31}a_{44} - a_{12}a_{23}a_{34}a_{41} - a_{12}a_{24}a_{31}a_{43} + a_{12}a_{24}a_{33}a_{41} + a_{13}a_{21}a_{32}a_{44} - a_{13}a_{21}a_{34}a_{42} - a_{13}a_{22}a_{31}a_{44} + a_{13}a_{22}a_{31}a_{44} - a_{14}a_{21}a_{32}a_{34}a_{41} + a_{13}a_{24}a_{31}a_{42} - a_{13}a_{24}a_{32}a_{41} - a_{14}a_{21}a_{32}a_{43} + a_{14}a_{21}a_{33}a_{42} + a_{14}a_{21}a_{33}a_{42} + a_{14}a_{22}a_{31}a_{43} - a_{14}a_{22}a_{31}a_{44} - a_{14}a_{21}a_{32}a_{31}a_{42} + a_{14}a_{21}a_{33}a_{42} + a_{14}a_{22}a_{31}a_{43} - a_{14}a_{22}a_{31}a_{44} - a_{14}a_{23}a_{31}a_{42} + a_{14}a_{21}a_{33}a_{42} + a_{14}a_{22}a_{31}a_{43} - a_{14}a_{22}a_{31}a_{44} - a_{14}a_{21}a_{32}a_{32}a_{41} - a_{14}a_{21}a_{32}a_{32}a_{41} - a_{14}a_{21}a_{32}a_{32}a_{41} - a_{14}a_{21}a_{32}a_{32}a_{41} - a_{14}a_{21}a_{32}a_{32}a_{41} - a_{14}a_{21}a_{32}a_{32}a_{41} - a_{14}a_{21}a_{23}a_{32}a_{41} - a_{14}a_{21}a_{23}a_{32}a_{41} - a_{14}a_{21}a_{23}a_{32}a_{41} - a_{14}a_{21}a_{23}a_{32}a_{41} - a_{14}a_{21}a_{23}a_{32}a_{41} - a_{14}a_{22}a_{31}a_{42} - a_{14}a_{22}a_{31}a_{42} - a_{14}a_{22}a_{31}a_{42} + a_{14}a_{22}a_{31}a_{42} - a_{14}a_{22}a_{31}a_{42} + a_{14}a_{22}a_{31}a_{42} - a_{14}a_{22}a_{31}a$$

$$\rightarrow sol2 := rhs(solns[2])$$

$$sol2 := \left(a_{11}a_{23}a_{34}y_4 - a_{11}a_{23}a_{44}y_3 - a_{11}a_{24}a_{33}y_4 + a_{11}a_{24}a_{43}y_3 + a_{11}a_{33}a_{44}y_2 - a_{11}a_{34}a_{43}y_2 - a_{13}a_{21}a_{34}y_4 + a_{13}a_{21}a_{44}y_3 + a_{13}a_{24}a_{31}y_4 - a_{13}a_{24}a_{41}y_3 - a_{13}a_{31}a_{44}y_2 + a_{13}a_{34}a_{41}y_2 + a_{14}a_{21}a_{33}y_4 - a_{14}a_{21}a_{43}y_3 - a_{14}a_{23}a_{31}y_4 + a_{14}a_{23}a_{41}y_3 + a_{14}a_{31}a_{43}y_2 - a_{14}a_{33}a_{41}y_2 - a_{21}a_{33}a_{44}y_1 + a_{21}a_{34}a_{43}y_1 + a_{23}a_{31}a_{44}y_1 - a_{23}a_{34}a_{41}y_1 - a_{24}a_{31}a_{43}y_1 + a_{24}a_{33}a_{41}y_1\right) / \left(a_{11}a_{22}a_{33}a_{44} - a_{11}a_{23}a_{32}a_{44} + a_{11}a_{23}a_{34}a_{42} + a_{11}a_{24}a_{32}a_{43} - a_{11}a_{24}a_{33}a_{42} - a_{12}a_{21}a_{33}a_{44} + a_{12}a_{21}a_{34}a_{43} + a_{12}a_{23}a_{31}a_{44} - a_{12}a_{23}a_{34}a_{41} - a_{12}a_{24}a_{31}a_{43} + a_{12}a_{24}a_{33}a_{41} - a_{12}a_{24}a_{31}a_{44} + a_{13}a_{21}a_{32}a_{44} - a_{13}a_{21}a_{34}a_{42} - a_{13}a_{22}a_{31}a_{44} + a_{13}a_{22}a_{34}a_{41}\right)$$

$$+ a_{13} a_{24} a_{31} a_{42} - a_{13} a_{24} a_{32} a_{41} - a_{14} a_{21} a_{32} a_{43} + a_{14} a_{21} a_{33} a_{42} + a_{14} a_{22} a_{31} a_{43}$$

$$- a_{14} a_{22} a_{33} a_{41} - a_{14} a_{23} a_{31} a_{42} + a_{14} a_{23} a_{32} a_{41})$$

$$> sol3 := rhs(solns[3])$$

$$sol3 := -(a_{11} a_{22} a_{34} y_4 - a_{11} a_{22} a_{44} y_3 - a_{11} a_{24} a_{32} y_4 + a_{11} a_{24} a_{42} y_3 + a_{11} a_{32} a_{44} y_2$$

$$- a_{11} a_{34} a_{42} y_2 - a_{12} a_{21} a_{34} y_4 + a_{12} a_{21} a_{44} y_3 + a_{12} a_{24} a_{31} y_4 - a_{12} a_{24} a_{41} y_3$$

$$- a_{12} a_{31} a_{44} y_2 + a_{12} a_{34} a_{41} y_2 + a_{14} a_{21} a_{32} y_4 - a_{14} a_{21} a_{42} y_3 - a_{14} a_{22} a_{31} y_4$$

$$+ a_{14} a_{22} a_{41} y_3 + a_{14} a_{31} a_{42} y_2 - a_{14} a_{32} a_{41} y_2 - a_{21} a_{32} a_{44} y_1 + a_{21} a_{34} a_{42} y_1$$

$$+ a_{22} a_{31} a_{44} y_1 - a_{22} a_{34} a_{41} y_1 - a_{24} a_{31} a_{42} y_1 - a_{24} a_{32} a_{41} y_1) / (a_{11} a_{22} a_{33} a_{44}$$

$$- a_{11} a_{22} a_{34} a_{43} - a_{11} a_{23} a_{32} a_{44} + a_{11} a_{23} a_{34} a_{42} + a_{11} a_{24} a_{32} a_{41} y_1) / (a_{11} a_{22} a_{33} a_{44}$$

$$- a_{11} a_{22} a_{34} a_{43} - a_{11} a_{23} a_{32} a_{44} + a_{11} a_{23} a_{34} a_{42} + a_{11} a_{24} a_{32} a_{31} a_{41} + a_{12} a_{33} a_{42}$$

$$- a_{12} a_{21} a_{33} a_{44} + a_{12} a_{21} a_{34} a_{43} + a_{12} a_{22} a_{31} a_{44} - a_{12} a_{22} a_{33} a_{44} + a_{12} a_{24} a_{33} a_{44} + a_{12} a_{22} a_{34} a_{41} + a_{13} a_{22} a_{34} a_{41} + a_{13} a_{22} a_{34} a_{41} + a_{13} a_{21} a_{32} a_{44} - a_{13} a_{21} a_{32} a_{44} + a_{12} a_{22} a_{31} a_{44} + a_{13} a_{22} a_{31} a_{44} + a_{13} a_{21} a_{22} a_{34} a_{41} + a_{13} a_{22} a_{31} a_{42} + a_{14} a_{22} a_{31} a_{32} a_{31} a_{42} + a_{14} a_{22} a_{32} a_{31} a_{44} + a_{12} a_{22} a_{31} a_{44} + a_{13} a_{22} a_{31} a_{44} + a_{13} a_{22} a_{31} a_{42} + a_{14} a_{23} a_{32}$$

>
$$a_{11} := u_{x10-}$$
 $a_{11} := u_{x10-}$ (9)

 $a_{12} := u_{x40} - a_{12} := u_{x40} - a_{12} = u_{x40} - a_{12} =$

$$a_{13} := -u_{x20+}$$

$$a_{13} := -u_{x20+}$$
(11)

>
$$a_{14} := -u_{x30+}$$
 $a_{14} := -u_{x30+}$ (12)

$$a_{21} := k_{z1} \cdot u_{x10}$$
 (13)

$$\begin{vmatrix} a_{2l} \coloneqq k_{zd} \cdot u_{xl0} & (13) \\ > a_{22} \coloneqq k_{zd} \cdot u_{xl0} & (14) \\ > a_{23} \coloneqq -k_{z2} \cdot u_{x20} + & (15) \\ > a_{24} \coloneqq -k_{z3} \cdot u_{x30} + & (16) \\ > a_{3l} \coloneqq 1 & a_{3l} \coloneqq 1 & (17) \\ > a_{3l} \coloneqq 1 & a_{3l} \coloneqq 1 & (18) \\ > a_{3l} \coloneqq 1 & a_{3l} \coloneqq 1 & (19) \\ > a_{3l} \coloneqq -1 & a_{3l} \coloneqq -1 & (20) \\ > a_{3l} \coloneqq k_{zl} & a_{4l} \coloneqq k_{zl} & (21) \\ > a_{4l} \coloneqq k_{zl} & a_{4l} \coloneqq k_{zl} & (22) \\ > a_{4l} \coloneqq -k_{z3} + & a_{4l} \coloneqq -k_{z3} + & (24) \\ > u_{2l} \coloneqq k_{zl} + & u_{xl0} + & (25) \\ > u_{2l} \coloneqq k_{zl} + & u_{xl0} + & (26) \\ > u_{2l} \coloneqq k_{zl} + & u_{xl0} + & (26) \\ > u_{2l} \coloneqq k_{zl} + & u_{xl0} + & (26) \\ > u_{2l} \coloneqq k_{zl} + & u_{xl0} + & (26) \\ > u_{2l} \coloneqq k_{zl} + & u_{xl0} + & (26) \\ > u_{2l} \coloneqq k_{zl} + & u_{xl0} + & (26) \\ > u_{2l} \coloneqq k_{zl} + & u_{xl0} + & (26) \\ > u_{2l} \coloneqq k_{zl} + & u_{xl0} + & (26) \\ > u_{2l} \coloneqq k_{zl} + & u_{xl0} + & (26) \\ > u_{2l} \coloneqq k_{zl} + & u_{xl0} + & (26) \\ > u_{2l} \coloneqq k_{zl} + & u_{xl0} + & (26) \\ > u_{2l} \coloneqq k_{zl} + & u_{xl0} + & (26) \\ > u_{2l} \coloneqq k_{zl} + & (27) \\ > u_{2l} \coloneqq k_{zl} + & (28) \\ >$$

Note that $ux_0[n]$ denotes $hat\{u\}_{xn}$ and $u_x[n\pm]$ denotes $u_{xn\pm}$.

$$\begin{array}{l} > \ u_{xl0-} \coloneqq -\frac{\mathrm{i}\cdot k_x \cdot \Delta_{\perp l-}}{L_{l-} - k_x^2} \\ & u_{xl0+} \coloneqq \frac{-\mathrm{i}k_x \Delta_{\perp l-}}{-k_x^2 + L_{l-}} \\ > \ u_{xl0+} \coloneqq -\frac{\mathrm{i}\cdot k_x \cdot \Delta_{\perp l+}}{L_{l+} - k_x^2} \\ & u_{xl0+} \coloneqq \frac{-\mathrm{i}k_x \Delta_{\perp l+}}{-k_x^2 + L_{l+}} \\ > \ u_{x20-} \coloneqq -\frac{\mathrm{i}\cdot k_x \cdot \Delta_{\perp 2-}}{L_{2-} - k_x^2} \\ > \ u_{x20-} \coloneqq \frac{-\mathrm{i}\cdot k_x \cdot \Delta_{\perp 2-}}{-k_x^2 + L_{2-}} \\ > \ u_{x20-} \coloneqq \frac{-\mathrm{i}\cdot k_x \cdot \Delta_{\perp 2-}}{-k_x^2 + L_{2-}} \\ > \ u_{x20+} \coloneqq \frac{\mathrm{i}\cdot k_x \cdot \Delta_{\perp 2-}}{L_{2-} - k_x^2} \\ > \ u_{x20+} \coloneqq \frac{-\mathrm{i}\cdot k_x \cdot \Delta_{\perp 3-}}{L_{2-} - k_x^2} \\ > \ u_{x30-} \coloneqq -\frac{\mathrm{i}\cdot k_x \cdot \Delta_{\perp 3-}}{L_{3-} - k_x^2} \\ > \ u_{x30-} \coloneqq -\frac{\mathrm{i}\cdot k_x \cdot \Delta_{\perp 3-}}{L_{3-} - k_x^2} \\ > \ u_{x30+} \coloneqq -\frac{\mathrm{i}\cdot k_x \cdot \Delta_{\perp 3-}}{L_{3-} - k_x^2} \\ > \ u_{x30+} \coloneqq -\frac{\mathrm{i}\cdot k_x \cdot \Delta_{\perp 3-}}{L_{4-} - k_x^2} \\ > \ u_{x30-} \coloneqq -\frac{\mathrm{i}\cdot k_x \cdot \Delta_{\perp 3-}}{L_{4-} - k_x^2} \\ > \ u_{x30-} \coloneqq -\frac{\mathrm{i}\cdot k_x \cdot \Delta_{\perp 3-}}{L_{4-} - k_x^2} \\ (34) \end{array}$$

$$| > u_{x40+} := -\frac{i \cdot k_x \cdot \Delta_{14+}}{L_{4+} - k_x^2}$$

$$| u_{x40+} := -\frac{1 \cdot k_x \cdot \Delta_{14+}}{-k_x^2 + L_{4+}}$$

$$| (36)$$

$$| > L_{1-} := \Delta_{N_1-}^2 + k_{N_1-}^2$$

$$| L_{1-} := k_{N_1-}^2 + k_{N_1-}^2$$

$$| L_{1+} := k_{N_1+}^2 + \Delta_{N_1+}^2$$

$$| L_{2-} := k_{N_2-}^2 + k_{N_1-}^2$$

$$| L_{2-} := k_{N_2-}^2 + k_{N_1-}^2$$

$$| L_{2-} := k_{N_2-}^2 + k_{N_1-}^2$$

$$| L_{2+} := k_{N_1+}^2 + \Delta_{N_2-}^2$$

$$| L_{2+} := k_{N_1+}^2 + \Delta_{N_2-}^2$$

$$| L_{2+} := k_{N_1+}^2 + k_{N_2-}^2$$

$$| L_{3+} := k_{N_1-}^2 + k_{N_1-}^2$$

$$| L_{3+} := k_{N_1+}^2 + k_{N_2+}^2$$

$$| L_{3+} := k_{N_1+}^2 + k_{N_2+}^2$$

$$| L_{4-} := k_{N_1-}^2 + k_{N_1-}^2$$

$$| L_{4-} := k_{N_1-}^2 + k_{N_1-}^2$$

$$| L_{4+} := k_{N_1+}^2 + \Delta_{N_2+}^2$$

$$| L_{4+} := k_{N_1+}^2 + \Delta_{N_2+}^2$$

$$| L_{4+} := k_{N_1+}^2 + \Delta_{N_2+}^2$$

$$| (42)$$

$$| > \Delta_{11-} := i \cdot (k_y \cdot \cos(\alpha) - k_{21-} \cdot \sin(\alpha))$$

$$| \Delta_{11-} := 1 \cdot (k_y \cdot \cos(\alpha) - k_{21-} \cdot \sin(\alpha))$$

$$| \Delta_{11+} := 1 \cdot (k_y \cdot \cos(\alpha) - k_{21-} \cdot \sin(\alpha))$$

$$| \Delta_{11+} := 1 \cdot (k_y \cdot \cos(\alpha) - k_{21-} \cdot \sin(\alpha))$$

$$| \Delta_{12+} := 1 \cdot (k_y \cdot \cos(\alpha) - k_{21-} \cdot \sin(\alpha))$$

$$| \Delta_{12+} := 1 \cdot (k_y \cdot \cos(\alpha) - k_{21-} \cdot \sin(\alpha))$$

$$| \Delta_{12+} := 1 \cdot (k_y \cdot \cos(\alpha) - k_{22-} \cdot \sin(\alpha))$$

$$| \Delta_{12+} := 1 \cdot (k_y \cdot \cos(\alpha) - k_{22-} \cdot \sin(\alpha))$$

$$| \Delta_{12+} := 1 \cdot (k_y \cdot \cos(\alpha) - k_{22-} \cdot \sin(\alpha))$$

$$| \Delta_{12+} := 1 \cdot (k_y \cdot \cos(\alpha) - k_{22-} \cdot \sin(\alpha))$$

$$| \Delta_{12+} := 1 \cdot (k_y \cdot \cos(\alpha) - k_{22-} \cdot \sin(\alpha))$$

$$| \Delta_{12+} := 1 \cdot (k_y \cdot \cos(\alpha) - k_{22-} \cdot \sin(\alpha))$$

$$| \Delta_{12+} := 1 \cdot (k_y \cdot \cos(\alpha) - k_{22-} \cdot \sin(\alpha))$$

$$| \Delta_{12+} := 1 \cdot (k_y \cdot \cos(\alpha) - k_{22-} \cdot \sin(\alpha))$$

$$| \Delta_{12+} := 1 \cdot (k_y \cdot \cos(\alpha) - k_{22-} \cdot \sin(\alpha))$$

(48)

$$\begin{array}{l} \Delta_{1,2+} := 1 \left(k_y \cos(\alpha) - k_{2,2+} \sin(\alpha) \right) & (48) \\ > \Delta_{1,3-} := i \cdot \left(k_y \cdot \cos(\alpha) - k_{2,3-} \sin(\alpha) \right) & \Delta_{1,3-} := 1 \left(k_y \cos(\alpha) - k_{2,3-} \sin(\alpha) \right) & (49) \\ > \Delta_{1,3+} := i \cdot \left(k_y \cdot \cos(\alpha) - k_{2,3+} \sin(\alpha) \right) & (50) \\ > \Delta_{1,3+} := i \cdot \left(k_y \cdot \cos(\alpha) - k_{2,4-} \sin(\alpha) \right) & (50) \\ > \Delta_{1,4-} := i \cdot \left(k_y \cdot \cos(\alpha) - k_{2,4-} \sin(\alpha) \right) & (51) \\ > \Delta_{1,4-} := i \cdot \left(k_y \cdot \cos(\alpha) - k_{2,4-} \sin(\alpha) \right) & (52) \\ > \Delta_{1,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,1-} \cos(\alpha) \right) & (53) \\ > \Delta_{1,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,1-} \cos(\alpha) \right) & (53) \\ > \Delta_{1,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,1-} \cos(\alpha) \right) & (53) \\ > \Delta_{1,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,1-} \cos(\alpha) \right) & (53) \\ > \Delta_{1,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,1-} \cos(\alpha) \right) & (54) \\ > \Delta_{1,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,1-} \cos(\alpha) \right) & (54) \\ > \Delta_{1,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,1-} \cos(\alpha) \right) & (54) \\ > \Delta_{1,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,1-} \cos(\alpha) \right) & (54) \\ > \Delta_{1,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,2-} \cos(\alpha) \right) & (54) \\ > \Delta_{1,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,2-} \cos(\alpha) \right) & (55) \\ > \Delta_{2,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,2-} \cos(\alpha) \right) & (55) \\ > \Delta_{2,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,1-} \cos(\alpha) \right) & (56) \\ > \Delta_{3,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,4-} \cos(\alpha) \right) & (57) \\ > \Delta_{3,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,4-} \cos(\alpha) \right) & (58) \\ > \Delta_{3,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,4-} \cos(\alpha) \right) & (58) \\ > \Delta_{3,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,4-} \cos(\alpha) \right) & (59) \\ > \Delta_{3,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,4-} \cos(\alpha) \right) & (59) \\ > \Delta_{3,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,4-} \cos(\alpha) \right) & (59) \\ > \Delta_{3,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,4-} \cos(\alpha) \right) & (59) \\ > \Delta_{3,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,4-} \cos(\alpha) \right) & (59) \\ > \Delta_{3,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,4-} \cos(\alpha) \right) & (59) \\ > \Delta_{3,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,4-} \cos(\alpha) \right) & (59) \\ > \Delta_{3,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,4-} \cos(\alpha) \right) & (59) \\ > \Delta_{3,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,4-} \cos(\alpha) \right) & (59) \\ > \Delta_{3,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,4-} \cos(\alpha) \right) & (59) \\ > \Delta_{3,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,4-} \cos(\alpha) \right) & (59) \\ > \Delta_{3,4-} := i \cdot \left(k_y \cdot \sin(\alpha) + k_{2,4-} \cos(\alpha) \right) & (59) \\ > \Delta_{3,4-} := i \cdot$$

$$k_{z1+} := \frac{k_{\parallel +}}{\cos(\alpha)} - k_y \tan(\alpha)$$

$$k_{z2-} := -\frac{k_{\parallel -}}{\cos(\alpha)} - k_y \tan(\alpha)$$

$$k_{z2-} := -\frac{k_{\parallel +}}{\cos(\alpha)} - k_y \tan(\alpha)$$

$$k_{z2+} := -\frac{k_{\parallel +}}{\cos(\alpha)} - k_y \tan(\alpha)$$

$$k_{z2+} := -\frac{k_{\parallel +}}{\cos(\alpha)} - k_y \tan(\alpha)$$

$$k_{z2+} := -\frac{k_{\parallel +}}{\cos(\alpha)} - k_y \tan(\alpha)$$

$$k_{z3-} := i \cdot \sqrt{k_x^2 + k_y^2 - k_{\parallel -}^2}$$

$$k_{z3-} := i \cdot \sqrt{k_x^2 + k_y^2 - k_{\parallel +}^2}$$

$$k_{z3+} := i \cdot \sqrt{k_x^2 + k_y^2 - k_{\parallel +}^2}$$

$$k_{z3+} := i \cdot \sqrt{k_x^2 + k_y^2 - k_{\parallel +}^2}$$

$$k_{z3+} := -i \cdot \sqrt{k_x^2 + k_y^2 - k_{\parallel +}^2}$$

$$k_{z4+} := -i \cdot \sqrt{k_x^2 + k_y^2 - k_{\parallel +}^2}$$

$$k_{z4+} := -i \cdot \sqrt{k_x^2 + k_y^2 - k_{\parallel +}^2}$$

$$(68)$$

>
$$k_{z4+} := -i \cdot \sqrt{k_x^2 + k_y^2 - k_{\parallel +}^2}$$

$$k_{z4+} := -i \sqrt{k_x^2 + k_y^2 - k_{\parallel +}^2}$$
(68)

$$k_{z4+} \coloneqq -1 \sqrt{k_x + k_y - k_{\parallel+}} \tag{68}$$

$$k_x \coloneqq \frac{k_{\parallel +}}{\epsilon} \tag{69}$$

$$k_{y} \coloneqq a_{y} \cdot k_{\parallel +}$$

$$k_{y} \coloneqq a_{y} k_{\parallel +}$$

$$(70)$$

>
$$k_{\parallel-} := \frac{\kappa_{\chi}}{\epsilon_{-}}$$

$$k_{\parallel-} := \frac{k_{\parallel+}}{\epsilon_{+}\epsilon_{-}} \tag{71}$$

Need to help maple to take limit as epsilon - and epsilon + go to zero by taking terms that go to Linfinity out of the square root.

$$\frac{\epsilon_{+}\left(-a_{y}+\sin(\alpha)\right)}{\cos(\alpha)}\tag{78}$$

> $simplify(mtaylor(u_{x2+}, [\epsilon_-, \epsilon_+], 2))$ $\frac{\epsilon_+(a_y + \sin(\alpha))}{\cos(\alpha)}$

$$\frac{\epsilon_{+}\left(a_{y}+\sin\left(\alpha\right)\right)}{\cos\left(\alpha\right)}\tag{79}$$

> $simplify(mtaylor(u_{x3+}, [\epsilon_-, \epsilon_+], 2))$

$$-\frac{2\sin(\alpha)\epsilon_{+}}{\cos(\alpha)} \tag{80}$$

u_perp leading order terms

> simplify(mtaylor(sol1,
$$[\epsilon_{-}, \epsilon_{+}], 4)$$
)

$$-2 I \epsilon_{-}^{2} \epsilon_{+} \cos(\alpha) \operatorname{csgn}(k_{\parallel +})$$
(81)

> $simplify(mtaylor(sol2, [\epsilon_-, \epsilon_+], 3))$

$$\frac{1\cos(\alpha) \in \epsilon_{+} k_{\parallel +}}{\sqrt{-k_{\parallel +}^{2}}} \tag{82}$$

$$\stackrel{\square}{>}$$
 simplify (mtaylor (sol3, [ϵ_{-} , ϵ_{+}], 1))

(83)

 $\rightarrow simplify(mtaylor(sol4, [\epsilon_-, \epsilon_+], 2))$

$$\frac{2\operatorname{I}\epsilon_{+}\operatorname{csgn}(k_{\parallel+})\sin(\alpha)^{2}}{\cos(\alpha)}$$
(84)

bx leading order terms

$$\begin{array}{|c|c|c|} & b_{x4-} \coloneqq \frac{\Delta_{||4-} \cdot u_{x4-}}{\mathrm{i} \cdot k_{||+}} : \\ \\ & b_{x1+} \coloneqq \frac{\Delta_{||1+} \cdot u_{x1+}}{\mathrm{i} \cdot k_{||+}} : \end{array}$$

$$>$$
 $b_{xl+} := \frac{\Delta_{\parallel l+} \cdot u_{xl+}}{\mathbf{i} \cdot k_{\parallel+}}$

$$b_{x2+} := \frac{\Delta_{\parallel 2+} \cdot u_{x2+}}{\mathbf{i} \cdot k_{\parallel +}}$$
:

$$b_{x3+} := \frac{\Delta_{||3+} \cdot u_{x3+}}{\mathbf{i} \cdot k_{||+}} :$$

$$| > simplify(mtaylor(b_{xl-}, [\epsilon_-, \epsilon_+], 1)) - 21 \sin(\alpha) \cos(\alpha)k_{y+}) |$$

$$> simplify(mtaylor(b_{xl-}, [\epsilon_-, \epsilon_+], 2)) - \frac{-21k_{y+} \epsilon_- \cos(\alpha)^2}{\sqrt{-k_{y+}^2} \sin(\alpha)} |$$

$$> simplify(mtaylor(b_{xl+}, [\epsilon_-, \epsilon_+], 2)) - \frac{\epsilon_+ (-a_y + \sin(\alpha))}{\cos(\alpha)} |$$

$$> simplify(mtaylor(b_{x2+}, [\epsilon_-, \epsilon_+], 2)) - \frac{\epsilon_+ (a_y + \sin(\alpha))}{\cos(\alpha)} |$$

$$> simplify(mtaylor(b_{x3+}, [\epsilon_-, \epsilon_+], 2)) - 21 \sin(\alpha) \cos(\alpha) |$$

$$> simplify(mtaylor(b_{x3+}, [\epsilon_-, \epsilon_+], 2)) - 21 \sin(\alpha) \cos(\alpha) |$$

$$> b_{\mu} = \frac{\Delta_{yl-\mu} - \sin(\alpha)}{|k_y|} |$$

$$> b_{\mu} = \frac{\Delta_{yl-\mu} - \sin(\beta)}{|k_y|} |$$

$$> b_{\mu} = \frac{\Delta_{yl-\mu} - \sin(\beta)}{|k_y$$

| >
$$simplify(mtaylor(b_{\perp 3+}, [\epsilon_{-}, \epsilon_{+}], 1))$$
 | $-2 \sin(\alpha)^{2}$ | (94)
| b_par leading order terms | $b_{\parallel J-} := -\frac{i \cdot k_{x} \cdot u_{xJ-} + \Delta_{\perp J-} \cdot soll}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J-} := -\frac{i \cdot k_{x} \cdot u_{xJ-} + \Delta_{\perp J-} \cdot soll}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+}}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{x} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{xJ} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{xJ} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot k_{xJ} \cdot u_{xJ+} + \Delta_{\perp J+} \cdot sold}{i \cdot k_{\parallel J+}} :$ | $b_{\parallel J+} := -\frac{i \cdot$

 $2\sin(\alpha)\cos(\alpha)$

(99)