

# ECE 18-649

# Final Project Report

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December 02, 2013

Group # 18

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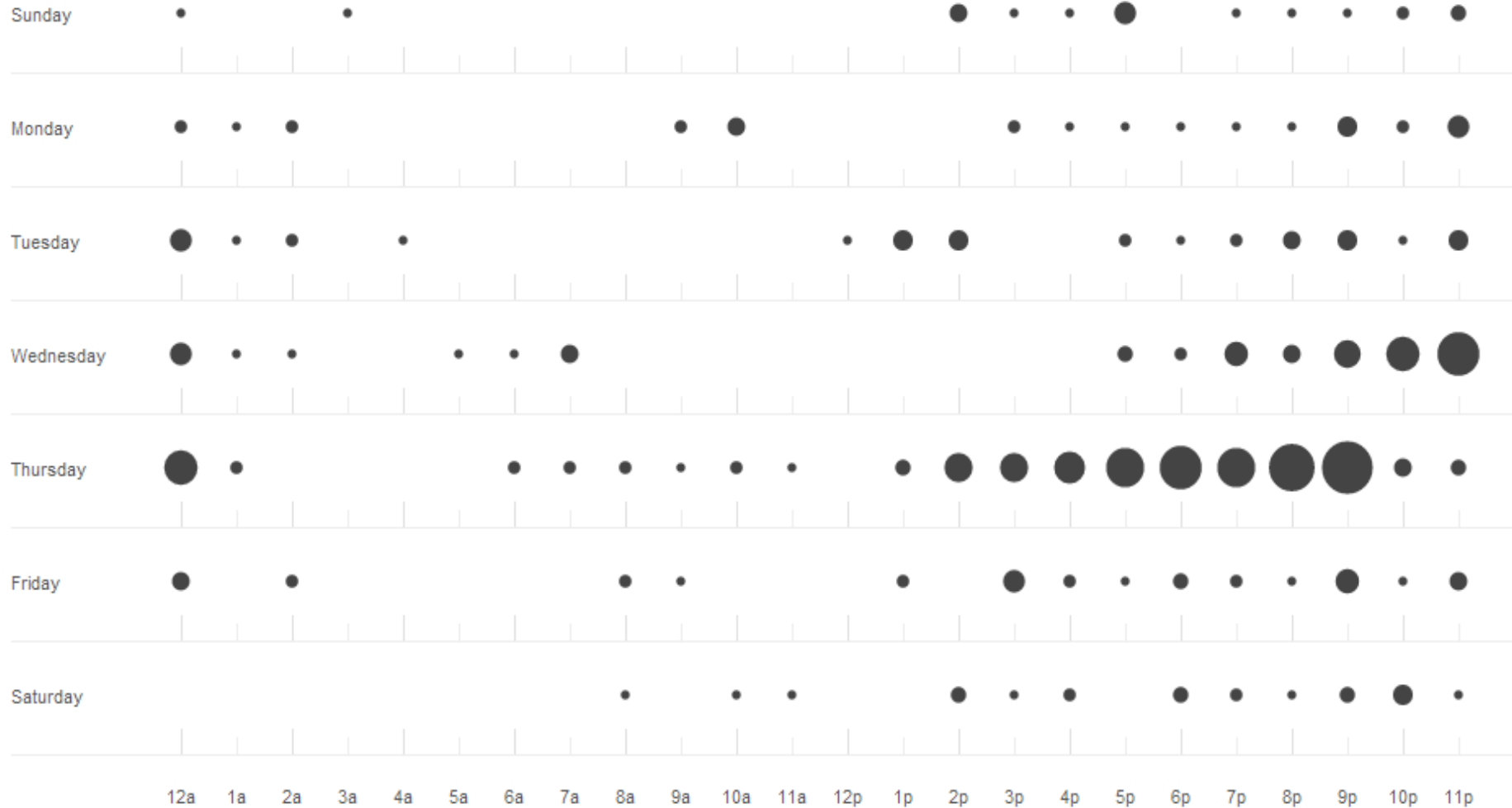
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# Overview

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- ❑ Project statistics
  - GitHub Commit Trends
  - Now vs. Midsemester
- ❑ Door Control
  - Design
  - Implementation
- ❑ Lessons learned
- ❑ Open issues
- ❑ Suggestions

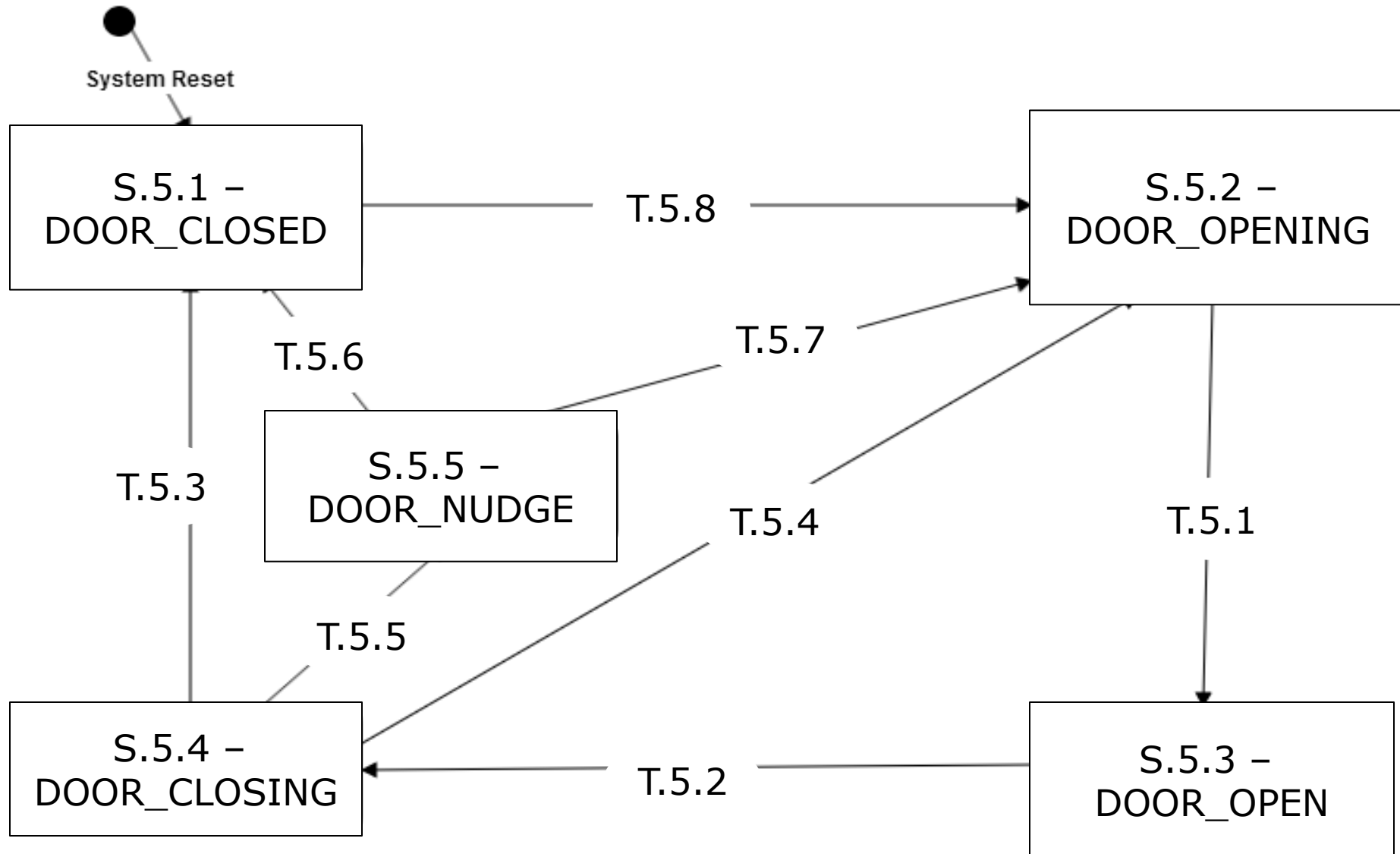
# Project Statistics



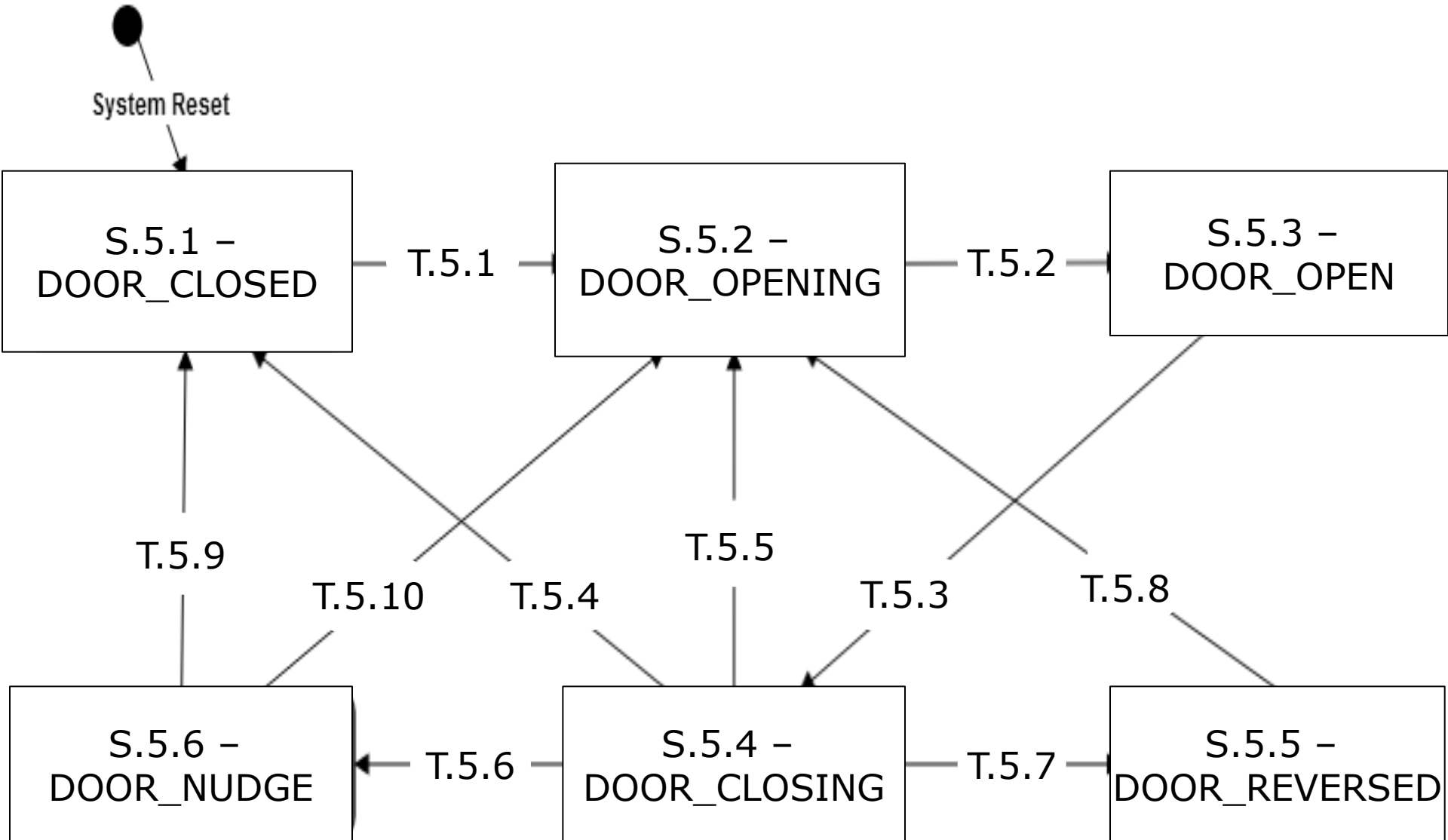
# Project Statistics

	Midsemester	Now
(# of sequence diagrams; # of arcs)	(18; 146)	(19; 163)
# of lines of requirements	58	75
(# of state charts; # of states; # of arcs)	(7; 31; 24)	(7; 48; 30)
# of lines of non-comment code	1302	1798
# of test files written (incl. ".cf" files and the custom acceptance test for P8)	54	60
# of peer reviews	52	81
total # of defects found & fixed via peer reviews	40	64
total # of defects found & fixed via test & other	12	20
# of revisions	20	48
# of GitHub commits	308	453

# Design of Door Control - Old



# Design of Door Control – New



# Design of Door Control - New

State	Description	Actions
S.5.1	DOOR_CLOSED	DoorMotor[b,r] = Stop, CountDown = 0, ReversedOnce = False
S.5.2	DOOR_OPENING	DoorMotor[b,r] = Open, Dwell = mDesiredDwell[b], CountDown = Dwell
S.5.3	DOOR_OPEN	DoorMotor[b,r] = Stop, Decrement CountDown
S.5.4	DOOR_CLOSING	DoorMotor[b,r] = Close
S.5.5	DOOR_REVERSED	ReversedOnce = True
S.5.6	DOOR_NUDGE	DoorMotor[b,r] = Nudge

# Design of Door Control

Transition #	Guard Condition
T.5.1	$mAtFloor[mDesiredFloor.f, b] == True \ \&\& \ (mDesiredFloor.b == b \    \ mDesiredFloor.b == BOTH) \ \&\& \ (mDriveSpeed(0,d) == True \    \ mDriveSpeed(s, Stop) == True)$
T.5.2	$mDoorOpened[b,r] == True$
T.5.3	$CountDown \leq 0 \ \&\& \ mCarWeight(x) \leq MaxCarCapacity$
T.5.4	$mDoorClosed[b,r] == True \ \&\& \ mCarWeight(x) \leq MaxCarCapacity$
T.5.5	$mCarWeight(x) > MaxCarCapacity$
T.5.6	$mDoorReversal[b,*] == True \ \&\& \ mCarWeight(x) \leq MaxCarCapacity \ \&\& \ ReversedOnce == True \ \&\& \ mDoorClosed[b,r] == False$
T.5.7	$mDoorReversal[b,*] == True \ \&\& \ mCarWeight(x) \leq MaxCarCapacity \ \&\& \ ReversedOnce == False \ \&\& \ mDoorClosed[b,r] == False$
T.5.8	None
T.5.9	$mDoorClosed[b,r] == True \ \&\& \ mCarWeight(x) \leq MaxCarCapacity$
T.5.10	$mDoorOpened[b,r] == False \ \&\& \ mCarWeight(x) > MaxCarCapacity$



# Door Control Implementation

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```
switch (state) {  
    // #state '5.1'  
    case DOOR_CLOSED:  
        // #state '5.1' actions  
        localDoorMotor.set(DoorCommand.STOP);  
        countDown = SimTime.ZERO;  
        reversedOnce = false;  
        int desiredFloor = mDesiredFloor.getFloor();  
        if (desiredFloor == 0) { break; }  
  
        // #transition 'T.5.1'  
        Hallway desiredHallway = mDesiredFloor.getHallway();  
        boolean atFloor = mAtFloor.isAtFloor(desiredFloor, hallway) &&  
            (desiredHallway == hallway || desiredHallway == Hallway.BOTH);  
  
        if (atFloor && (mDriveSpeed.getSpeed() == 0.0 || DriveSpeed.getDirection()  
            == Direction.STOP)) {  
            newState = State.DOOR_OPENING;  
        }  
        else { newState = state; }  
        break;  
}
```

# Design of Door Control

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```
case DOOR_OPENING:
localDoorMotor.set(DoorCommand.OPEN);
countDown = Dwell;
if (mDoorOpened.getValue() == true) {
    newState = State.DOOR_OPEN;
}

case DOOR_OPEN:
localDoorMotor.set(DoorCommand.STOP);
countDown = SimTime.subtract(countDown, period);
if (countDown.isLessThanOrEqual(SimTime.ZERO) &&
    mCarWeight.getWeight() <= Elevator.MaxCarCapacity) {
    newState = State.DOOR_CLOSING;
}

case DOOR_CLOSING:
localDoorMotor.set(DoorCommand.CLOSE);
//#transition 'T.5.4'
if (mDoorClosed.getValue() == true &&
    mCarWeight.getWeight() <= Elevator.MaxCarCapacity) {
    newState = State.DOOR_CLOSED;
}
```

# Design of Door Control

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```
//#transition 'T.5.5'
else if (mDoorOpened.getValue() == false &&
        mCarWeight.getWeight() > Elevator.MaxCarCapacity) {
    newState = State.DOOR_OPENING;
}
//#transition 'T.5.6'
else if (mDoorReversal.getEitherReversed() == true &&
        reversedOnce == true && mCarWeight.getWeight() <=
        Elevator.MaxCarCapacity)
{
    newState = State.DOOR_NUDGE;
}
//#transition 'T.5.7'
else if (mDoorReversal.getEitherReversed() == true &&
        reversedOnce == false && mCarWeight.getWeight() <=
        Elevator.MaxCarCapacity)
{
    newState = State.DOOR_REVERSED;
}
case DOOR_REVERSED:
    reversedOnce = true;
```

# Design of Door Control

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```
case DOOR_NUDGE:
    localDoorMotor.set(DoorCommand.NUDGE);
    // #transition 'T.5.9'
    if(mDoorClosed.getValue() == true &&
        mCarWeight.getWeight() <= Elevator.MaxCarCapacity) {
        newState = State.DOOR_CLOSED;
    }
    // #transition 'T.5.10'
    else if(mDoorOpened.getValue() == false &&
        mCarWeight.getWeight() > Elevator.MaxCarCapacity) {
        newState = State.DOOR_OPENING;
    }
```

# Unit Testing – Door Control

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- ▣ Unit Test Files – 3
- ▣ Total Assertions passed – 244
- ▣ Failing Assertions – 0

# Lessons Learned

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- ❑ Version control is your friend
- ❑ Consistency facilitates communication
  - Use a single naming/style convention
  - Use same software for state charts and sequence diagrams
- ❑ Most of your time should be spent on design rather than on implementation and testing

# Lessons Learned

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- ❑ Rerun all tests after changing code
- ❑ What worked well
  - Peer reviews
    - ❑ Helped catch almost all the major bugs, made sure we had a solid design
  - State charts
    - ❑ Great guide to implementation
  - Scenarios and Use Cases
    - ❑ Helped us visualize different elevator behaviors

# Lessons Learned

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- Use checklists
- What didn't work well
  - Unit and Integration tests
    - Most errors were due to timing rather than implementation



# Open Issues

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- ❑ Even smarter Dispatcher design
  - Considered skipping HallCalls when car is overweight
  - Too complex, current version works well, not enough time

# Open Issues

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- ❑ Controllers assume all other controllers work perfectly
  - Network faults could cause very unpredictable behavior
  - Would need to redesign for reliability
  - Can't be added on

# Suggestions

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- ❑ Run a script that runs acceptance tests
  - Run them overnight, check for any RT warnings/exceptions/stranded passengers
  - Great for figuring out weird, rare bugs
  
- ❑ Found a bug during acceptance testing?
  - Replace `super("name", verbose)` with `super("name", true)`
  - Easy way to get all `log()` outputs without adding in a bunch of `System.out.println()`
  - Make sure you undo this before handin!

# Suggestions

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## □ For simulator:

- Add timing information in .stats outputs
- Makes it possible to run all tests in bulk instead of running them one by one and checking stdout output