

Example 2: Sweep Servo

- **Digital I/O**
 - pin12, Pulse Width Modulation (PWM) pin with Duty Cycle
- **Servo library** to control the **servo step motor**.
- Questions to answer
 - How to include a library in the sketch? What is the difference between `#include <xxx.h>` and `#include "xxx.h"`?
 - In the sketch, which one is the class of the servo motor? Which is the object of servo motor?
 - In the sketch, how to use one function provided by the class?
 - If you need to control several motors, what changes do you need to make for the circuit and for the sketch?